

COMBIVIS 6

MANUAL V6.7.0







1 Preface

The described hardware and software are developments of the KEB Automation KG. The enclosed documents correspond to conditions valid at printing. Misprint, mistakes, and technical changes reserved.

1.1 Signal words and symbols

Certain operations can cause hazards during the installation, operation or thereafter. Refer to the safety information in the documentation about these operations. Security signs are located on the device or on the machine. A warning contains signal words which are explained in the following table:

 DANGER	➤ Dangerous situation, which will cause death or serious injury in case of non-observance of this safety instruction.
 WARNING	➤ Dangerous situation, which may cause death or serious injury in case of non-observance of this safety instruction.
 CAUTION	➤ Dangerous situation, which may cause minor injury in case of non-observance of this safety instruction.
ATTENTION	➤ Situation, which can cause damage to property in case of non-observance.
	➤ Is used when the result will be better, more economic, or trouble-free by following these procedures.

1.2 More symbols

- ▶ This arrow starts an action step.
- / - Enumerations are marked with dots or indents.
- => Cross reference to another chapter or another page.

	Note to further documentation. Document search on www.keb.de	
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1.3 Laws and guidelines

KEB Automation KG confirms with the CE mark and the EC declaration of conformity that our device complies with the essential safety requirements.

The CE mark is located on the name plate. The EC declaration of conformity can be downloaded on demand via our website. Further information is provided in chapter "Certification".

1.4 Warranty

The warranty on design, material or workmanship for the acquired device is given in the current terms and conditions.

	Here you will find our current terms and conditions. Terms and Conditions	
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Further agreements or specifications require a written confirmation.

1.5 Support

Through multiple applications not every imaginable case has been taken into account. If you require further information or if problems occur which are not treated detailed in the documentation, you can request the necessary information via the local KEB Automation KG agency.

The use of our units in the target products is beyond of our control and therefore exclusively the responsibility of the machine manufacturer, system integrator or customer.

The information contained in the technical documentation, as well as any user-specific advice in spoken and written and through tests, is made to best of our knowledge and information about the application. However, they are considered for information only without responsibility. This also applies to any violation of industrial property rights of a third-party.

Selection of our units in view of their suitability for the intended use must be done generally by the user.

Tests can only be done by the machine manufacturer in combination with the application. They must be repeated, even if only parts of hardware, software or the unit adjustment are modified.



1.6 Copyright

The customer may use the instructions for use as well as further documents or parts from it for internal purposes. Copyrights are with KEB Automation KG and remain valid in its entirety.

Other wordmarks or/and logos are trademarks (™) or registered trademarks (®) of their respective owners and are listed in the footnote on the first occurrence.

1.7 License agreement

The conditions for using of KEB Software are listed in the GENERAL TERMS OF CONTRACT FOR THE CESSION OF SOFTWARE LICENSE PRODUCTS (EULA).

	Here you will find our current EULA	
	EULA	

1.8 Terms / Definitions

Download	Transferring / writing data from COMBIVIS to the KEB device
Upload	Transferring / reading data from the KEB device to COMBIVIS
Configuration-ID (cfg)	Any device type, firmware version, speed mode gets a unique identifier (number). Based on this, COMBIVIS can identify the device and select and display the correct parameter description.
CV6	Abbreviation for COMBIVIS 6
CVs6	Abbreviation for COMBIVIS studio 6

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2 Overview

2.1 Properties

- Based on CODESYS Automation Platform and .NET-Framework
- History for program errors and messages
- Integrated start-up assistants (wizards)
- Integrated KEB document database
- Integrated device configurator
- Integrated determination of the energy efficiency of KEB COMBIVERT
- Integrated Safety Editor for safe communication to the KEB Safety Modules
- 16-channel oscilloscope
- Serial communication via protocol DIN 66019II (serial or USB) or TCP/IP UDP
- IP-addressing for several devices
- Automatically detection of USB-converters
- Searching on several serial interfaces in parallel
- HSP-5 service via KEB-USB-serial converter or KEB port expander
- Update function via Internet
- Can be used to COMBIVIS 5 in parallel, but no service of the same COM-Port
- Support of COMBIVERT type F5/ B6/ G6/ F6/ H6/ P6/ S6/ T6, COMBICONTROL C6 and Step-per/BLDC
- Older devices like COMBIVERT 51 to 58 / F0 to F4 are not supported!
- No visualization of operator parameter menu of F5 Devicenet- and early InterBus- and CAN Operators (separate operator menu in CV5)
- Different versions can be installed in parallel

Enhancements of version 6.7.0 compared to version 6.6.0 amongst others:

- New versions can be installed in parallel to former version
- Version manager
- Project can be stored compatible to current or former version or other profile
- Navigator order of devices and folders enhanced
- Storing of parameter lists format "dw5" preferred to "cvxpl"
- Backup preferably creates "dw5" format (previously "cvxpl")
- Scopes can be attached to the device
- Display of STRING parameters
- Package Manager displayed in CV 6 for deinstalling of packages
- Import / Export of CV options
- FTP communication accelerated, i.e., device storage wizard works faster.
- Vendor name is printed out with Safety Editor configuration
- Safety Editor uses English with language setting "not English or German"
- Anonymised usage analysis
- Fieldbus wizard with selection of process data size
- No release for Microsoft Windows 7 or 8/8.1
- Additional Profile COMBIVIS studio 6 safety

Fixed Bugs of version 6.6.0

- Errors when printing parameter lists and configurations
- CAN EDS file, various errors
- IEC Plaintexts in German generated error message
- Safety Editor "Year 2038 Bug"
- Recipe generation error with empty first line
- Script error due to incorrect call of KEB homepage
- False access type in Powerlink xdd export
- S6 standard mapping, data type of "modes of operation" wrong

For more information => Release Info under menu "Help" → "Show release notes"

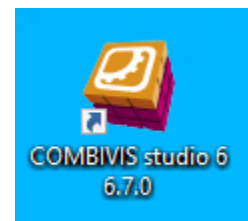
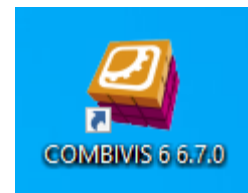
2.2 Types

The free of charge COMBIVIS installation file consists of 3 modules:

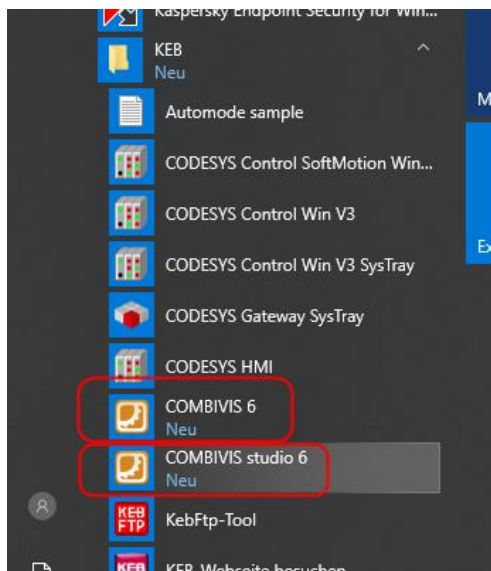
The respective program version is opened by selecting the program profile.

- Parameterization version "**COMBIVIS 6**" (issue of this manual)
 - For parameterizing and analysis of KEB COMBIVERT
 - Calculation of energy efficiency
 - KEB Product Configurator
 - Document data bench (registration needed)
 - Without run time limitation

- Programming version "**COMBIVIS studio 6**"
 - Additionally:
 - SPS programming in IEC 61131-3 (C6 controllers)
 - Bus configuration (e. g. EtherCAT, CAN, Profinet ...)
 - Configuration of Remote I/So
 - Other additional components
 - Licensing requested with costs
 - Demo version for free, time-constrained (1h) and no boot projects

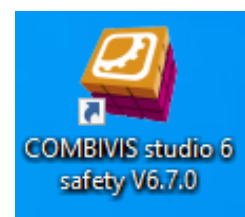


The two modules can be started via the desktop icons or the start menu.



Optional:

- Programming version „**COMBIVIS studio 6 Safety**“
 - Additionally, to COMBIVIS studio 6:
 - CODESYS Safety Extensions
 - Adaptions for safety



This version is safety conform tested and fixed.

So, some later fixed enhancements or bugfixes of COMBIVIS studio 6 might

not be included.

The offering of the profile can be selected at installation of COMBIVIS studio 6.
Opening by icon on the desktop.

Additionally, the other program files can be installed:

- Visualization platform “COMBIVIS studio HMI”
 - Editor with complete SCADA functionality
 - Wide graphics library and toolbox with customized control elements
 - Easy data exchange with COMBIVIS studio 6 projects
 - Chargeable licensing required
 - Demo version for free, time-constrained

- Remote maintenance with “COMBIVIS connect”
 - Monitoring, project update and maintenance via "end-to-end"-VPN
 - Allows direct global support of KEB devices
 - Control centre free of charge
 - Requires one-time licensing a company domain

For further information, please contact KEB.

2.3 System Requirements

ATTENTION

- COMBIVIS 6 and COMBIVIS studio 6 are designed to work on Windows Desktop systems only. Other systems like Windows Embedded, Windows IoT or Windows Server are not supported.

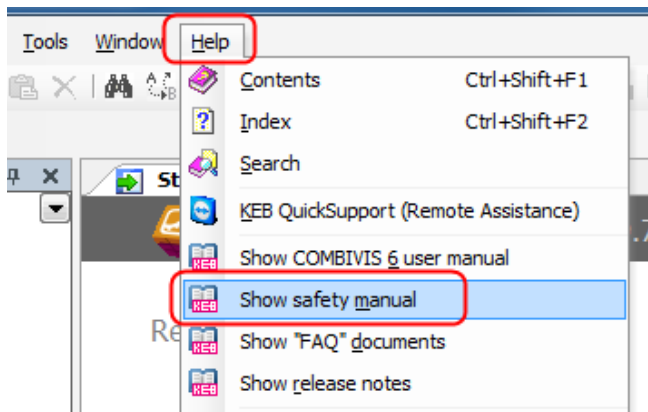
Minimum equipment for smaller projects:

- Windows 10, in 32-bit or 64-bit version
- Microsoft .NET framework version 4.7.2 (will be installed if it is missing)
- 2 GHz Processor
- 2 GB RAM (4 GB recommended)
- 2.5 GB hard disk storage free
- Screen resolution min. 1024 x 768
- Display size 100% or 125% (150% with limitations)

For the **Safety Module Editor** in COMBIVIS (Configuration / parameterization of safety modules in COMBI-VERT F6, S6, and H6) (=> [14 KEB Safety Module Editor](#)) some other requirements are valid:

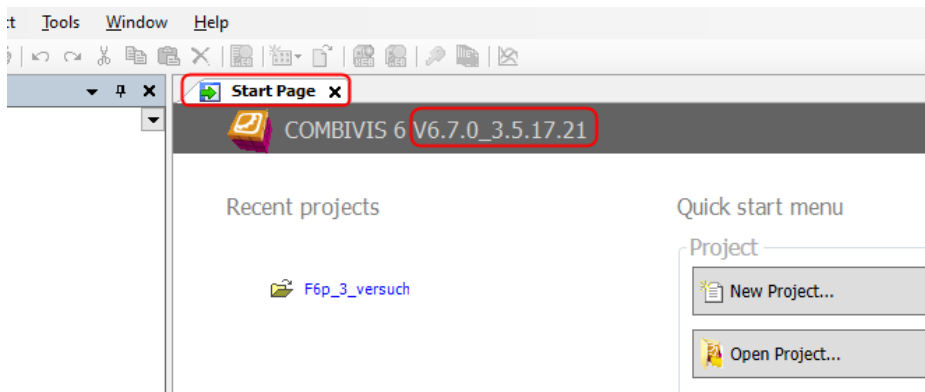
- The safety module editor requires a Microsoft Windows 10 operating system.
- The current service pack should be installed.
- The language must be English or German. If not, English is used.

The system requirements for the **COMBIVIS studio 6 Safety Editor** (Programming of KEB Safety PLC und Safety I/O modules) can be found in the current manual. It is accessible via menu bar: “Help” → “Show safety-manual”.



2.4 Version Information

The version information is displayed at the start page



And, by menu: "Help" → "About..."



Version of COMBIVIS 6:
e.g., 6.7.0

Version of underlying CODESYS-Software:
3.5.17.21

2.5 Online Tutorials

On the KEB YOUTUBE channel information and tutorials are offered.

Information, Applications, Technology:

<https://www.youtube.com/channel/UCf577xwEcis-zTqrSAUCVXw>



Tutorials:

https://www.youtube.com/playlist?list=PLWebek4oOI_UOXashjFA58aE1bHToOM-



2.6 Interface Hardware

2.6.1 Connection of COMBIVERT F5.



HSP-5 interface D-SUB 9-pole X4A:
USB-serial-converter Part No. 0058060-0040 note1)



HSP5 diagnostic interface
X6B in field bus-operators
and interface-operators:
KEB-USB-serial-converter
Part No. 0058060-0040
+
HSP5-adapter D-SUB 9-pole / RJ45
Part No. 00F50C0-0020

By using an interface operator
(Part No. 00F5060-2000) con-
nection at D-SUB 9-pole X6C:
KEB-USB-serial-converter
Part No. 0058060-0040
Or:
RS-232 cable PC / operator Part
No. 0058025-001D

Connection also via IP-operator
Part No. 00F5060-8000 or
Profinet-operator Part No. 00F5060-L100
Please see FAQ-documents for instructions.

Note1): After disconnecting the operator from the device, the baud rate of the device internal HSP5 interface must be reset to 38400 baud by restarting the F5 (or set manually by parameter Sy11 to 38.4 kBaud). The connection HSP5-operator works with 250kBaud, which is too much for the PC.

Connection possible also by KEB Port Expander (=> [2.6.4 Port Expander](#))

2.6.2 Connection of COMBIVERT B6.



HSP5 diagnostic interface X6B

Connection by: USB–serial converter
Part No. 0058060–0040

+
HSP5–adapter D–SUB 9–pole / RJ45
Part No. 00F50C0–0020

Or KEB Port Expander, => [2.6.4 Port Expander](#)

2.6.3 Connection of COMBIVERT G6.



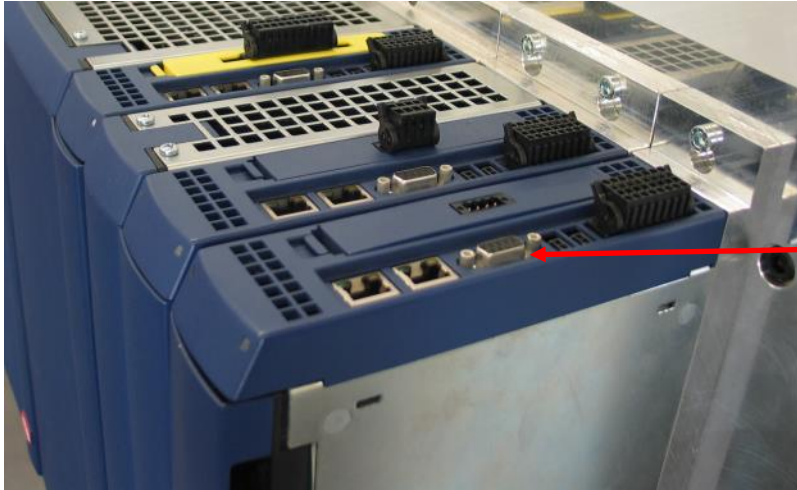
Connection to D–SUB 9–pole X4A,
Protocol DIN 66019II:

KEB–USB–serial converter, Part No. 0058060–0040

Or:

RS–232 cable PC / operator
Part No. 0058025–001D

2.6.4 Connection of COMBIVERT H6.



Connection drive units directly to serial D-SUB 9-pole protocol DIN 66019II:
RS-232 cable PC / operator
Part No. 0058025-001D
or:
KEB-USB-serial converter
Part No. 0058060-0040

Access to drive units also via control unit by UDP/IP

2.6.5 Connection of COMBIVERT P6.



Interface X6A:
Connection of the drive controller directly to serial D-SUB 9-pole protocol DIN 66019II:
KEB-USB-serial converter
Part No. 0058060-0040
or
RS-232 cable PC / operator
Part No. 0058025-001D

2.6.6 Connection of COMBIVERT F6.

COMBIVERT F6 housing size D – W:



Connection directly to serial D-SUB 9-pole protocol DIN 66019II:
 KEB-USB-serial converter
 Part No. 0058060-0040
 or
 RS-232 cable PC / operator
 Part No. 0058025-001D

COMBIVERT F6 housing size 1 – 9:



F6-Pro: Multi Ethernet interface: EtherCAT or Ethernet

Instead of operator:
 Interface X4A:
 Connection directly to serial D-SUB 9-pole protocol DIN 66019II:
 KEB-USB-serial converter
 Part No. 0058060-0040
 or
 RS-232 cable PC / operator
 Part No. 0058025-001D

Via pluggable operator:
 LAN interface: Part No. 00F6P00-2000
 USB-B interface: Part No. 00F6P00-3000

Pluggable operator with LAN Interface Part No. 00F6P00-2000:



LAN interface cable
The IP address must be adjusted in parameter Fb01 by keyboard => device manual.

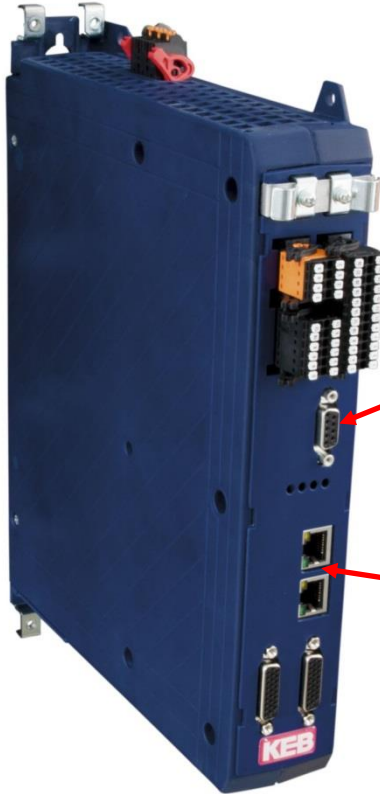
Pluggable operator with USB Interface Part No. 00F6P00-3000:



USB A-B cable

The F6 operator can be used also on COMBIVERT S6 and H6. A good-shielded D-sub 9-pole extension cable can be used to connect the operator with the serial DIN 66019 interface on the COMBIVERT S6/H6.

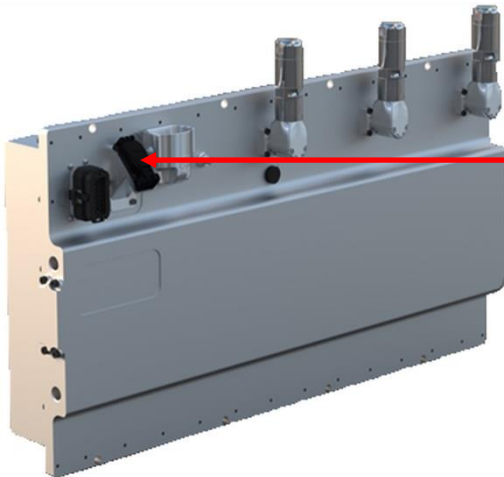
2.6.7 Connection of COMBIVERT S6.



Connection directly to serial D-SUB 9-pole protocol DIN 66019II:
KEB-USB-serial converter
Part No. 0058060-0040
or
RS-232 cable PC / operator
Part No. 0058025-001D

F6-Pro: Multi Ethernet interface: EtherCAT or Ethernet

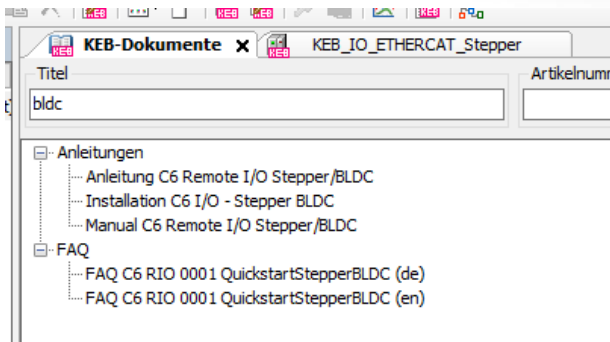
2.6.8 Connection of COMBIVERT T6.



Connection via LAN interface by standard LAN cable

2.6.9 Connection of C6 Stepper/BLDC

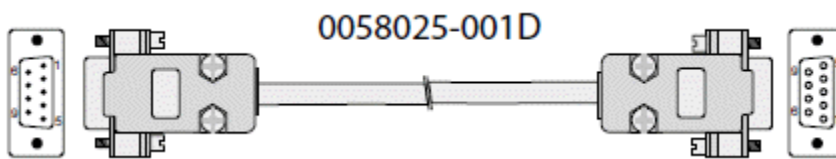
Connection via COMBICONTROL C6 with COMBIVIS studio 6
Sample project available. See document data bench: FAQ C6 RIO 0001 QuickstartStepperBLDC



2.7 Accessories

2.7.1 DIN 66019II - RS-232 cable, PC / Operator

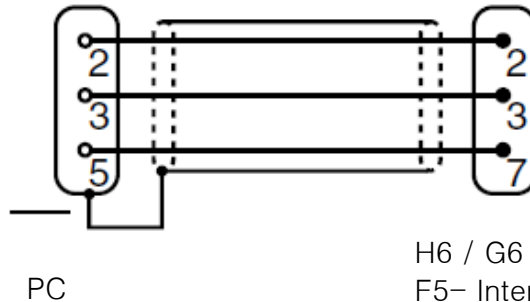
Part No. 0058025-001D



D-Sub 9-pole female

D-Sub 9-pole male

Housing (PE)



H6 / G6 / S6 / F6 / P6 /
F5- Interface operator

2.7.2 KEB-USB-Serial Converter

Part No. 0058060-0040

Converts USB into serial DIN 66019 II and HSP5 D-SUB 9-pole



- The USB-serial-converter represents a virtual COM interface
- It is not a customary USB serial converter, because the serial protocol is not transferred completely
- On USB's side always DIN66019II is running
- A connection of several USB-serial-converters, each with a serial- or HSP5-unit, is possible
- Both interfaces are potential separated
- Don't need an external voltage supply
- The 9-pole serial side supports with auto detection:
- DIN66019 based on of RS 232
- HSP5 (TTL level)
- 38.4 kBaud should be used as baud rate
- Max. baud rate is 115,2 kBaud
- No support for automatic adjusting of baud rates
- Baud rate can be adjusted with COMBIVIS 6
- Cannot be used for firmware flashing

File Transport Program FTP / Drive Storage

Transferring of receipts by [17.2 FTP Program](#) or the wizard drive storage to COMBIVERT F6/S6 is possible from Version V2.4

Matching USB converters are signed with "FTP ready".



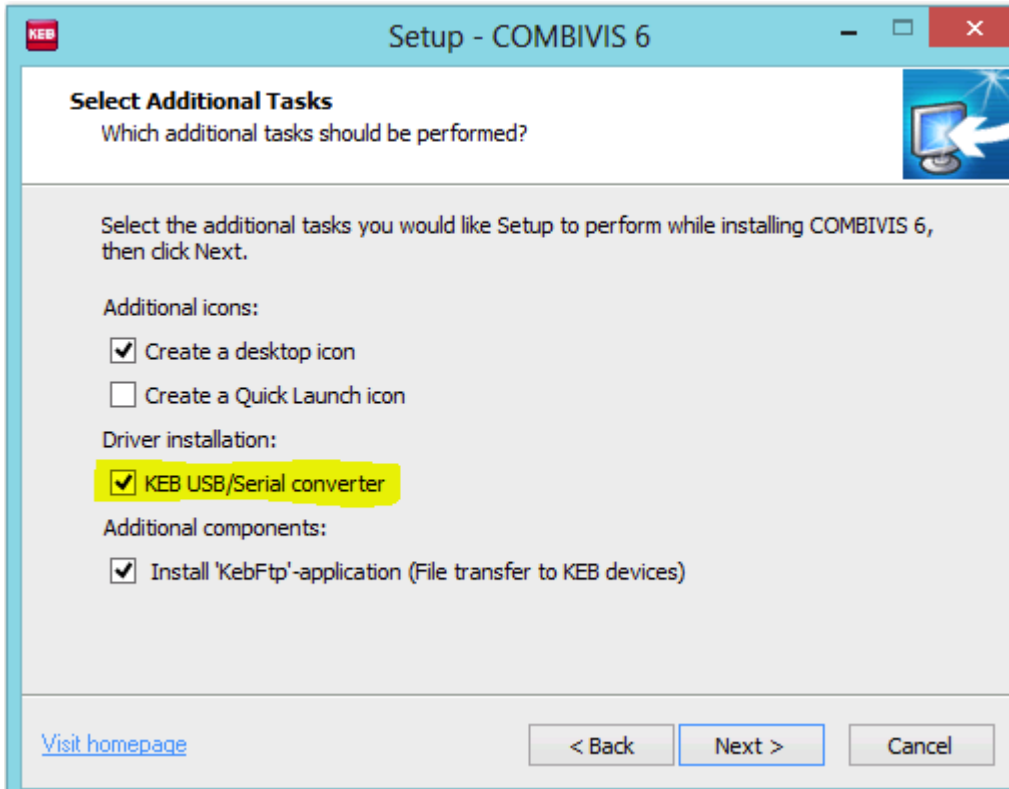
/2018/29/0010
Mat.No. 0058060-0040
USB SERIELL WANDLER
Software V2.40
FTP Ready



Made in Germany
by KEB Automation KG
32683 Berntrup
www.keb.de

Driver installation

While installation of COMBIVIS 6 the driver for the KEB USB Converter will be installed automatically. If it is not wanted it can be disabled at setup:



The signed driver “kebcd.c.inf” can be found in the COMBIVIS 6 installation folder “C:\Programs\KEB\COMBIVIS_6\Drivers”.

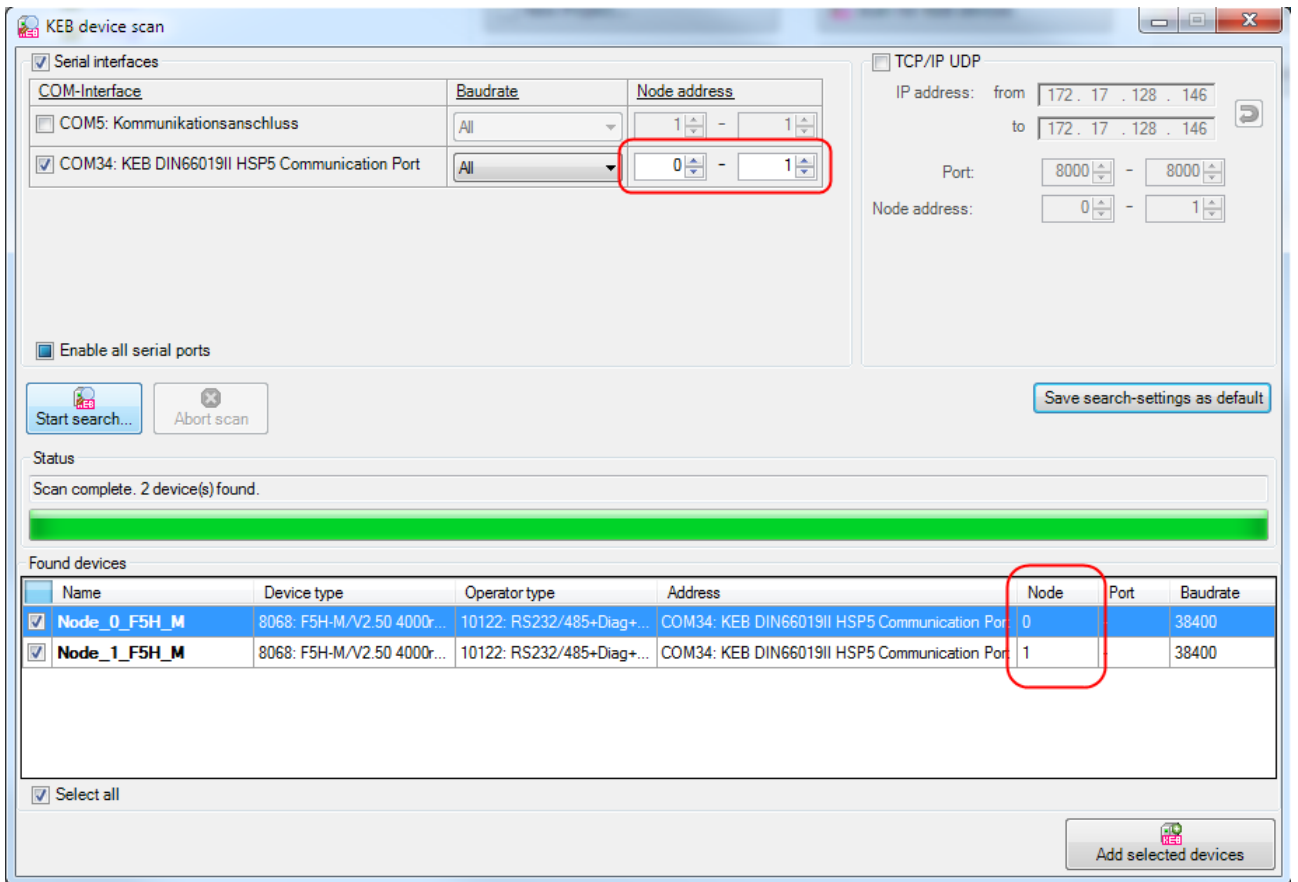
The KEB-USB converter 0058060-0020 is no longer manufactured. It has basically the same properties, but no potential separation. Due to data transport problems this should not be used on COMBIVERT F6 / S6.

Please note at COMBIVERT F5/B6 on HSP5 interface:

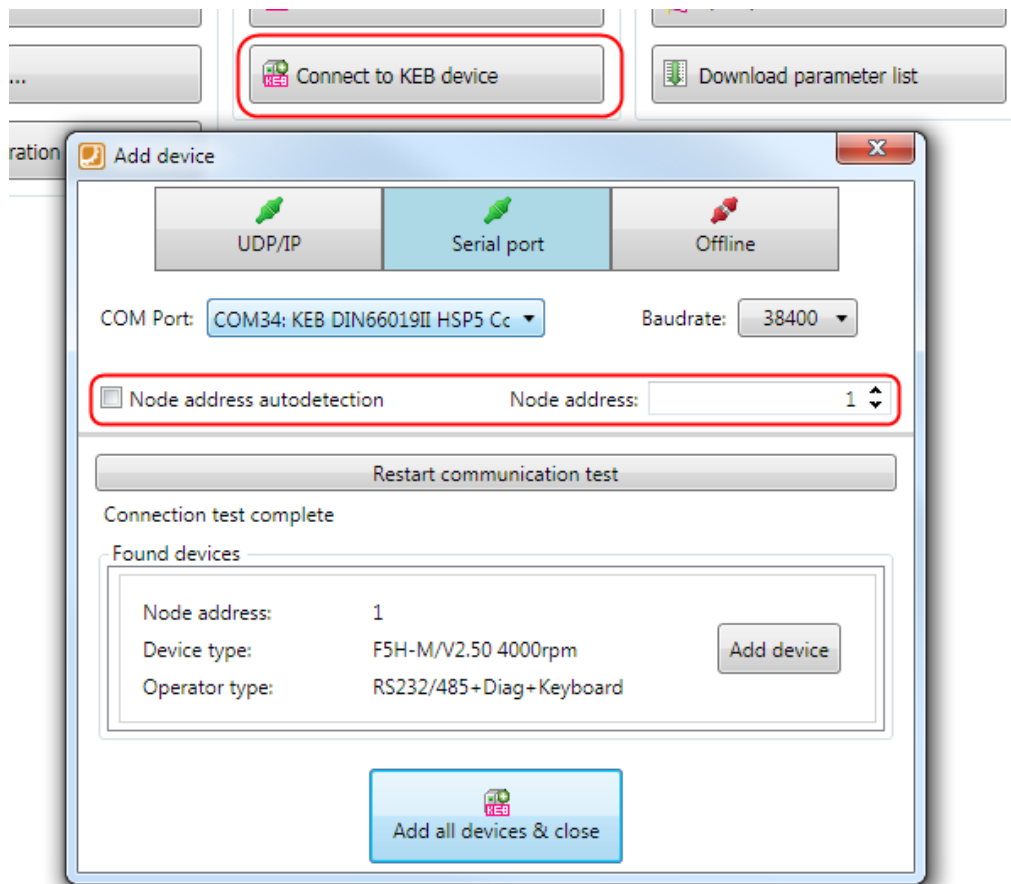
Node addresses are not specified in HSP5 interface of the USB-serial converter. So COMBIVIS 6 will find a device on each scanned address!

E.g., while scanning address 0 and 1 the same device will be found and included twice, regardless of which current node address is adjusted.

So, search for connection by HSP5 only on one address!



In "Connect to device" remove the checkmark "Node address autodetection", otherwise the device will be integrated in the project up to 240 times! Typically, node address 1 is used.



2.7.3 HSP5-Adapter

D-SUB 9-pole / RJ45
Part No. **00F50C0-0020**

Useful for COMBIVERT B6 and F5 bus operators (HSP5) only with KEB-USB-serial converter!



2.7.4 Port Expander

Ethernet / USB – HSP5 converter

Part-No. 00F5025-0080

The Port Expander has been discontinued and is only available for a limited time!

The port expander is a communication gateway with Ethernet and USB interface and 4 HSP5/485 interfaces for connection to drive controllers or operators of KEB COMBIVERT.

With the port expander up to 4 devices with HSP5 interface with COMBIVIS 6 can be addressed, because the port expander can convert the HSP5 protocol to DIN66019.

Connection options in detail:

Input side:

- USB on USB-B-interface
- Ethernet:
 - ARP Address Resolution Protocol Response
 - ICMP Echo Response (Ping)
 - TCP/IP DIN66019II, Modbus/TCP, Http
 - TCP/UDP DIN66019II, Modbus/TCP
 - DHCP BootP Response, switchable

Output side:

- At each of the 4 output interface a HSP5 device (F5 control board (X4A) direct / F5 bus operator / B6)
- Port 4 (X4D) may alternatively be set to RS485 bus DIN66019II so theoretically up to 235 participants with a serial interface DIN 66019II. (F5-Interface Operator / G6 / H6 / P6 / F6 / S6)

Power is supplied by an external 24V power supply or via the USB cable.

The Port Expander can be run locally on the table or mounted on a DIN rail in the control cabinet.

Numbers:

Part number	Name	Characteristics
00F5025-1080	PORT EXPANDER SET	with USB A-B, Cable -4025 und HSP5 Adapter - 0020
00F5025-0080	PORT EXPANDER	USB-, Ethernet-, 4x HSP5-interface, ext. 24V
00F50C4-1010	USB- Cable	USB A-B, 4-pol., l = 1 m
00F50C0-4010	Cable RS 485/ HSP5	Connection RJ 45 – D-SUB 9, l = 1 m
00F50C0-4020	Cable RS 485/ HSP5	Connection RJ 45 – D-SUB 9, l = 2 m
00F50C0-4025	Cable RS 485/ HSP5	Connection RJ 45 – D-SUB 9, l = 2.5 m
00F50C0-4050	Cable RS 485/ HSP5	Connection RJ 45 – D-SUB 9, l = 5 m
00F50C0-0020	Field bus adapter HSP5	D-SUB 9 / Western 400 mm
00F50C0-0021	Cable RS 485/ DIN 66019II	Connection RJ 45 – D-SUB 9, l = 2,5 m

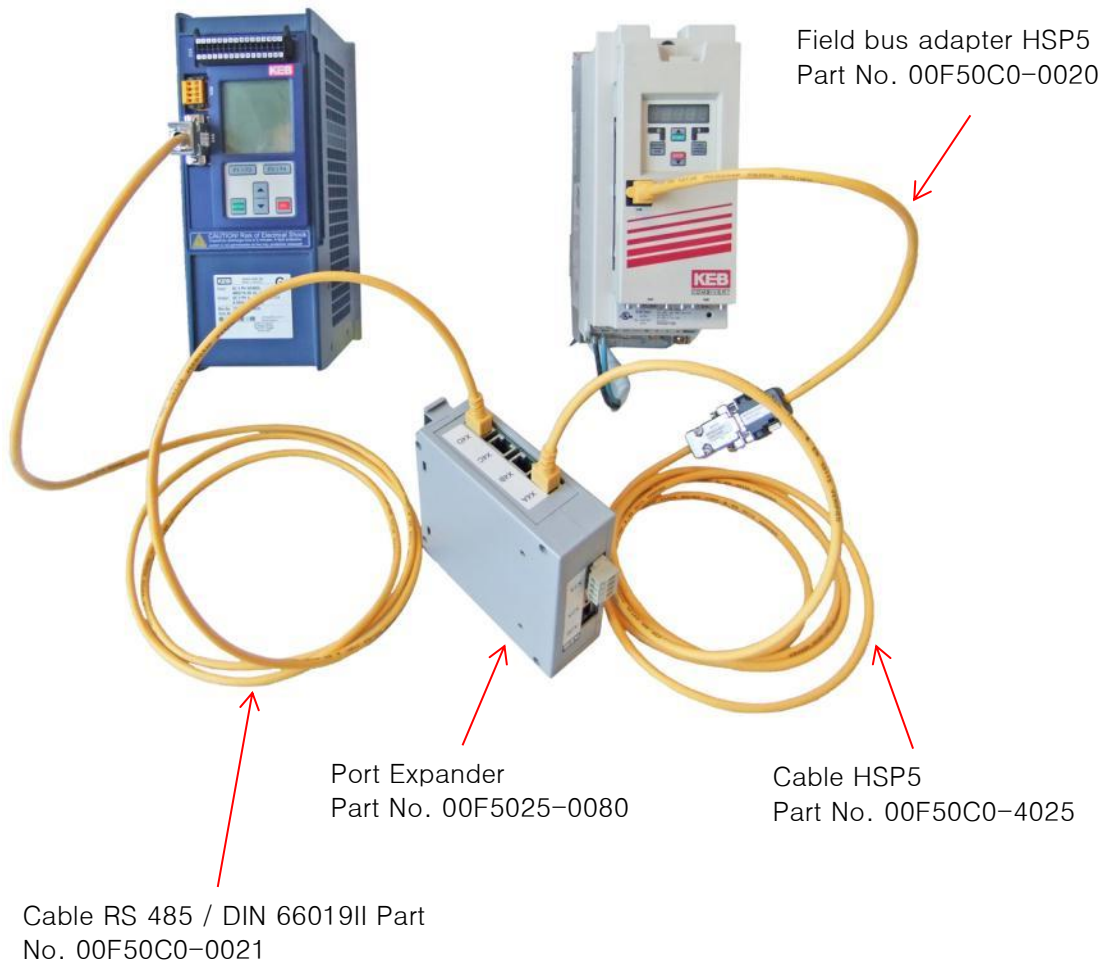
The inexpensive starter kit Part No. 00F5025-1080 belongs of:

	Part number	Name	Characteristics
1x	00F5025-0080	PORT EXPANDER	USB-, Ethernet-, 4x HSP5-Schnittst., ext. 24V
1x	00F50C4-1010	USB- Cable	USB A-B, 4-pol., l = 1 m
1x	00F50C0-4025	Cable RS 485/ HSP5	Connection RJ 45 – D-SUB 9, l = 2.5 m

1x	00F50C0-0020	Fieldbus Adapter HSP 5	D-SUB 9 / Western 400 mm
----	--------------	------------------------	--------------------------



Wiring examples:



Communication Port Expander to serial
DIN 66019II (only port 4) Type G6, F6,
S6, H6 and P6

Communication Port Expander to
HSP5 (port 1-4) Type F5 and B6

The cable Part No. 00F50C0-4025 can also be plugged directly into the Sub-D9-pol HSP5 socket of the F5 instead of the operator.

Further information can be found in the manual. Please search for "00F5025-0080" or "Port Expander" on the KEB homepage www.keb.de.

For searching of the devices, the node addresses 0 to 5 must be adjusted (node 0 = Port Expander, node 1-4= the HSP5 ports X4A – X4D).

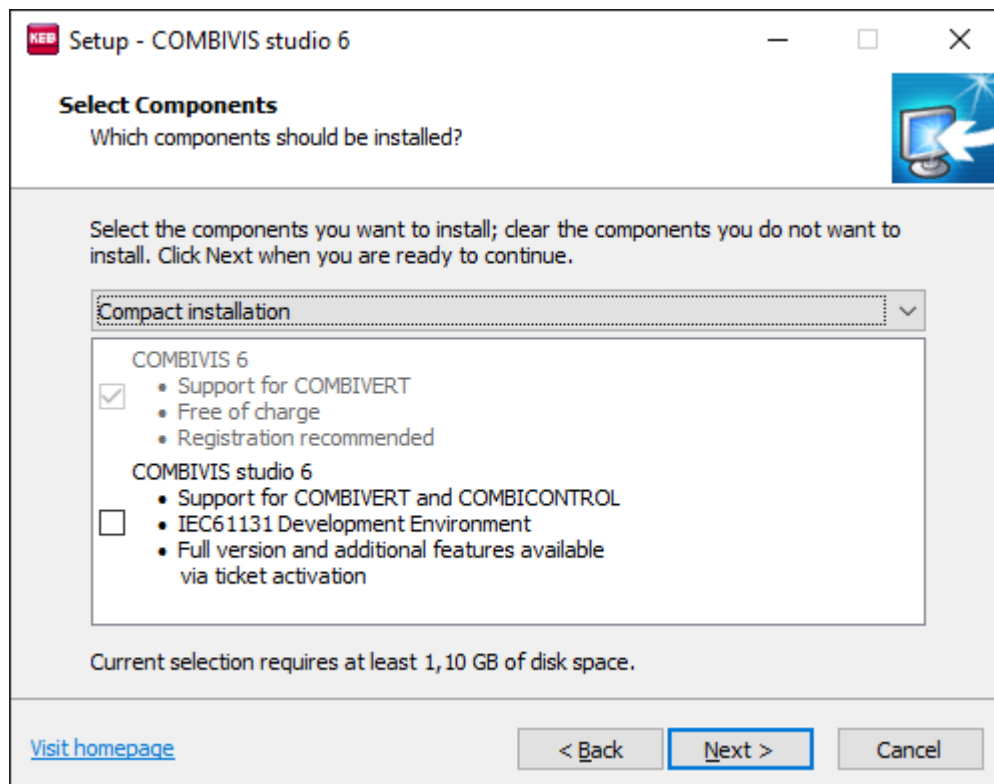
Driver installation

You will find the USB driver "FTDI_USB_Serial_Converter" in the COMBIVIS 6 installation folder "C:\Programs\KEB\COMBIVIS_6\Drivers" (please unpack before installation).

2.8 Installation

Since version 6.6.0 there is only one installation file. When installing, you can choose whether the standard version COMBIVIS 6 or the extended COMBIVIS studio 6 version should be installed.

For a new installation or when updating COMBIVIS 6, the selection is pre-set to COMBIVIS 6. When updating COMBIVIS studio 6, COMBIVIS studio 6 is pre-selected.



When COMBIVIS studio 6 is chosen, the COMBIVIS studio 6 safety profile can be selected additionally. COMBIVIS studio 6 safety includes the CODESYS safety extensions and some safety adaptations (=> [2.2 Types](#)).

Sandbox Installation

Since version 6.7.0, several COMBIVIS versions can be installed in parallel.

Use cases:

- Allow parallel installations of safety-version and non-safety version
- Allow keeping old version installed
- Allow pre-testing of beta versions quickly, avoid influence on a productive environment

In case of parallel installation, some files are shared:

- Document database
- Feature management
- KEB version manager

Some files are used individually:

COMBIVIS

- Parameter descriptions / wizard descriptions
- Configurator database
- Updates

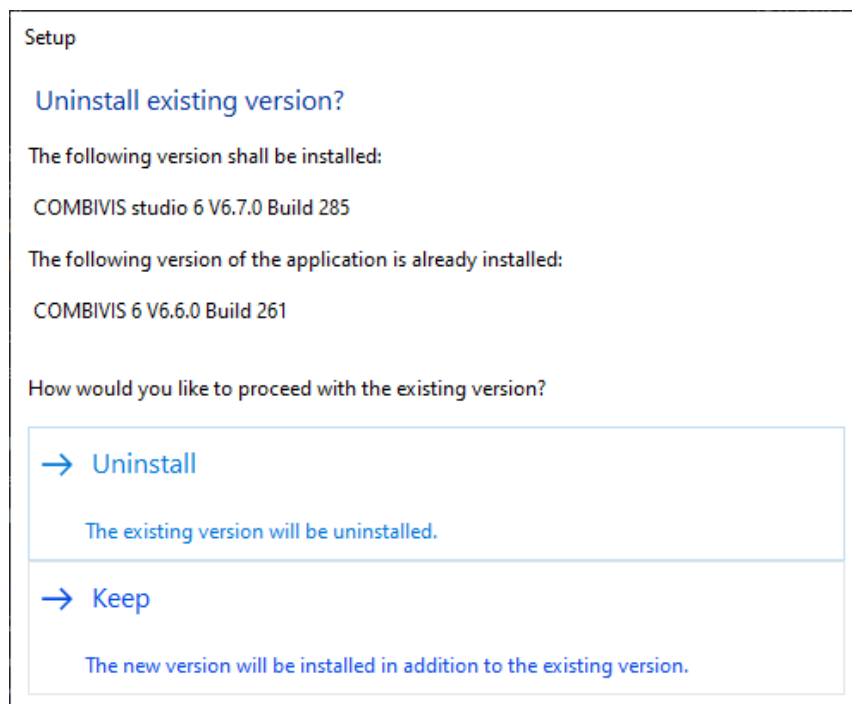
COMBIVIS studio

- Complete development environment including compiler
- Libraries (optional shared)
- Device descriptions (optional shared)

Misc.

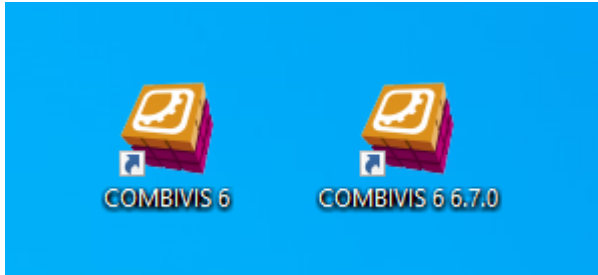
- Visu profiles
- Options
- Packages, plugins

When starting the installation, you can choose whether the previous version should be deleted or remain.



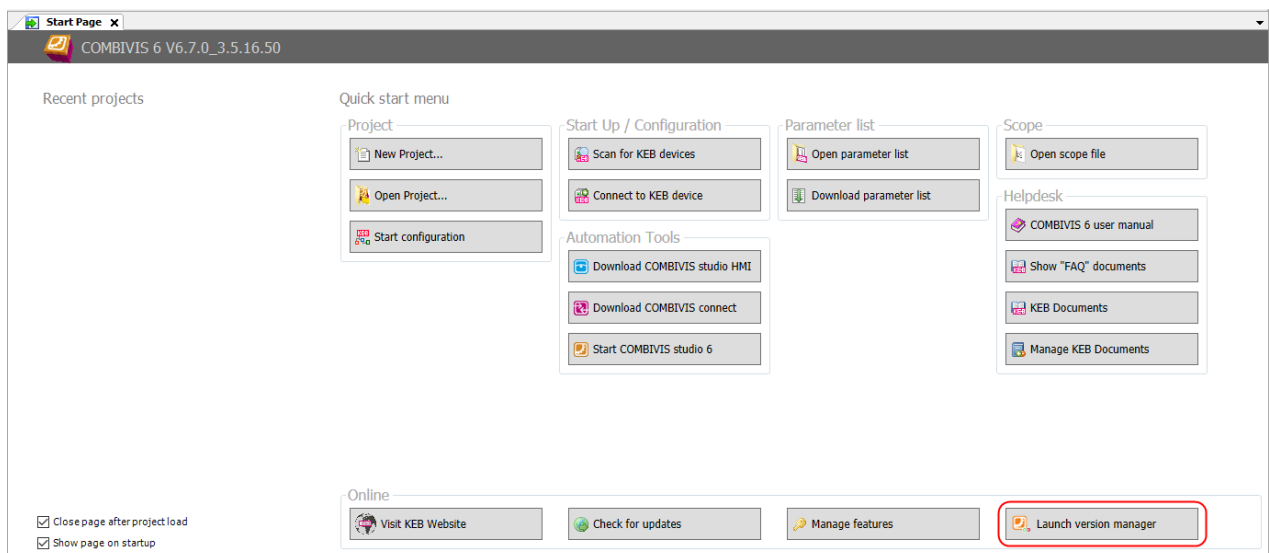
- Uninstall: the older version will be uninstalled; the new version will be installed and substitutes the old version.
- Keep: The new version is installed and add.

After “keep” you find 2 (or more) start icons on the Windows desktop:

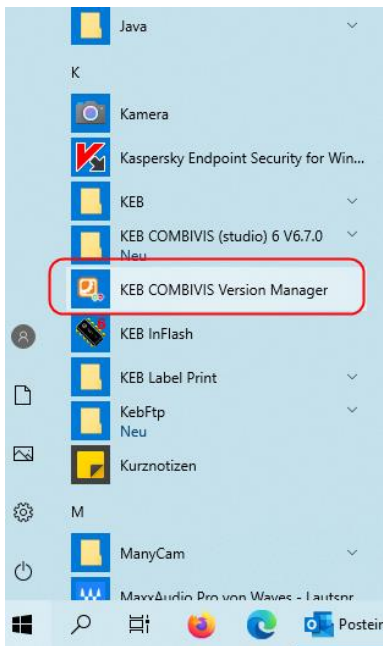


2.9 Version Manager

On the start page you will find the version manager:

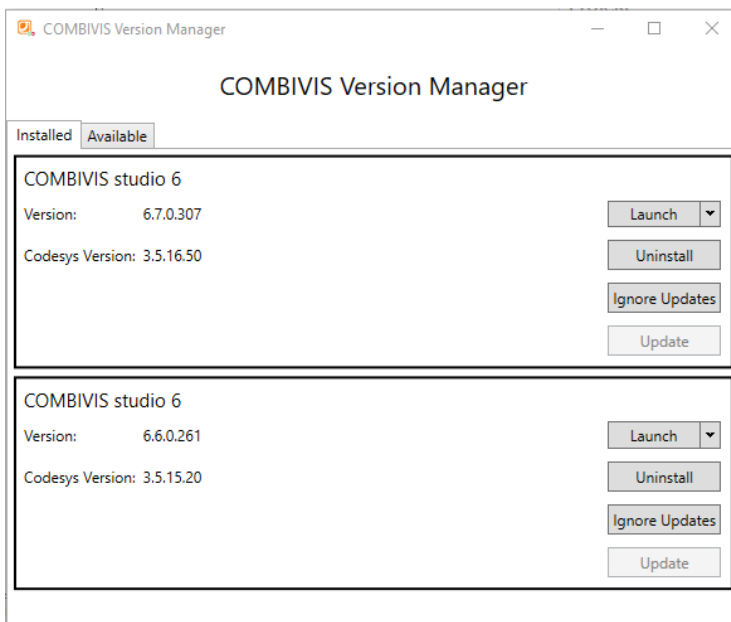


Or in Windows Start Menu:



This can be used to manage the individual versions.

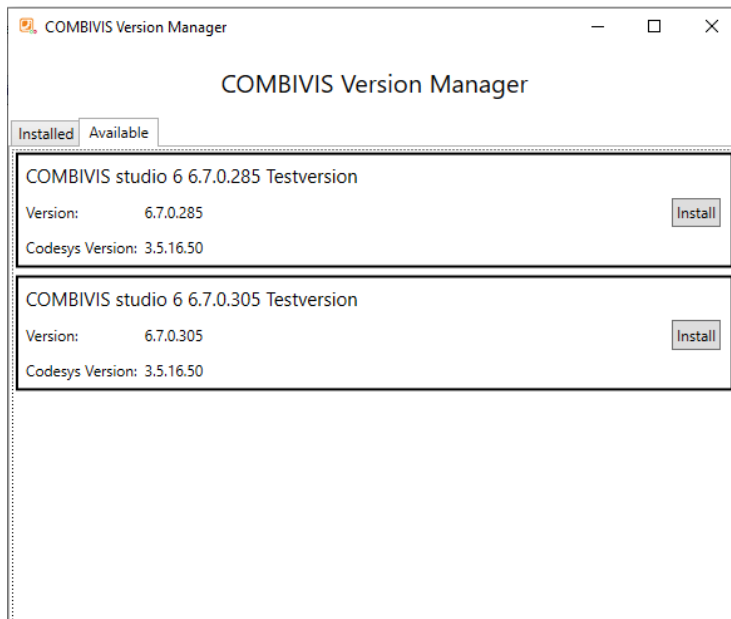
The "Installed" card shows the installed versions:



Function fields:

- **“Launch”**: launches profile in this version (CV6 or CV studio 6 or CV studio 6 Safety).
- **“Uninstall”**: uninstall version
- **“Ignore Updates”**: do not update version. Updates are carried out within the version (documents, parameter description, etc.).
- **“Update”**: install newer version

On the "Available" card, versions provided by KEB but not installed are offered for installation (internet connection required):



2.10 Silent Installation

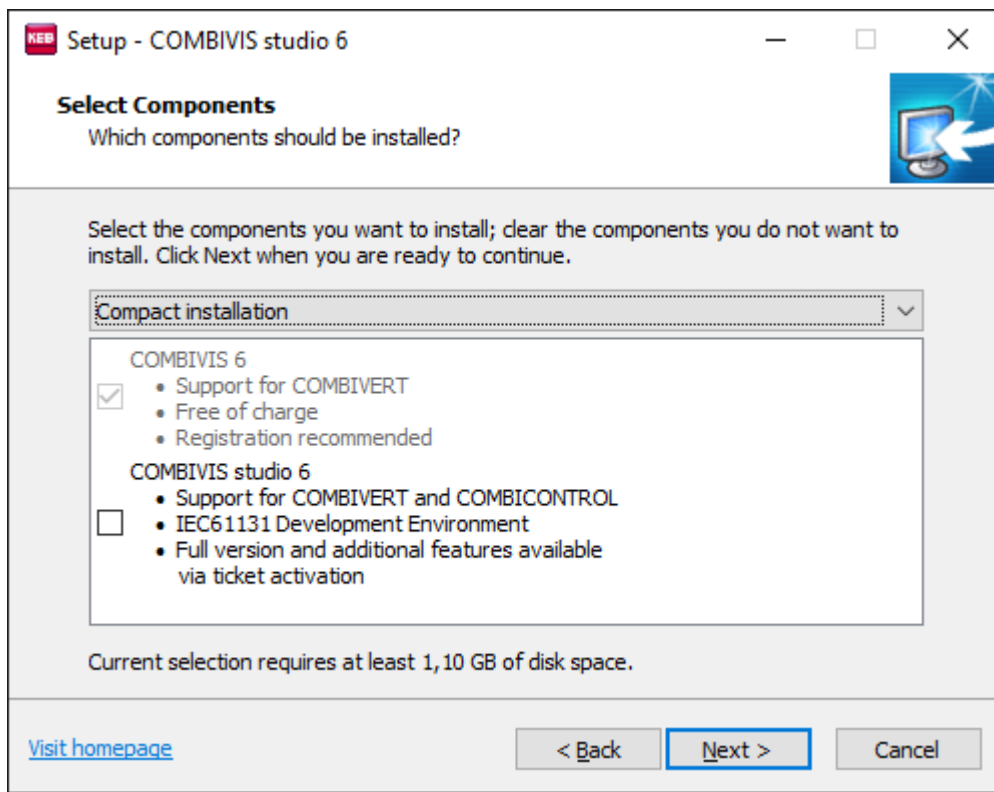
The COMBIVIS 6 setup was created by "INNO Setup" installer. The setup file can be performed also in 'silent mode'. More information will be found here: <http://www.jrsoftware.org/ishelp/index.php?topic=setupcmdline>.

COMBIVIS (studio) 6.6.0 Setup can be configured so that "Compact installation" is set from the start:

For this you must add the parameter / TYPE = "compact" to the call, for example:

```
"Setup_COMBIVIS_studio_6_V6.6.0_B227_R17_(TC1).exe" /TYPE="compact"
```

Result:



Prevent the standard association of the file extension ".project" with CV:

```
"Setup_COMBIVIS_studio_6_V6.6.0_B227_R17_(TC1).exe" /MERGETASKS="!associateProjectFileExtension"
```

This command can also be combined with the above "Types" parameter.

2.11 KEB Analysis

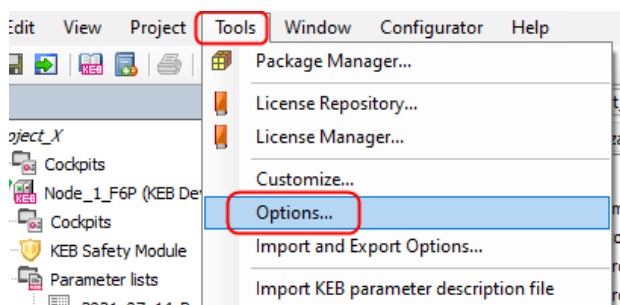
KEB COMBIVIS 6 uses AppCenter, an analysis service from Microsoft, from version 6.7.0. KEB thus receives information on how users use the programme.

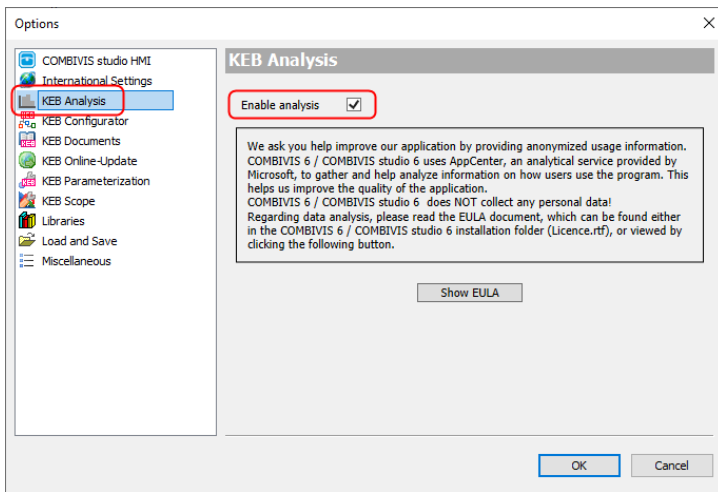
For example: Which version is used? Which parts of the programme are used how often? On which operating system is COMBIVIS running?

No personal data is collected!

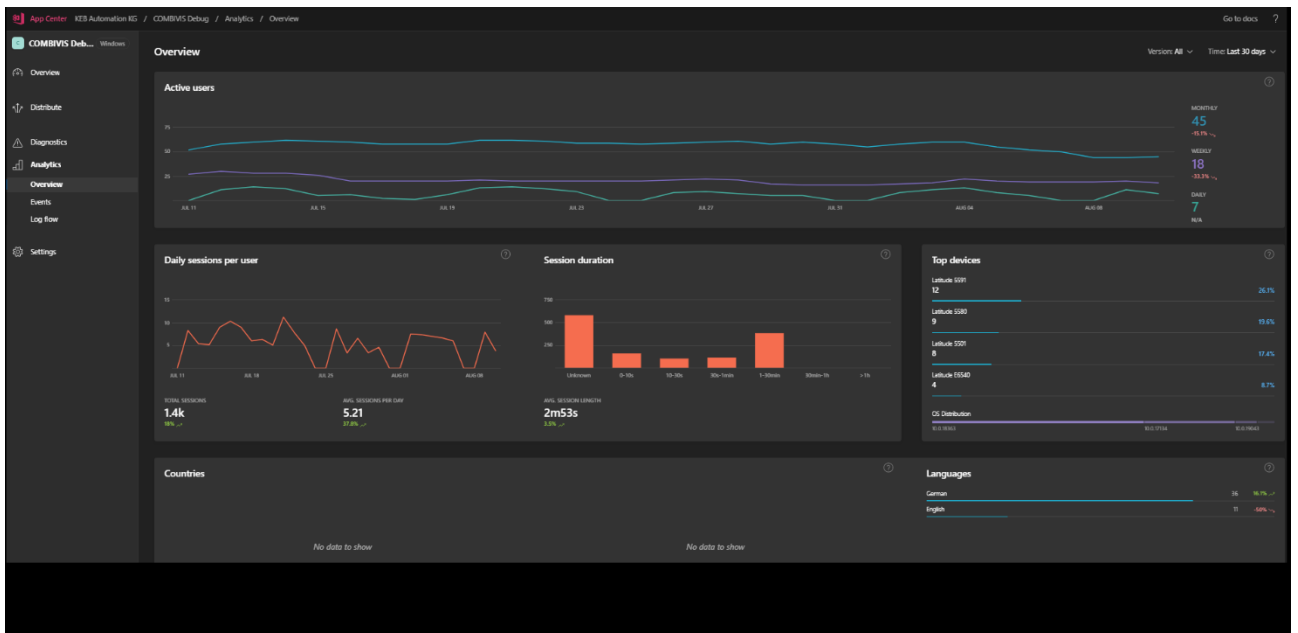
The analysis can be switched off:

Menu "Tools" → "Options" → "KEB Analysis":





A sample for analysis of used OS, PC type, language, using time:



3 Start-Up

Handling of a KEB device in COMBIVIS 6 requires at every time generating a new project or starting an existing project.

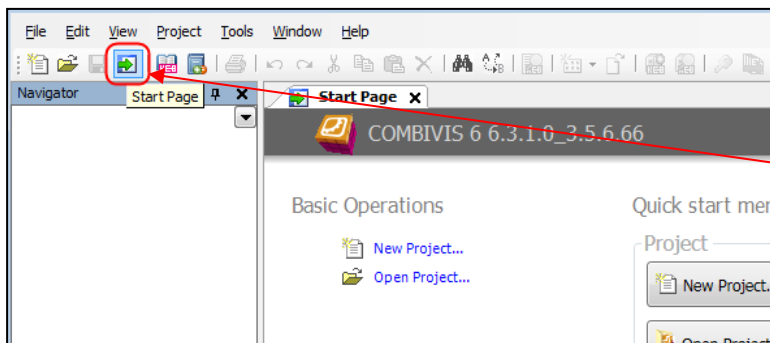
Communication set-up to the device can be done


- Via setting a new project and project assistant (=> [chapter 3.1](#))
- Or directly by scanning of interfaces (=> [chapter 3.2](#))
- Or setting of communication values directly at known hardware (=> [chapter 3.3](#))

At last, both a temporary project is generated in the background. It can be saved later by menu "File" → "Save project as..."

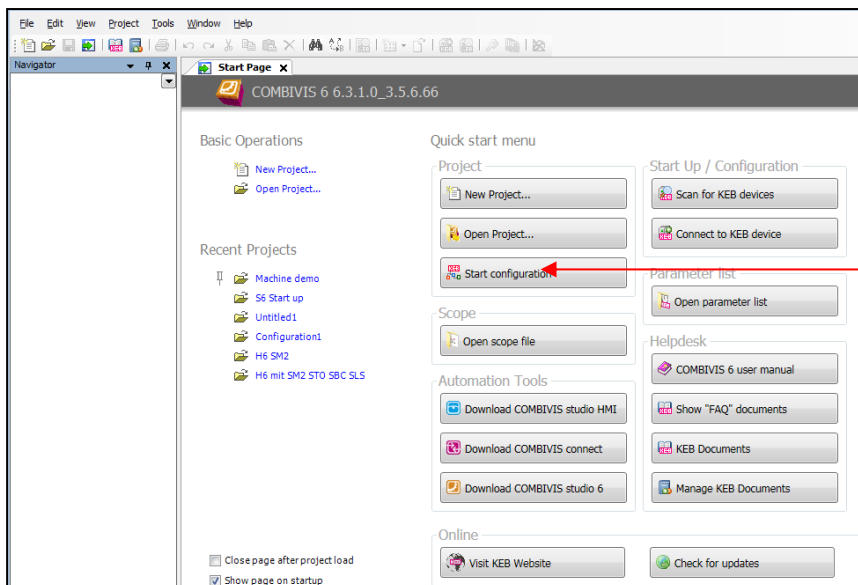
If only an **existing parameter list may be loaded** to the KEB COMBIVERT, the function "Download parameter list" on the start page can be used (=> [chapter 3.6](#)).

In COMBIVIS basic settings you will find the start page after starting up COMBIVIS



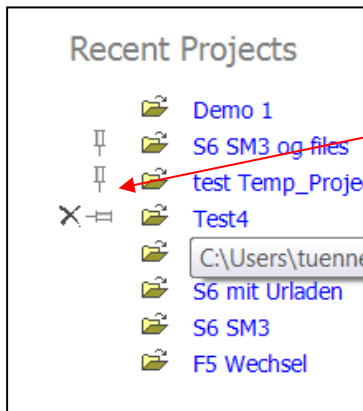
Via icon  the starting page can be activated again at any time

On the start page some direct-link buttons are offered.



By pulling the mouse cursor on a button the description of the function is shown

Recent projects:



With “needle vertical” projects can be fixed in the position in the list. With “cross” the name can be deleted out of the list.

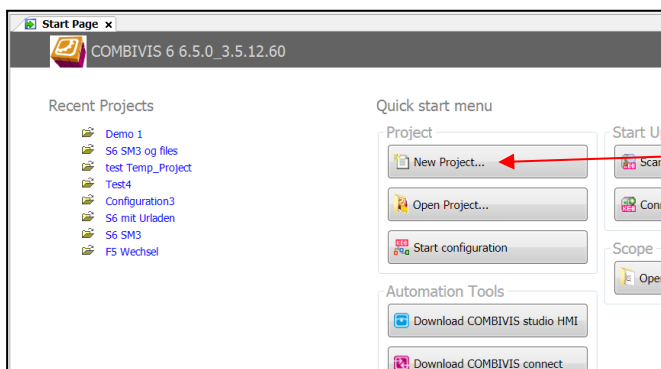
3.1 Start-Up with project assistant

3.1.1 Starting via Project Assistant

The automated project wizard (assistant) opens a new project, operates a predefined searching for connected devices and integrates the located devices into the project.

After entering “New project” the window “project assistant” / “empty project” will be shown.

Alternatively, one of the last used projects can be opened.

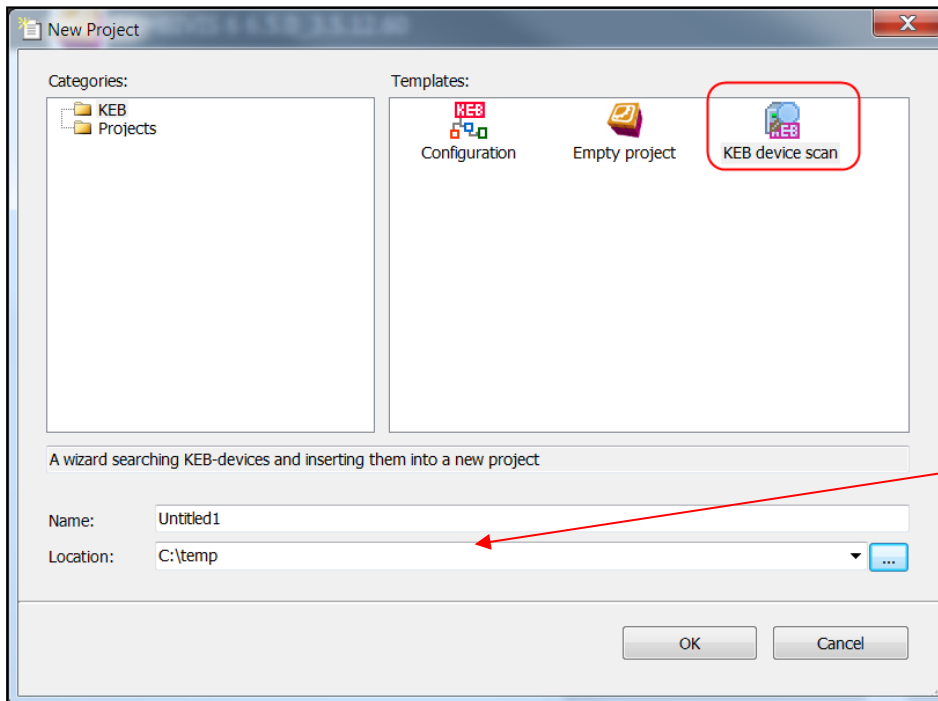


By “New Project” a project is generated, and the project assistant starts

By selection “Empty project” the searching / integration of devices must be done manually.

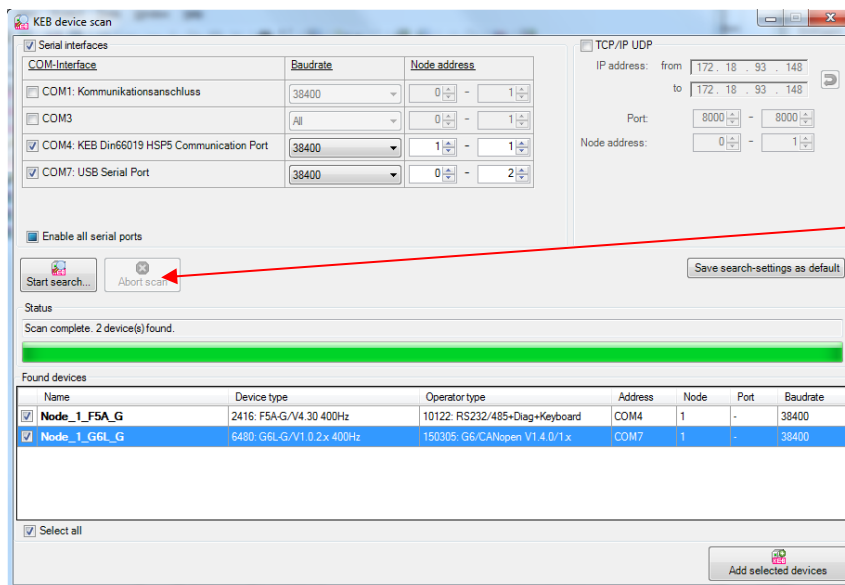
The icon “Configuration” opens the KEB System Configuration

The icon “KEB device scan” opens the device scan window (=> [3.1.2 Scan for devices](#))



Input of project's name and storage location

The scanning runs automatically depending on pre-configuration.



Start or interrupt – The adjustments can be changed and reconfigured.

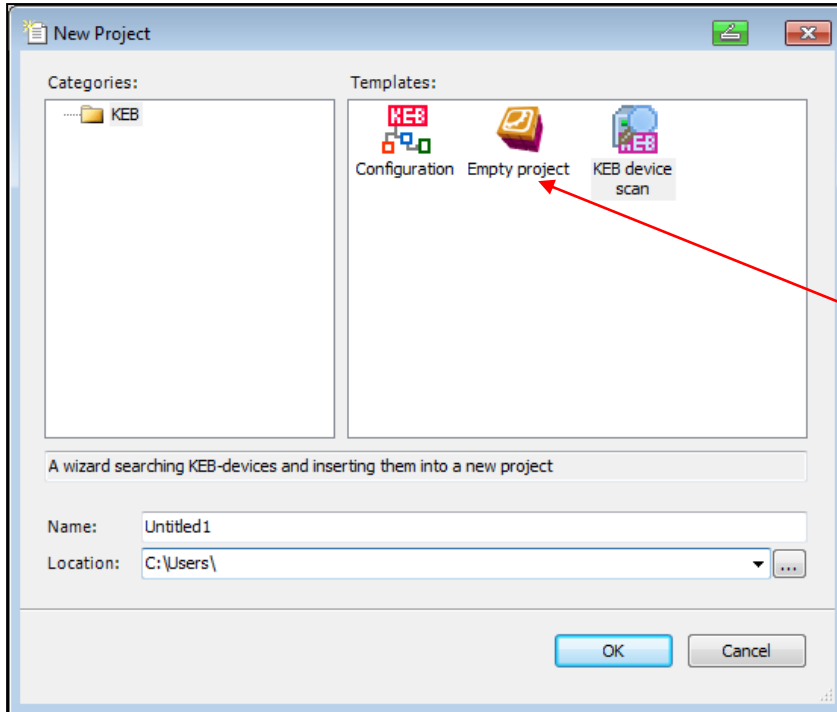
Please note: Drive controller connected by RS485 need to have different node addresses!

The explanation of the functions of the window can be found in chap. [3.1.3 Searching for devices -manually](#)

If devices are found, please see => [4 Device editor](#)

If no device will be found, please change adjustments, => [3.1.3 Searching for devices - manually](#)

3.1.2 Start-Up with Empty Project

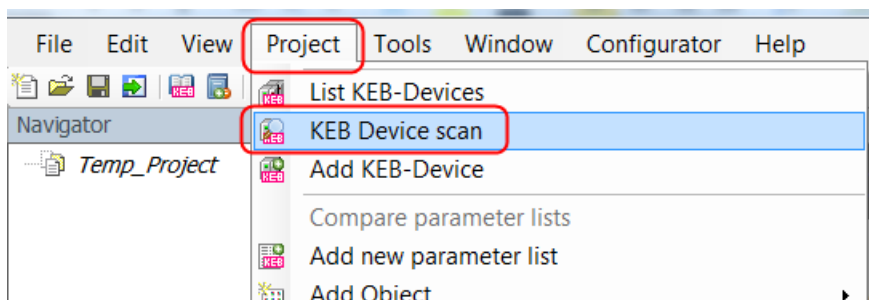


Start with an empty project

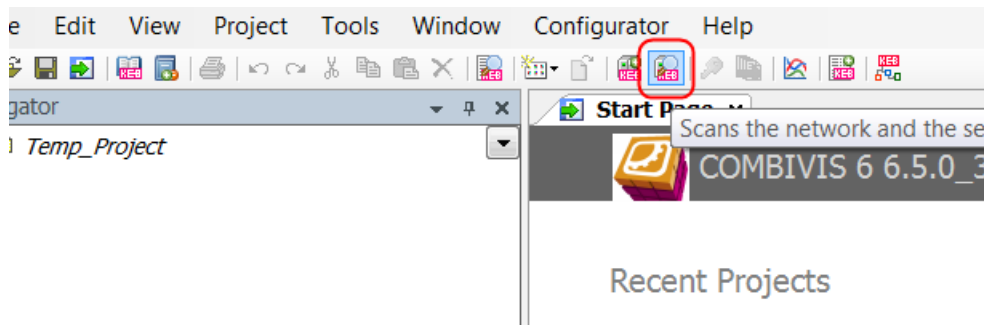
With an empty project it is possible to start a specific scan with connected devices or without connected devices they can be integrated manually.

3.1.3 Searching for Devices – Manually

Open an empty project – or from an existing project – click on:
Menu bar “Project” → “KEB device scan”



Or another way: Click on button “KEB device scan” in the tool bar.



The scan run can be controlled in the window “KEB device scan”. Differing to the standard setting other COM-interfaces, addresses, baud rates or IP-addresses can be scanned temporarily.

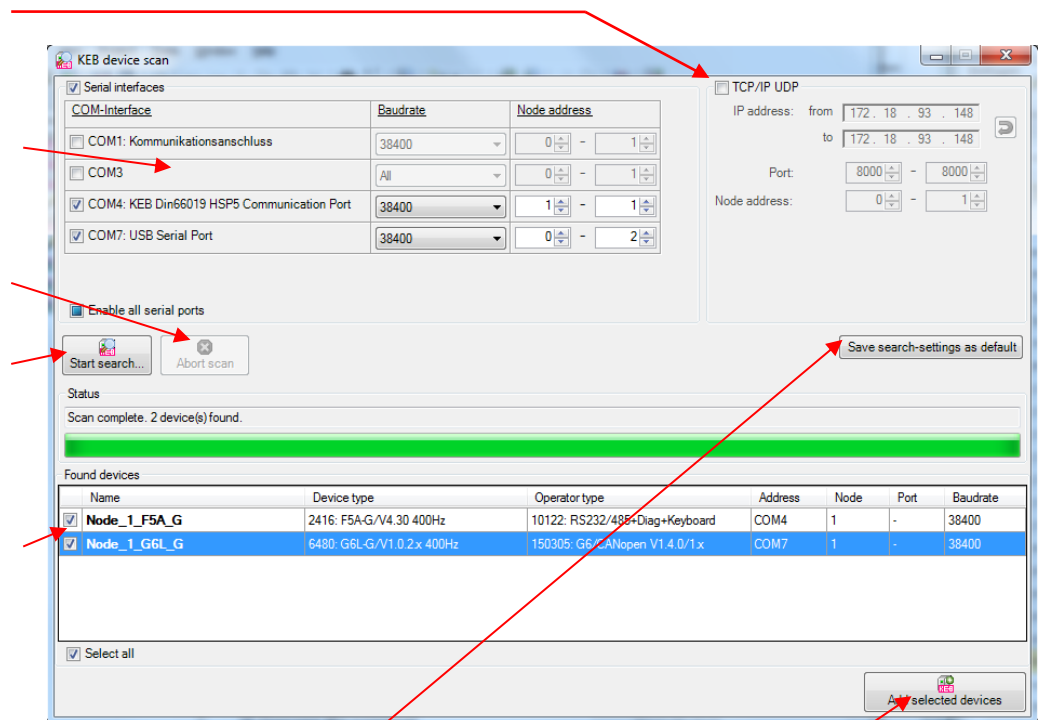
Scan area
TCP/IP UDP

Scan area of
COM-interfaces

Stop searching

Start searching

Select devices,
which are to add
on (☑)



Store current setting as
default

Adding the located de-
vices to the active pro-
ject

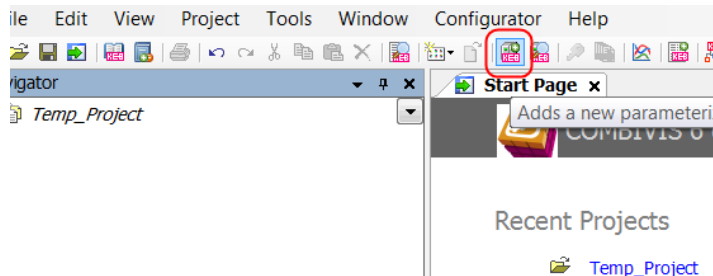
If searching via KEB USB serial converter at F5/B6 (HSP5 protocol) please read the notes in [2.6.2 KEB USB-serial converter!](#)

With known communication data, a device can be set directly without searching => [3.2 Directly scan for devices](#)

3.1.4 Start-Up Offline (Without Device)

If COMBIVIS 6 shall be opened without a connected device, then it must be added manually. So, for example a parameter list can be manually generated offline.

- Open an empty project
- Click left mouse key on button on tool bar: “Add a new KEB device to the project”

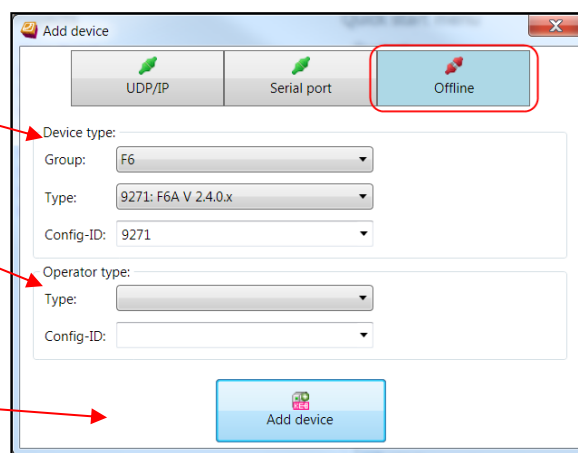


Choose “Offline”:

Choose device group and –type respectively device Config-ID

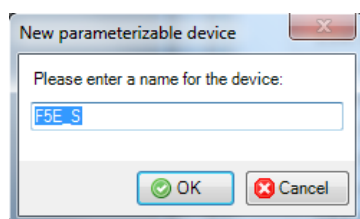
If necessary, also choose an operator or control type (G6)

Enter:
“Add device”



For help of adjustment of the correct device group an overview list for COMBIVERT F5 and G6 can be found under: Menu “Help” → “Show COMBIVIS 6 “FAQ”-Documents” → “COMBIVIS 6” → “CV6 FAQ0005 F5 G6 Short names operating modes”.

Fill in the name of the device which is to add.



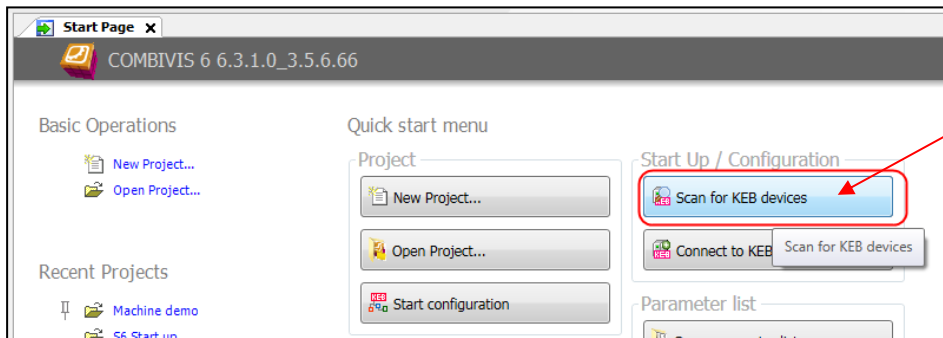
The device name must not begin with a character (0...9)! CV6 sets an underline in front of the character automatically.

Offline device will be added and the window “device editor” opens.

→ Continue in [4 Device editor](#)

3.2 Directly Scan for Devices on Interfaces

By using the button “Scan for devices” a temporary project is generated and a window with scan properties opens.



By "Scan for devices" a temporary project is generated, and the scan assistant starts

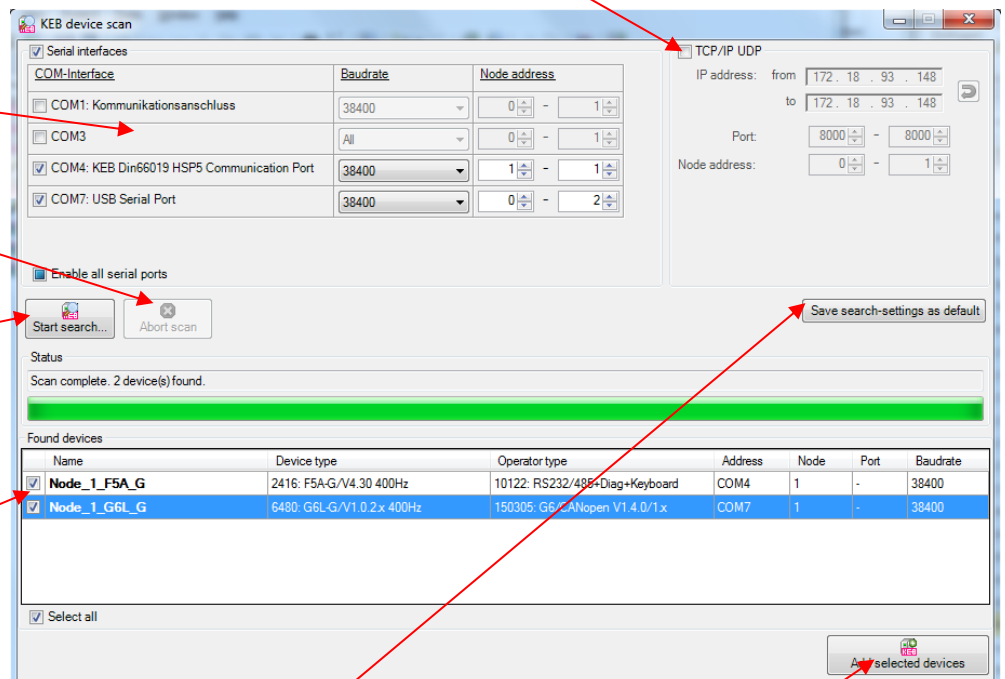
Scan area of Ethernet interfaces

Scan area of serial interfaces

Stop searching

Start searching

Select devices, which are to add on (☑)



Store current setting as default

Adding the located devices to the active project

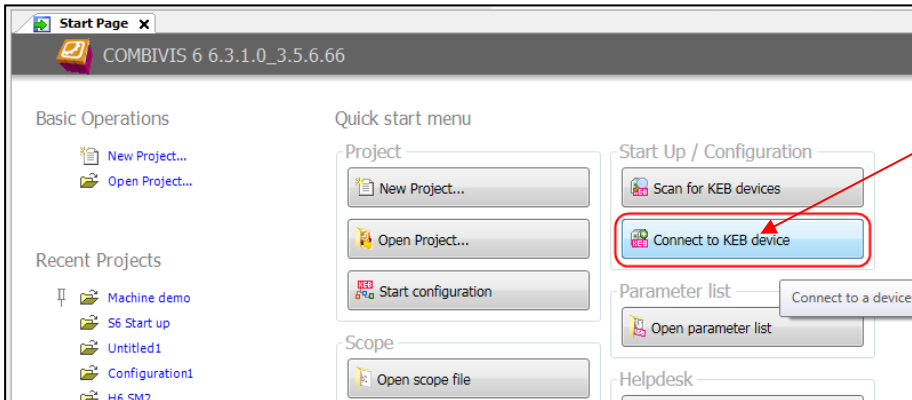
The found devices will be opened in the navigator window.

3.3 Directly Connect to Device (Add Device)

By using the button "Connect to device" a temporary project is generated and a window with interfaces properties opens.

In the case of an online connection, after setting the connection data, a scan is carried out and found KEB devices are displayed immediately.

Because COMBIVIS knows all the parameters of all KEB devices from type F5, a device can also be created "virtually".



By “Connect to device” a temporary project is generated, and the scan assistant starts

When connecting via UD / IP (Ethernet):

The window shows an input field for the IP address. At the same time, a network scan is performed, and the devices found are listed. Default port and node address are detected automatically. The devices found via the IP address are listed below and can be added to the project.

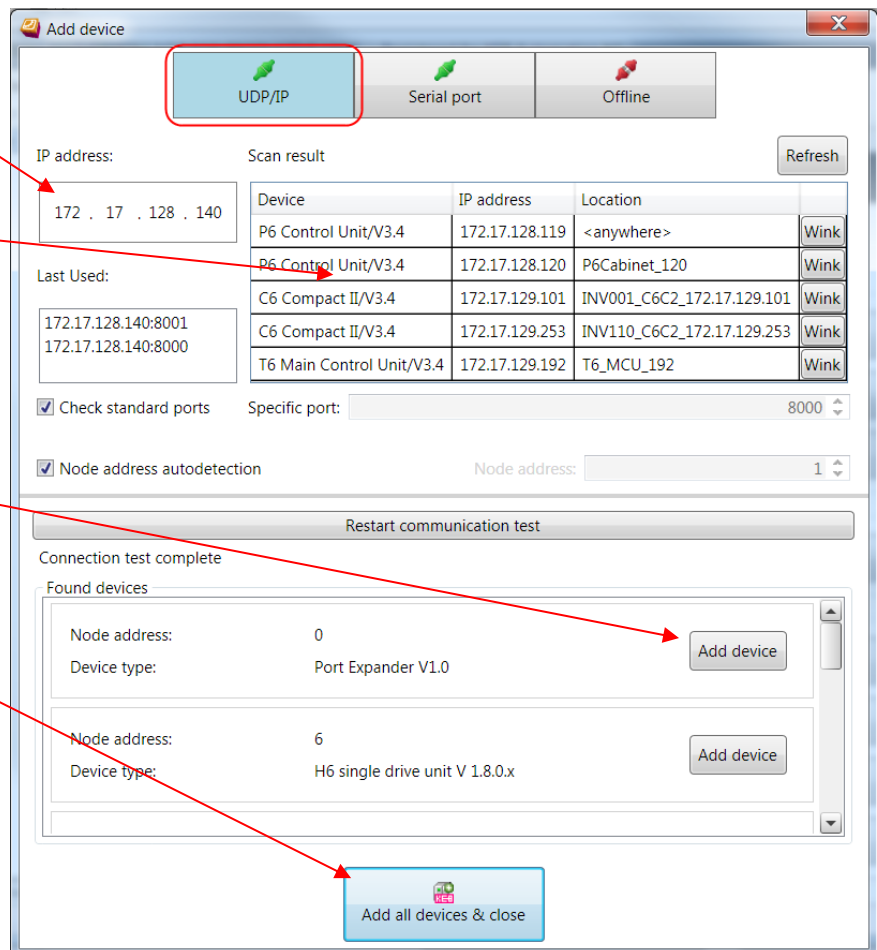
Set communication data
IP address

Devices found in network

By IP address found devices:

Enter: “Add device” – adds this device to project and window stays open

“Add all devices and close” – Window closes



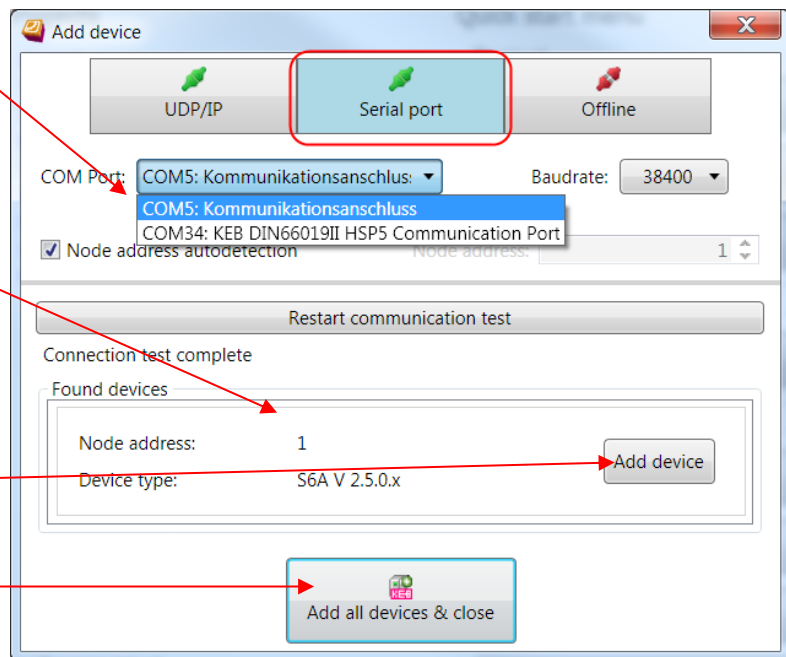
Note: With the KEB Port Expander Part No. 00F5025-0080, the automatic search will find the devices on each scanned port (8000 and 8001) and lists them twice. Please set a fixed port here.

At communication via serial or USB:

Set communication data
Detected USB connections
are suggested. Set baud rate
manually

"Communication Test" –
runs through each setting
change once. Found devices
are listed immedi-
ately.

Enter: "Add device" – adds
this device to project and
window stays open.
"Add all devices and close"
– Window closes



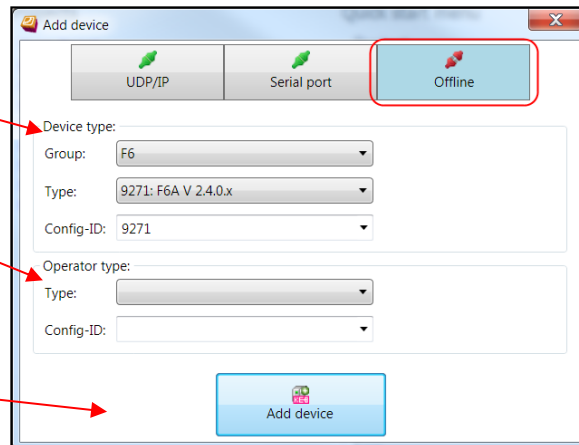
Offline (virtual device):

With "Offline", the device can be selected manually based on the type / firmware version or with a known configuration identifier.

Choose device group and –type
respectively device Config-ID

If necessary, also choose an
operator or control type (G6)

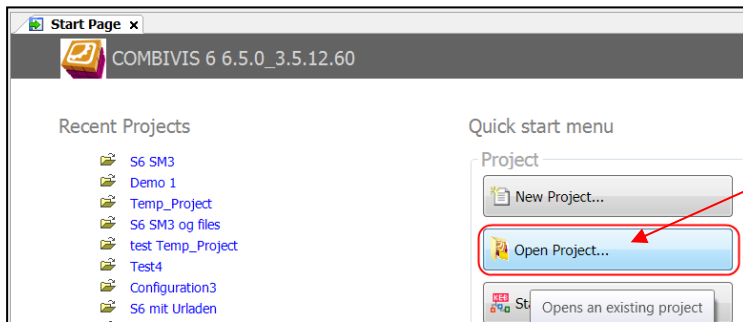
Enter:
"Add device"



The found devices will be opened in the navigator window.

3.4 Open an Existing Project

On Start page:



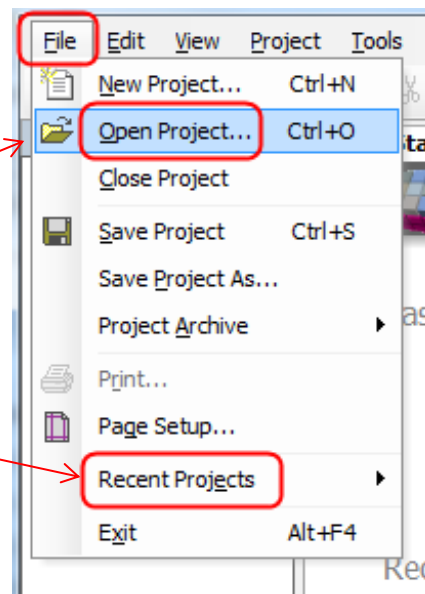
By "Open Project" a project will be opened

Or:

Open an existing project with "File" → "Open project"

Or:

Open an existing project with "File" → "Recent projects"

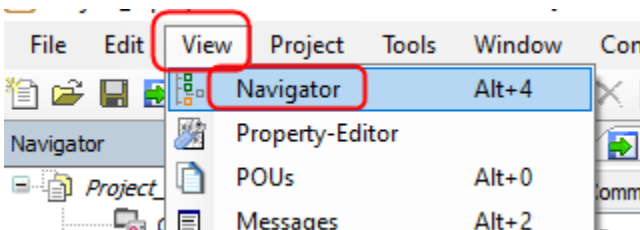


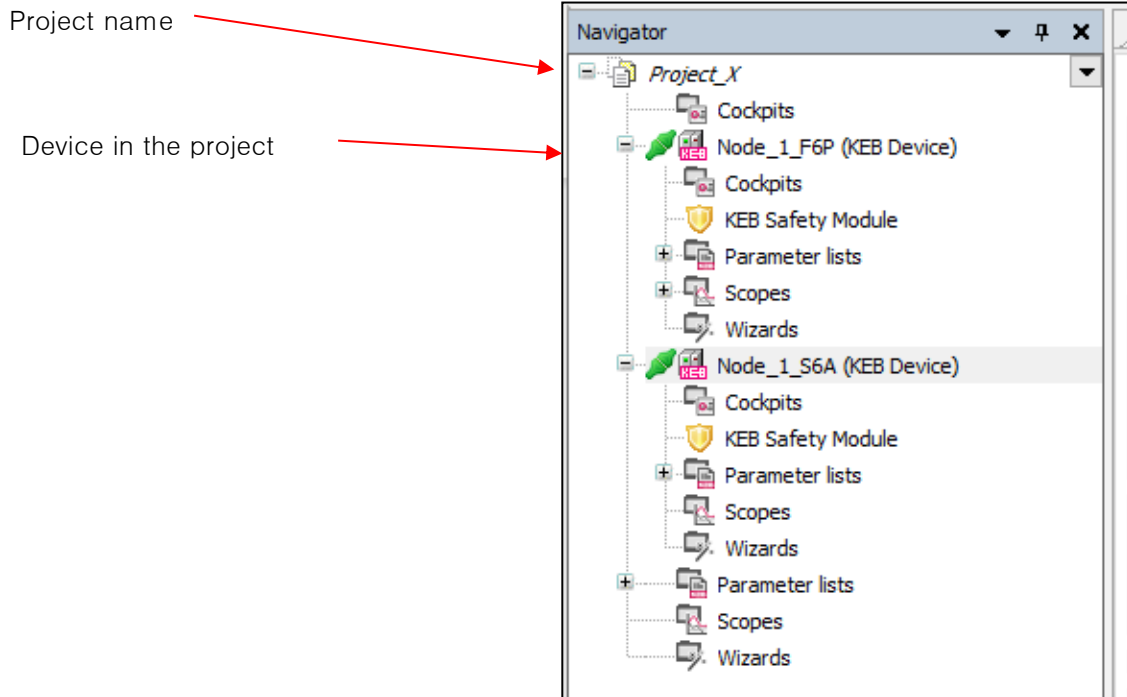
After opening an existing project without connected devices: When saving the project, the state of the devices will remain.

3.5 Navigator

The navigator window shows all devices, lists, scopes, and other folders belonging to the project.

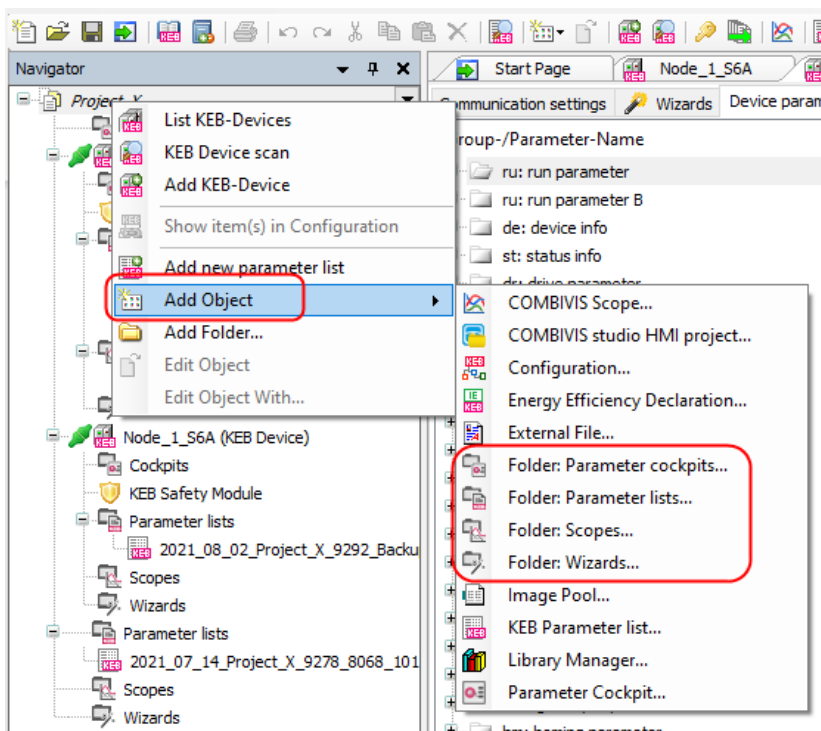
The navigator normally appears on the left side of the window. If it is not visible there, it can be displayed with the menu bar "View" → "Navigator".





Predefined folders are attached to the project and the device ([Parameter Cockpits => Chap.22](#), [Parameter Lists => Chap.8](#), [Scopes => Chap.9](#), [Wizards => Chap.10](#)). If not needed, these can be deleted.

Add a folder, a list, or a scope by click on the project name or device name → right mouse button → "Add object".

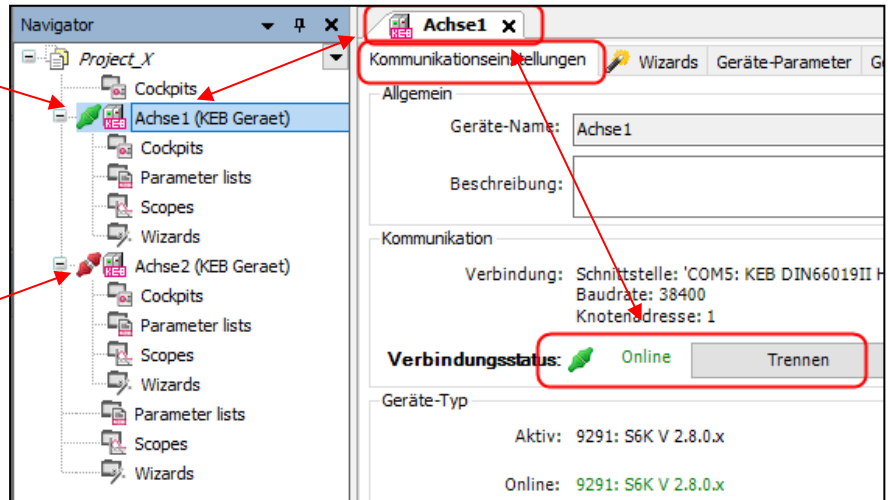


Objects attached to the project apply to several units, objects attached to the unit only apply to this unit.

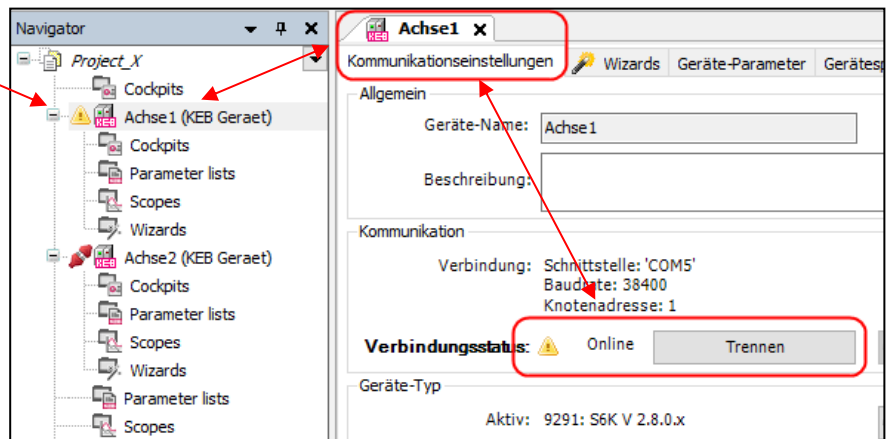
Display of the communication status:

Device online, connection active

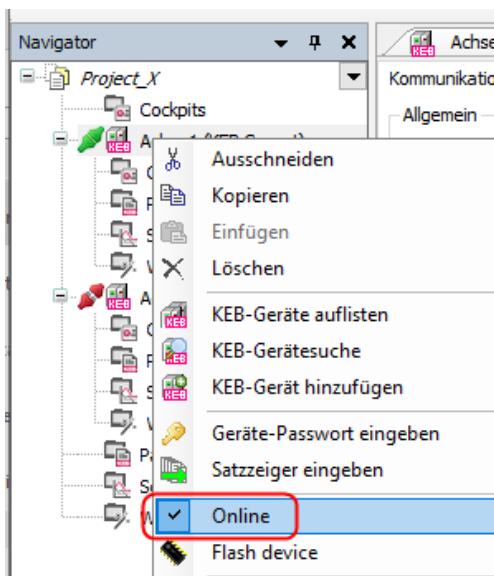
Device disconnected/
offline, no observing of
the communication



Device online, but no con-
nection

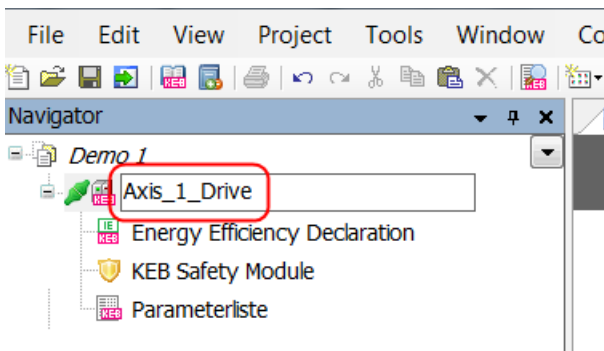


Alternatively, the communication status can also be changed via the context menu: right mouse button → "Online" / "Offline".



Change device name:

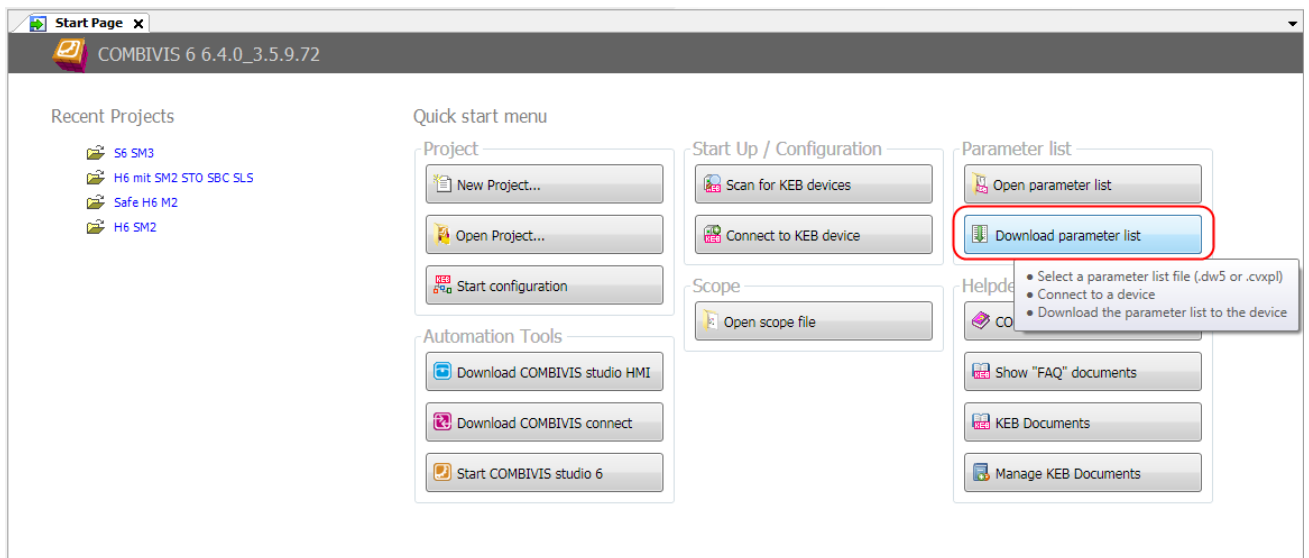
The name of the device in the project can be renamed. Therefore click with left mouse key on the name of the device in the navigator. Then the name can be changed. The device name must not begin with a character (0.....9)!



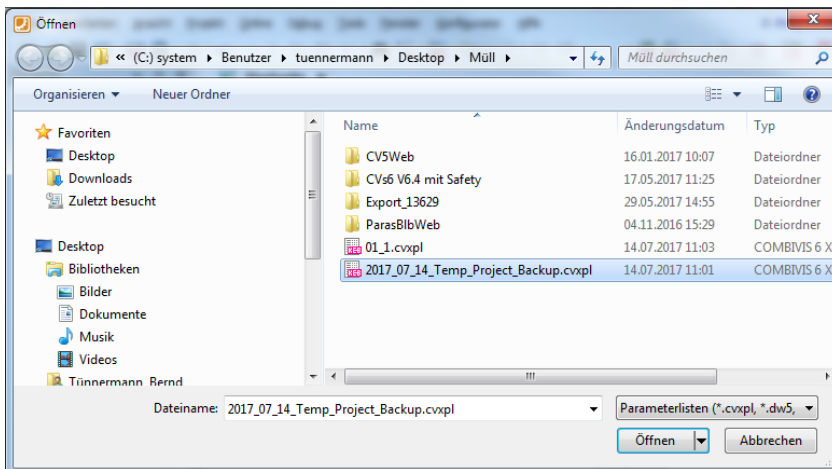
3.6 Direct download of a parameter list

The function specifies a path with which a parameter list saved anywhere can be load into a KEB device (Download).

By choice box "Download parameter list" on the start page a temporary project is created, the belonging parameter list is chosen; the communication to the COMBIVERT is set und after connecting the parameter list is loaded to the device.



Mark the parameter list and "open":



A temporary project is created and a device matching the parameter list is added. The communication settings are asked for.

When connecting via UD / IP (Ethernet):

The window shows an input field for the IP address. At the same time, a network scan is performed, and the devices found are listed. Default port and node address are detected automatically. The devices found via the IP address are listed below and can be added to the project.

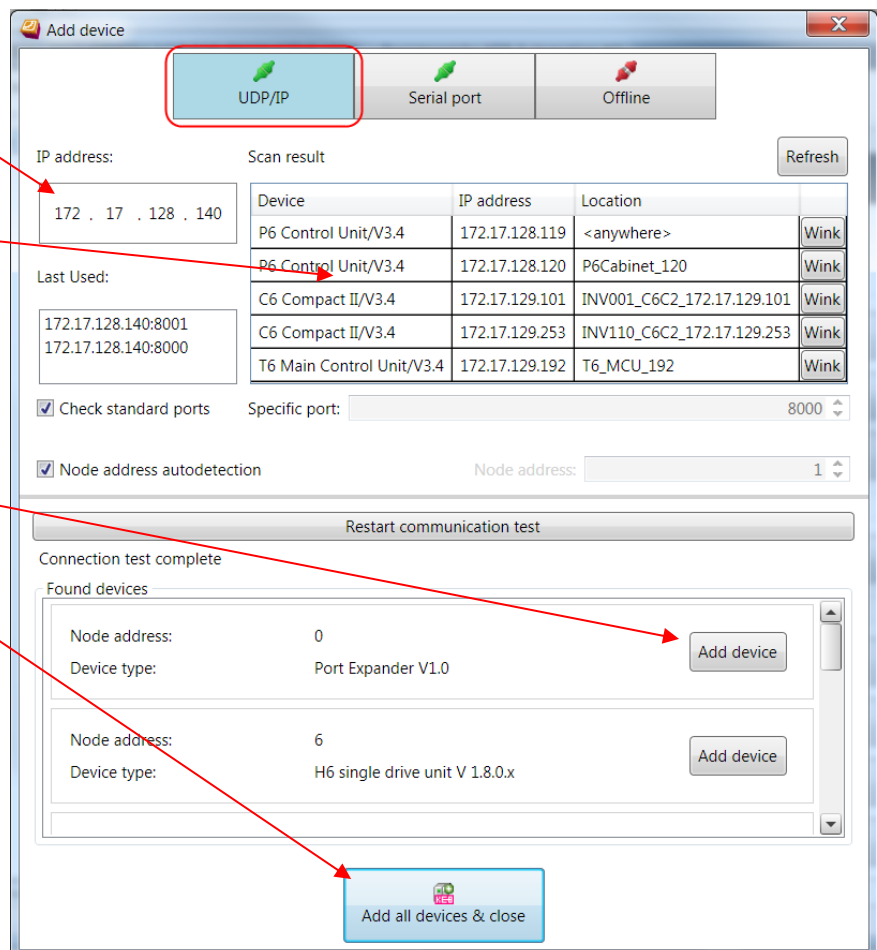
Set communication data
IP address

Devices found in network

By IP address found devices:

Enter: "Add device" – adds this device to project and window stays open

"Add all devices and close" – Window closes



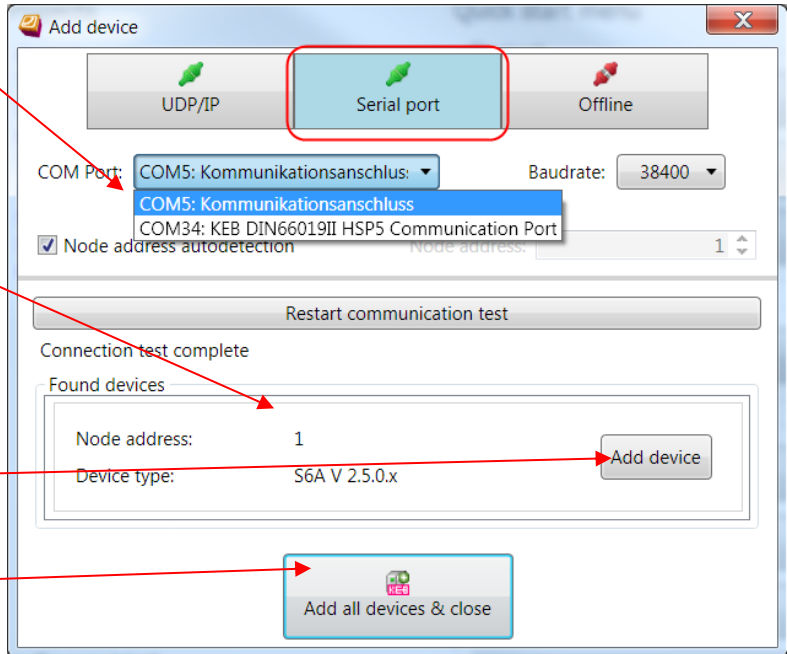
Note: With the KEB Port Expander Part No. 00F5025-0080, the automatic search will find the devices on each scanned port (8000 and 8001) and lists them twice. Please set a fixed port here.

At communication via serial or USB:

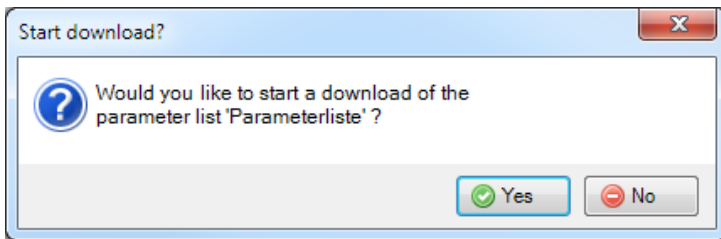
Set communication data
Detected USB connections
are suggested. Set baud rate
manually

"Communication Test" –
runs through each setting
change once. Found devices
are listed immedi-
ately.

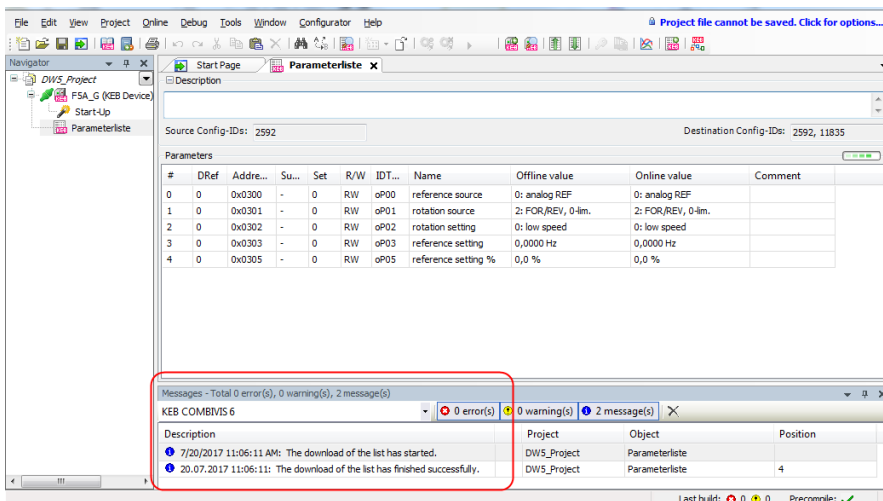
Enter: "Add device" – adds
this device to project and
window stays open
"Add all devices and close"
– Window closes



Enable download by "Yes":



After download, the result of the operation is display in the Message Window on the bottom of the COMBIVIS window:

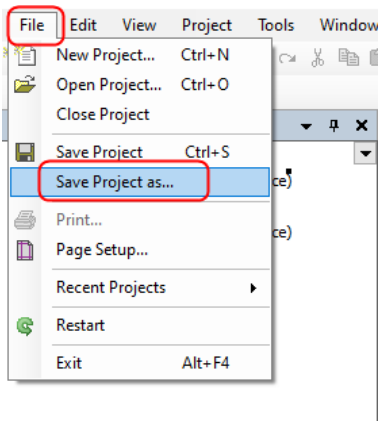


The download is finished and the COMBIVIS can be closed.

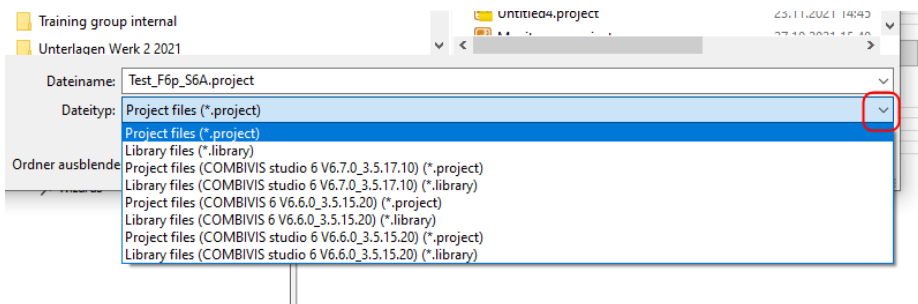
3.7 Storing the Project

The project can be stored in the current version or in former version. And as well as can be stored in COMBIVIS studio 6 as COMBIVIS 6 or the other way round.

by "File" → Save Project" with the same name and profile or by "Save Project as..." with a new name or in other profile.



"File" → "Save project as ..." → File type



If another profile of older version is needed, please contact KEB.

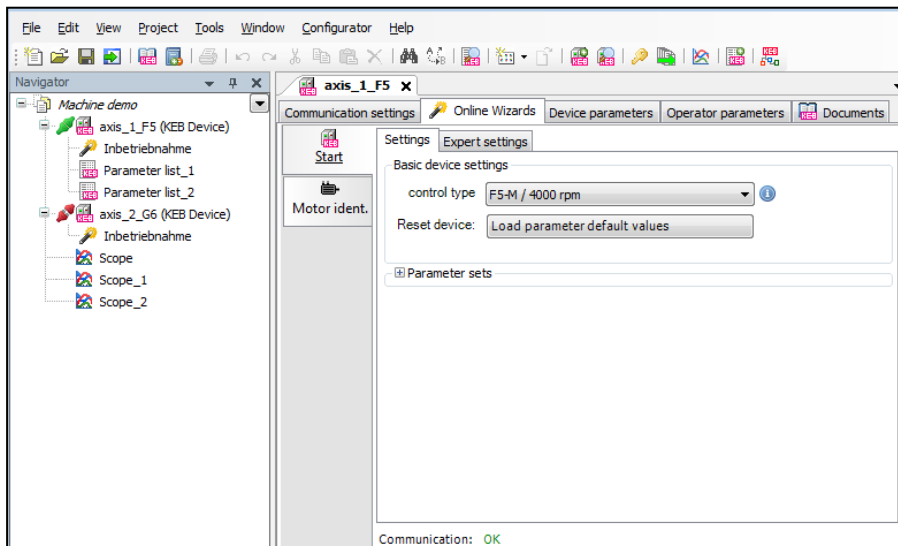
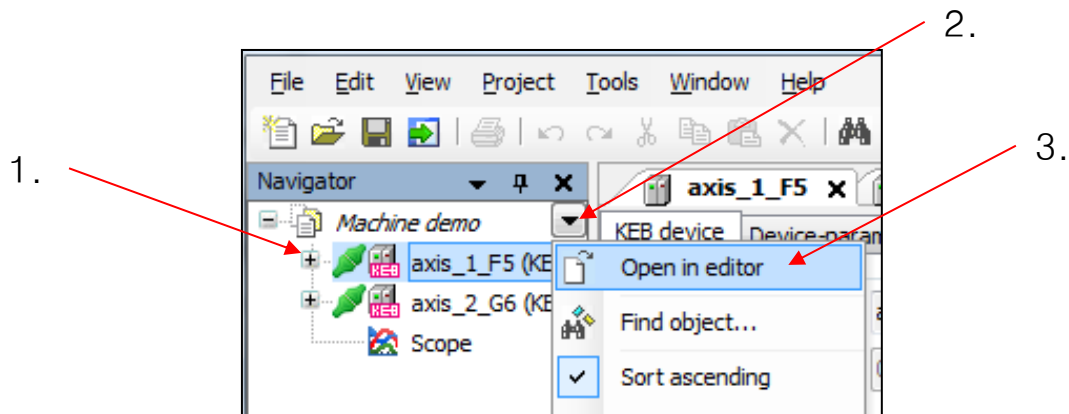
4 Device Editor

- Online data communication, all parameter values will be modified online in the device.
- Parameter storing must be affected by a separate parameter list (=>: [8.17 Parameter backup](#))
- Each device has got its own device editor.

4.1 Open Device Editor

There are two ways to open the device editor:

- Via double-click in the navigator on the name of the device(s) which is/are to edit, or:
 - Marking the name of the device(s) (1.)
- click on “down arrow” (2.)
- “open in editor” (3.)

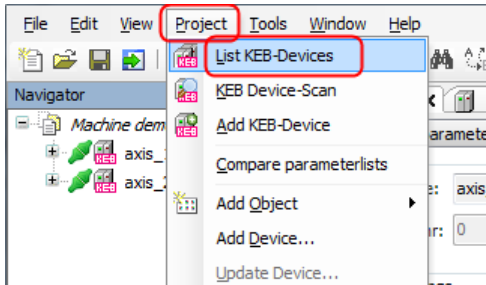


4.2 Device Reference

The device reference number is the instrument to precisely distinguish all devices in the project. This number will be assigned in order of locating during device scan and describes the position of the drive controller in the data bus. It is independent from device node address. That means it can be changed after modification of the wiring and a new scan! Each device reference can only exist once. It cannot be changed manually.

A reference list with all devices can be displayed:

- Context menu right mouse key in navigation window → “List KEB-Devices”
- In menu bar; “project” → “List KEB-Devices”

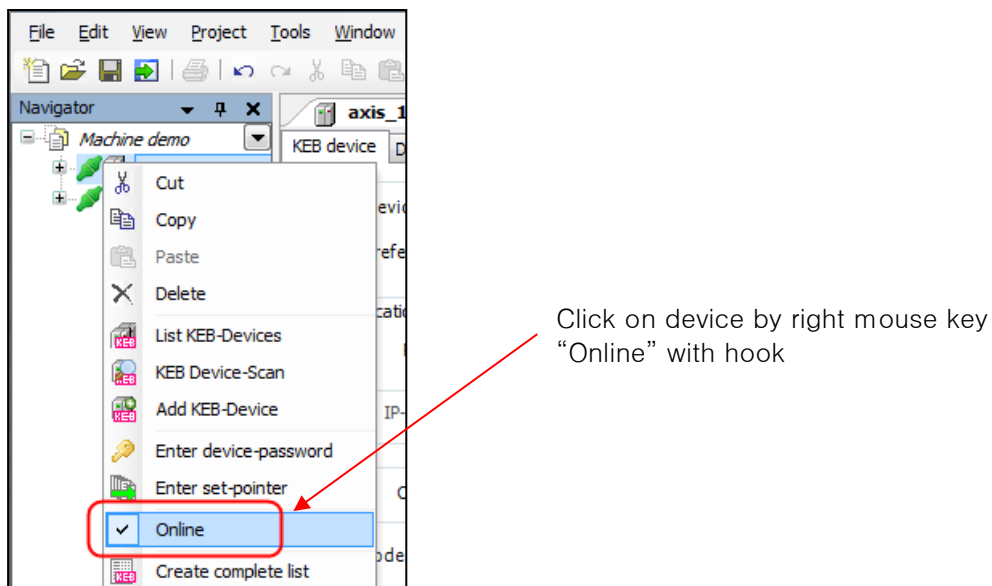


The screenshot shows a window titled 'Parameterizable KEB-Devices' for 'Machine demo.project'. It contains a table with the following data:

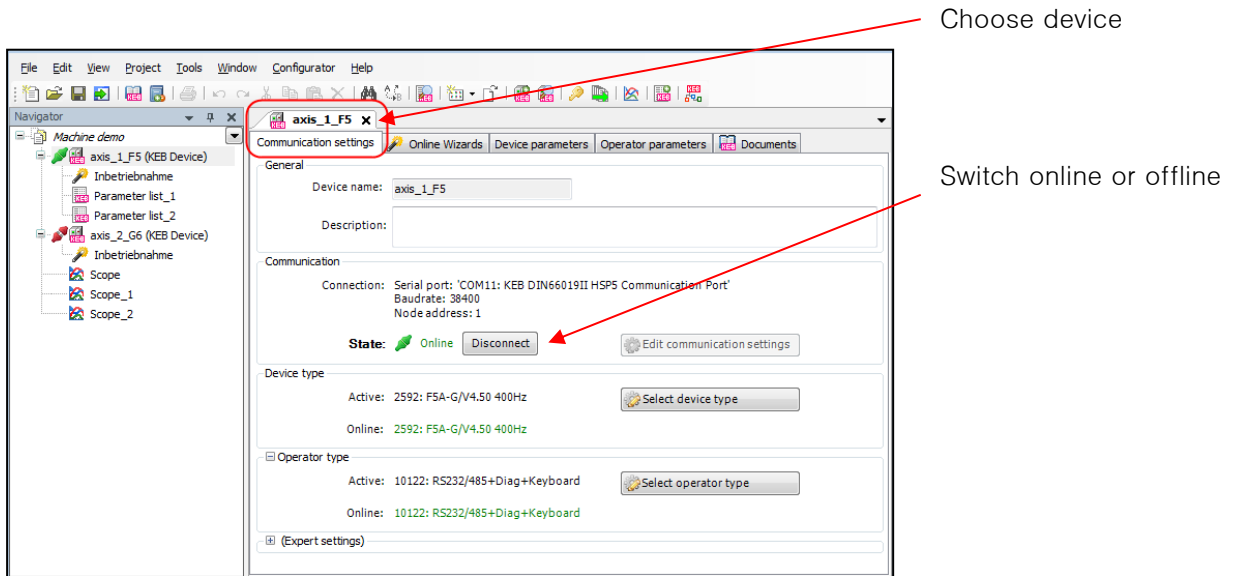
Device name	Dev.-ref.	Device ConfigID	Device type	Operator ConfigID	Operator type	Comm.-Status	Protocol	Comm. Address	Node address
axis_1_F5	0	2420	F5A-M/V4.30 4...	10122	RS232/485+Diag...		SERIAL	COM7 (384...	2
axis_2_G6	1	7080	G6P-S/V1.0.3...	150304	G6/CANopen V1...		SERIAL	COM7 (384...	1

4.3 Switching Online / Offline of Active Device

If an active device may be saved against unplanned adjustment or communication data may be changed the device can/ must be switched offline



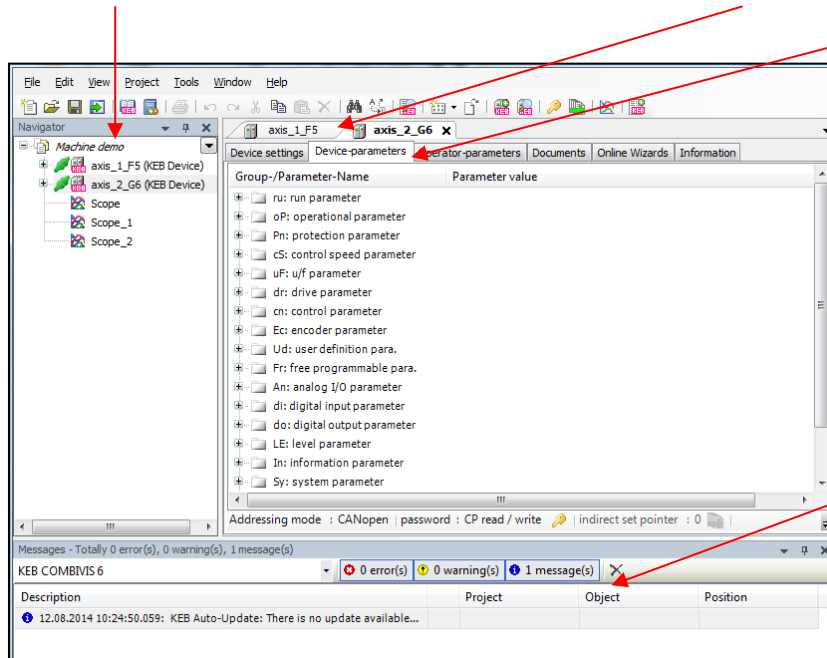
Alternative:



4.4 Screen Layout

Navigator: presentation and activation of the project's particular objects and devices

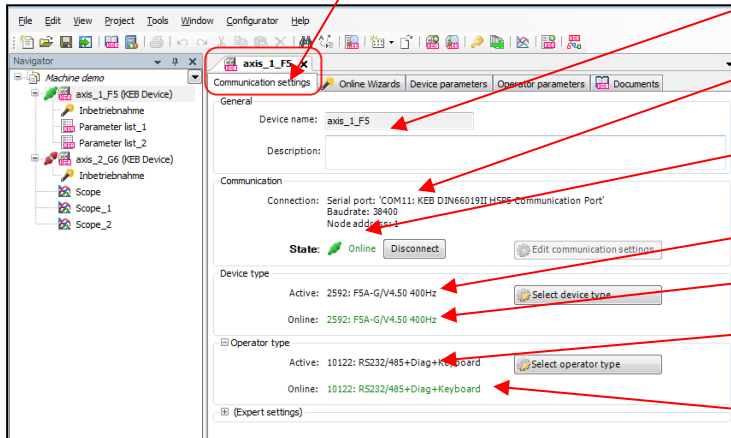
Editor: Editing objects and devices, brake down in tabs according to:
a) device and b) range



4.5 KEB-Device

Communication properties

Selection of devices or object's function tables



KEB-device:

Device name and notes

Communication data

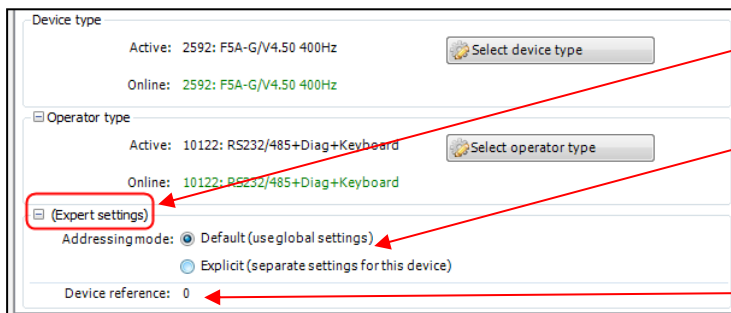
Status of the device (online / offline)

Firmware ID stored in the project

Firmware ID currently in device

Operator ID stored in the project

Operator's currently firmware ID



Expert settings

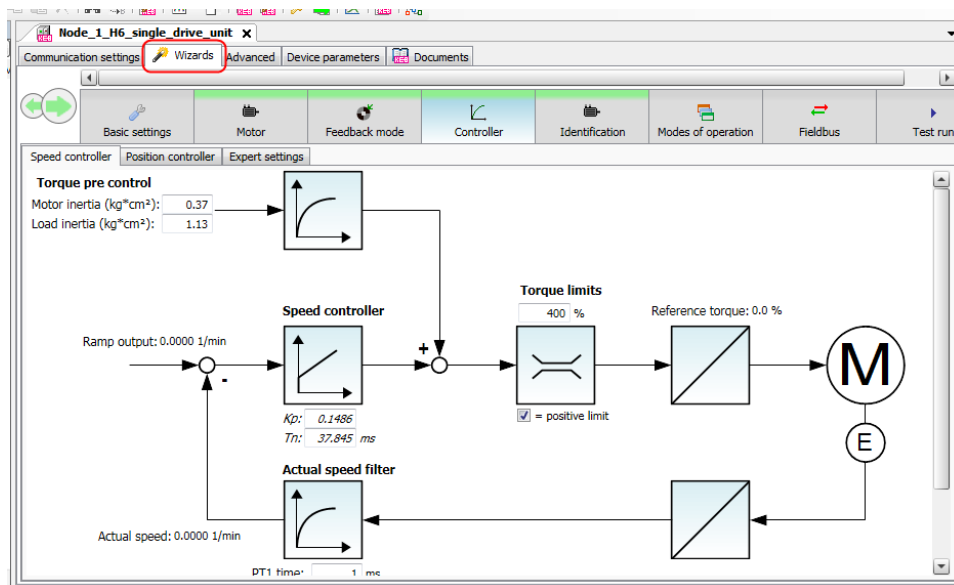
Addressing mode of parameters global or explicit = individual for each device

Device reference is set automatically at scanning

4.6 Online Wizards

Depending on the device type some Online Wizards are displayed.

Online wizards are a start-up and adjustment help. Parameters and adjustments are done direct in the device (=> [10.1 Online Start-up Wizard](#)).



4.7 Device Parameters

In the tab Device-parameters the function parameters of the device (Drive controller) are displayed in the current state. Modifiable parameters can be changed directly in the device here. Parameters of the pluggable operators at COMBIVERT F5 or control cards of COMBIVERT B6 and G6 are displayed in tab operator-parameters.

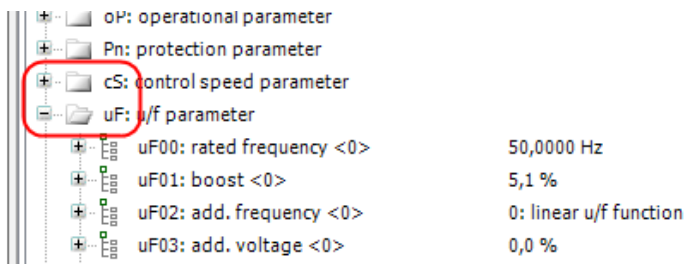
Group-/Parameter-Name	Parameter value
ru: run parameter	
operational parameter	
oP00: reference source <0>	0: analog-REF
oP00: reference source <0>	0: analog REF
oP00: reference source <1>	0: analog REF
oP00: reference source <2>	0: analog REF
oP00: reference source <3>	0: analog REF
oP00: reference source <4>	0: analog REF
oP00: reference source <5>	0: analog REF
oP00: reference source <6>	0: analog REF
oP00: reference source <7>	0: analog REF
oP01: rotation source <0>	2: FOR/REV, 0-lim.
oP02: rotation setting <0>	0: low speed
oP03: reference setting <0>	0,0000 Hz
oP05: reference setting % <0>	0,0 %
oP06: min. reference forward <0>	0,0000 Hz
oP10: max. reference forward <0>	-1: = forward parameter
oP10: max. reference forward <0>	70,0000 Hz
oP11: max. reference reverse <0>	-1: = forward parameter

Parameter groups:
Open via click on “+” / “-” or tab key “Enter” / “Space”

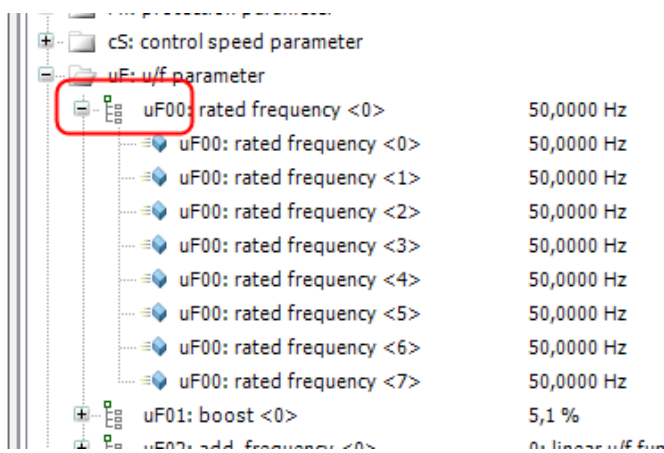
Open set-programmable or ARRAY or STRUCT or STRING parameters

Edit parameter values:
Left mouse – double click, or marking parameter and press key: “Enter” or:
Double click → modify value in property editor

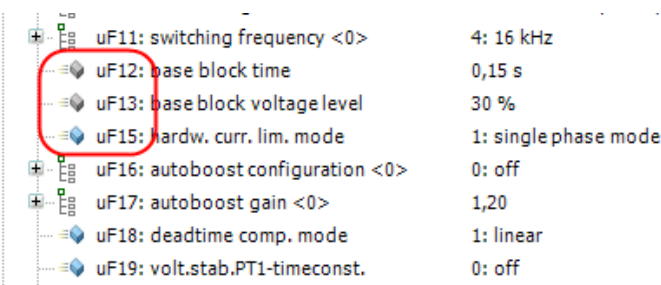
One distinguishes parameter groups:



Set programmable parameter or ARRAYS: By opening with the “+” the individual set programmable parameters or the subindices of the ARRAYS are displayed:



Or variables: All variables are global and have in all parameter sets the same value. (Blue cube: writeable and readable, grey cube: only readable)



Display options can be changed by context menu:

All in monitor indicated parameters will be updated

Only selected parameters will be indicated and updated

“Right mouse key”

Open parameter groups, possible with keys r, o, p, c... (F8), close with “space”-key

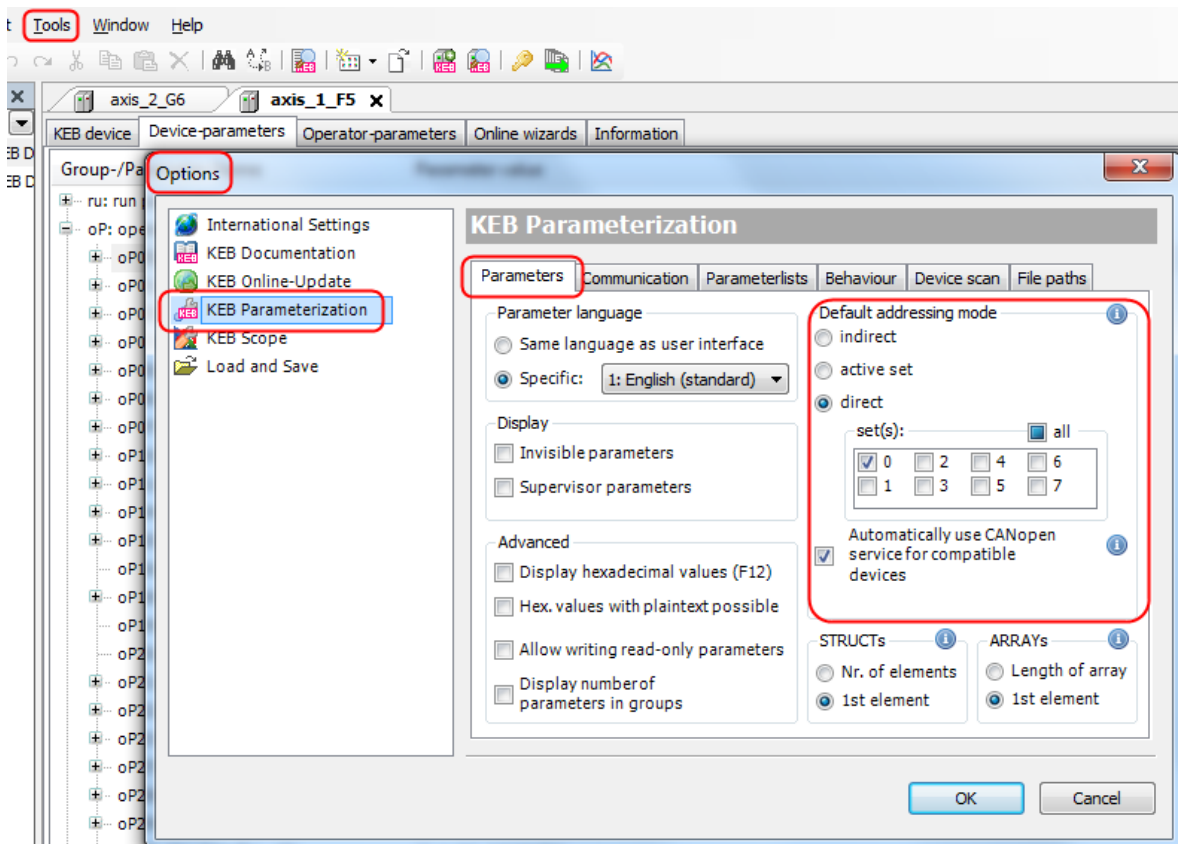
Create a new parameter list with selected Parameters. Multiple selections by “Shift” and “Ctrl” -key. At first open all parameter groups from which parameters may be selected.

Show in KEB Documents explanation for the parameter, => [11.4 Help](#)

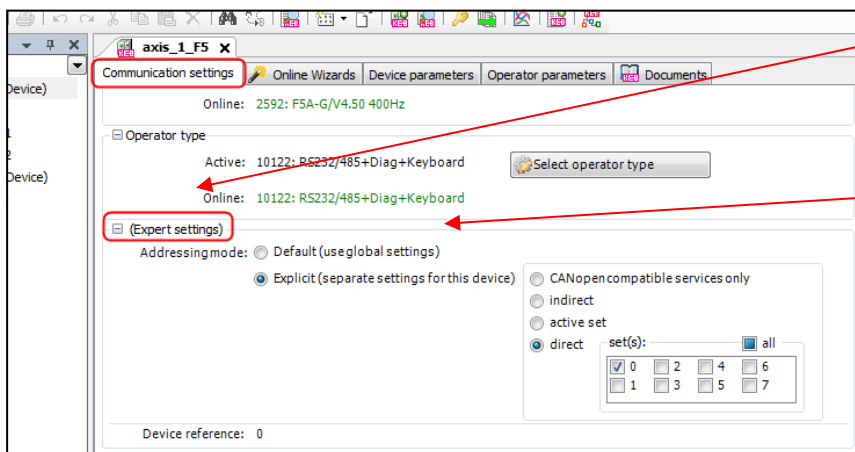
4.7.1 Set Addressing

Is valid for COMBIVERT Type F5/ G6/ B6. In the basic setting of COMBIVIS 6 selection of parameter sets is direct.

Global adjustments for all devices in “Tools” → “Options” → “KEB Parameterization” → Tab: “Parameters”



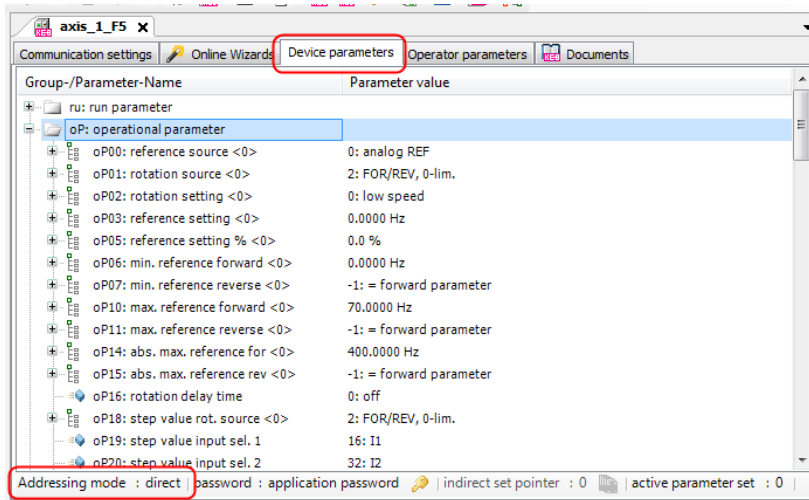
Or explicit adjustment only for the current device: in “device editor” → “Communication settings” → “Expert settings” → “Addressing mode”



Expert settings

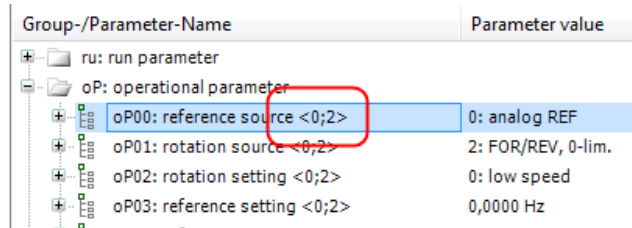
Addressing mode of parameters global or explicit = individual for each device

In the editor, the current addressing mode is permanently displayed at the bottom.

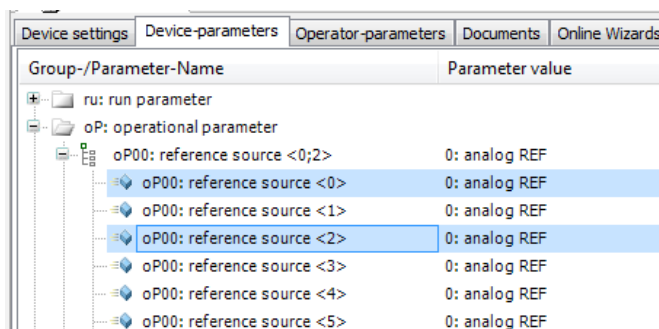


4.7.2 Direct Addressing

For each parameter is displayed, at what rate he is. In the first bottom view the address related parameter is shown. (In this picture: set 0 and 2).

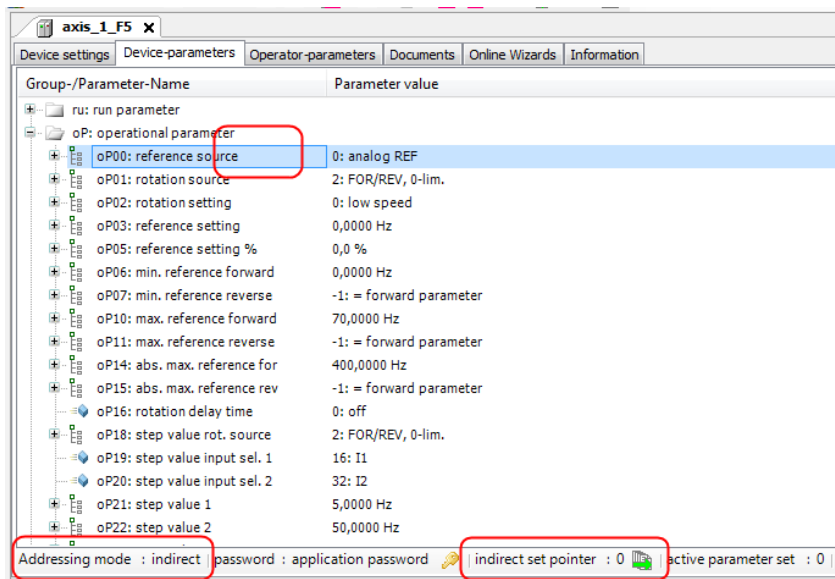


In the second bottom view (second "+") all 8 parameters are shown in direct addressing mode.



4.7.3 Indirect Addressing

It works by set pointer Fr09. In the first bottom view shown values belong to the set to which the set pointer Fr09 is placed. Not-set-programmable parameters have in all sets the same value.

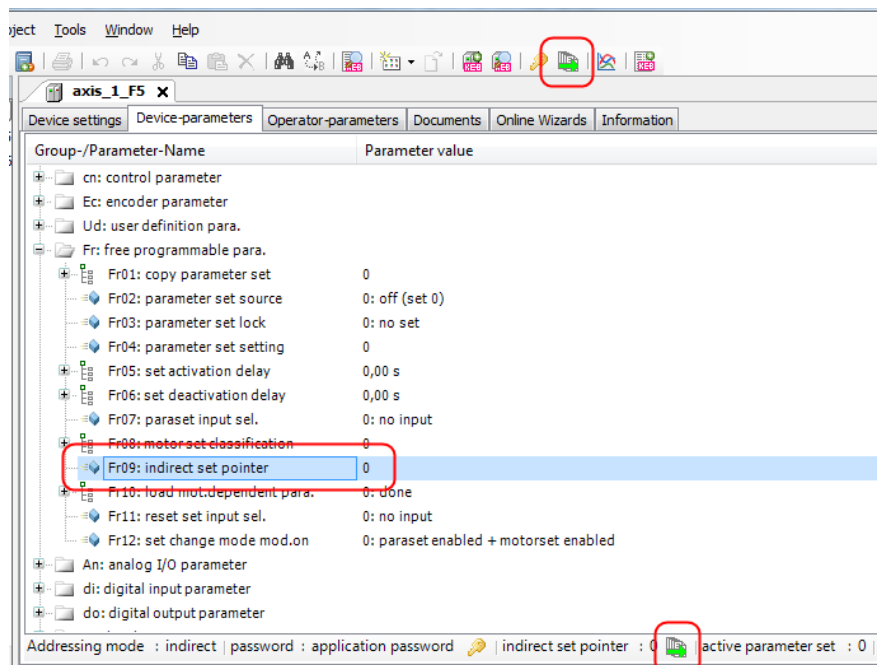


Only at the set pointer is shown to which set the actual shown values are belonging. The pointer is displayed permanently at the bottom of the editor window.

The adjustment of the set pointer Fr09 can be done at the parameter in the editor or direct under the icon



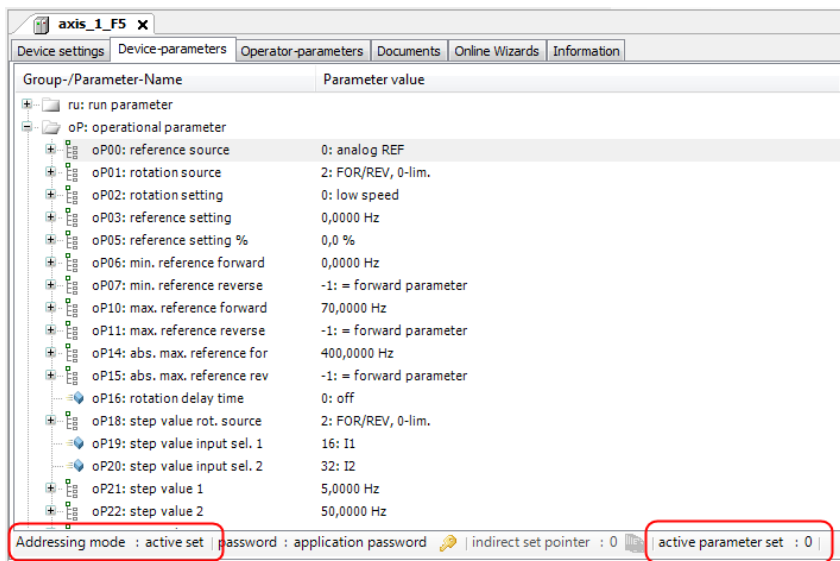
in the tool bar.



In the second bottom view (second "+") all 8 parameters are shown in direct addressing mode.

4.7.4 Active Set

In the first bottom view the parameters of the actual used set are shown (=> parameter ru26, active set). In the second bottom view (second "+") all 8 parameters are shown in direct addressing mode.

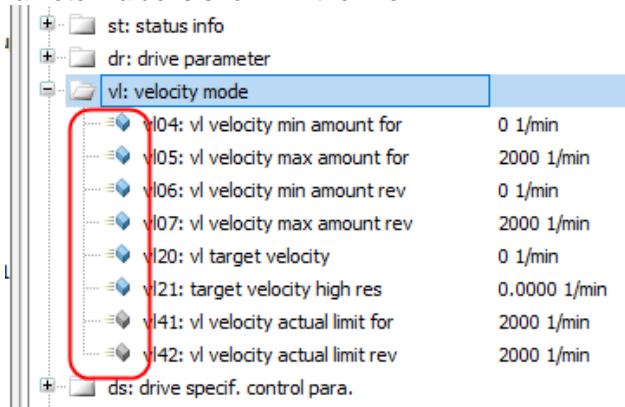



4.7.5 Addressing according CiA 301.

4.7.5.1 Addressing of the COMBIVERT F6, H6, P6, S6, T6


Addressing is done according to CiA 301.

VARIABLES are marked with a blue or grey cube. (Blue: readable + writeable / grey: readable only). The parameter value is shown in the line.



STRUCTURE parameters are marked with a "tree symbol" . The associated sub-indices are again marked with blue/grey cubes (Blue: readable + writeable / Grey: readable only).

ru80: relative load	0.0 %
ru81: actual torque	0.000 Nm
ru82: actual power/energy (Count)	7
ru82: mechanical power [1]	0.000 kW
ru82: electrical output power [2]	0.000 kW
ru82: electrical power loss [3]	0.000 kW
ru82: out. energy mot. [4]	0.4 KWh
ru82: out. energy mot. volatile [5]	0.000 KWh
ru82: out. energy gen. [6]	0.0 KWh
ru82: out. energy gen. volatile [7]	0.000 KWh
ru83: diff. speed (Count)	3
ru84: ref value display	0.0000 1/min

ARRAY parameters are marked with a "tree symbol" . The corresponding sub-indices are again marked with blue/grey cubes (Blue: readable + writeable / Grey: readable only).

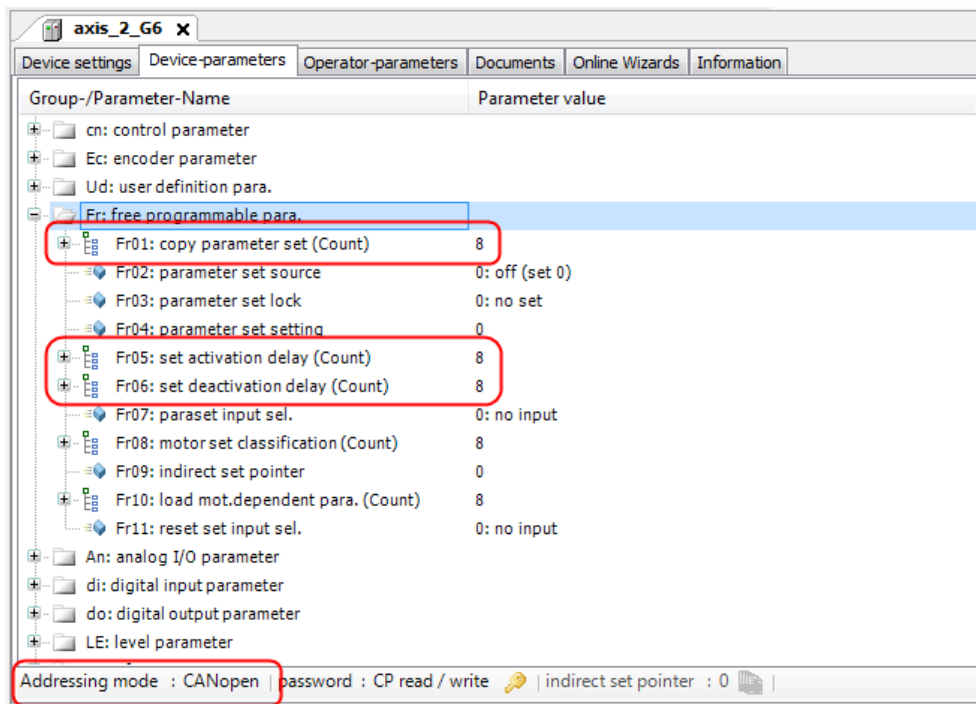
ru82: out. energy gen. [6]	0.0 KWh
ru82: out. energy gen. volatile [7]	0.000 KWh
ru83: diff. speed (Count)	3
ru83: diff. speed [1]	0.0000 1/min
ru83: diff. speed [2]	0.0000 1/min
ru83: diff. speed [3]	0.0000 1/min
ru84: ref value display	0.0000 1/min

STRING parameters include text. Available only in COMBIVERT F6-Pro and S6-Pro (e.g., fb110).

fb105: MAC Address (EoE Channel)	
fb106: MAC Address (EthChannel)	
fb108: Ethernet over fieldbus IP configuration (Count)	
fb109: basic IP configuration (Count)	
fb110: Scan names (Count)	
fb110: Scan names [1]	
fb110: Scan names [2]	
ec: encoder parameter	

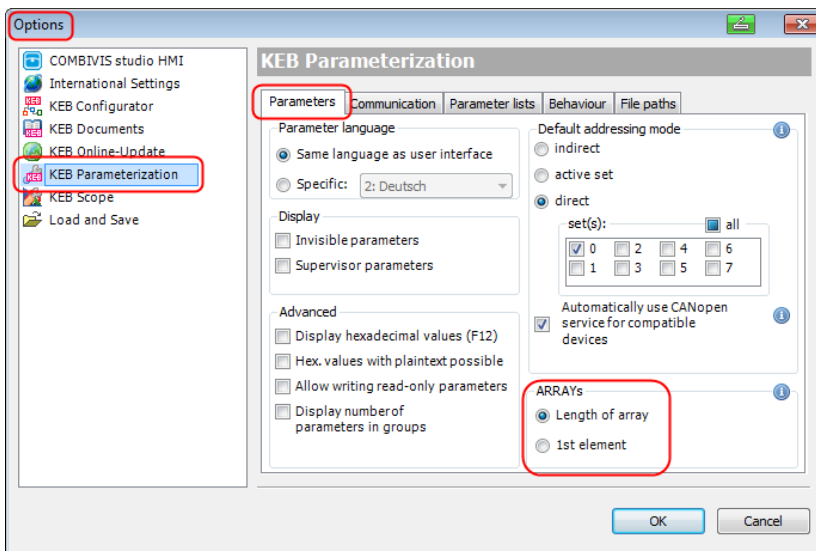
4.7.5.2 Addressing of the COMBIVERT G6

The addressing of CiA 301 is like the direct addressing sentence of COMBIVERT F5. The subindices are numbered from 1 to x. The set 0 here corresponds to the subindex 1. Set 1 to subindex 2, etc. In the first bottom view (parameter sets closed) the number of available subindices is shown if the parameter is set programmable. At not-set-programmable parameters the value is displayed.

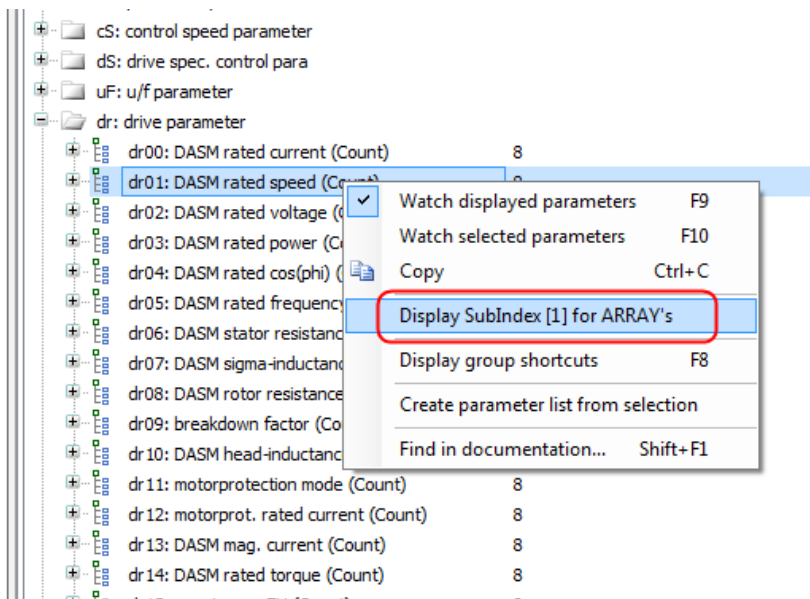


The display of closed parameters in the first bottom view can be changed.

By in "Tools" → "Options" → "KEB-Parameterization" → Tab: "Parameter" → "ARRAYS" can be chosen if the number of subindices or the value of the first subindex will be shown.

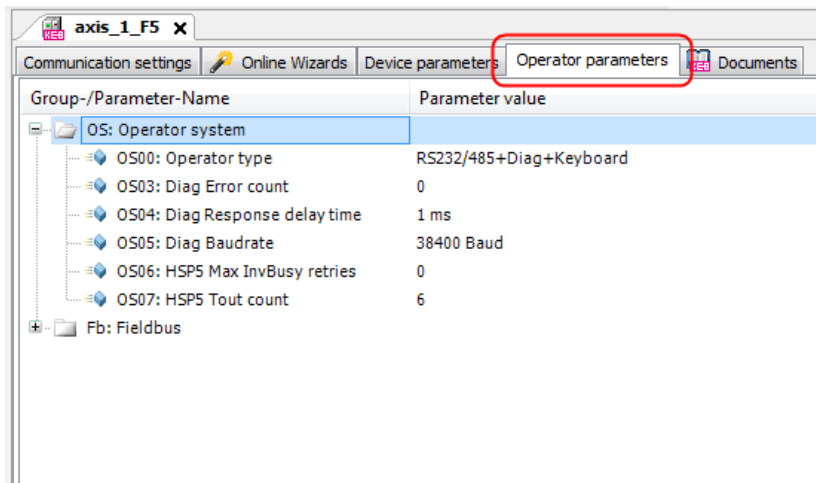


Or use context menu: right mouse key: "Display Subindex [1] for ARRAYS"



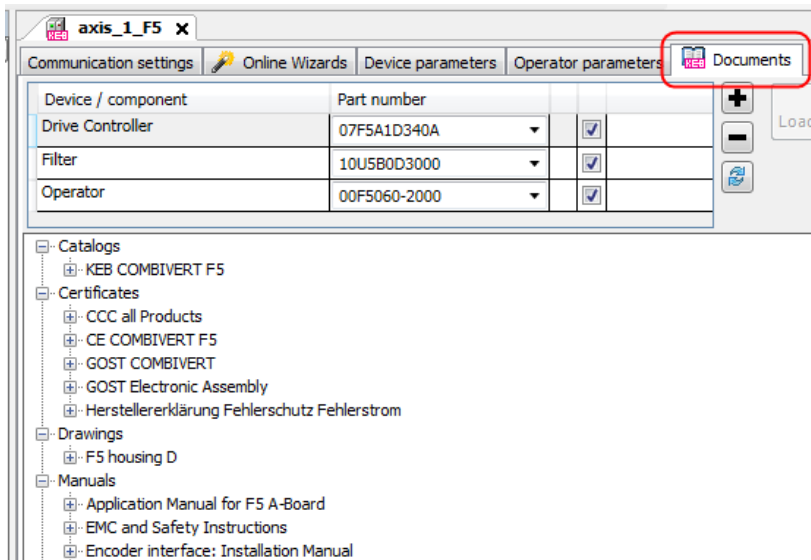
4.8 Operator Parameters

The tab is shown only if an operator is detected. At COMBIVERT G6 the communication board is named as operator. Same behaviour as in tab “device parameters”.



4.9 Documents

In the tab documents all available documents (manual, data sheets...) are displayed. Only the associated documents are displayed by entering the device part numbers. Part numbers you enter here will be permanently assigned to the device but can be changed by overwriting.

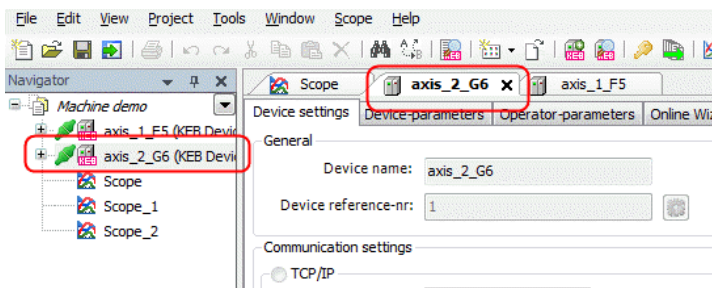


=> [13 Document Database](#)

4.10 Display Changing Between Editors

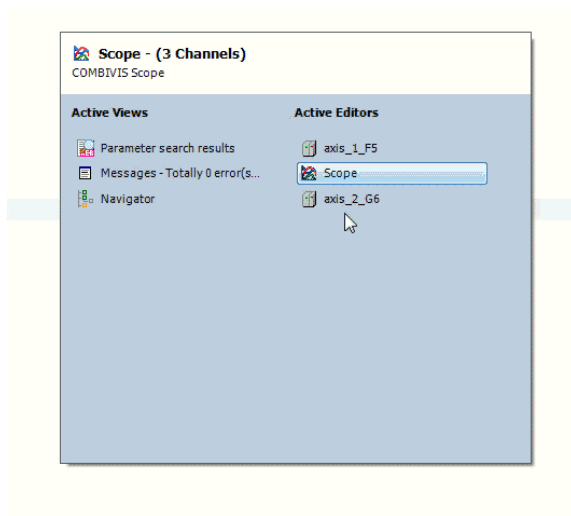
Display of editors can be changed by:

- Click on editor tab
- Double-click on the object in the navigator



- Key combination “CTRL+Tab”

While fixing the “CTRL” key and one of the “←”, “↑”, “→”, “↓” keys can be selected which editor shall be opened. It displays only active editors.



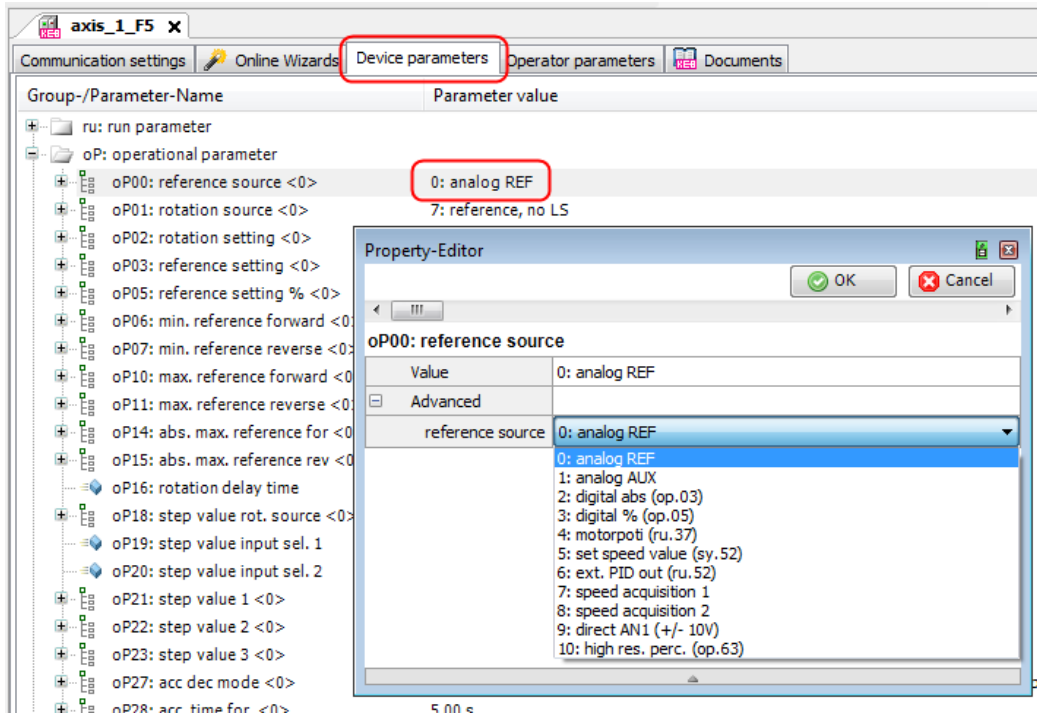
4.11 Drive Storage

The KEB COMBIVERT F6 / S6 can manage the recipe management. Certain parameter lists can be stored in the device memory and can later be loaded into the runtime environment in different ways.

For storing the device storage wizard (=>[17.1 device storage wizard](#)) or the KEB FTP program (=>[17.2. KEB FTP](#)) can be used.

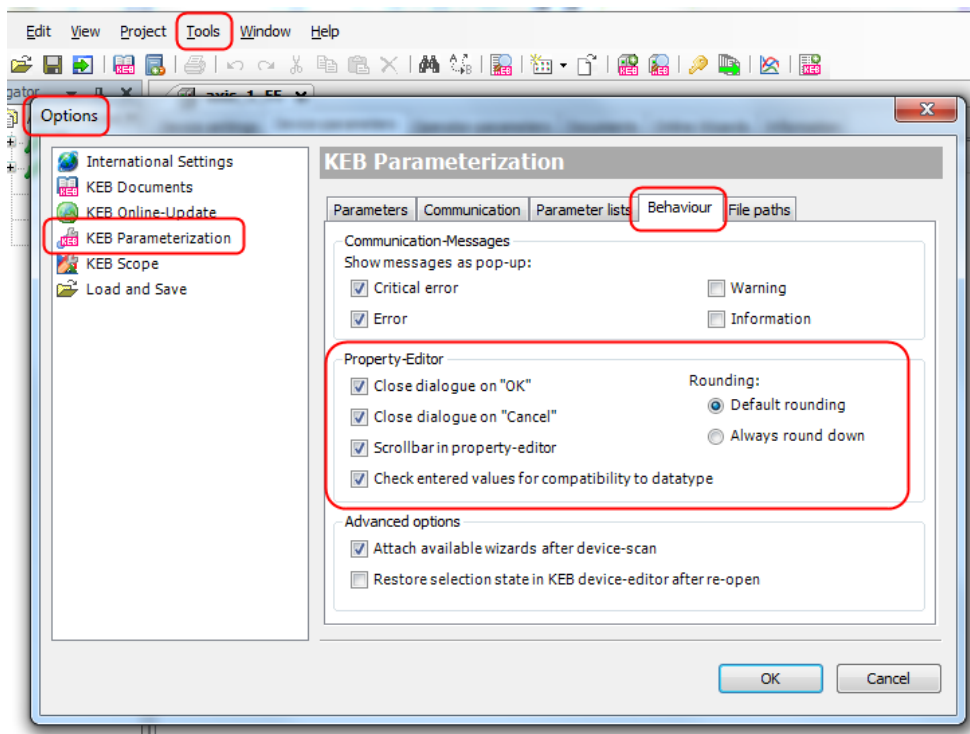
5 Property Editor

For changing the parameter value, the property editor can be opened by double click with mouse on the value or mark by mouse and press “enter”-key

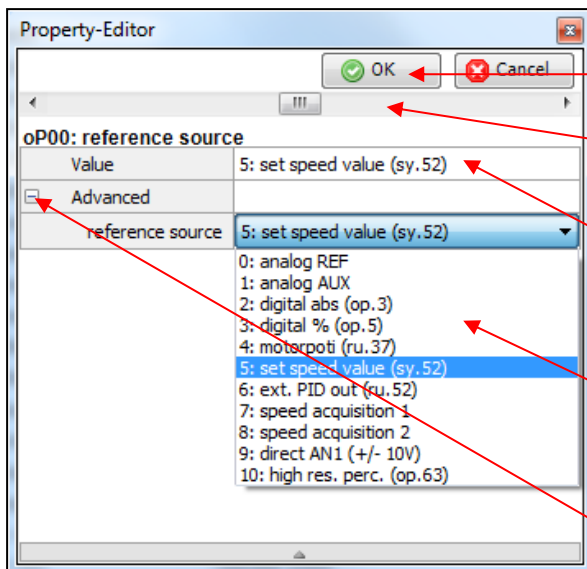


5.1 Basic Setting

In area “Property editor” can be adjusted if input window should be displayed sequential or permanently. Please click on: “Tools” → “Options” → “KEB Parameterization” → “Behaviour”.



5.2 Feature Selection



“OK” takes the current value

Scroll bar, slid able by mouse

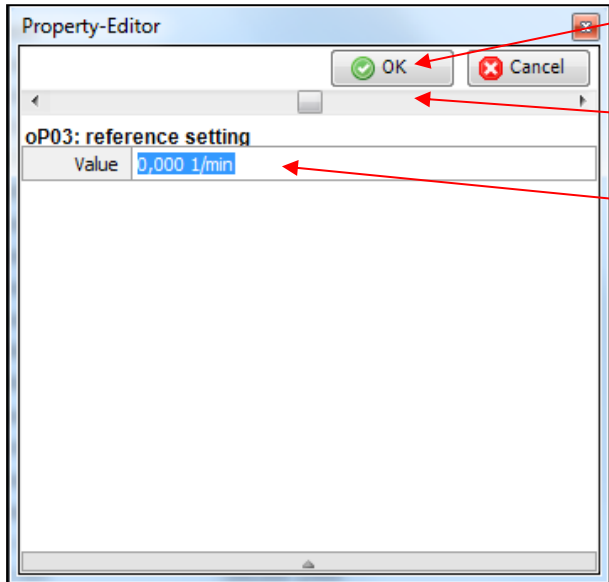
Input value. This value will be taken by “OK”. (Can also be given directly as a number)

Selection list

Selection list viewable / hidden

Selection list and scroll bar can be used in parallel

5.3 Numerical Value Input



“OK” takes the current value

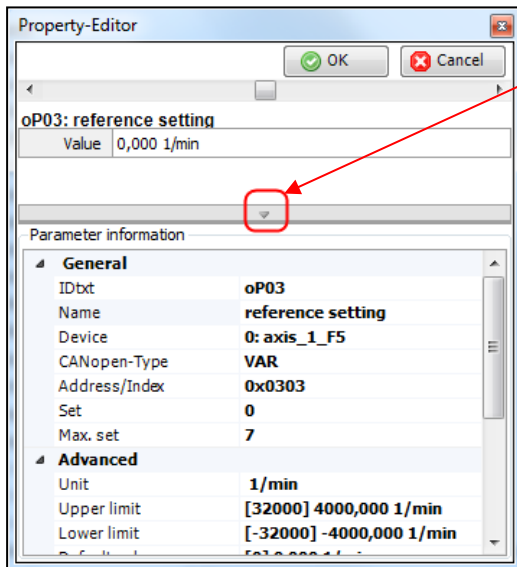
Scroll bar, moveable by mouse

Direct input of a number or value.
This value will be taken with “OK”

Direct input and scroll bar can be used in parallel.

5.4 Parameter Properties / Information

The COMBIVIS device description file contains a lot of information "around" the parameters. These are shown when you click on the bar with the small triangle at the bottom of the Property-Editor window.



Via click on this arrow a window will be opened which displays basic data of the parameter:
Hex. -address
Limits
Default value
Resolution
Data length
...

5.4.1 Plaintext Export in IEC 61131-3

With version **COMBIVIS studio 6** the parameter plaintexts can be exported in IEC 61131 format.

Context menu at the parameter: “generate IEC 61131-3 code” → “Create plaintext-function...”

Group-/Parameter-Name	Parameter value
ru: run parameter	
ru01: exception state	55: ERROR safety module
ru02: warning bits	0: no warning
ru03: warning state	0: no exception
ru04: supply unit state	4: run
ru05: set value display	0,0000 1/min
ru06: ramp out display	0,0000 1/min
ru07: act. frequency	0,0000 Hz
ru08: act. value	0,0012 1/min
ru09: act. encoder speed	0,0099 1/min
ru10: act. apparent current	0,00 A
ru11: act. active current	0,00 A
ru12: act. reactive current	0,00 A

Context menu for 'ru01: exception state':

- Watch displayed parameters (F9)
- Watch selected parameters (F10)
- Copy (Ctrl+C)
- Display group shortcuts (F8)
- Create parameter list from selection
- Generate IEC 61131-3 Code**
 - Create Plaintext-function (IEC 61131-3)
 - Create Norm function (IEC 61131-3)
- Find in documentation... (Shift+F1)

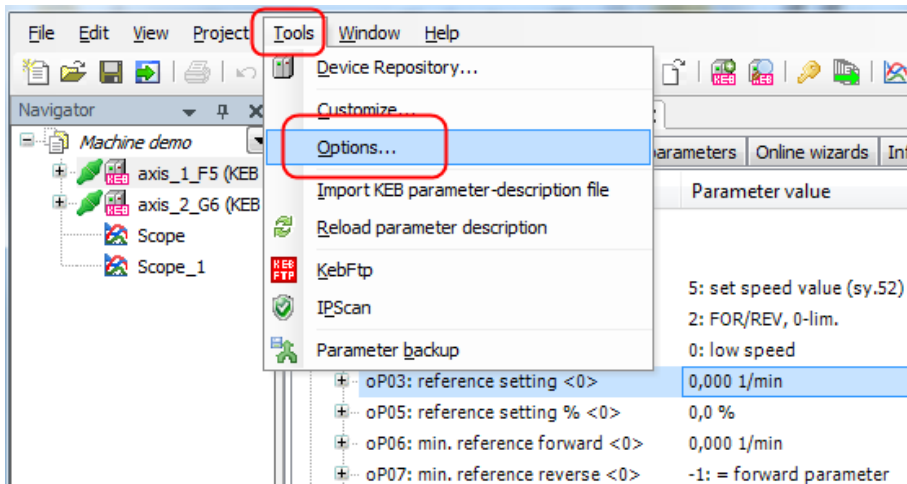
```

1  (*
2  This function generates the plaintext for parameter "ru01: exception state" (Device-Type: 9266: *)
3  (no guarantee for correctness and completeness)
4
5  [KEB IEC-Code-Generator Version: 6.5.0.201]
6  *)
7  FUNCTION GetPlainText_ru01 : STRING(35)
8  VAR_INPUT
9  // The value for which the plaintext is desired
10 value : DINT;
11 END_VAR
12
13
14 CASE value OF
15   16#00000000: GetPlainText_ru01 := 'no exception';
16   16#00000001: GetPlainText_ru01 := 'ERROR chain';
17   16#00000002: GetPlainText_ru01 := 'ERROR supply';
18   16#00000003: GetPlainText_ru01 := 'ERROR overcurrent FG';
19   16#00000004: GetPlainText_ru01 := 'ERROR overcurrent analog';
20   16#00000005: GetPlainText_ru01 := 'ERROR overpotential';
21   16#00000006: GetPlainText_ru01 := 'ERROR underpotential';
22   16#00000007: GetPlainText_ru01 := 'ERROR overload';
23   16#00000008: GetPlainText_ru01 := 'reset E. overload';
24   16#00000009: GetPlainText_ru01 := 'ERROR overload 2';
25   16#0000000A: GetPlainText_ru01 := 'ERROR overheat pmod.';
26   16#0000000B: GetPlainText_ru01 := 'reset E. overheat pmod.';
27   16#0000000C: GetPlainText_ru01 := 'ERROR overheat thermal';
28

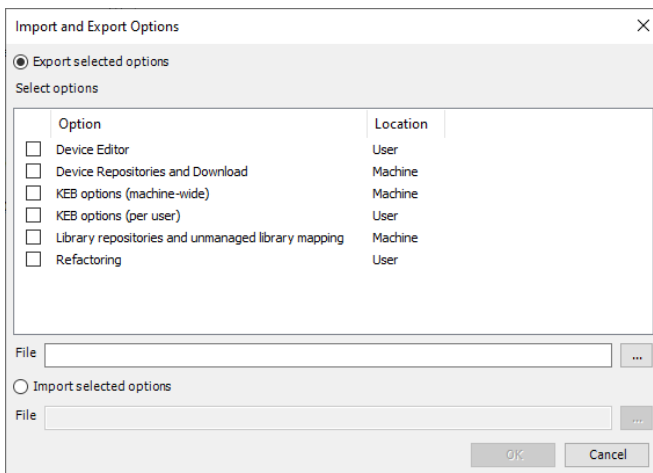
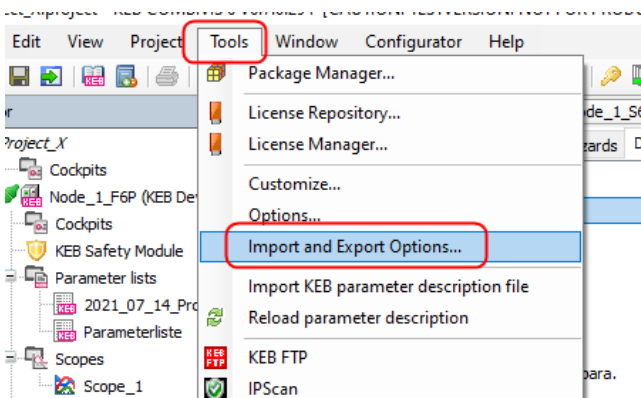
```

6 General Adjustments

General and special options can be indicated and adjusted in “Tools” → “Options...”.



These adjustments will be saved automatically non-volatile.
 In the event of a version update, the option settings are retained.
 The settings can be exported and imported on another computer:
 Menu bar "Tools" → "Import and Export Options..."

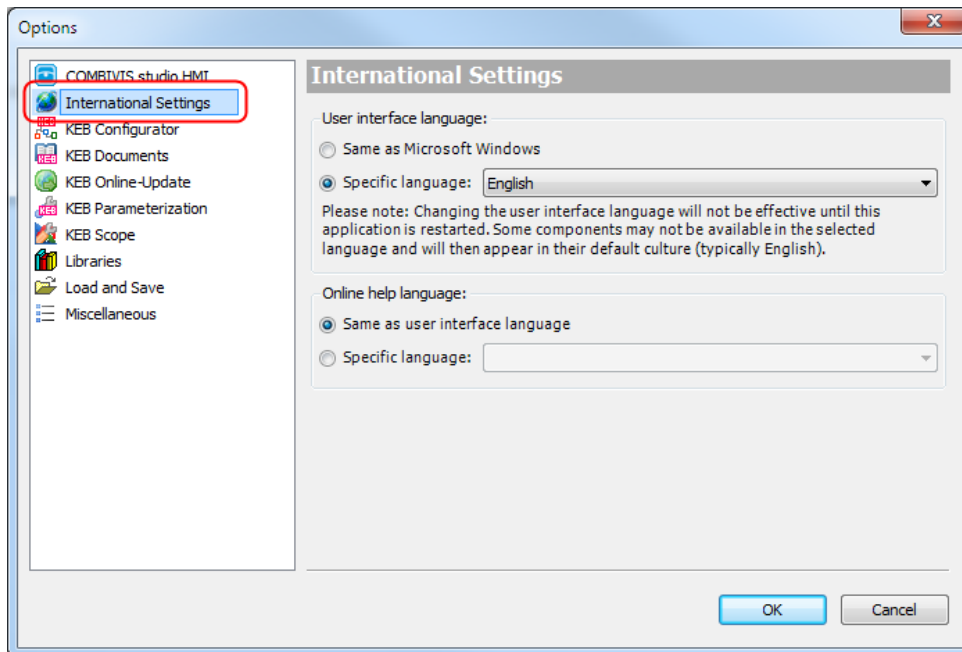


6.1 Options - Language Settings

There are 3 language areas:

- Program language
- Parameter language
- Help

These can be handled independent. If a language is not available English is shown.

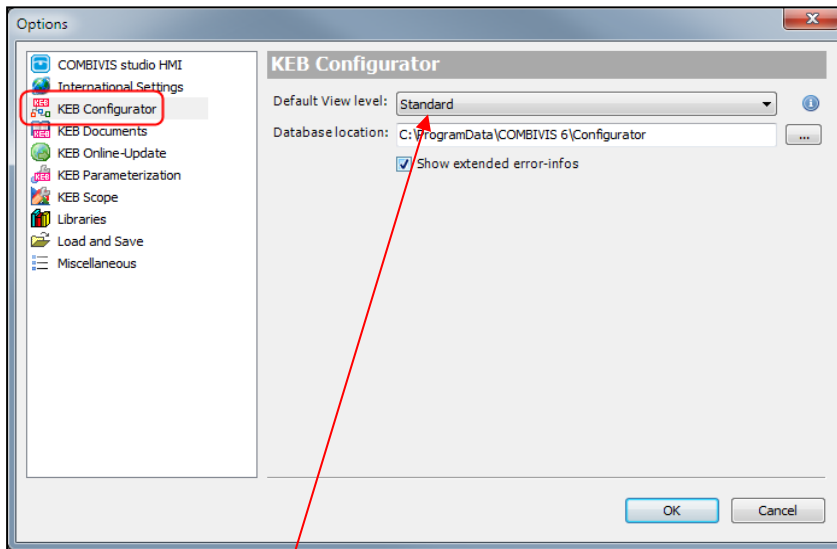


The parameter language can be adjusted by: "Options" → "KEB Parameterization" → "[6.5 Parameter](#)".

6.2 Configurator

KEB Configurator settings can be adjusted for each start of the configurator.

=> [18 Configurator](#)



Specifies the scope of columns in the generic selection dialogs and the amount of information to be displayed in the property grid.

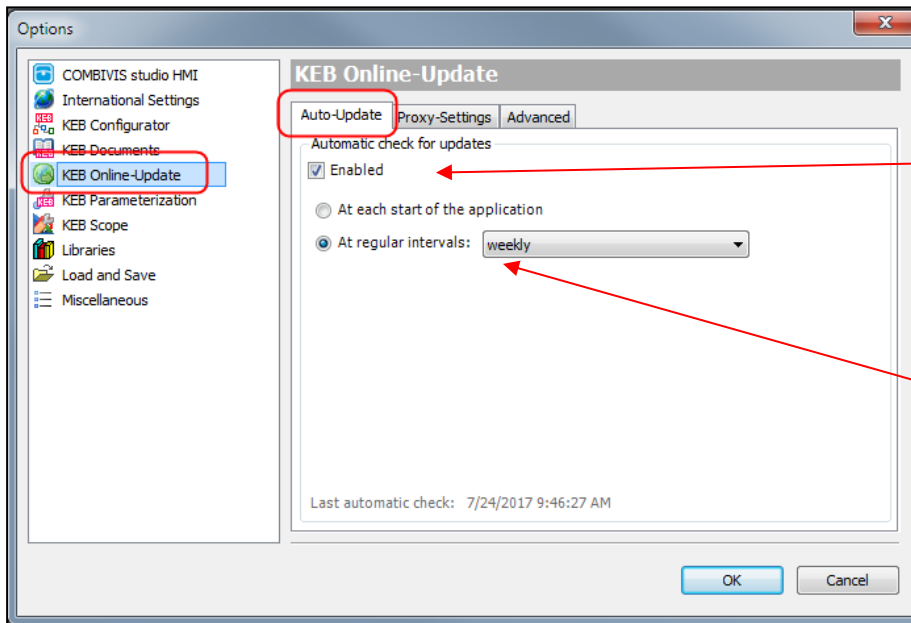
- Standard:
All relevant properties are displayed.
- Expert:
All relevant plus some specialized properties are displayed.
- Internal:
All properties are displayed.

6.3 Options - KEB Documents

=> [13.2 Use KEB Documents](#)

6.4 Options - Online-Update

KEB COMBIVIS 6 can search for available updates and install if an internet connection is available. It is not only sought after program update, but also for updates to instructions, parameter files (required at firmware update in KEB- devices) and libraries.

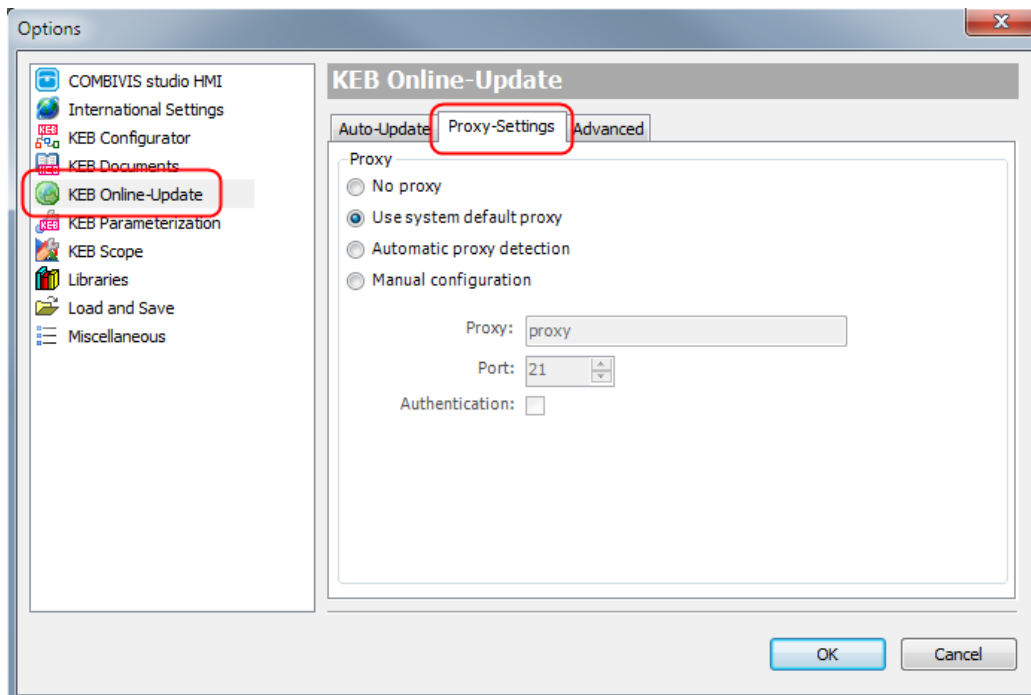


Activates auto-matically updates

Choose at which date the update will be done

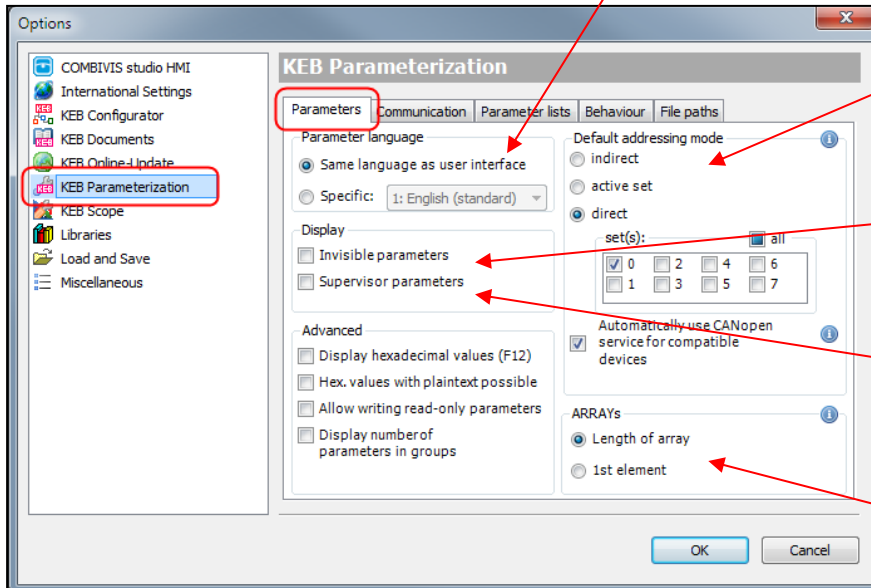
Automatically check for updates weekly / monthly means next test 7/30 days after the last test if an Internet connection exists or at the next connecting after this date.

COMBIVIS 6 uses the system settings for proxy settings. The settings can be changed explicit.



6.5 Parameterization - Parameter View

Parameter language
 If language file is not available, English will be used



Addressing mode of parameters => [4.7.1 Set Addressing](#)

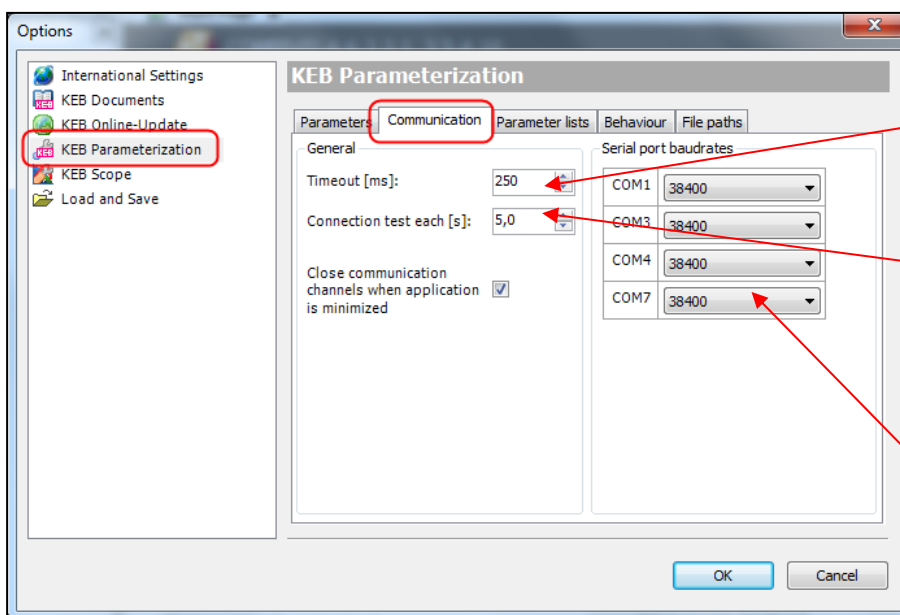
Display of normally invisible service parameters

Display of service parameters with special password protection

Adjustments according to CiA 301

Instead of number of subindices the first value of subindex 1 is shown

6.6 Parameterization - Communication



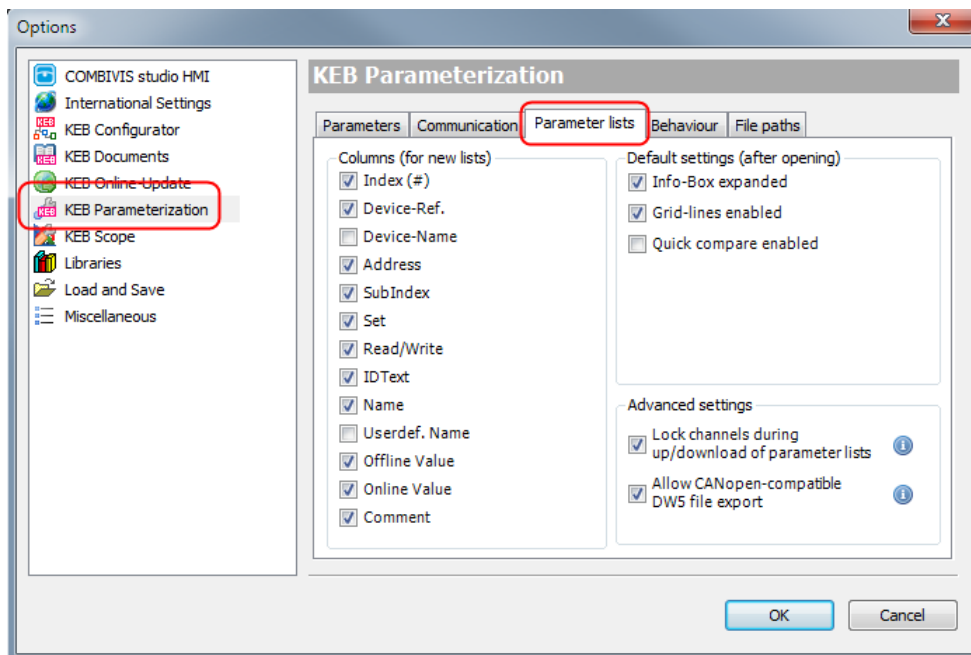
Maximum waiting time for reply

Control of circuit status after each x seconds

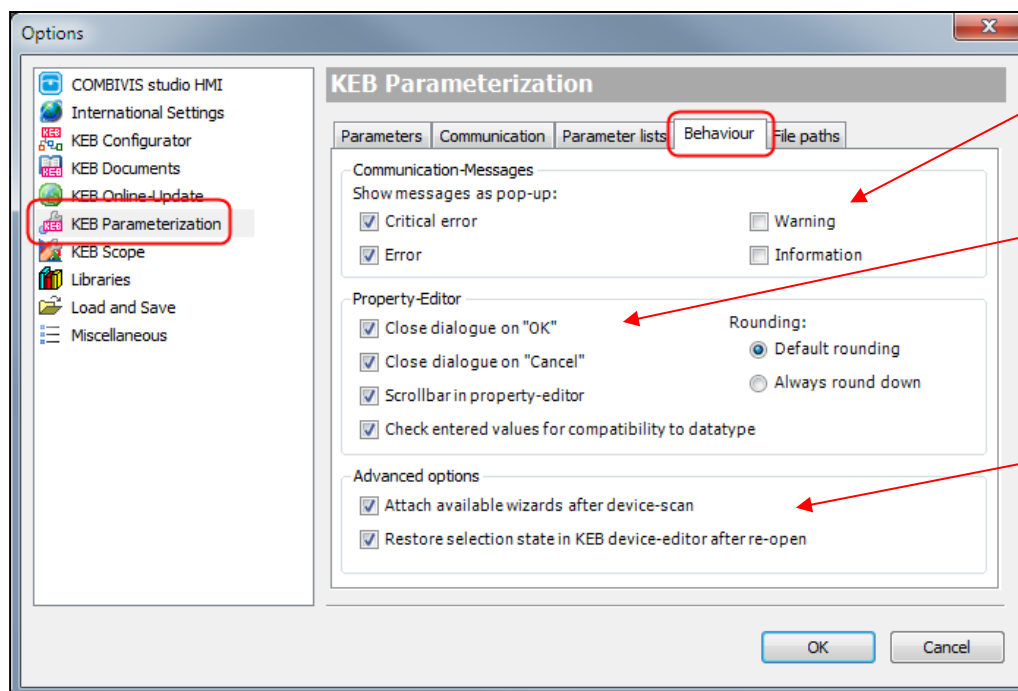
Active attribution of interface and respective transfer rate. The number of COM interfaces depends on the PC hardware.

6.7 Parameterization - Parameter Lists

Default settings of new opened parameter lists



6.8 Parameterization - Behaviour



Behavior at error messages

Behavior of the property editor (input window)

Available assistants will be directly attached to the located device

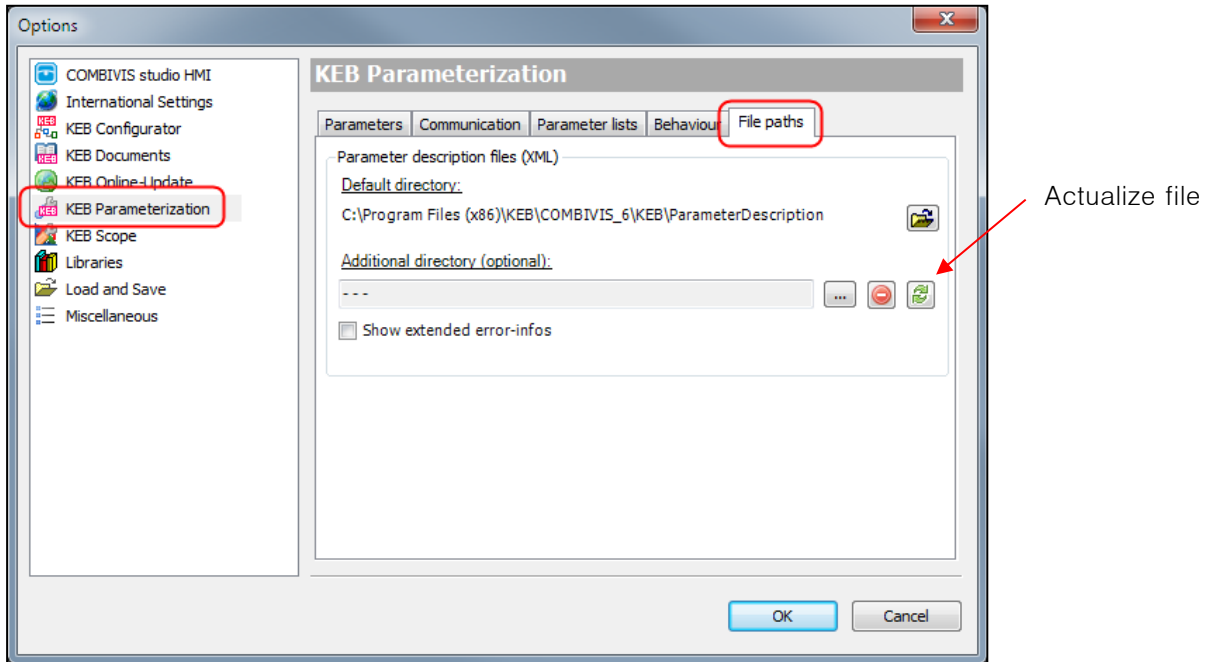
6.9 Parameterization - Data Paths for Parameter Description

Data path for the parameter description file (XML-file). Depending on drive mode and firmware for each KEB device one or more parameter description files are necessary. If the file is not available in COMBIVIS no parameters are displayed in the editor. By [online update function](#) the database can be actualized automatically.

On the mains path the XML-Files of all addressable devices are stored.

Normally the parameter description (XML-file) may be stored in the default file. A second path / folder for e.g., additional/special parameter descriptions can be defined.

This folder can be placed elsewhere but the data path must be achieved here.

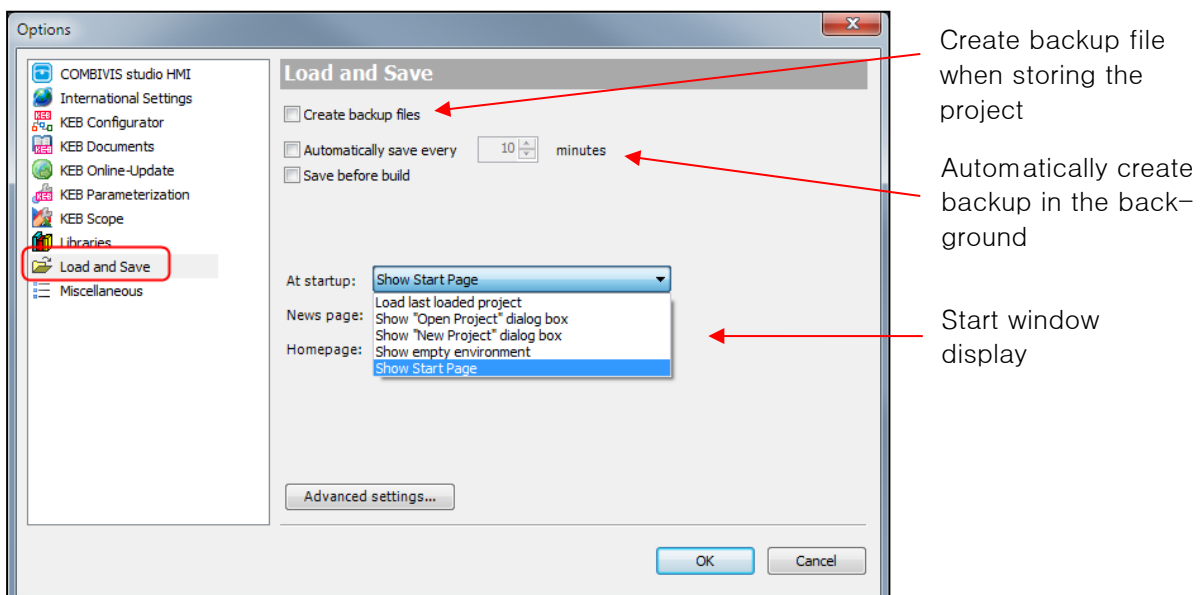


6.10 Options – KEB Scope

=> [9.3 Scope Basic Settings](#)

6.11 Options - Load and Save

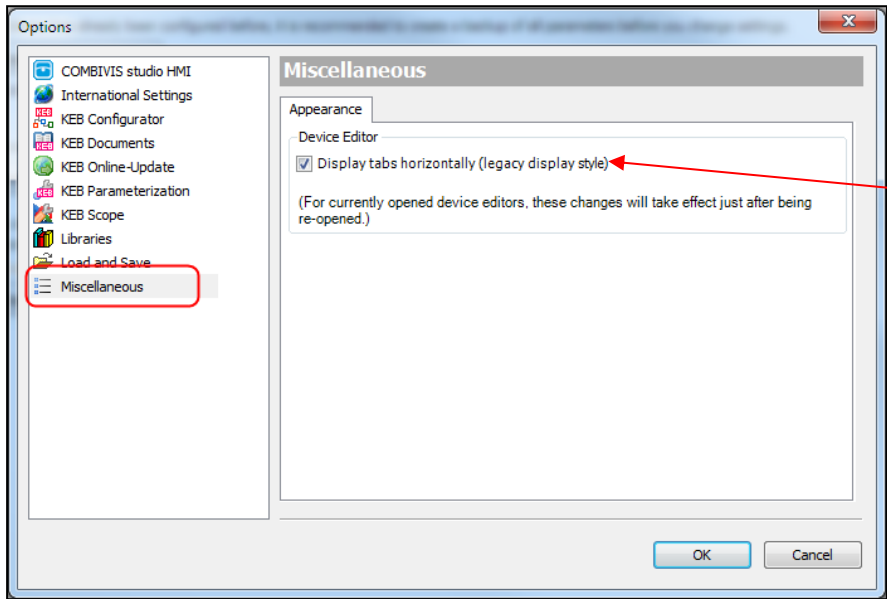
Settings for loading, saving and for the start-window



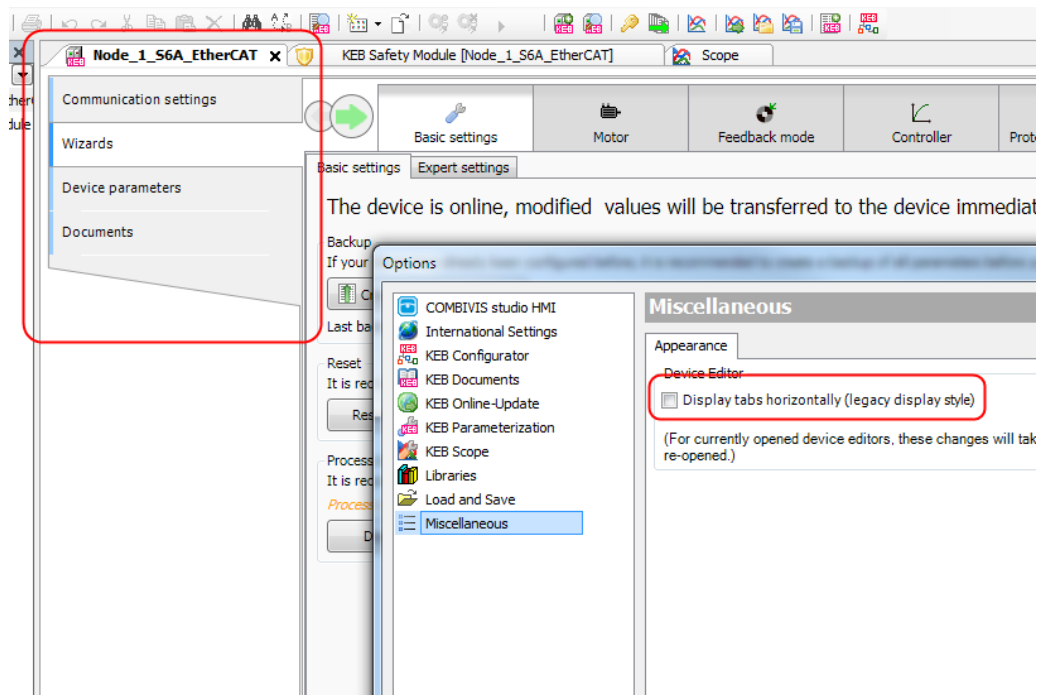
The backup is stored as “xxx.backup” and can be made readable again by changing in “xxx.project”.

6.12 Miscellaneous

In default all tabs in the device editor are directed horizontally. Alternatively, the tabs can be directed vertically.

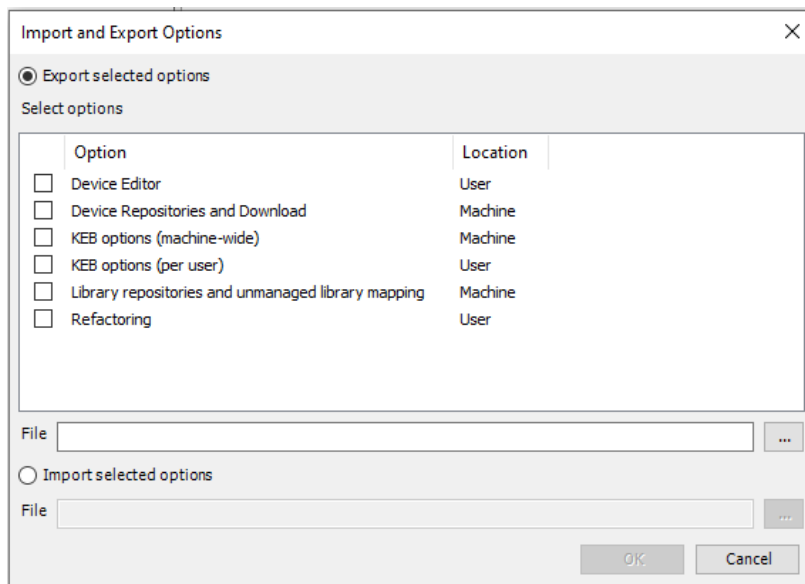
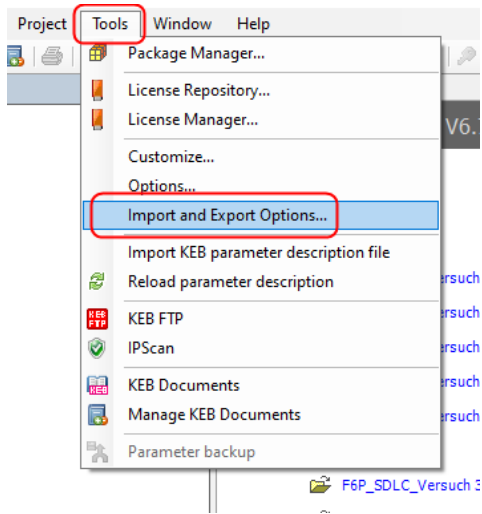


Set tabs in device editor horizontally instead of vertically (default)



6.13 Export or Import Options

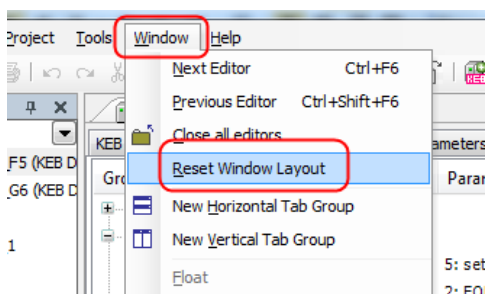
Certain options can be exported or imported.



7 Window Layout

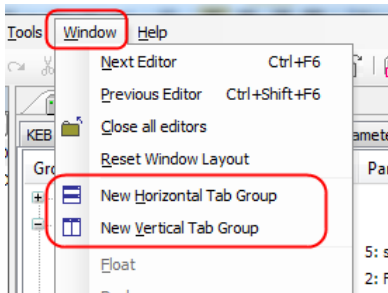
Reset window layout:

All changes in the window layout can be reset by: Menu bar: "Window" → "Reset Window Layout"



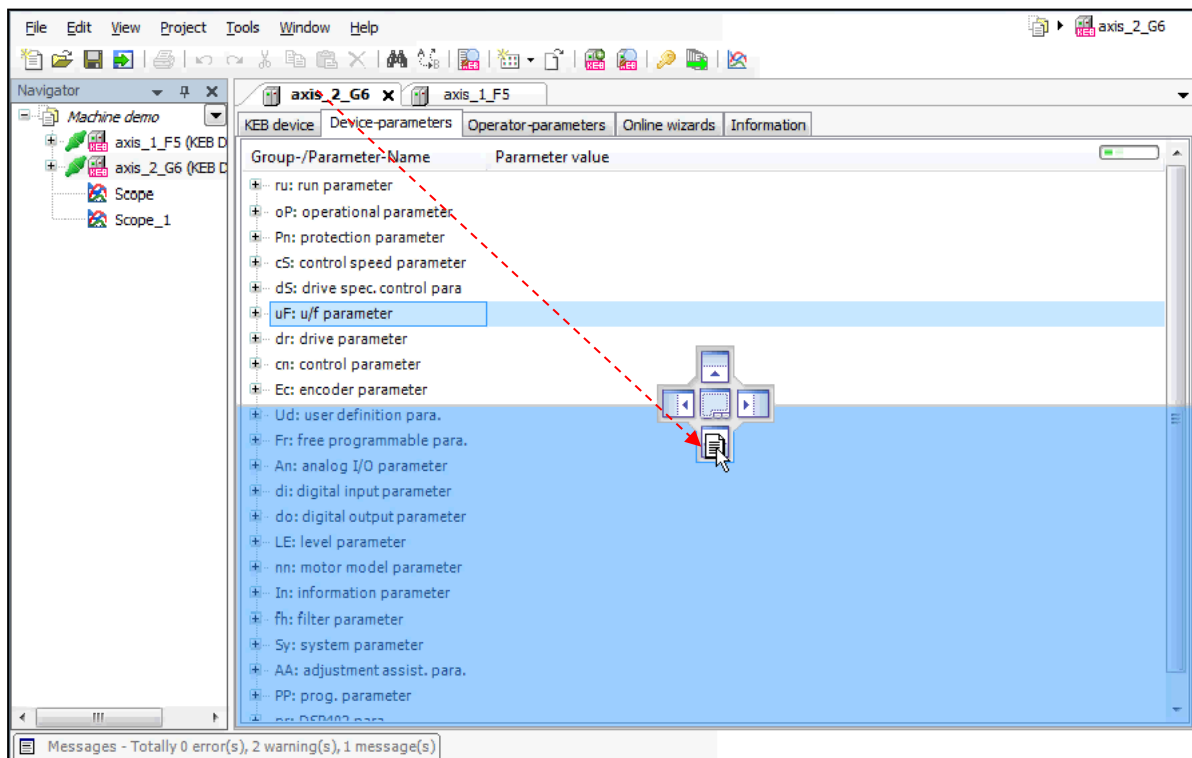
Change window layout manually:

The data tabs (editor-window, scope, parameter list...) can be displayed one below the other or side by side: Activate the data tab group which is to relocate – choose task menu “Window” → “New Horizontal or New Vertical Tab Group”.



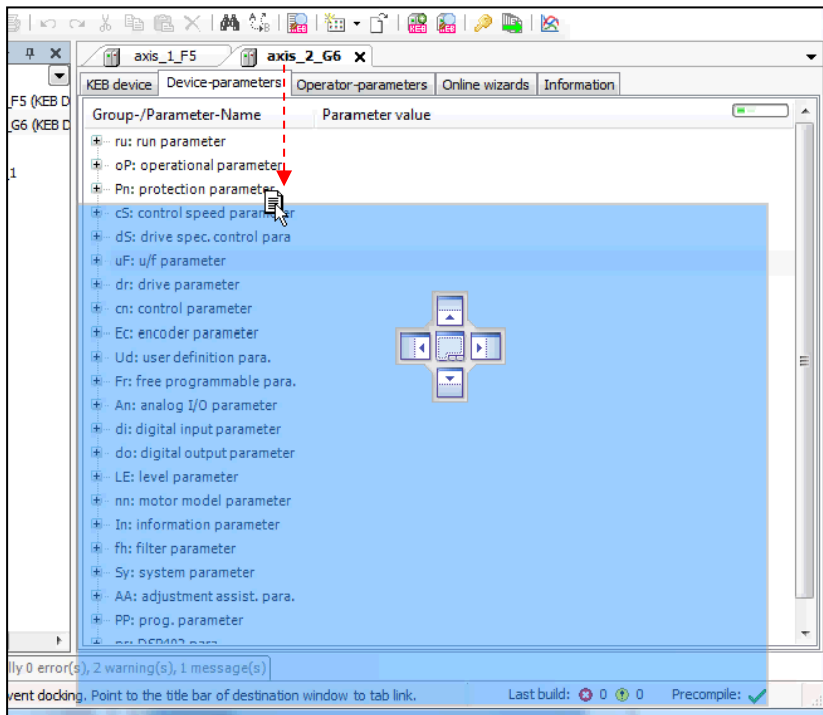
Alternative:

Click on data tab which is to relocate, hold the key and put it to the middle of the screen. A cross for the orientation will appear. If the data tab will be arranged above, below, on the right or on the left side depends on the selection (blue deposited area).

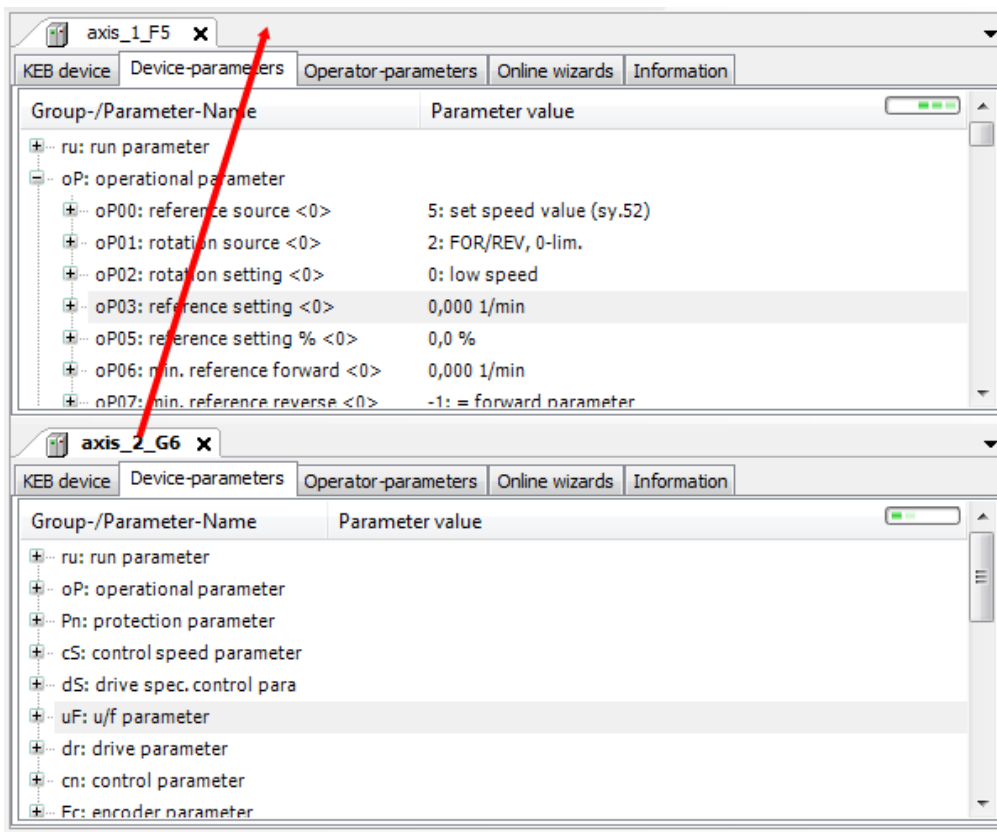


The window can be shifted superimposed to the actual COMBIVIS window. At multiple screens using the window can be pushed to the other screen. The pushed window may be placed anywhere at the screen by mouse pointer. To reset it may be placed on the centre of the orientation cross.

Window Layout



Data tabs which are arranged one below the other or side by side can be rearranged by drag and drop to be placed as flags.



Same behaviour when the flag is pulled to the centre of the orientation cross (see before).


8 Parameter Lists

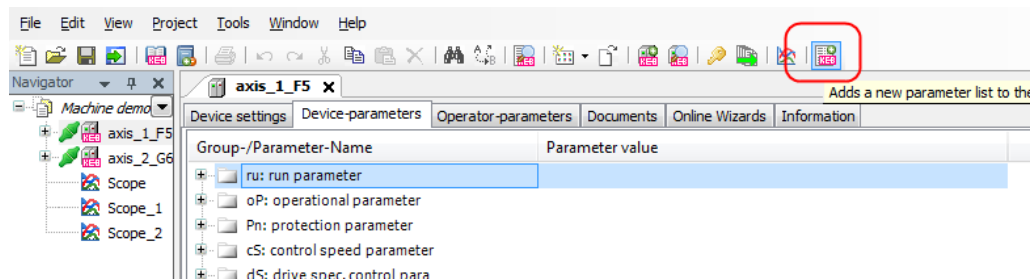
8.1 Properties

- Parameter lists can be attached to projects or devices
- Parameters of different devices can be stored in one list and can be uploaded or downloaded in parallel
- Online and offline data will be indicated in the list at the same time
- Direct or indirect set addressing or addressing according to CiA 301 of the parameters
- “Drag and drop function” for parameters out of the device editor
- Direct shifting/copying of parameters between editor and parameter list
- Parameter lists will be saved with the project
- Export / import of “.dw5” and “.wr5” lists
- Printer functions
- Parameter can get user-defined names
- Parameter lists can be exported individually in CV6 or CV5 format
- Parameter lists can be compared with actual device adjustments or with other parameter lists
- Online and offline values can be compared directly
- Export as recipe directly to the COMBIVERT
- Export as EtherCAT CoE startup command file
- The last upload or download is listed

If only an **existing parameter list may be loaded** to the KEB COMBIVERT, the function “Download parameter list” on the start page can be used ([=> 3.6 Direct Download of a Parameter List](#)).

8.2 Open a Blank List

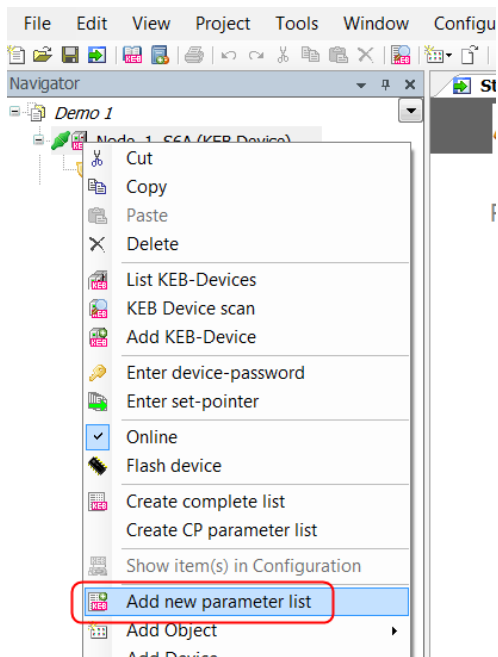
Attach a parameter list to a device or project: Mark device or project → in tool bar click on icon  → give new list a name → “Add”



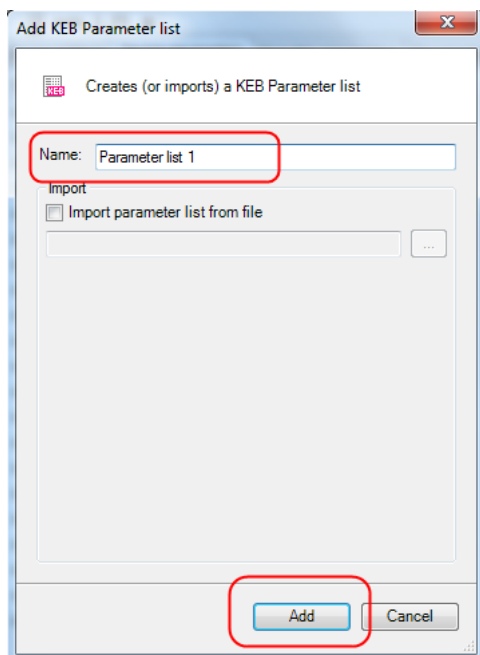
Or:

Mark device in the navigator with right mouse key → “Add parameter list”.

Parameter Lists




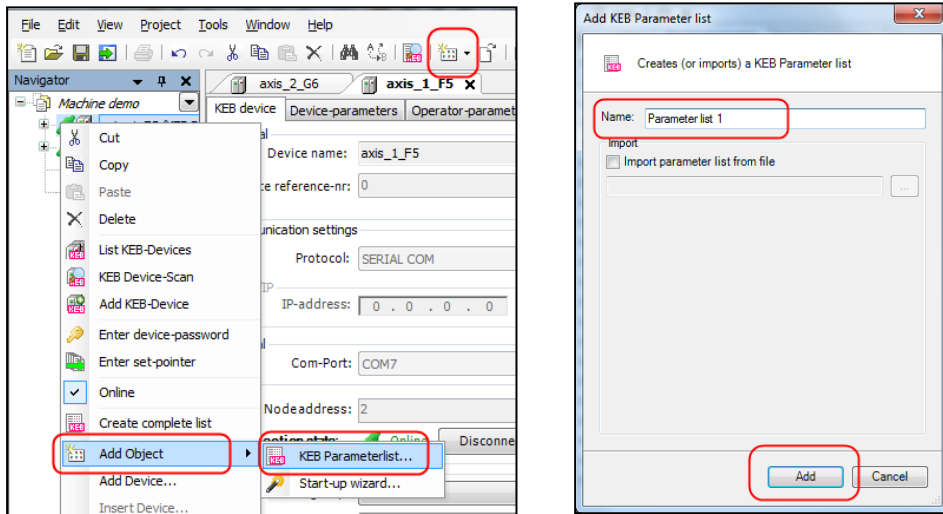
Choose a name for the list and “Add”.



Alternative:

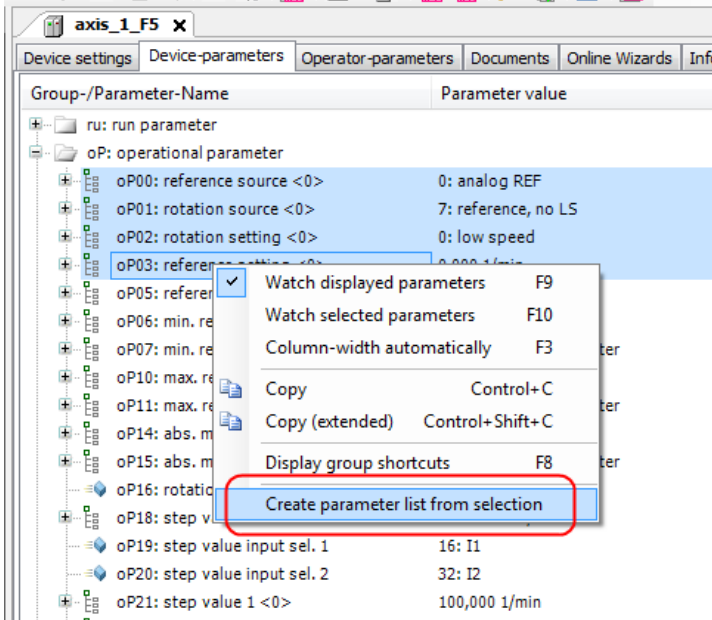
Right-mouse-key → choose “Add Object” → “KEB Parameter list...” → give list a name → “Open”, or:

In tool bar click on icon  → “KEB Parameter list...” → give new list a name → “Add”



8.3 Open List with Marked Parameters

When some parameters are marked, a new parameter list can be opened by context menu: “right mouse key” → “Create parameter list from selection”.
 With key “shift” and “Ctrl” several parameters in different groups can be marked at the same time. But all used groups must be opened before marking the parameters.




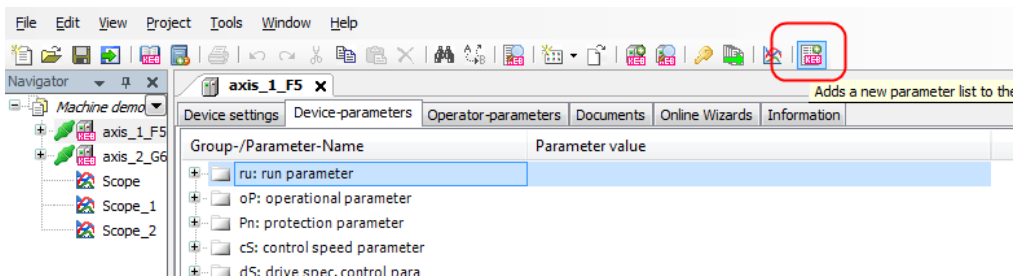
8.4 Open Existing List

Valid file formats:
 cvxpl = CV6-format
 dw5 = CV5 and CV6-parameter list
 wr5 = CV5-work list

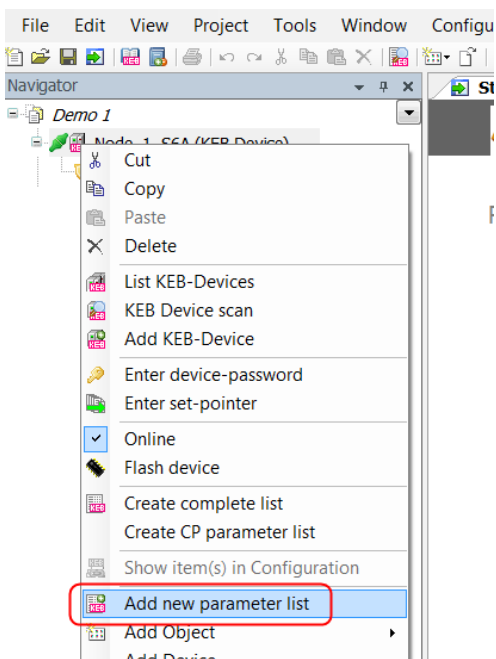
Parameter lists can be opened at an empty project. The matching device will be added automatically in offline mode.

Parameter Lists

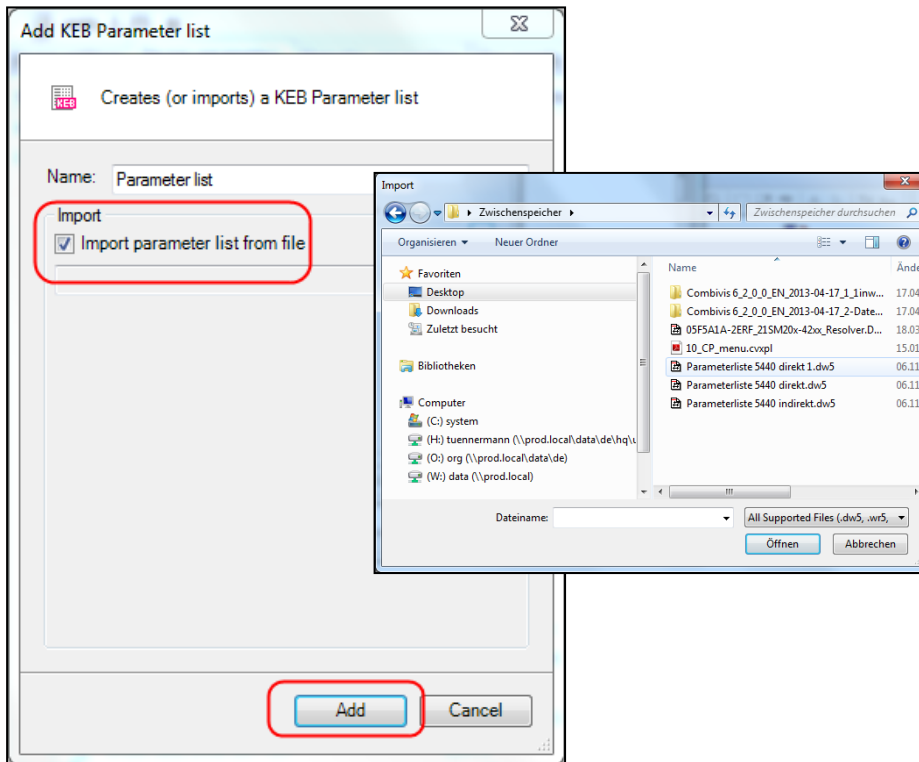
Attach a parameter list to a device or project: mark device or project → in tool bar click on icon  → hook at “Import parameter list from file” → file extension: “.cvxpl”= CV6-format / “.dw5” + “.wr5” = CV5-format → “Open” → “Add”



Or:
Click with right mouse key on device → “Add new parameter list”




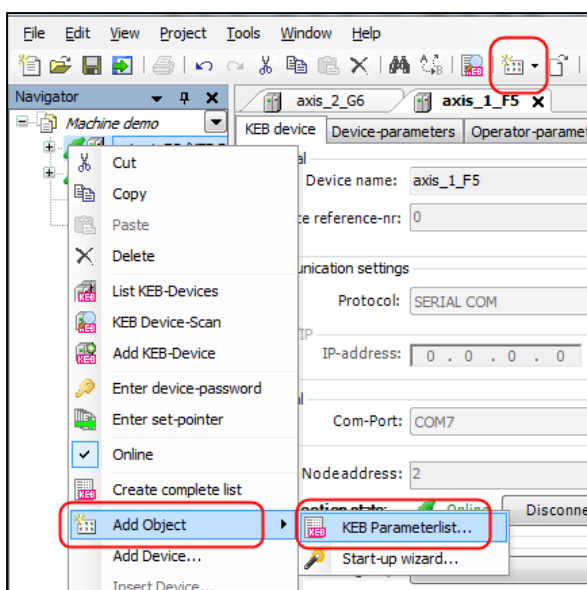
Set the hook in “Import parameter list from file” → find the file → choose the file → “open”.

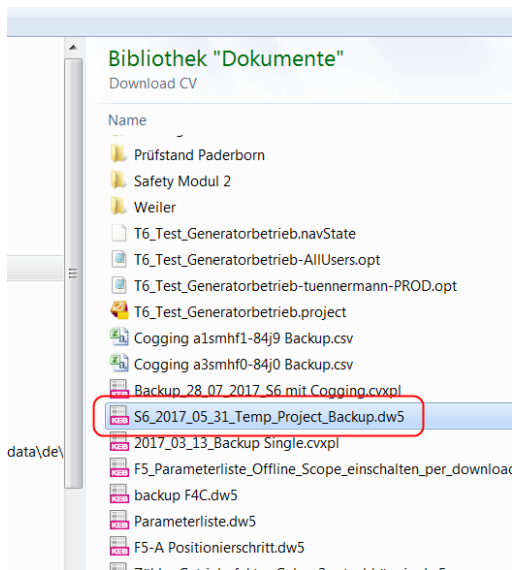


Alternative:

Attach a parameter list to a device or project: Respective device/project
 Right-mouse-key → choose “Add Object” → “KEB Parameter list...” → hook at “Import parameter list from file” → file extension: “.cvxpl”= CV6-format / “.dw5” + “.wr5” = CV5-format → “Add”, or:

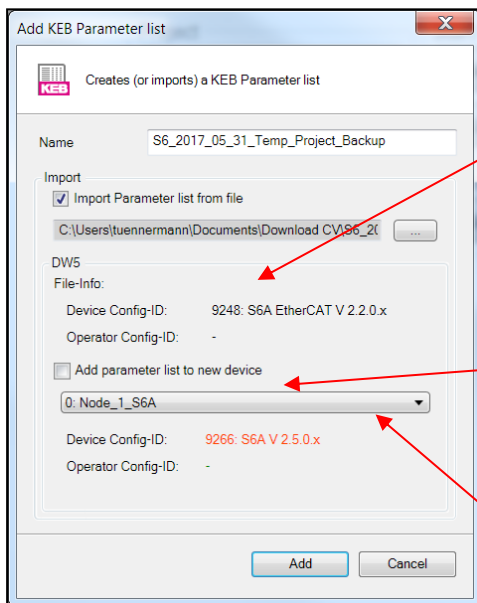
In tool bar click on icon  → “KEB Parameter list...” → hook at “Import parameter list from file” → file extension: “.cvxpl”= CV6-format / “.dw5” + “.wr5” = CV5-format → “Add”





Next step:

The parameter list is appended to the device at which the dialog was opened. But it can also be chosen whether it is hung on another device in the project or on a virtual device, which has the same type as the one with which the list was created earlier.



Type and Firmware version of origin device / parameter list

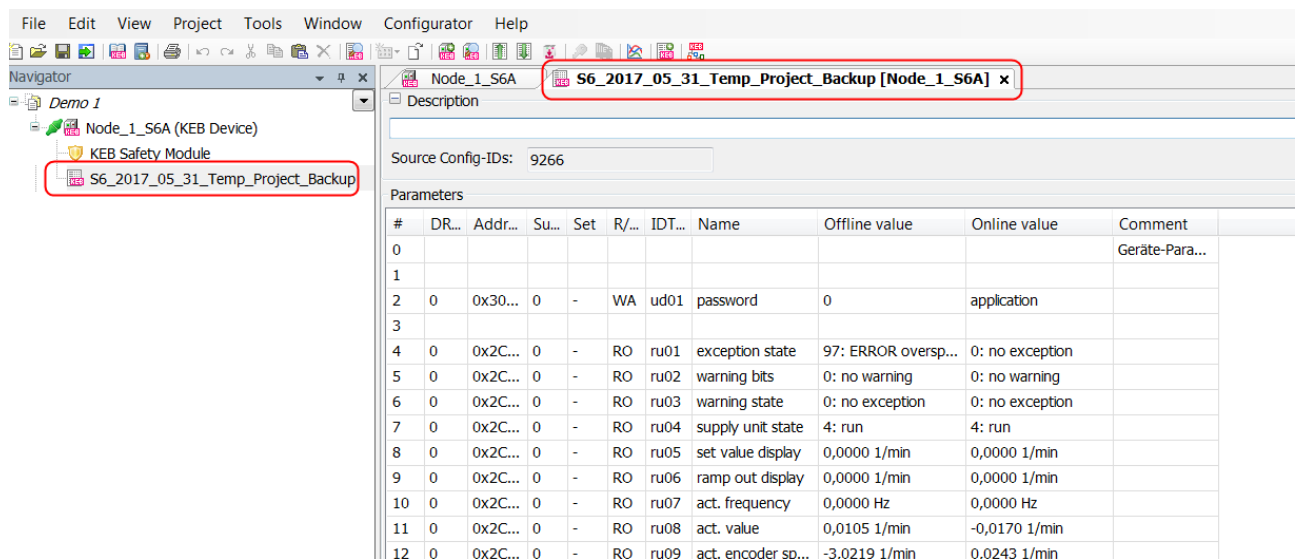
Add new device: a new device with matching type and will be add to the project (Offline)

Assign to existing device: parameter list will be added to a device of the project. No check of compatibility!

Choose one device of the project. The Firmware ID (Config-ID) is compared between list and device: orange=different

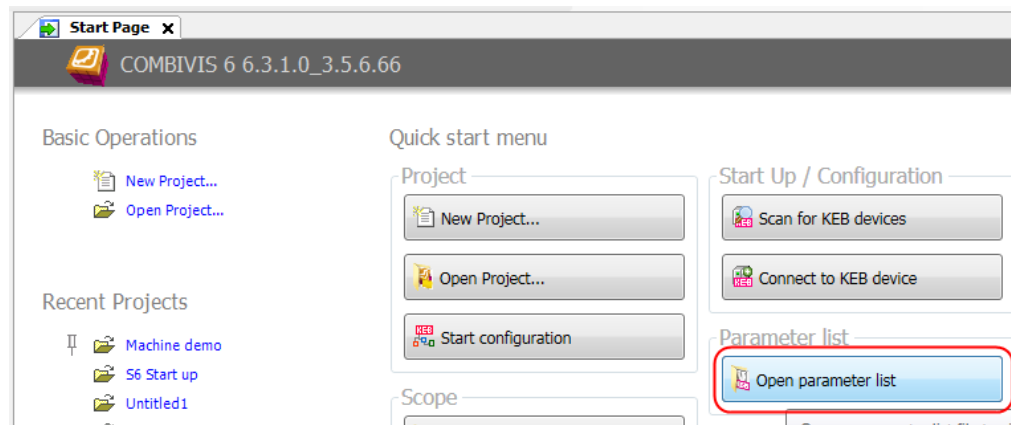
If there are parameters of several devices in the list (only at .cvxpl lists), it can be chosen which device of the list will match which device in the project.

The new added parameter list will be opened directly in the editor



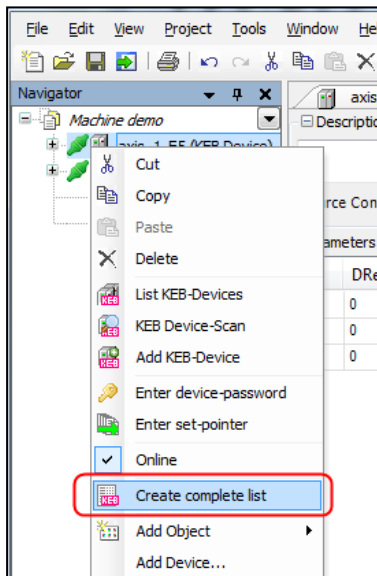
Open parameter list without open project:

A stored parameter list can be opened directly from Windows Explorer by double click or with button “Open parameter list” on COMBIVIS Start Page. A temporary project will be created in background.



8.5 Create Complete List

Open choice box by click with right mouse key on the respective device → Choose “Create complete list” → A parameter list with all device parameters will be created.



Please note:
 This complete list is filled in column “offline” with COMBIVIS–default values and does not include yet the actual values of the device. For data storage it is essential to take an upload from the device before saving!

8.6 Layout of Parameter List

Fading out description

Area for notes

Origin Config-ID of the parameters

Time stamp of modification, Upload or Download

Basis Config-ID of devices in this parameter list

#	DR...	Addr...	Su...	Set	R/...	IDT...	Name	Offline value	Online value	Comment
0							Geräte-Para...			
1										
2	0	0x30...	0	-	WA	ud01	password	0	application	
3										
4	0	0x2C...	0	-	RO	ru01	exception state	0: no exception	0: no exception	
5	0	0x2C...	0	-	RO	ru02	warning bits	0: no warning	0: no warning	

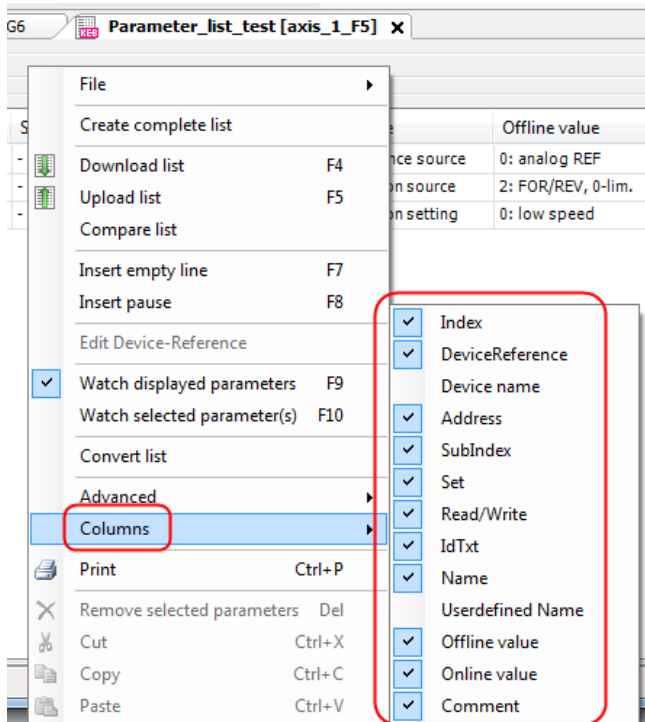
#	DRef	Device	Address/Index	SubIndex	Set	R/W	IdTxt	Name	Userdefined Name	Offline value	Online value	Comment
0	0	axis_1_F5	0x0300	-	0	RW	oP00	reference source	reference source	0: analog REF	0: analog REF	
1	0	axis_1_F5	0x0301	-	0	RW	oP01	rotation source	rotation source	2: FOR/REV, 0-lim.	2: FOR/REV, 0-lim.	
2	0	axis_1_F5	0x0302	-	0	RW	oP02	rotation setting	rotation setting	0: low speed	0: low speed	

*= not shown in default adjustment, => [6.7 Parameterization – Parameter Lists](#)

In the subindex and set column is only one value shown, depending on the valid addressing mode for this parameter.

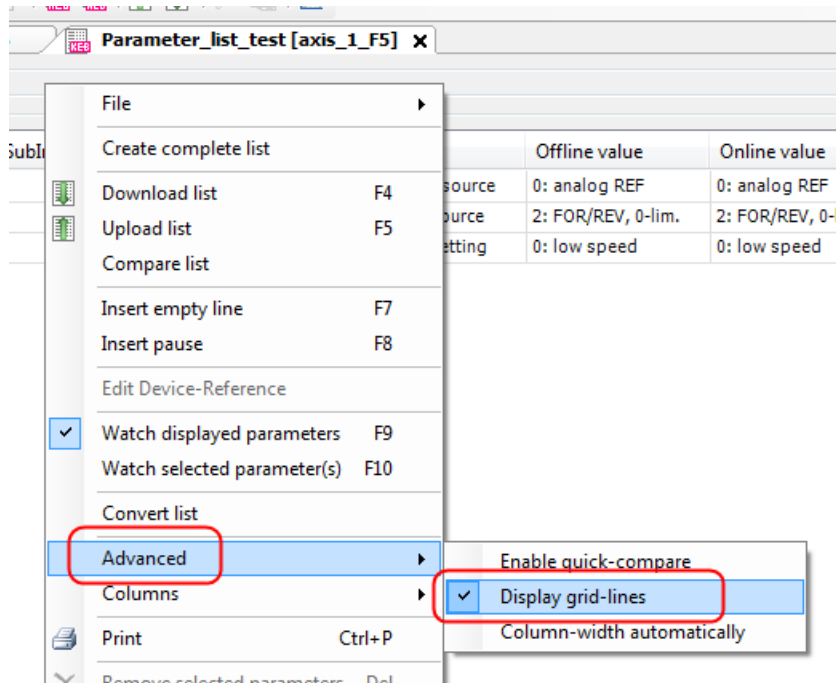
Display of columns in the parameter list:

The columns which may be shown can be chosen by pulling up and close with mouse or: “right mouse key” → “columns” → “set hook”



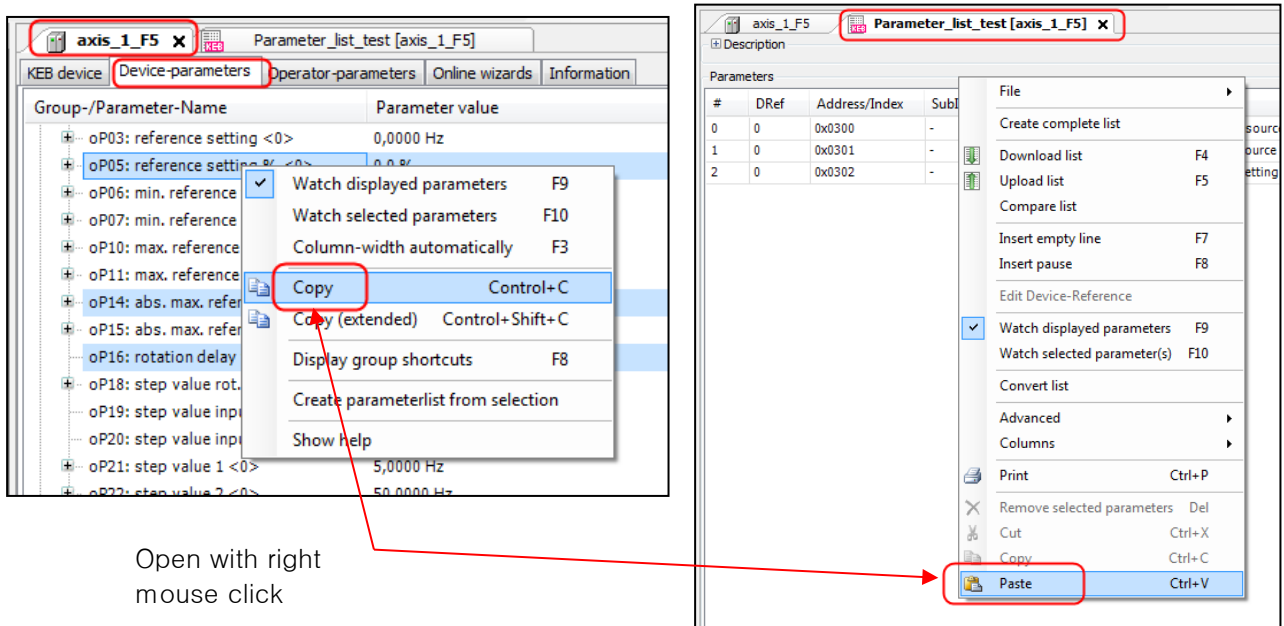
Display grid lines:

The grid lines can be activated by: “right mouse key” → “Advanced” → “Display grid lines”



8.7 Self-Created Parameter List

Open blank list (=> [8.2 Open Blank List](#)) → mark and copy the parameter in the device editor → insert into the parameter list.



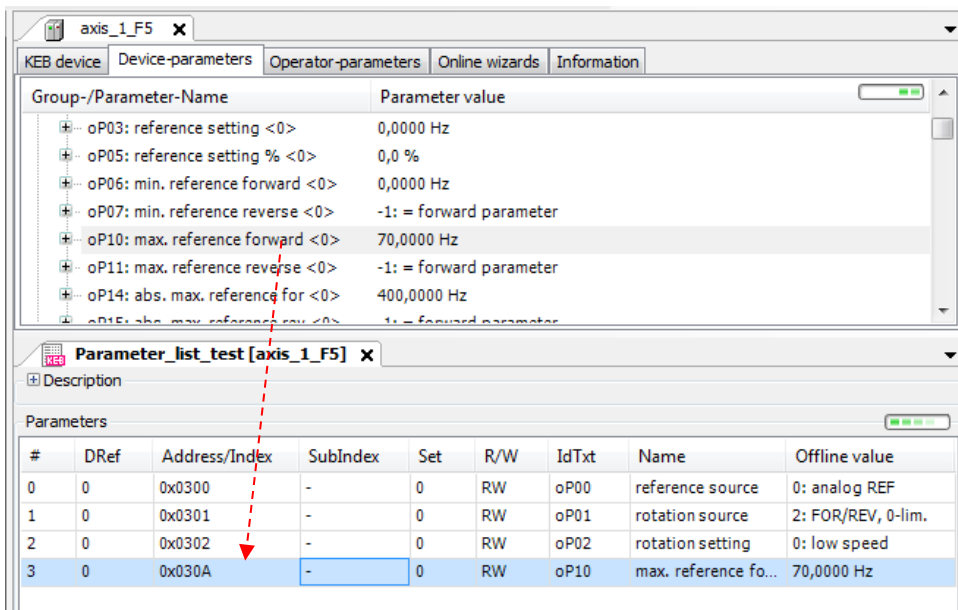
Open with right mouse click

“Copy” command: the selected parameters are copied.

“Copy (extended)” command: the selected parameters plus the underlying subindices or set programmable parameters are copied.

Alternatively:

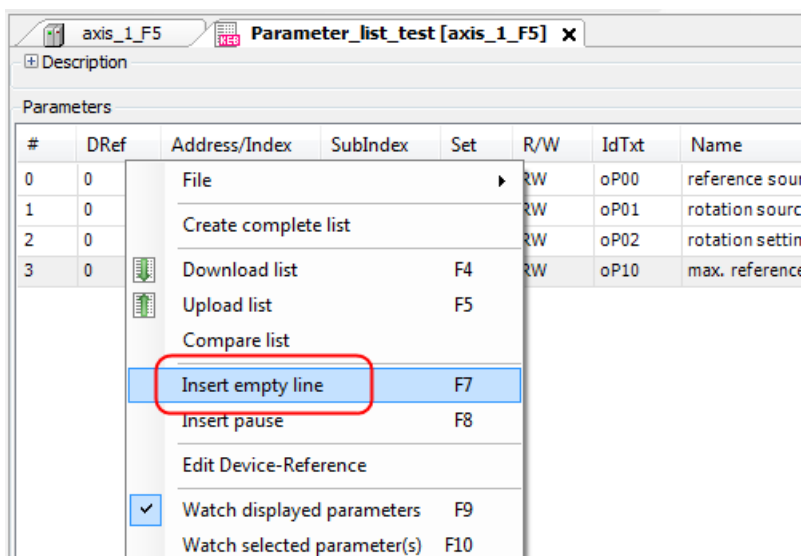
Open list → place device editor and parameter list window beside each other (=> [7 Window layout](#)) → mark the parameter in the device editor with left mouse key → hold the key → pull the parameter into the parameter list (Drag&Drop).



The parameter value is kept by copying the parameter.

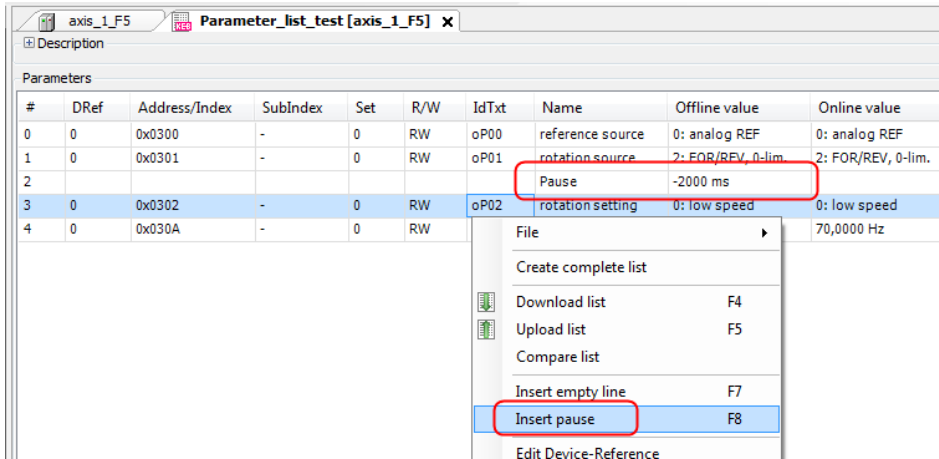
8.8 Insert an Empty Line

To insert an empty line “right mouse key” → “Insert empty line”



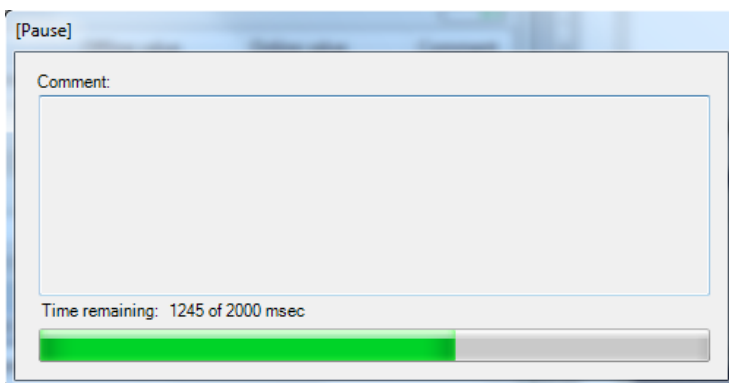
Empty lines have no influence. They are used only for structuring.

8.9 Insert a Transfer Pause



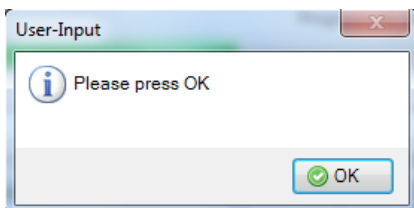
Transfer pause without confirmation:

Offline value: -2000 ms: 2sec pause, the remark text will be shown, after that the download goes on automatically.



Transfer pause with confirmation:

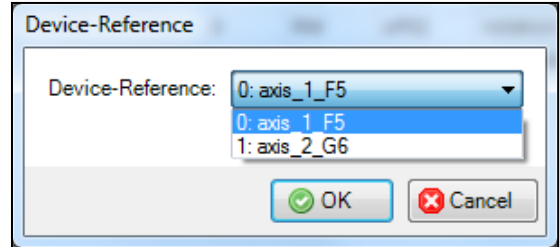
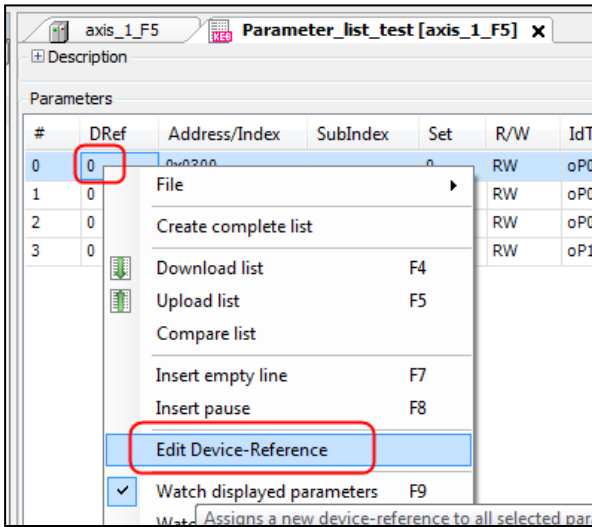
Set offline value: (+) xx ms: unlimited pause and display of remark text. Download goes on after click on "OK".



8.10 Changing of Device Reference

The device reference of a parameter can be affected by double-click on the device reference number.

The change of one or more device references can be affected by marking of the corresponding lines in the column "DRef" → "right mouse key" → "Edit Device-Reference" → choose new device reference → "OK".



8.11 Upload from Drive Controller into Parameter List


Definition: with "Upload" is meant the reading of data from the KEB device into COMBIVIS.



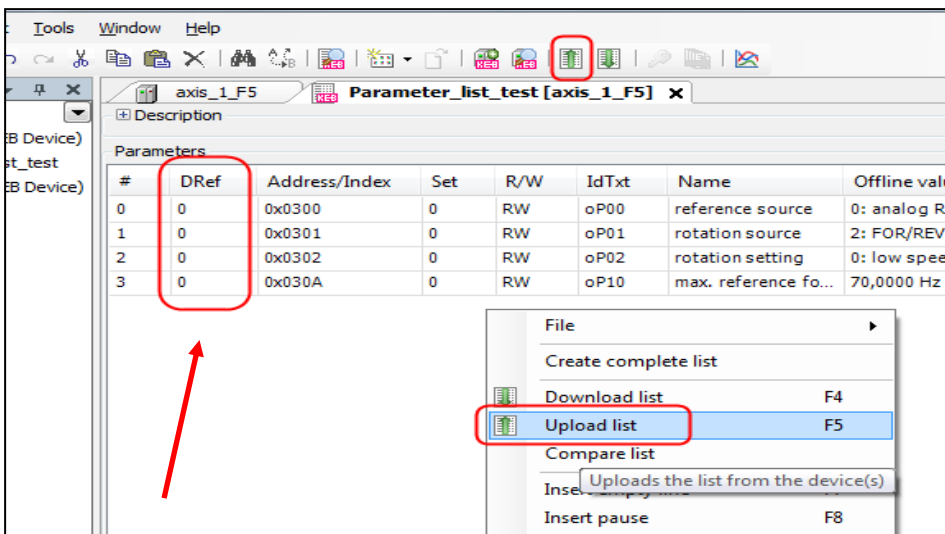
WARNING

Open the control release or the STO inputs before upload, because at upload some pointer can be changed. Especially when values are written by bus system at the same time an unexpected moving of the drive can occur.

Carrying out the upload into an opened parameter list:

- Click on icon  in the tool bar, or:
- Click right mouse key in the parameter window, choose "Upload list", or:
- Tap key "F5" and answer the following questions with "Yes".

The column "Offline value" will become overwritten with the values (online values) which are adjusted in the device.



Be sure that the device reference in the list matches the target device's reference!

Otherwise adapt the reference of the list (=> [8.10 Changing of Device Reference](#)).

8.12 Parameter Download

Definition: with "Download" is meant the transfer of data from COMBIVIS to the KEB device.




WARNING

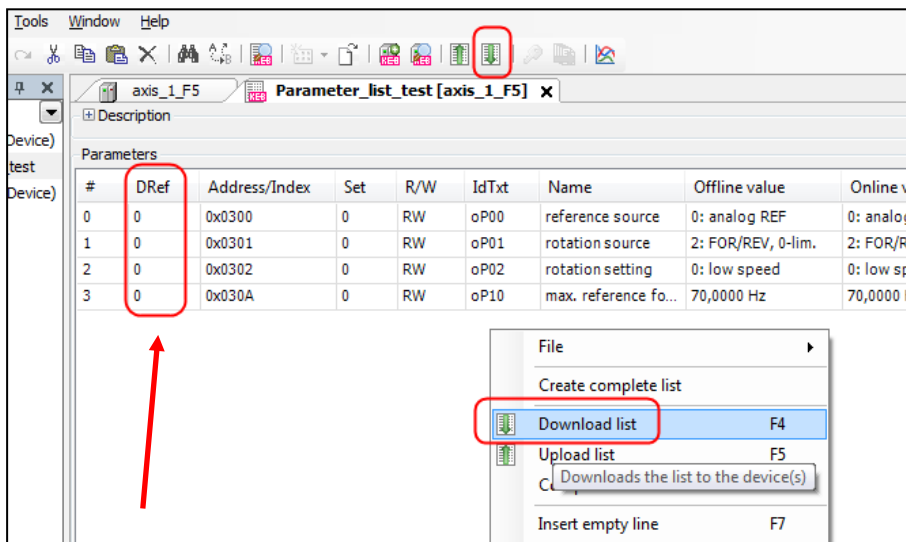
Open the terminal control release or the STO inputs before download of parameter list into the device because some parameters can be written only at open control release terminal. And an unexpected moving of the drive can occur.

If only one existing parameter list is to be loaded into a KEB COMBIVERT, the function "Download of a parameter list" can be used on the start page (=> [3.6 Direct Download of a parameter list](#)).

Carrying out the download of an opened parameter list:

- Click on icon  in the tool bar, or:
- Click right mouse key in the parameter window, choose "Download List", or:
- Tap key "F4" and answer the following questions with "Yes".

The values, which are adjusted in the device, will become overwritten with the values of the column "Offline Values". Only the writeable parameters which are in the list will get overwritten. All the rest will remain unaffected.

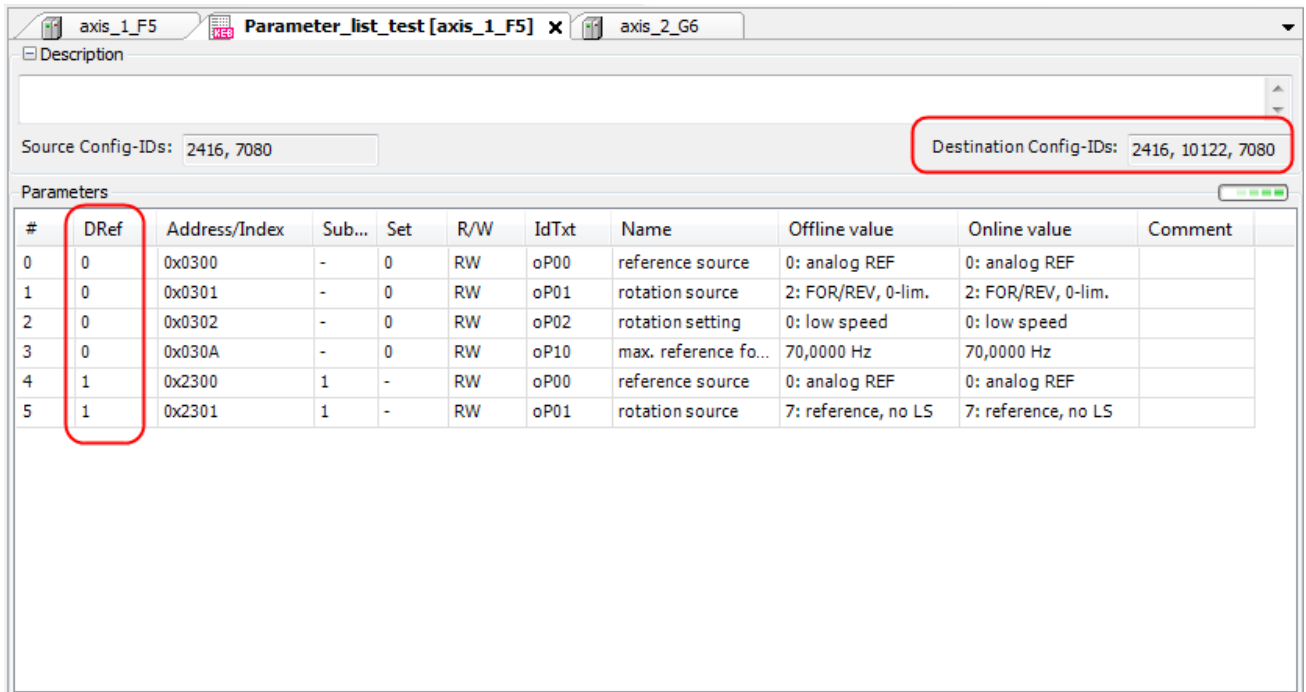


Be sure that the device reference in the list matches the target device's reference!

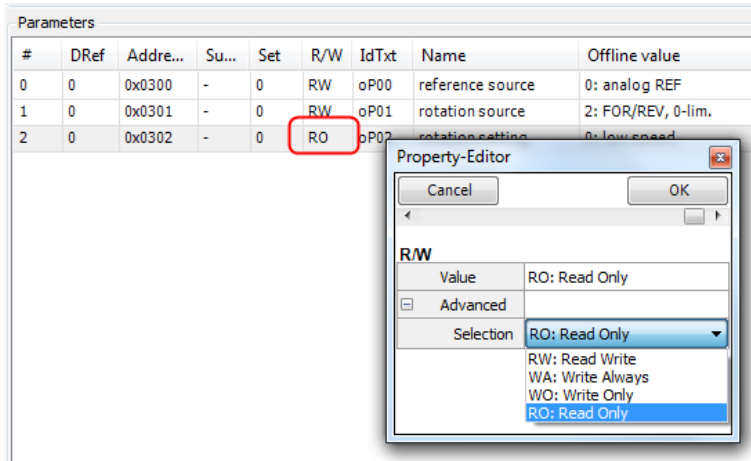
Otherwise adapt the reference of the list (=> [8.10 Changing of Device Reference](#)).

Parameter-Download from a parameter list to several devices:

Parallel up-/download from/to several devices (here: DRef 0 and 1) from a list is possible. Each parameter is dedicated to one device. Therefore the suitable target-CFG-IDs must be registered. Missing CFG-IDs will be added at up/download optionally.

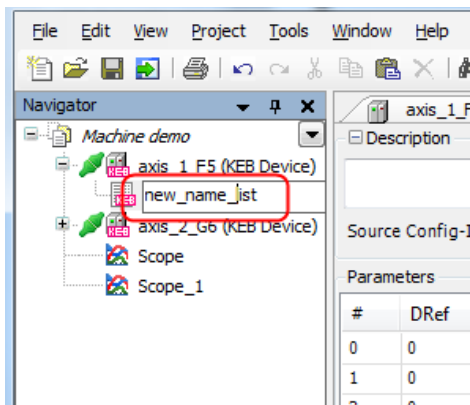


Parameters can be excluded from downloading if they are set in the R/W column to "Read only".



8.13 Renaming Parameter List

Double-click slowly in the navigator on parameter list's name and rename.



8.14 Comparing Parameter Lists Directly

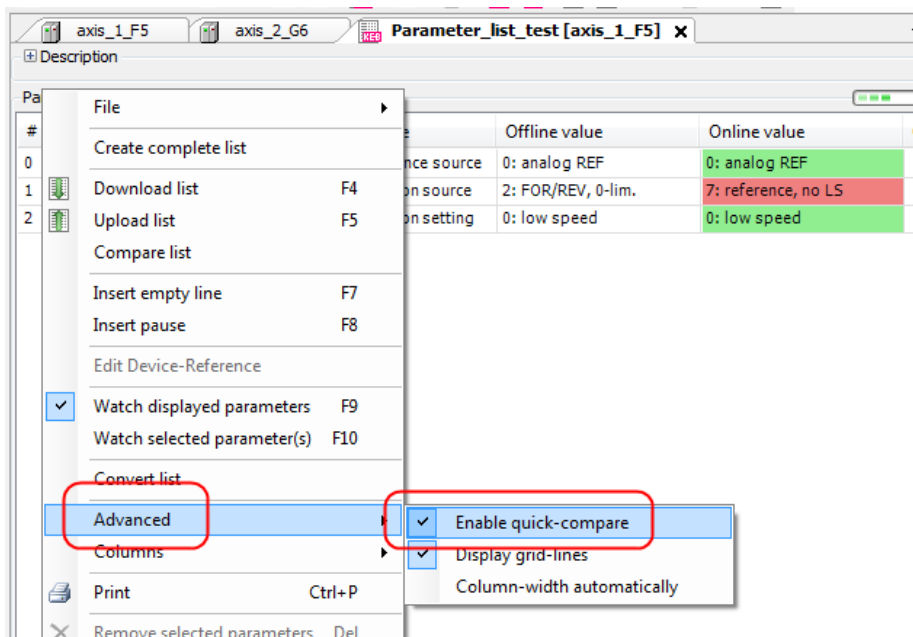
On- and offline values can be compared in a parameter list directly by context menu: Right mouse key → “Advanced” → “Enable quick-compare”

In column “Online value”:

Green: On-/ offline values equal

Red: On-/ offline values unequal

Yellow: Parameter not existing



Please note:

If the parameter list is designed with indirect set pointer, all parameters in all sets will be compared only with 1 set (the set to which the set pointer Fr09 is adjusted). For an expedient comparing use direct set or CiA 301 addressing for the parameter list. (=> [8.17 Parameter backup](#))

Some parameter values depend on pointer positions (e.g., Ud16, Ud22, In24 ...). Online (in the device) these parameters are shown only once. In a complete data saving list these parameters are shown each by each with the related pointer. So, the different list parameters are compared every time with the same device parameter!

Example: Ud15 (CP-selector) is the pointer for Ud16 (CP-Address). In Ud15 one of 36 possible parameters and in Ud16 the related (application-) parameter address can be chosen. In a data saving list all 36 Ud15 and Ud16 must be listed, but online, in the device, Ud15 shows every time the same value. That gives at comparing once an equal and 35 times an unequal value.

#	DRef	Addr...	Set	R/W	IdTxt	Name	Offline value	Online value	Comm
549									
550	0	0x0802	I	RW	Ud02	control type	4: F5-M / 4000 rpm	4: F5-M / 4000 rpm	
551	0	0x0809	I	RW	Ud09	drive mode control	0: dr. mode ref.val.(sy.4...	0: dr. mode ... LS => RUN	
552	0	0x080F	I	WA	Ud15	cp selector	1	1	
553	0	0x0810	I	RW	Ud16	cp address	0209h	0209h	
554	0	0x0811	I	RW	Ud17	cp set norm	1: S0 + direct (bit 0-7)...	1: S0 + dire... + standard	
555	0	0x080F	I	WA	Ud15	cp selector	2	1	
556	0	0x0810	I	RW	Ud16	cp address	0201h	0209h	
557	0	0x0811	I	RW	Ud17	cp set norm	1: S0 + direct (bit 0-7)...	1: S0 + dire... + standard	
558	0	0x080F	I	WA	Ud15	cp selector	3	1	
559	0	0x0810	I	RW	Ud16	cp address	0200h	0209h	
560	0	0x0811	I	RW	Ud17	cp set norm	1: S0 + direct (bit 0-7)...	1: S0 + dire... + standard	
561	0	0x080F	I	WA	Ud15	cp selector	4	1	
562	0	0x0810	I	RW	Ud16	cp address	020Fh	0209h	
563	0	0x0811	I	RW	Ud17	cp set norm	1: S0 + direct (bit 0-7)...	1: S0 + dire... + standard	
564	0	0x080F	I	WA	Ud15	cp selector	5	1	
565	0	0x0810	I	RW	Ud16	cp address	0210h	0209h	

8.15 Comparing Parameter Lists

A parameter list can be compared with an actual device adjustment or with the offline values of another parameter list.

Also, two different comparing modes are available:

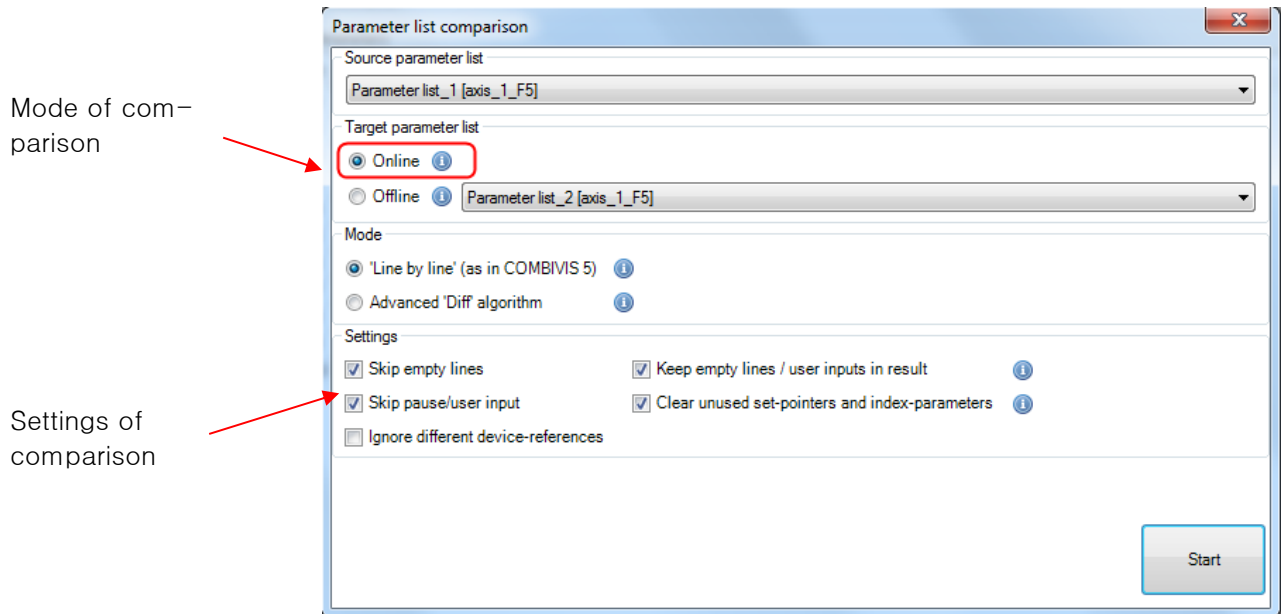
- Line by line comparing mode
- Advanced mode, especially for offline-offline comparison, which can detect blocks of belonging parameters. By this missing or too much parameter can be identified and marked.

Find by context menu - right mouse key → “Compare list”

The screenshot shows the KEB software interface with a parameter list table. A context menu is open over the table, and the 'Compare list' option is highlighted with a red circle. The table contains the same data as the previous image, with columns for #, DRef, Addr..., Set, R/W, IdTxt, Name, Offline value, and Online value.

8.15.1 Online Comparison

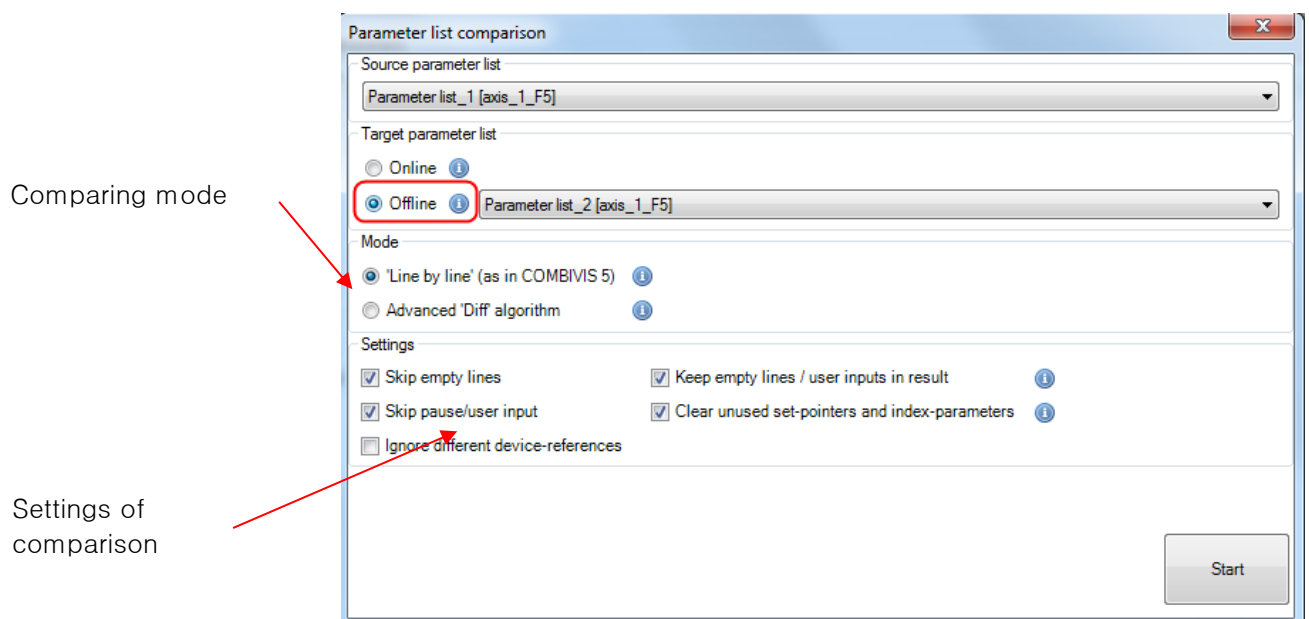
Comparing of a parameter list's offline values with actual online values in a device generates a new parameter list with the different values of the device. The values of the parameter list are shown also in the offline column in the new difference list.



It is possible to compare one list with parameters of several devices in parallel.

8.15.2 Offline Comparison

Comparing of a parameter list's offline values with another offline parameter list creates a new list with the unequal values of the 2nd list.



Comparison method

There are two different comparison methods:

Line-by-line comparison mode:

Only the values in the same lines will be compared, independent which parameter is in this line! Displacements in the list, e.g., by additional parameters will cause in a wrong result!
 This method works if both lists come from equal device e.g., backup before and after a changing

Advanced "Diff" algorithm:

This mode identifies groups of parameters which are in the same line on both lists. By this, missing parameters or too much parameter can be identified.

Please check the result. It is not guaranteed that all differences are found!

If the list is most in different direction a satisfying result is impossible.

Example:

Two parameter lists with parameters which are not included at the other list. Also, at different adjustments at parameters which are in both lists.

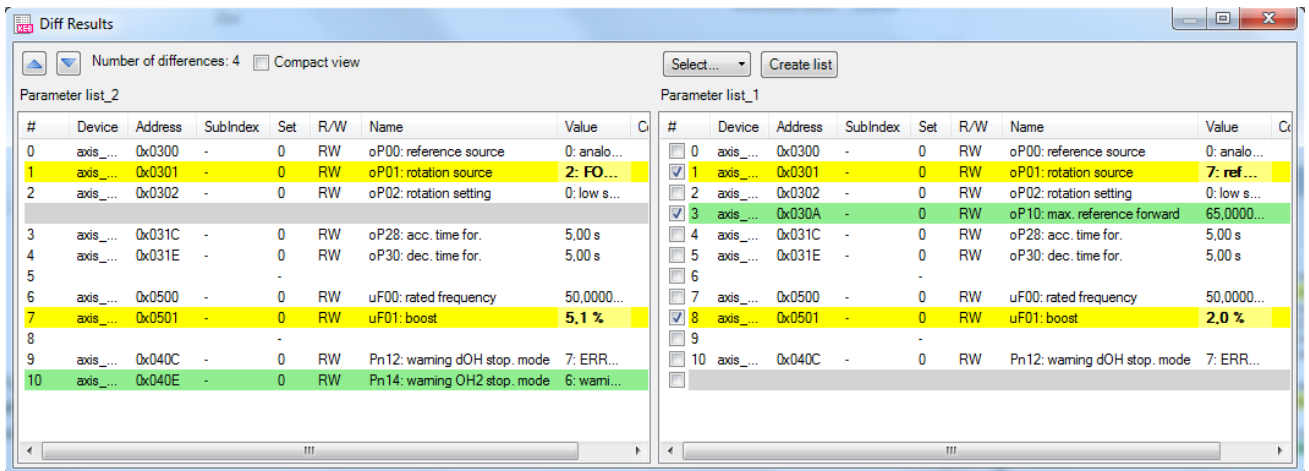
#	DRef	Adresse...	Set	R/W	IdTxt	Name	Offline value
0	0	0x0300	0	RW	oP00	reference source	0: analog REF
1	0	0x0301	0	RW	oP01	rotation source	2: FOR/REV, 0-lim.
2	0	0x0302	0	RW	oP02	rotation setting	0: low speed
3	0	0x031C	0	RW	oP28	acc. time for.	5,00 s
4	0	0x031E	0	RW	oP30	dec. time for.	5,00 s
5							
6	0	0x0500	0	RW	uF00	rated frequency	50,0000 Hz
7	0	0x0501	0	RW	uF01	boost	5,1 %
8							
9	0	0x040C	0	RW	Pn12	warning dOH stop...	7: ERROR disabled
10	0	0x040E	0	RW	Pn14	warning OH2 stop...	6: warning by dig. output

#	DRef	Adresse...	Set	R/W	IdTxt	Name	Offline value
0	0	0x0300	0	RW	oP00	reference source	0: analog REF
1	0	0x0301	0	RW	oP01	rotation source	7: reference, no LS
2	0	0x0302	0	RW	oP02	rotation setting	0: low speed
3	0	0x030A	0	RW	oP10	max. reference forw...	65,0000 Hz
4	0	0x031C	0	RW	oP28	acc. time for.	5,00 s
5	0	0x031E	0	RW	oP30	dec. time for.	5,00 s
6							
7	0	0x0500	0	RW	uF00	rated frequency	50,0000 Hz
8	0	0x0501	0	RW	uF01	boost	2,0 %
9							
10	0	0x040C	0	RW	Pn12	warning dOH stop...	7: ERROR disabled

Result:

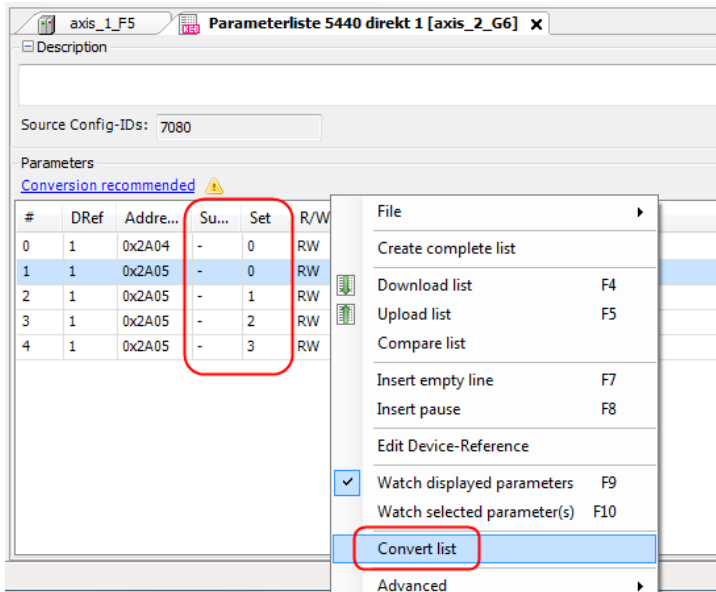
Yellow: parameters with different adjustments.

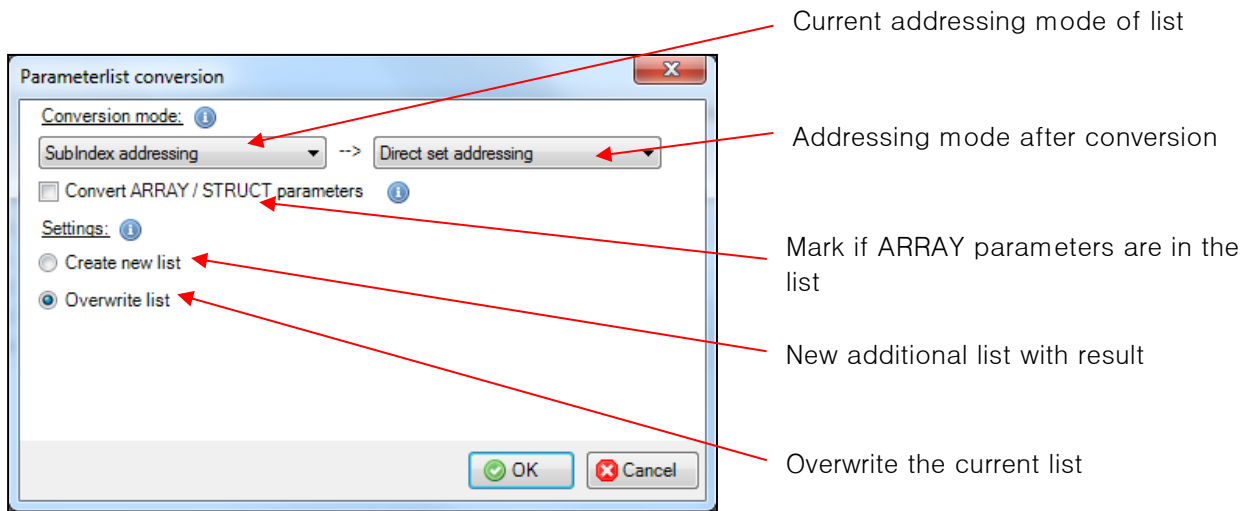
Green/grey: Parameters missing in one of both lists.



8.16 Convert Addressing of Parameter Lists

With this command the addressing mode of a parameter list can be changed. E.g., a set addressed list into a list with subindex addressing/CIA 301 and vice versa. Also, an indirect addressed list can be changed to direct addressing.



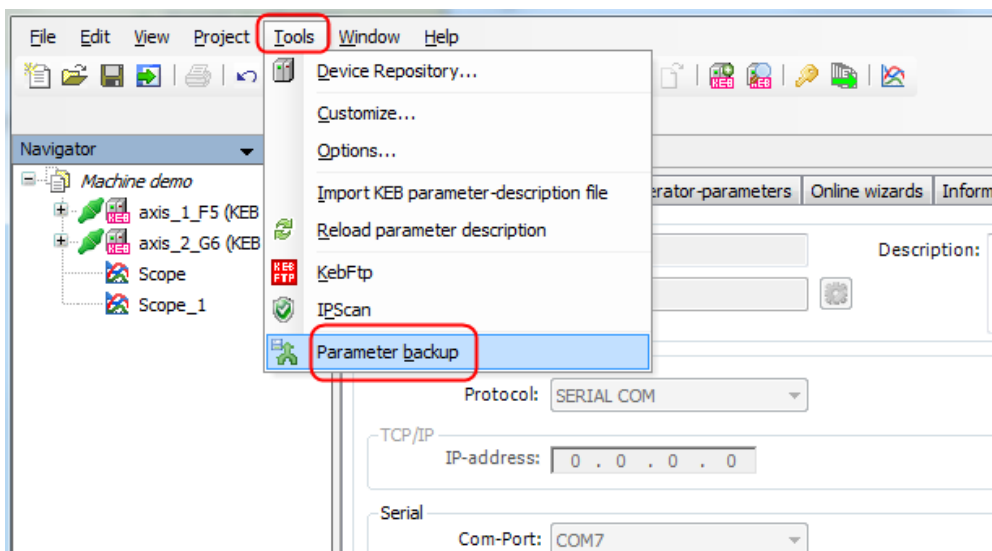


8.17 Parameter Backup

A parameter backup is useful after the completion of the machine function or before a planned change of the setting. If necessary, the functionality of the axis has then been saved for a later device replacement.

The parameter backup generates a parameter list in the project. This can be exported. In the wizard for the F6 / H6 / S6 / T6 / P6 there is also the backup function. This generates a backup file, which can be converted to a parameter list in the project (=> [10.1.1.1. Basic Settings](#)).

For all KEB COMBIVERT:
Open → “Tools” → “Parameter Saving”



All parameters of all devices can be saved in one list!

Choose devices you want to save from

Choose if device- and/or operator parameters are to save

Parameter backup

Please select the devices whose parameters shall be stored

Device	Device parameters	Operator parameters	Parameters together	Sets together	Indirect
<input checked="" type="checkbox"/> [0] Node_1_F6P	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
<input checked="" type="checkbox"/> [1] Node_1_S6A	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>

Select only online devices.

Create single merged list Create separate lists

Create dw5 files instead of parameter list objects in the project

Start

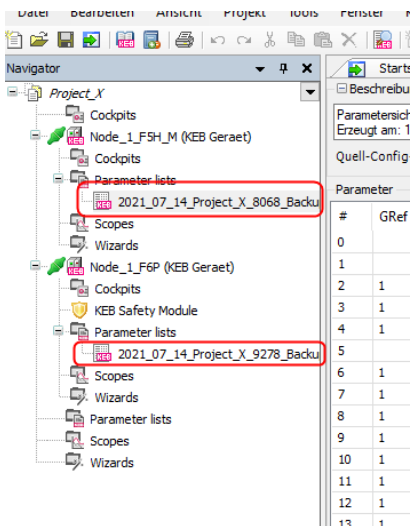
Choose how to address the parameters. For explanation see below =>

[Chapter 8.17.1 Sort mode](#)

Indirect set addressing possible only at F5, B6 und parts of G6

"Create a single merged list": All parameters of the selected units are saved in one list. This is positioned in the Navigator at the project. The distinction is made by the unit reference.

"Create separate lists": A separate list is created for each selected device. This is positioned in the navigator at the respective device.



"Create DW5 files instead of parameter list objects in the project": The separate lists are saved outside COMBIVIS as parameter lists in ".dw5" format.

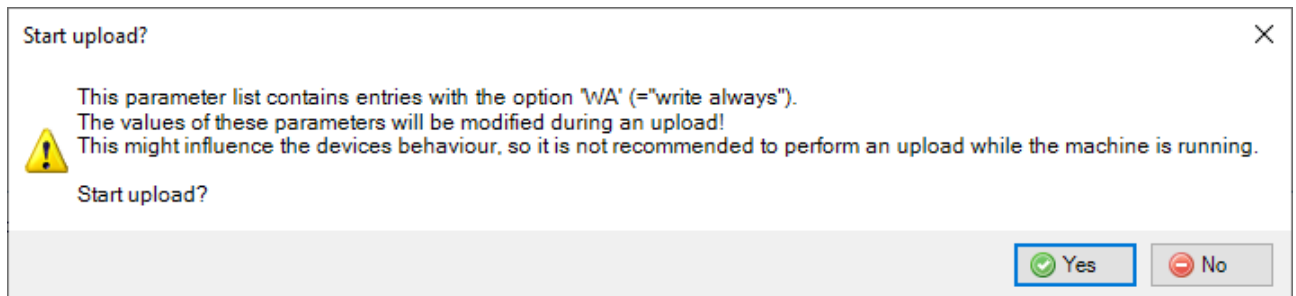
"Start" → Upload starts.

An interruption is possible with "Abort".

After upload is finished a window for adjustment of storage location will open.

This list can be integrated in the project, or it can be stored externally.

After the start a message can be shown:



Explanation: If "WA" parameters are included in the list, the upload should not be started if data is being written to the COMBIVERT at the same time by a bus system or other parallel communication. During the upload, pointers to memory cells must be adjusted. If information is written via this pointer at the same time, it may end up in a wrong cell. This could be, for example, a wrong target position. After the backup is finished, all pointers are back in their original position.

The lists can be exported from the navigator. => [Chap. 8.20 Export parameter list.](#)

8.17.1 Sort Mode

Depending on the type of the COMBIVERT not all addressing modes are available.

Parameter list design with indirect set addressing:

Design of the list:

- Set pointer Fr09 = 0
- All set programmable parameters of set 0 and all not set programmable parameters
- Set pointer Fr09 = 1
- All set programmable parameters of set 1
-
- Set pointer Fr09 = 7
- All set programmable parameters of set 7
- Operator parameters

If the drive controller works in contouring mode (synchronous bus mode) the indirect set addressing must be used!

Parameter list design with direct set addressing, joined parameters:

Without set pointer, each parameter belongs direct to one set or several sets

Design of the list:

- Parameter X of set 0
- Parameter X of set 1
- Parameter X of set 2
- Parameter X of set 3
-
- Parameter X of set 7
- Parameter Y of set 0
- Parameter Y of set 1
- Parameter Y of set 2
- Parameter Y of set 3
-
- Parameter Y of set 7
-
- Operator parameters

All not set programmable parameters are written in set 0

At subindex / CiA 301 addressing “joined parameters” is used always!

Parameter list design with direct set addressing, joined sets:

Without set pointer, each parameter belongs direct to one set or several sets.

Design of the list:

- All set programmable parameters of set 0 and all not set programmable parameters
- All set programmable parameters of set 1
-
- All set programmable parameters of set 7
- Operator parameters

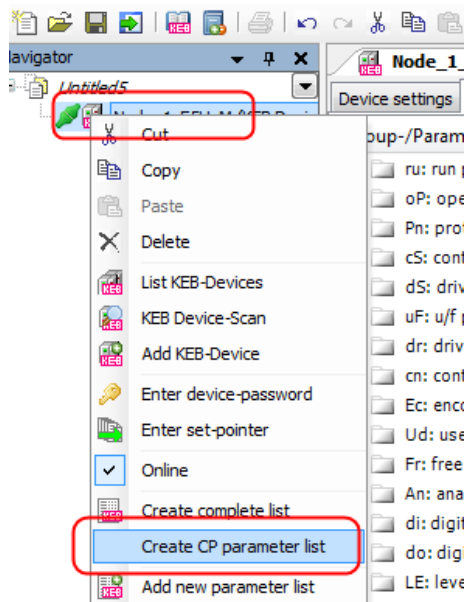
8.18 CP Parameter

CP-parameters are parameters displayed in the device display at COMBIVERT F5, B6, and G6 in a separate menu. The CP-parameters show selectable application parameters.

In COMBIVIS 6 there is no actual CP parameter menu. This means that no operation is possible like on the display of the device.

A list can be created which shows the assignment of CP parameter and application parameter.

→ Click with right mouse key on the device in the navigator → “Create CP parameter list”.



#	IdTxt	Name	Online value	Comment
0	Ud01	password	CP read / write	
1	ru07	actual value display	0.000 1/min	
2	ru01	set value display	1751.075 1/min	
3	ru00	inverter state	0: no operation	
4	ru15	apparent current	0.0 A	
5	ru16	peak apparent current	0.0 A	
6	ru12	actual torque display	0.00 Nm	
7	ru18	actual DC voltage	315 V	

In the column “#” the number of the CP parameter is shown. The parameter is the assigned application parameter.

For example, in the picture above: CP03 shows “ru00 inverter state”

Please note:

- The assignment of the CP parameter is read out while creating the list. A subsequent change in the device is not reflected in the list!
- A scaling or set assignment is not considered!

8.19 Save / Export Parameter List

A parameter list can be exported from the project into following formats:

- “dw5”= COMBIVIS format - only 1 device in the list
- “cvxpl”= COMBIVIS format – several devices in the list
- “wr5”= COMBIVIS format – work list
- EtherCAT CoE startup command file



➤ A “wr5” list does not store any values, just a list of (online) parameters!

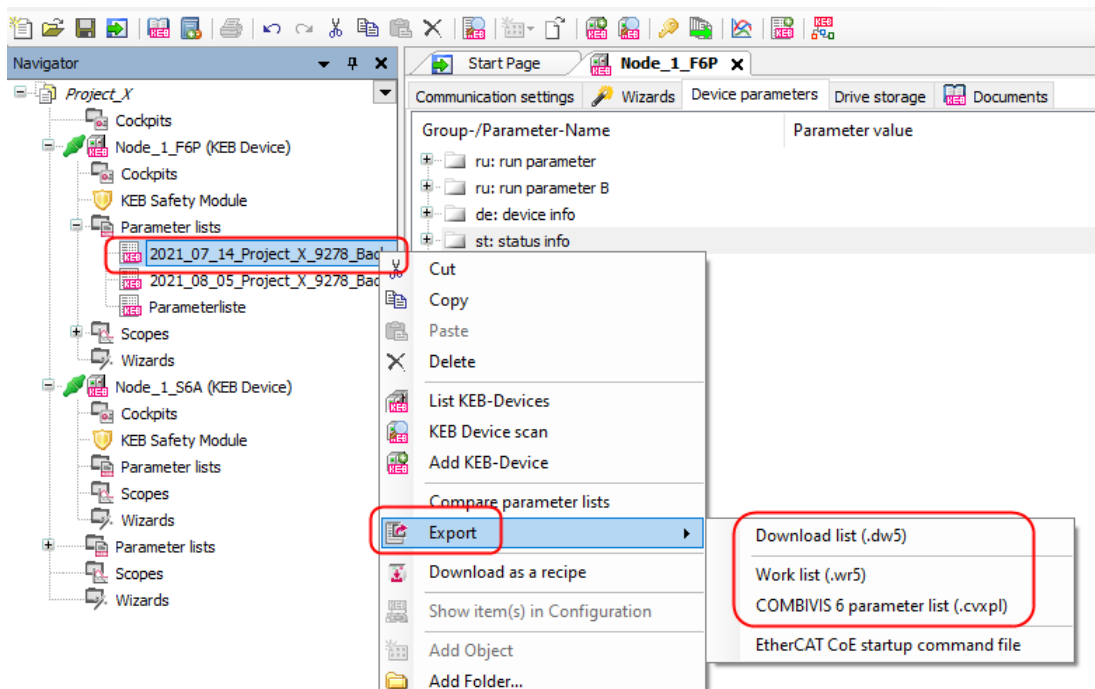


➤ Parameter lists to be used on COMBICONTROL C6, F5-LCD operator or F6 operator must be stored in "dw5" format.

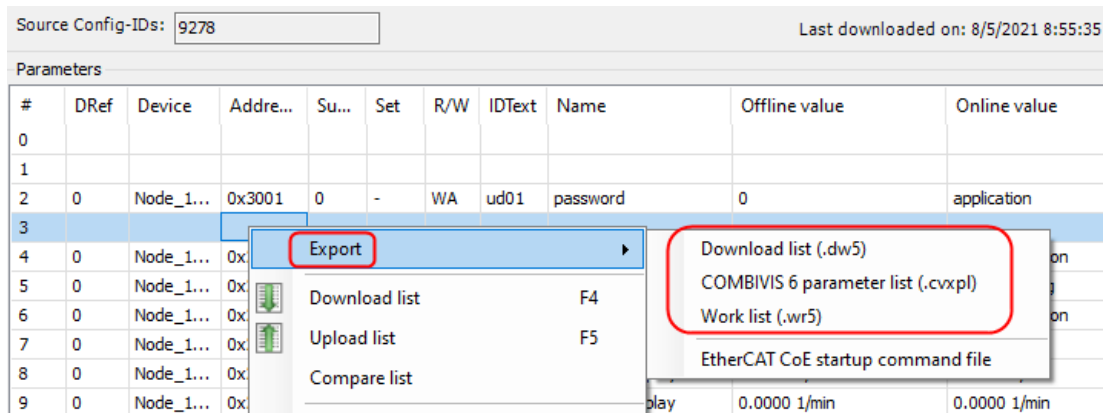
Export:

Select parameter list in Navigator → right-mouse-click → “Export” → select storage format → select storage location.

Parameter Lists



Alternatively, from open parameter list: right-mouse-click → “Export” → select format:

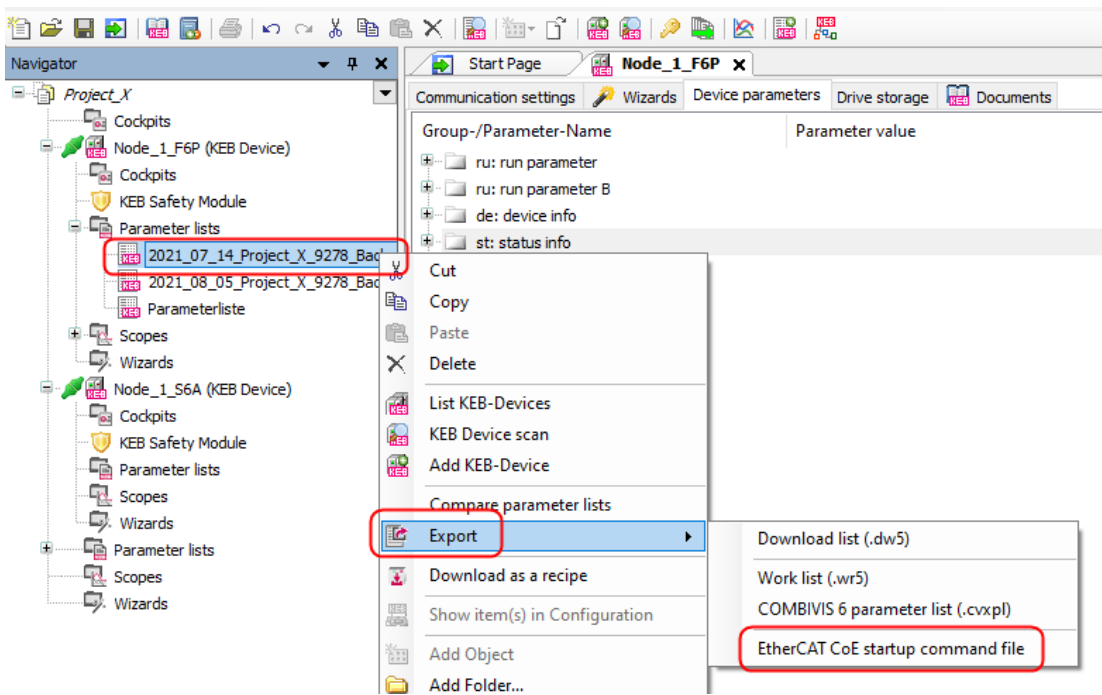


EtherCAT CoE startup command file

A parameter list can also be exported to an EtherCAT compatible XML format.

This list can be transferred, for example, as a start-up list to an EtherCAT compliant PLC (COMBICONTROL C6, TwinCAT 3.x).

Select parameter list in Navigator → right mouse click → Export → EtherCAT CoE startup command file.



9 Scope

9.1 Characteristics

- Running of one Scope per project possible, but several scopes can be added and displayed
- Scope files can be attached to the project or to devices
- Scope files are saved with the project when it is saved
- Total up to 16 channels per scope
- COMBIVERT F5 / B6 / G6: Up to 4 channels per device work in fast Scope mode, (2x32-Bit + 2x16-Bit) or (1x32-Bit + 3x16-Bit) or 4x16-Bit parameter length. The order does not matter.
- COMBIVERT F6 / H6 / S6: no fast Scope mode up to firmware version 2.0. From version 2.1 up to four 32-Bit parameters can be used in fast Scope mode (Service 21).
- Display as dot, line, step curve or interpolated curve
- It is possible to record channels in all devices of the project at the same time
- Export in XML-format with file extension “.sc6” for import in another COMBIVIS 6 project
- Export in Excel-compatible “CSV”-format
- Offline mode (4 channels buffer in one device)
- Online Trigger mode
- 2 horizontal and 2 vertical cursors at the same time
- Extensive zoom-functions
- Auto scaling function (splaying of the curve to the whole X- and Y-range)
- Y-axis additionally with parameters unit
- Import of .sc5-files (COMBIVIS 5) is not possible

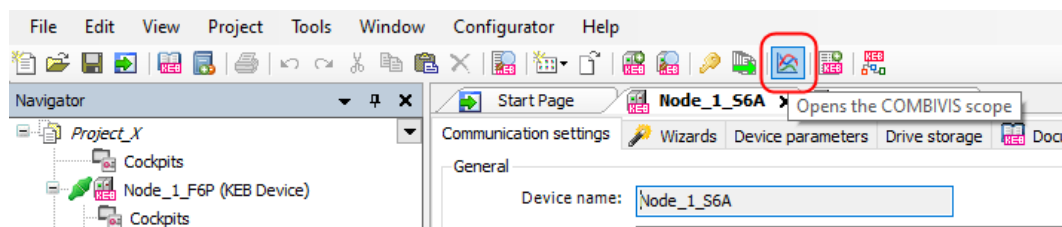
9.2 Add Scope to the Project

Following possibilities are offered for to add a scope:

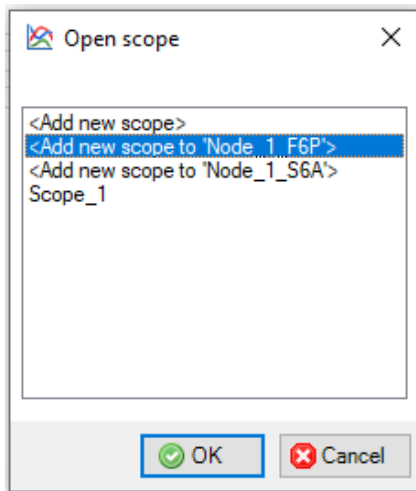
- A new, empty scope
- Import an external scope with file extension “.sc6” or “XML”
- A scope with the same adjustments as an existing

9.2.1 Add a New Scope

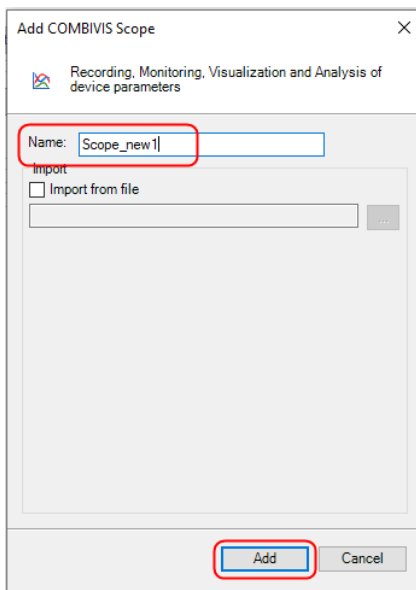
Click on icon  in the tool bar.



→ Add a new scope:

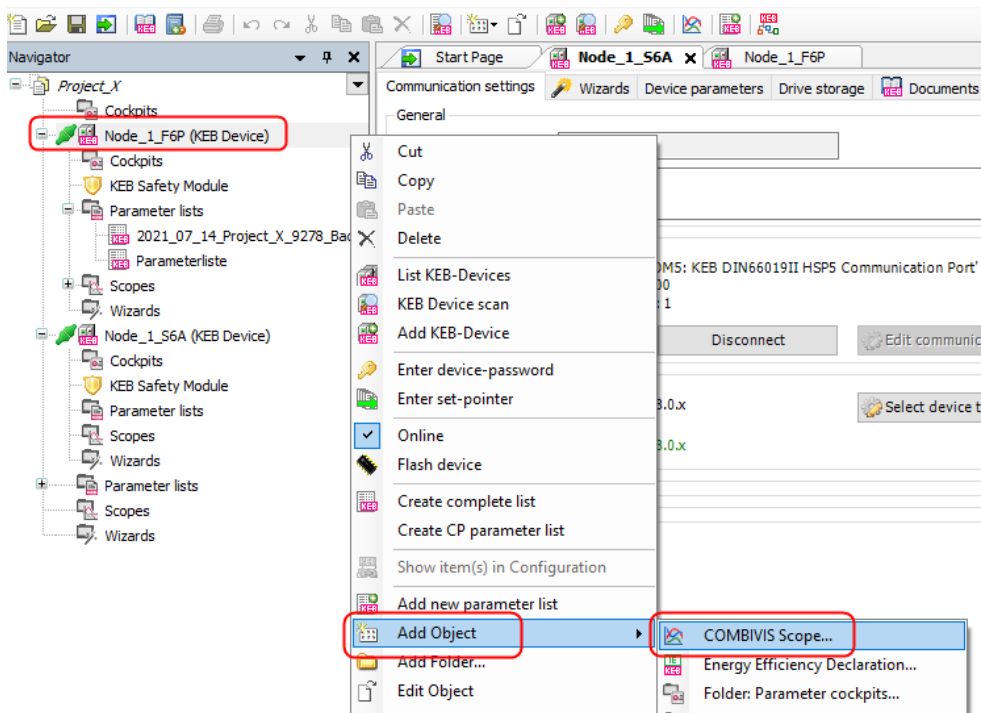


→ Name the new scope and add:

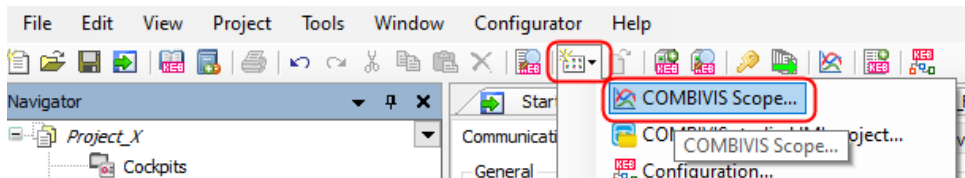


Alternative way: Right mouse key on "Project" → "Add Object" → "COMBIVIS Scope"

Scope



Or: in the tool bar: icon “Add Object”→ “COMBIVIS Scope”

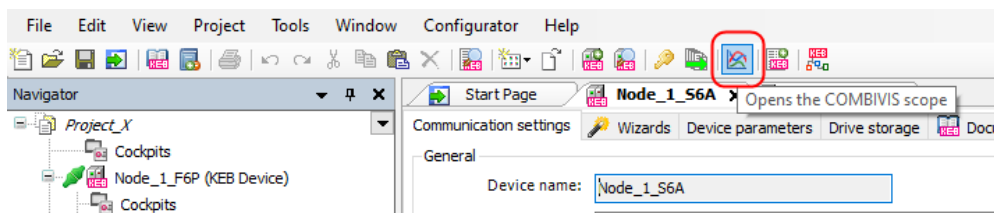


Note: Only one scope can be active at the same time!
With each scope one recording can be saved with the project.
Channels and adjustments can be different in each scope.

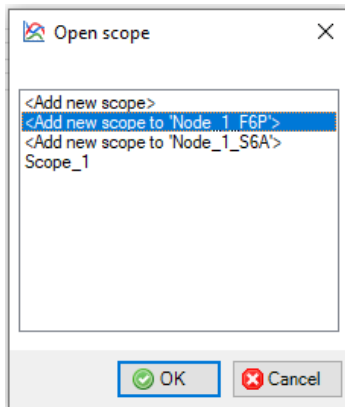
9.2.2 Open an External Scope

External stored scopes can be opened in a current project or directly with a temporary project.

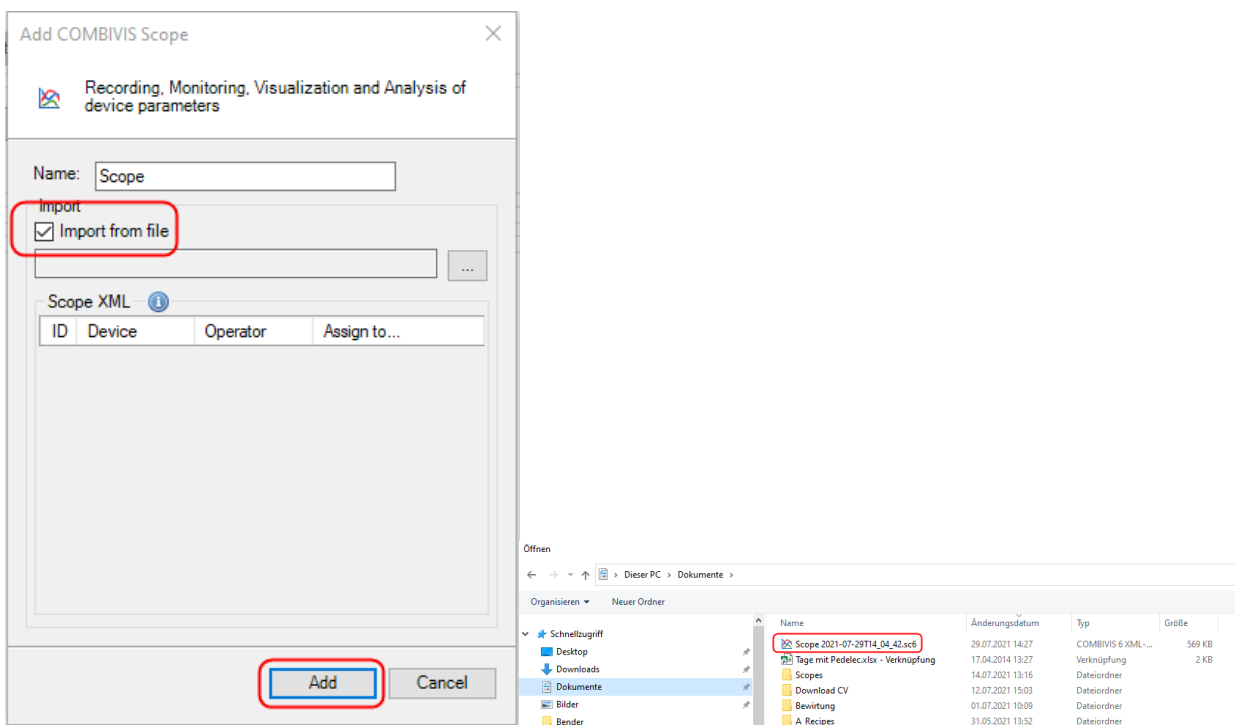
In a project click on icon  in the tool bar.



→ Add a new scope at the project or directly at a device:

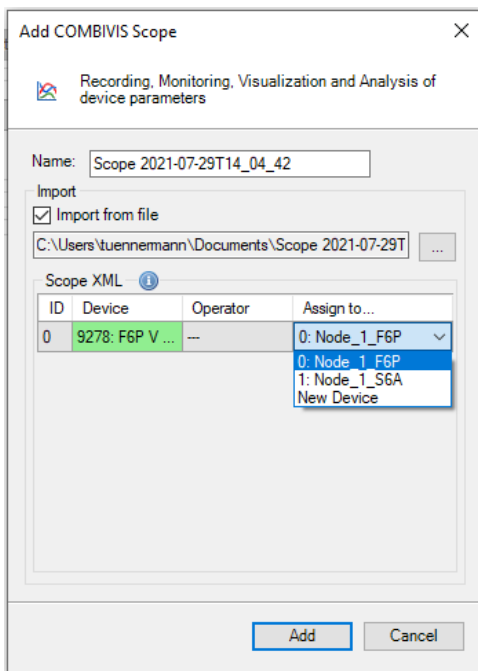


→ Set hook at import from file → choose the file → open:



→ Choose to which device the scope channels shall belong → OK

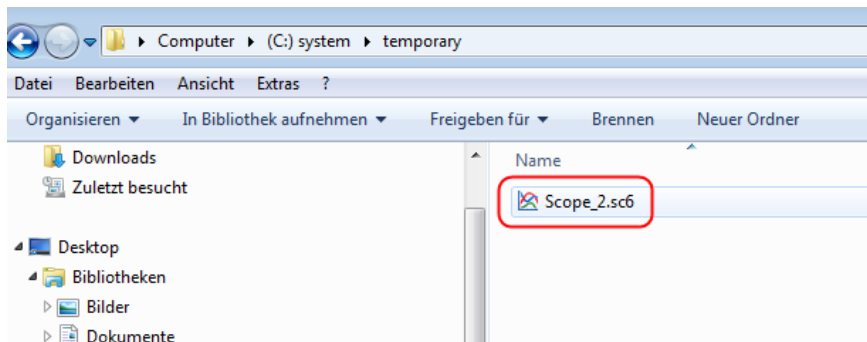
Selection "New device" adds a new virtual device to the project. This is necessary if there are no device or only non-compatible devices in the project.



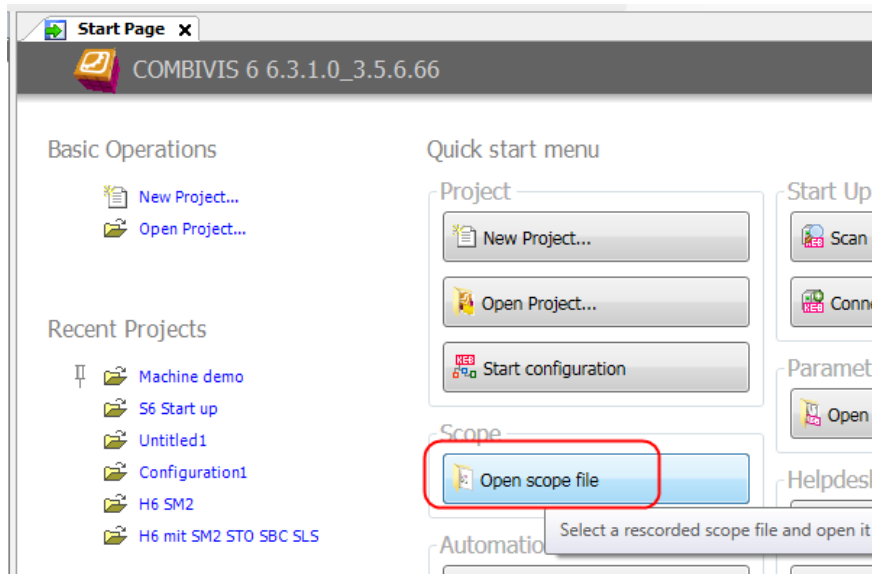
Different channels in the opened scope can belong to different devices of the project. The version of the COMBIVERT is stored in the scope, so at opening it is pre-selected if a matching device is found in the project.

Directly with temporary project in background:

Choose scope file in Windows Explorer, then double-click or in context menu “Open with....”



On Start Page with button “Open Scope”

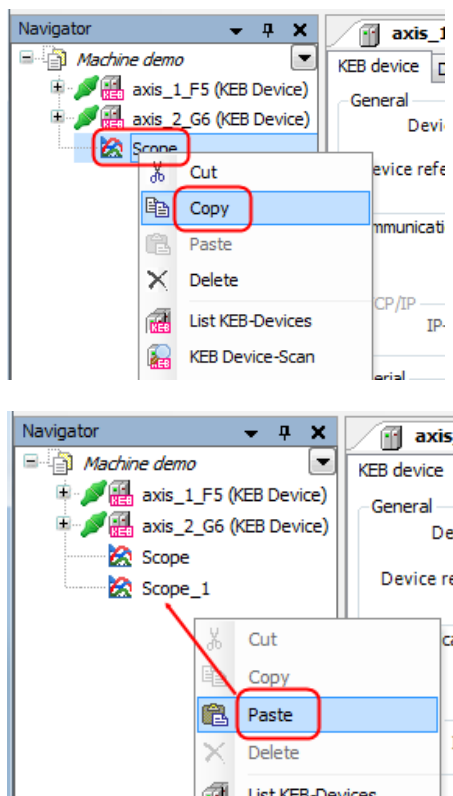


9.2.3 Add a Scope with Similar Settings – Copy Scope

A second scope may be recorded with the same adjustments later than the first one. So, a comparison can be done e.g., after changing of parameters. For that it is possible to copy a scope to a second one identical scope. When the new scope is started the old curve will be overwritten. It saves a new channel assignment and new adjustment settings.

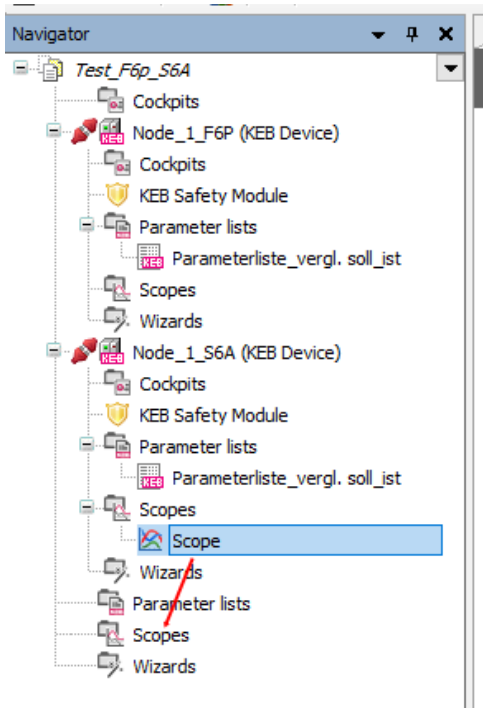
Copy scope:

By “copy” and “paste” in the navigator, it is easily possible to create a similar scope.

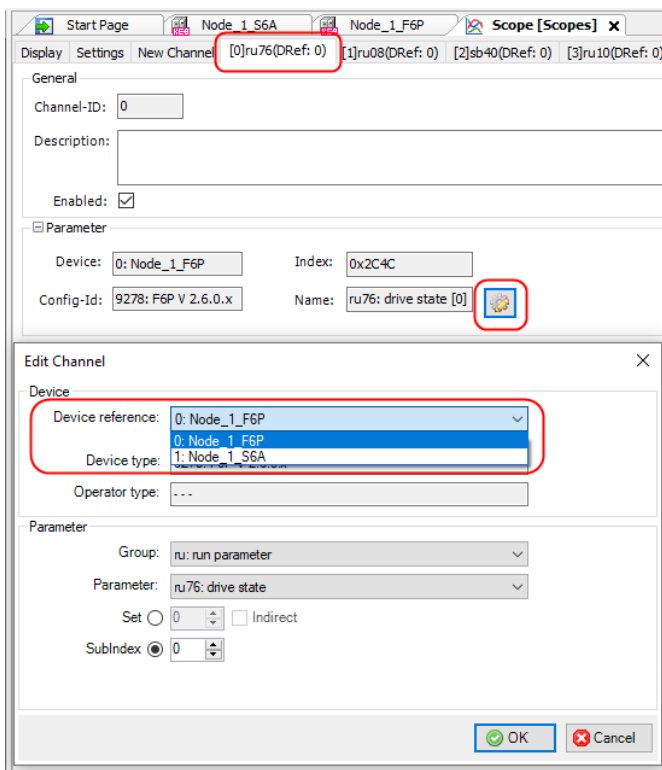


9.2.4 Moving Scope in the project

A scope can be moved in the project with the mouse pointer. E.g., from the drive to the project or from one drive to another. **The channel assignment is retained, i.e., the original assignment is not changed or adapted.**

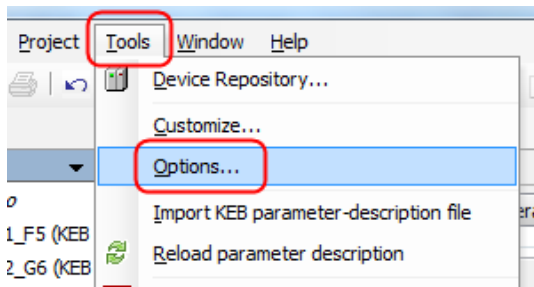


The assignment of the channels can be adjusted in the settings of each channel.

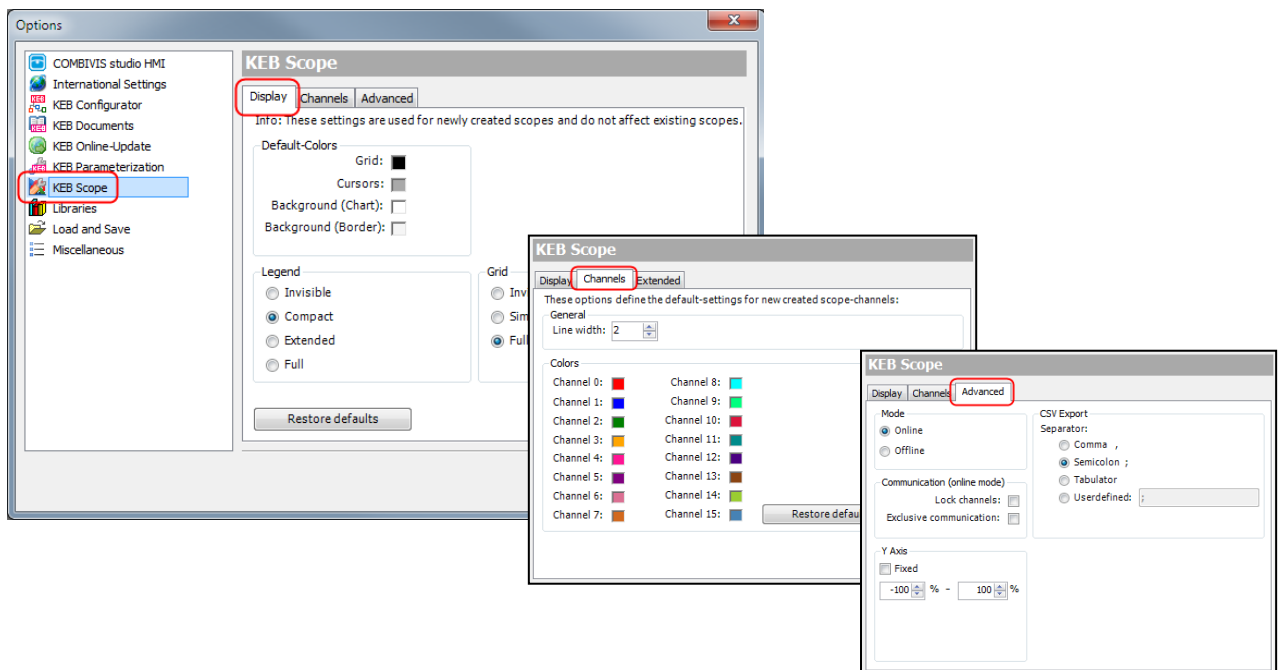


9.3 Scope Basic Settings

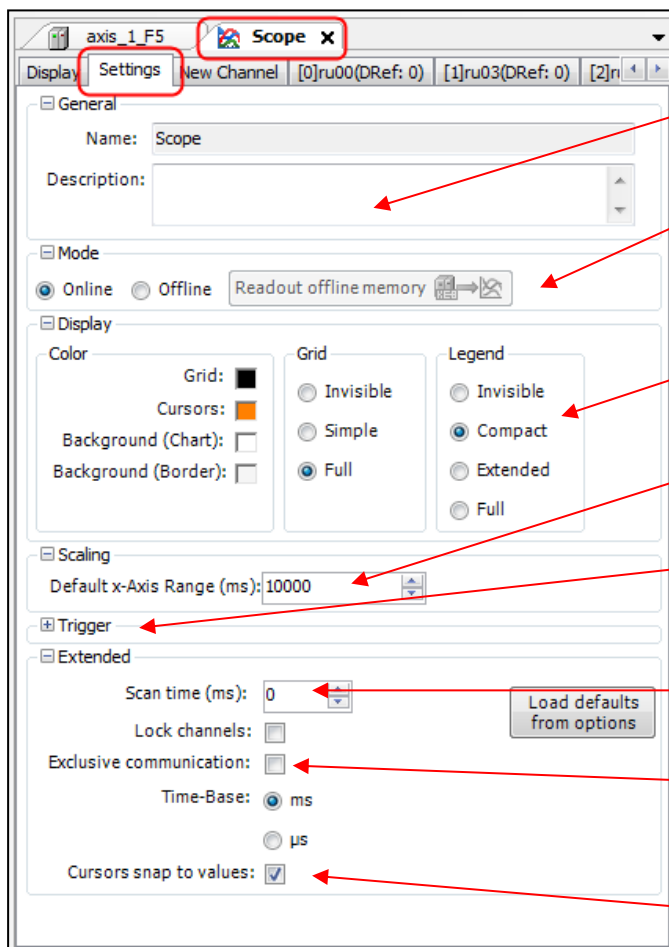
It is possible to configure basic setting in window “KEB Scope-Settings”. These adjustments will be pre-set always when a new scope will be opened.



Menu bar → “Tools” → “Options” → in window “KEB Scope-Settings”



In window “**Settings**” in scope itself settings can be adjusted which are valid only for this scope.



Description for scope

Online (direct display of recorded values in CV6) / Offline mode (see there)

Display / design of cursor, grid, and legend

Basis of time axis (X-axis)

Trigger option (Identification of special occurrences in recording – see there)

Time gap between two measured points: 0 = shortest time

Data channel is reserved only for scope

Cursors snap into measured value

Limitation of communication:

Lock channels: The specified parameter on a channel can be accessed and queried only by Scope. Other parameters are accessible.

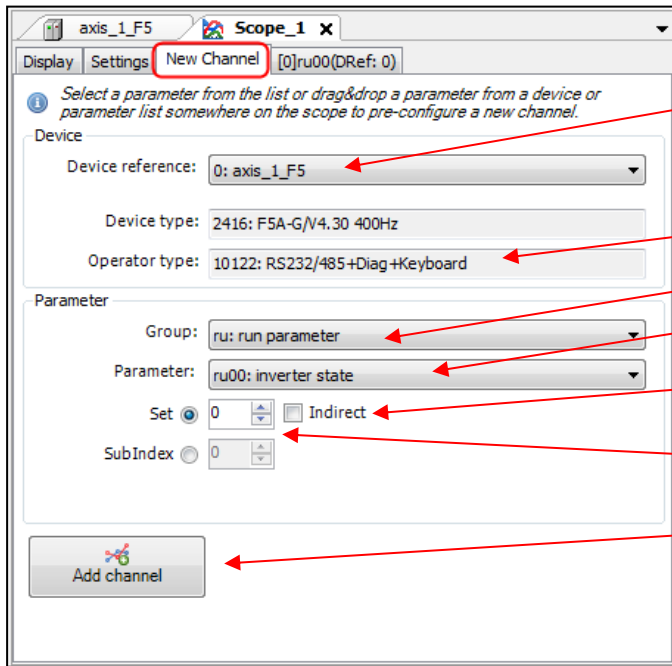
Exclusive communication: All communication with the devices is limited to the scope. Simultaneous change of a parameter is not possible (Also the test run wizard of the x6-devices no longer works). At disabled function parameters can be adjusted while scope is running and displays changes coevally (e.g., for speed controller adjustment).

In the default setting (both functions off), the communication is split between the read-out scope channels and all device parameters visible in other windows. The scope scan rate is therefore faster if all editor windows are hidden.

9.4 Channel Configuration / New Channel

Channel allocation

In window “New Channel” a parameter can be chosen directly for this channel.



Device reference (-selection) (doesn't mean device's bus address!). I.e., from which device the channels shall be recorded

Control data of device

Parameter group selection

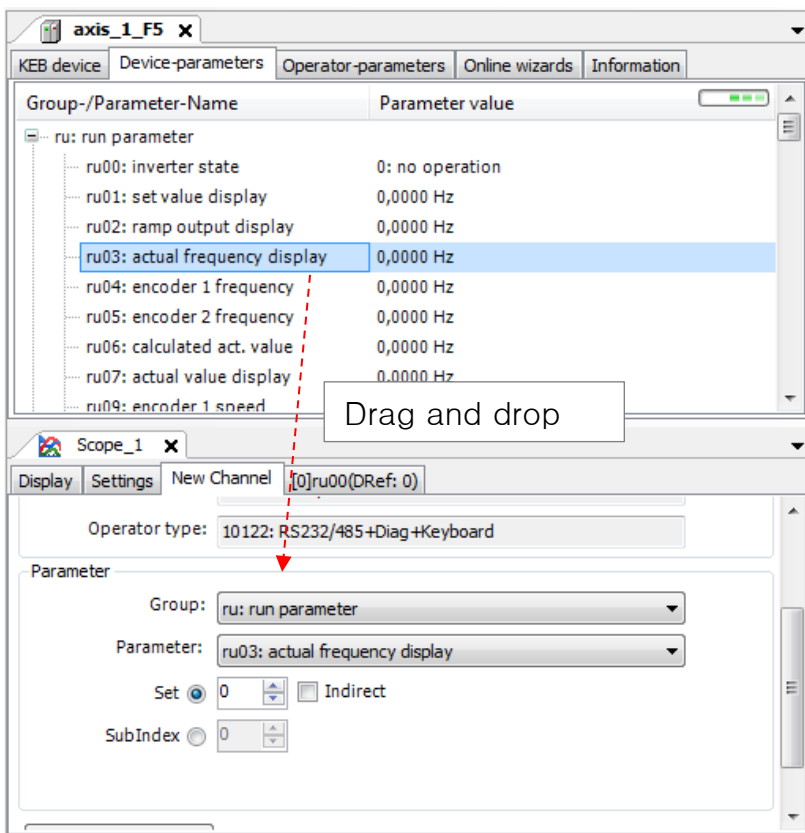
Parameter selection

Set addressing mode (directly or indirectly)

Set selection

Acceptance and activation of the channel

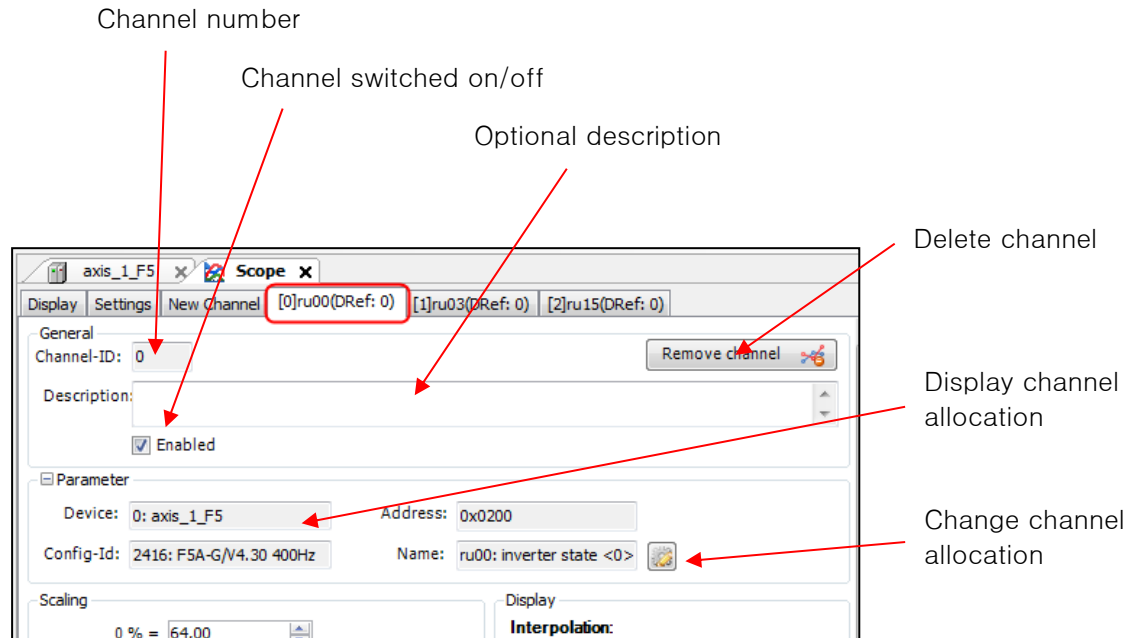
Alternative:



Select parameter in device-editor and pull it to the window "scope". (Doesn't matter if scope is in tab "display", "settings" or "new channel")

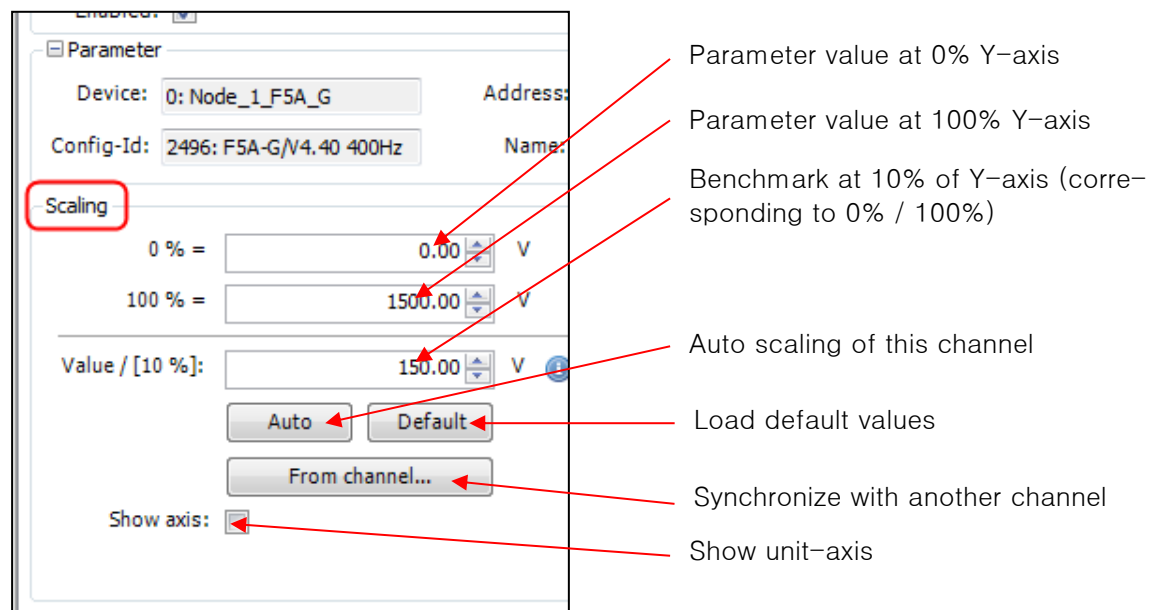
Please do not forget acceptance and activation!

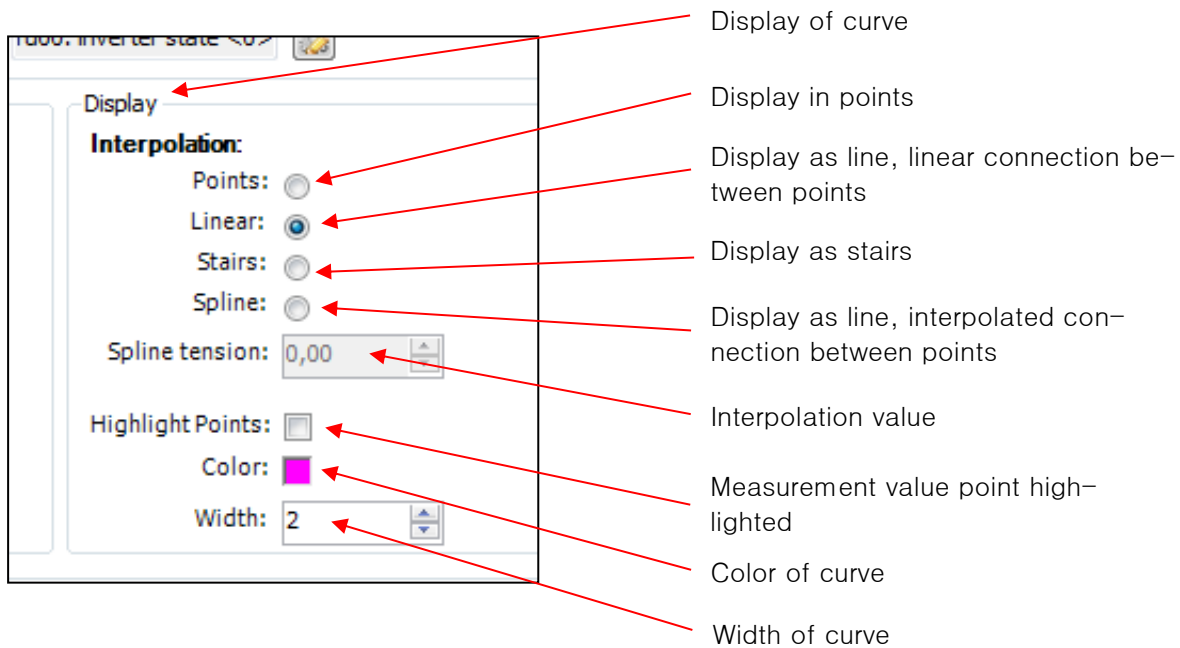
9.5 Channel Settings



A disabled (not "enabled") channel is not shown in the display and not recorded at the next recording.

Scaling can be set manually for each channel.





9.6 Fast Scope Mode

The fast Scope mode depending on the device type is a possibility of fast and simultaneous transmission of measured values. It works like a process data communication

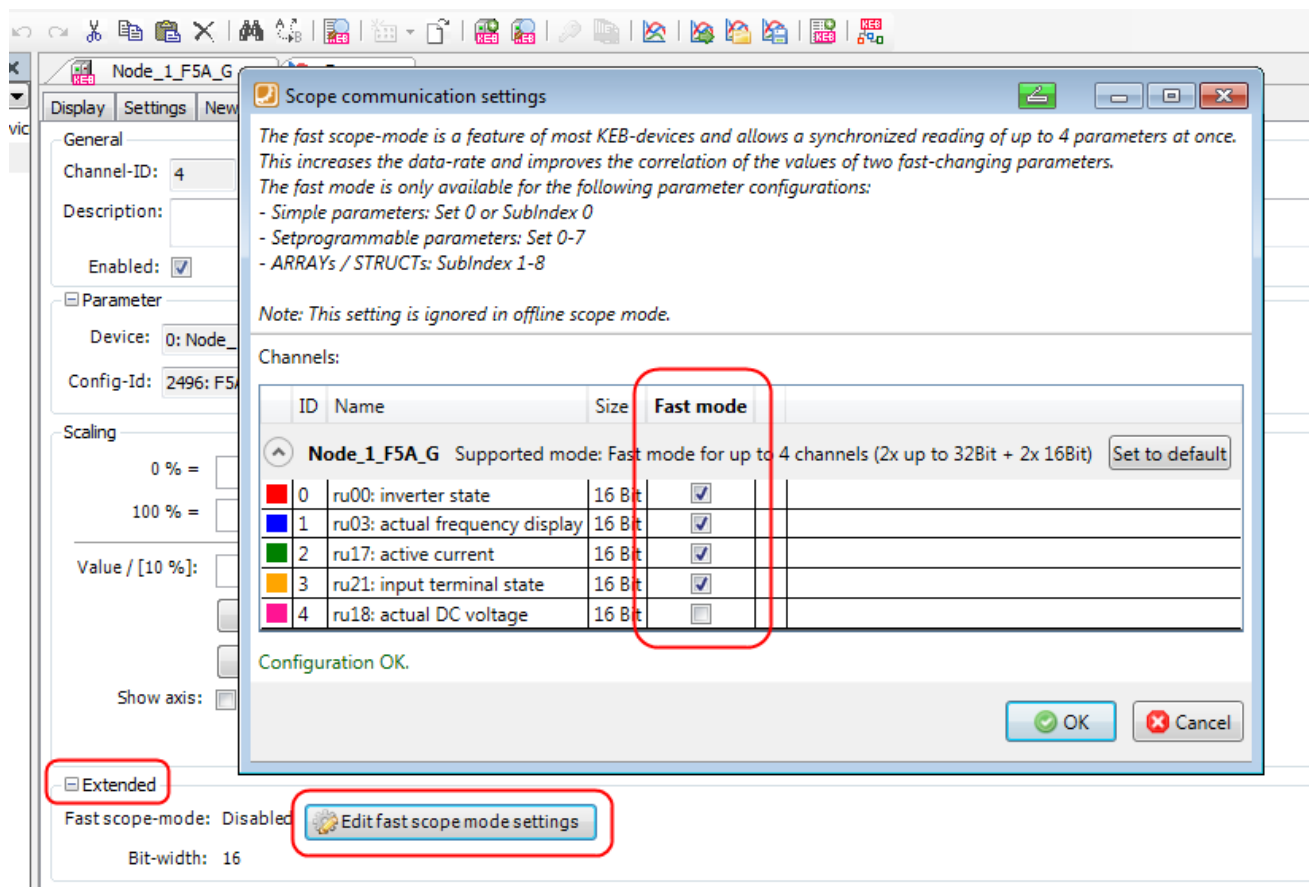
- COMBIVERT F5 / B6 / G6: Up to 4 channels per device work in fast Scope mode, (2x32-Bit + 2x16-Bit) or (1x32-Bit + 3x16-Bit) or 4x16-Bit parameter length. The order does not matter.
- COMBIVERT F6 / H6 / S6: no fast Scope mode up to firmware version 2.0. From version 2.1 up to four 32-Bit parameters can be used in fast Scope mode (Service 21).

Typically, the first chosen channels are placed automatically in fast Scope mode if it is available.

An assignment of parameters outside the fast Scope mode leads to a considerable slowdown in the recording raster because a time gap must be offered for the additional asynchronous values.


The fast Scope mode works only in direct addressing mode.

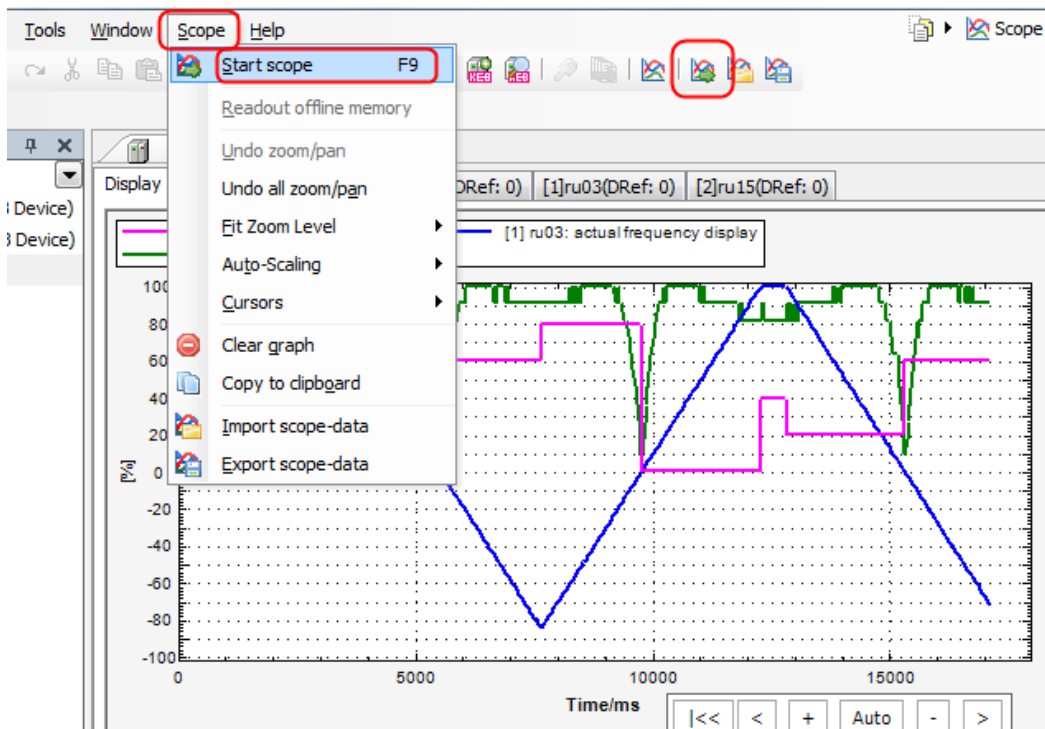
The assignment can be changed in menu "channel" → "extended" → "Edit fast scope mode settings":



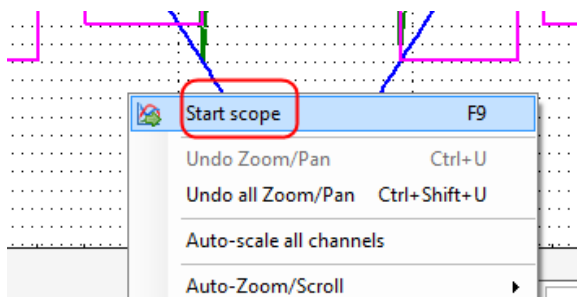
9.7 Recording

Start recording in window "Display" as follows:

- Menu: "Scope" → "Start scope" or
- Context menu / right mouse key → "Start scope"
- Tap key "F9" or
- Click on symbol 

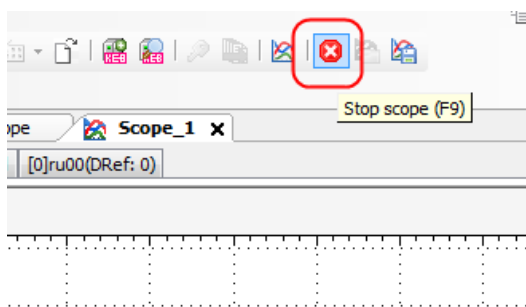


- “Right mouse key” → “Start scope” or



Start with “F9”–key works also in other windows of COMBIVIS 6.

Stop with same functions but a stop-icon will be shown:



Recording time is not limited. Per hour with 4 channels at 15ms cycle time the size will be approx. 90 MB.

9.8 Display Window

Behaviour of the display while recording:
Context menu / "Right mouse key" → "Auto-Zoom/Scroll":

Saves the current Y-axis proportioning for a new recording

At recording the displayed window jumps with the recorded value to the next window width

The window runs synchronous with the actual recorded value

Channel	Value	Difference
Vertical 2		
is (21.03.2013 12:05:34)	0ms	
forward acceleration	[0] 0: no operation	
0125 Hz	[0] 0,0000 Hz	
A	[0] 0,0 A	

9.9 Adapt Display

Time axis (X-axis)

Stretch / compress time axis

Fading in and out of cursor value schedule

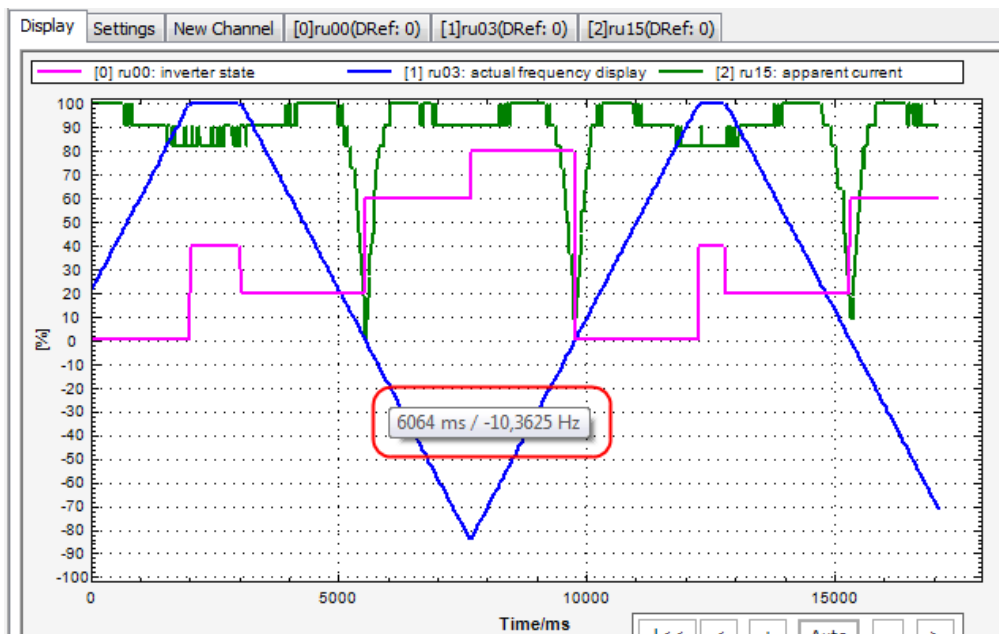
Scrolling window

Display of full recording time in the window

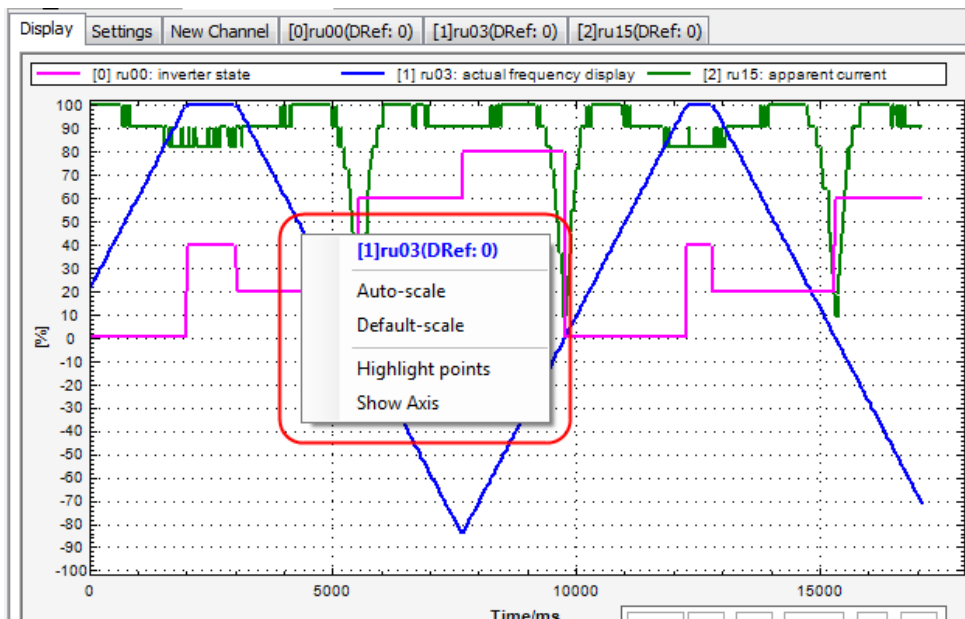
X-Axis: Recording time in ms or μ s

Y-Axis: Parameter value in basic setting refers to
 100% = maximum value range
 0% = 0
 -100% = min. value range

By passing the curve with the mouse, the actual value will be displayed.



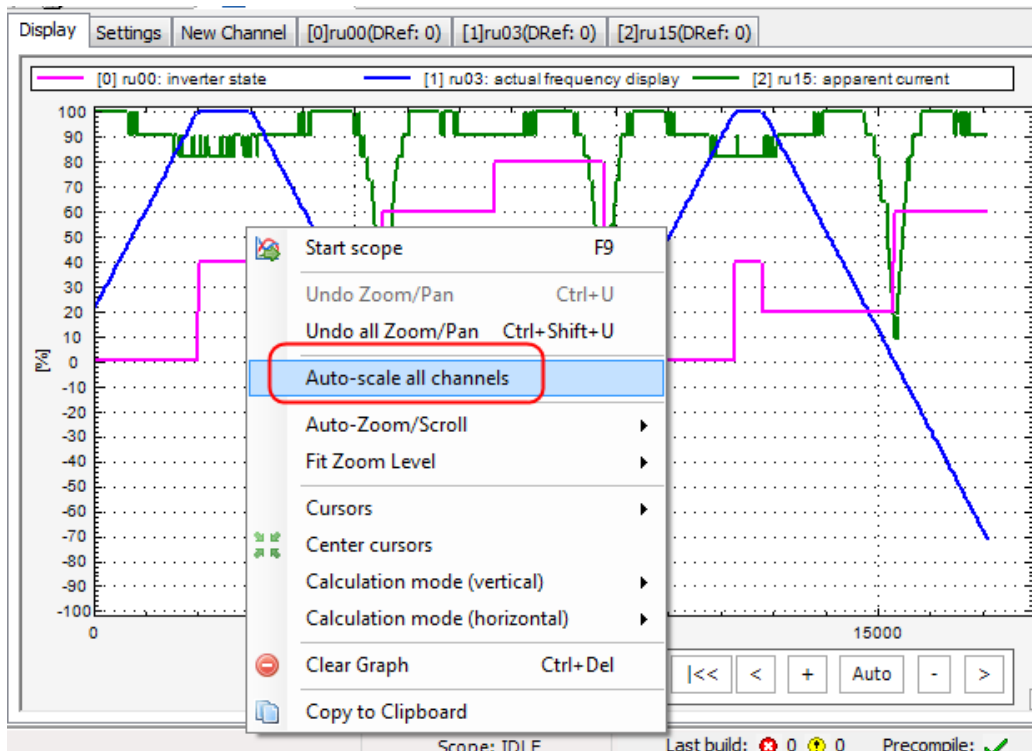
By right mouse key click on the curve a window opens with adjustment possibilities.



Stretching / compressing of display after recording:

Click with "right mouse key" in the display window: "Auto-scale all channels":

All actual values will be stretched on the Y-axis all over the window from -100% to +100%

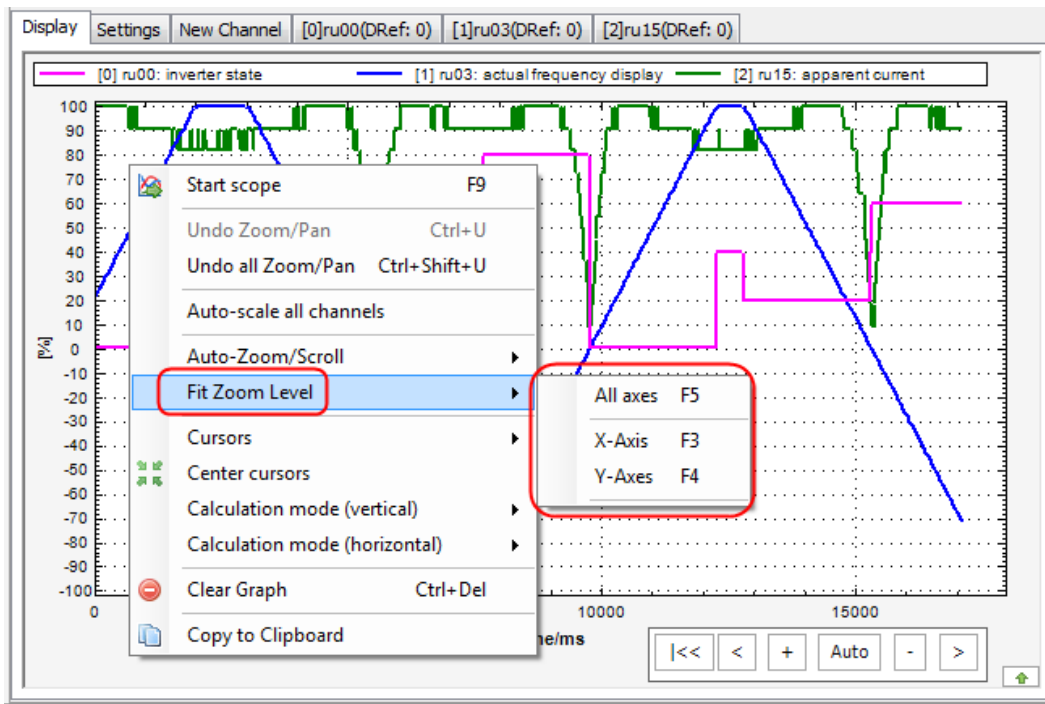


9.10 Display – Zoom

At zooming the relation between the curves is kept.

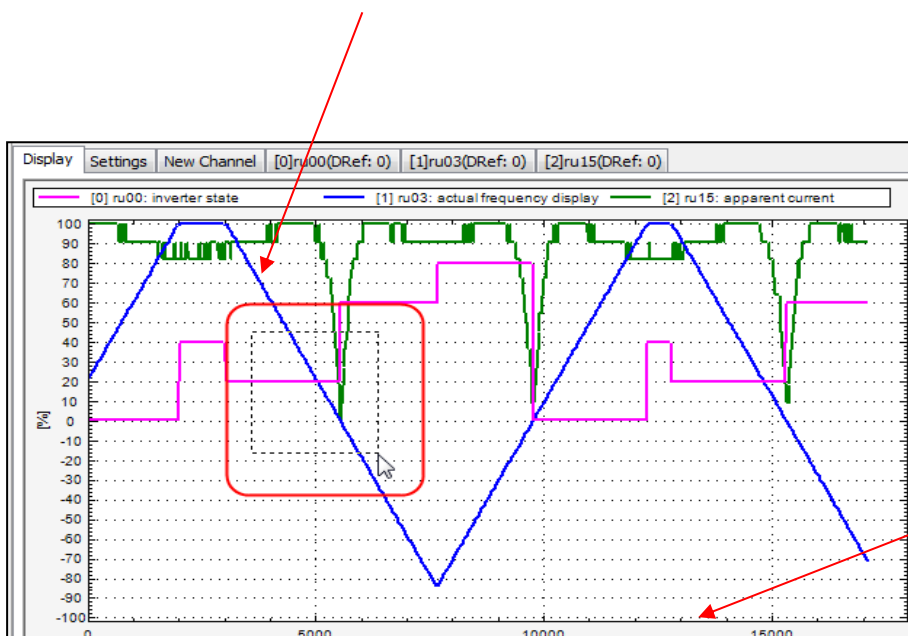
Zoom to display 0-100% (or rather -100- +100%):

- “Right mouse key” → “Fit Zoom level” → “All axes” (or only “X- or Y-axis”)
- Tab key F5 (F3 / F4)



Zoom by mouse:

- Whole display with mouse wheel or keys “+” and “-“
- Parts of display: mark with left mouse key



The view in the window can be displaced by using the buttons “← ↑ → ↓”

Or:
Tap key “Ctrl” and left mouse key in parallel

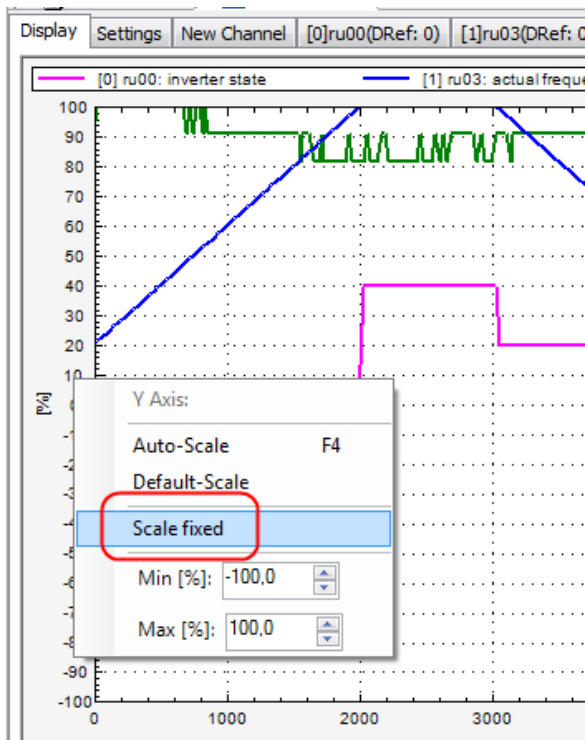
Or:
With pressed mouse wheel

Or:
Only the time (X-) axis: click and hold with mouse and scroll to right or left side

Or by button “Auto” on the right bottom of the Scope window

Scaling / fixing of Y-axis:

Zooming will be done only at the time- (X-) axis by mouse
Point to the Y-(%) axis → context menu / “right mouse key” → “Scale fixed”



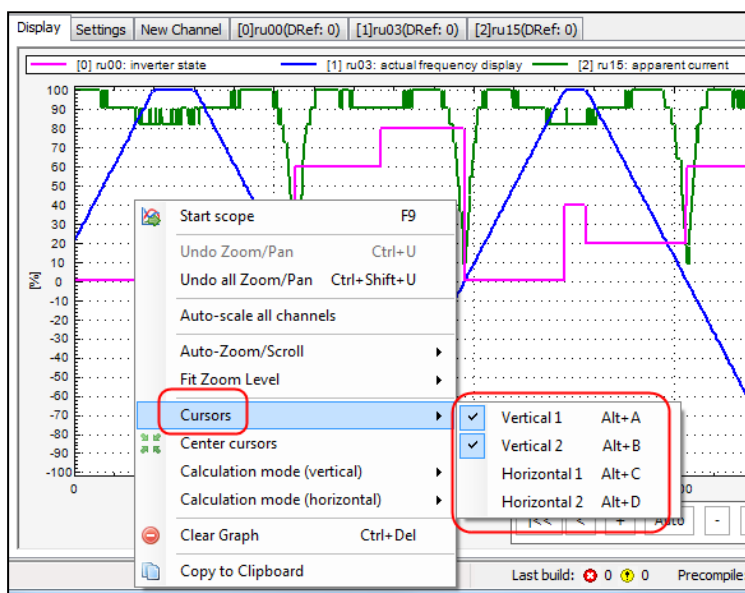
Also, a manually scaling of the Y-axis can be done.

9.11 Display – Cursors

There are 2 vertical and 2 horizontal cursors:

To integrate: “Right mouse key” → “Cursors” → “Vertical 1 or 2 and horizontal 1 or 2”

The cursors will be placed in the centre of the display. Displace them by picking with the left mouse key.

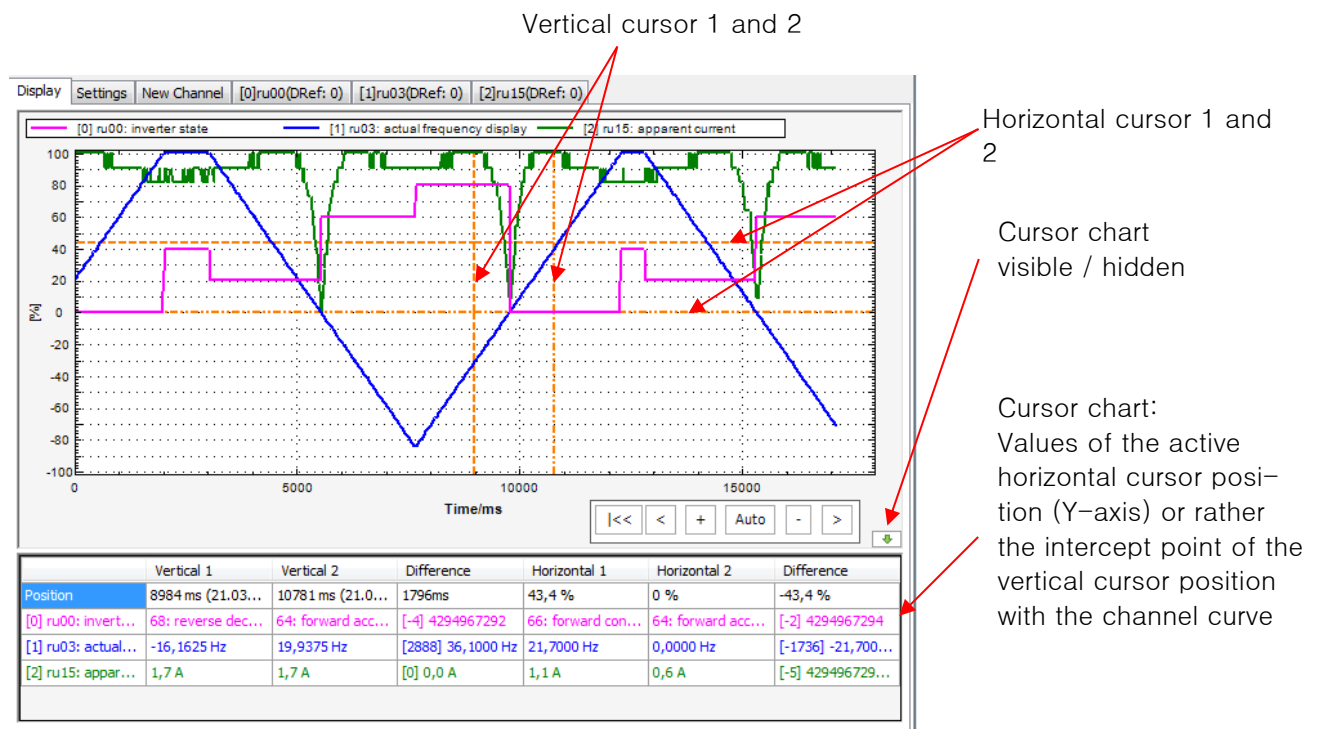


Alternative with keys:

- Alt+A: Vertical 1
- Alt+B: Vertical 2
- Alt+C: Horizontal 1
- Alt+D: Horizontal 2

The cursor will always be first placed in the centre.

The cursor can be moved by pressed left mouse key or by using key combination “Alt+→” and “Alt+←”

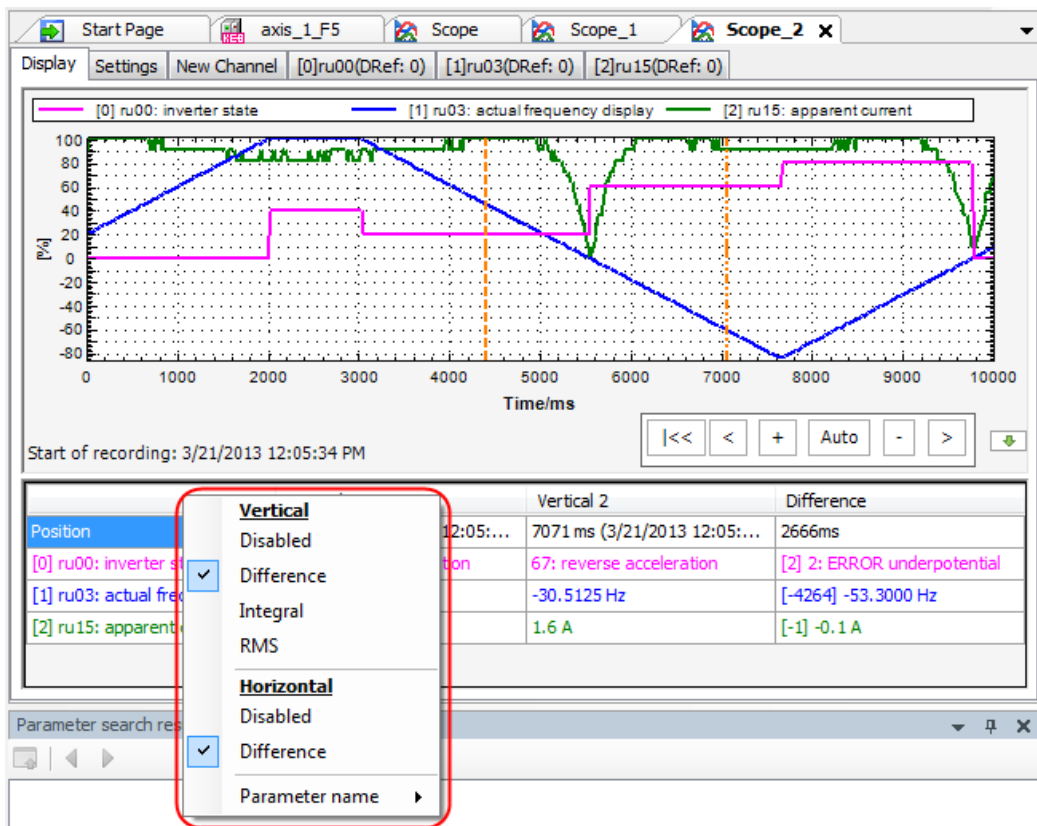


Calculation mode:

Based on vertical cursor values, it is possible to realize several calculation types: difference, integral or average. On basis of horizontal cursor values only difference is possible.

By context menu / "right mouse key" in the cursor list area the calculation mode can be chosen. Or for changing click onto the name with left mouse key.

Scope



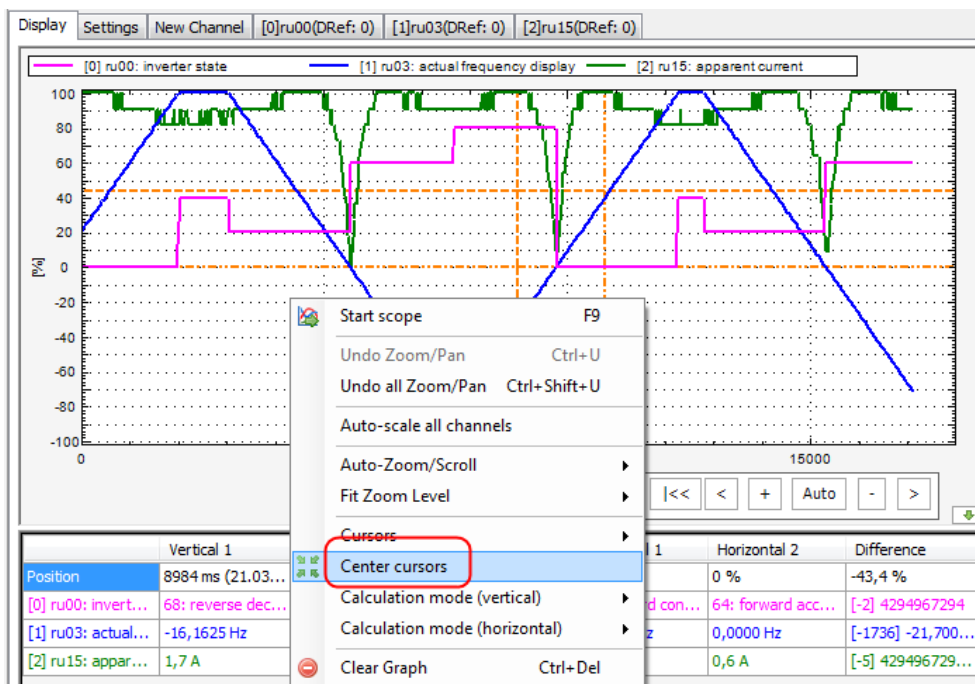
	Vertical 1	Vertical 2	Difference	Horizontal 1	Horizontal 2	Difference
Position	8984 ms (21.03...)	10781 ms (21.0...)	1796ms	43,4 %	0 %	-43,4 %
[0] ru00: invert...	68: reverse dec...	64: forward acc...	[-4] 4294967292	66: forward con...	64: forward acc...	[-2] 4294967294
[1] ru03: actual...	-16,1625 Hz	19,9375 Hz	[2888] 36,1000 Hz	21,7000 Hz	0,0000 Hz	[-1736] -21,700...
[2] ru15: appar...	1,7 A	1,7 A	[0] 0,0 A	1,1 A	0,6 A	[-5] 429496729...

	Vertical 1	Vertical 2	Integral	Horizontal 1	Horizontal 2	Difference
Position	8984 ms (21.03...)	10781 ms (21.0...)	Diff.: 1796ms	43,4 %	0 %	-43,4 %
[0] ru00: invert...	68: reverse dec...	64: forward acc...	118,20468*s	66: forward con...	64: forward acc...	[-2] 4294967294
[1] ru03: actual...	-16,1625 Hz	19,9375 Hz	3,84689781640...	21,7000 Hz	0,0000 Hz	[-1736] -21,700...
[2] ru15: appar...	1,7 A	1,7 A	2,649399 A*s	1,1 A	0,6 A	[-5] 429496729...

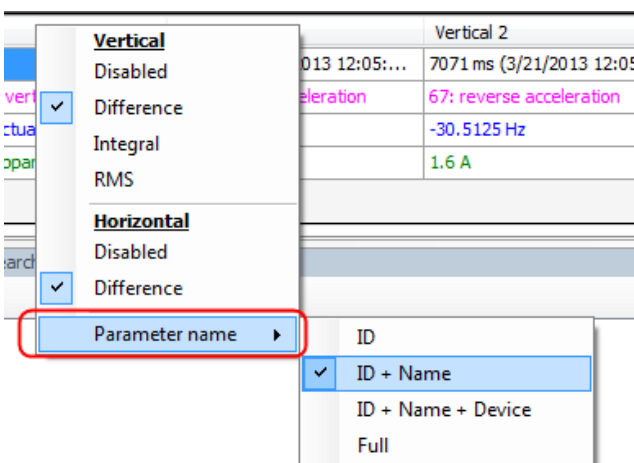
	Vertical 1	Vertical 2	RMS	Horizontal 1	Horizontal 2	Difference
Position	8984 ms (21.03...)	10781 ms (21.0...)	Diff.: 1796ms	43,4 %	0 %	-43,4 %
[0] ru00: invert...	68: reverse dec...	64: forward acc...	65,771	66: forward con...	64: forward acc...	[-2] 4294967294
[1] ru03: actual...	-16,1625 Hz	19,9375 Hz	10,941 Hz	21,7000 Hz	0,0000 Hz	[-1736] -21,700...
[2] ru15: appar...	1,7 A	1,7 A	1,518 A	1,1 A	0,6 A	[-5] 429496729...

With this it is possible to get very easy the RMS current of a drive over a running circuit.

If the cursors are no longer in the picture due to zooming, they can be brought back into the picture with the context menu "right mouse button" → "Centre cursors".

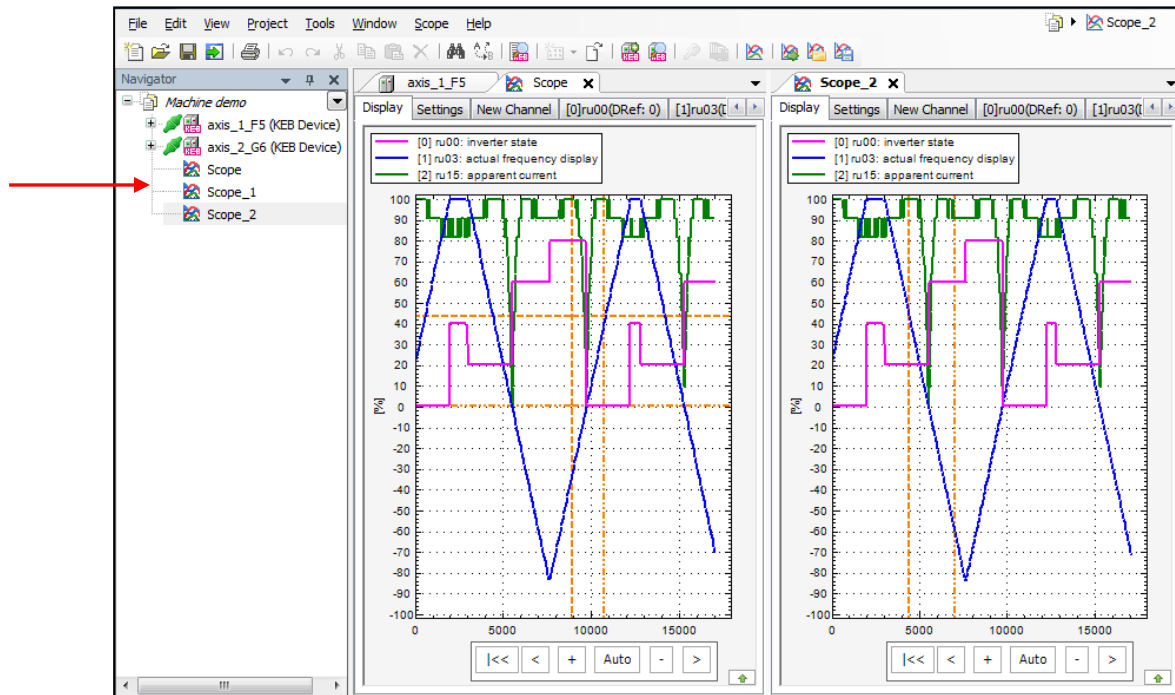


The displayed length of the parameter name in the cursor list can be chosen in the context menu:



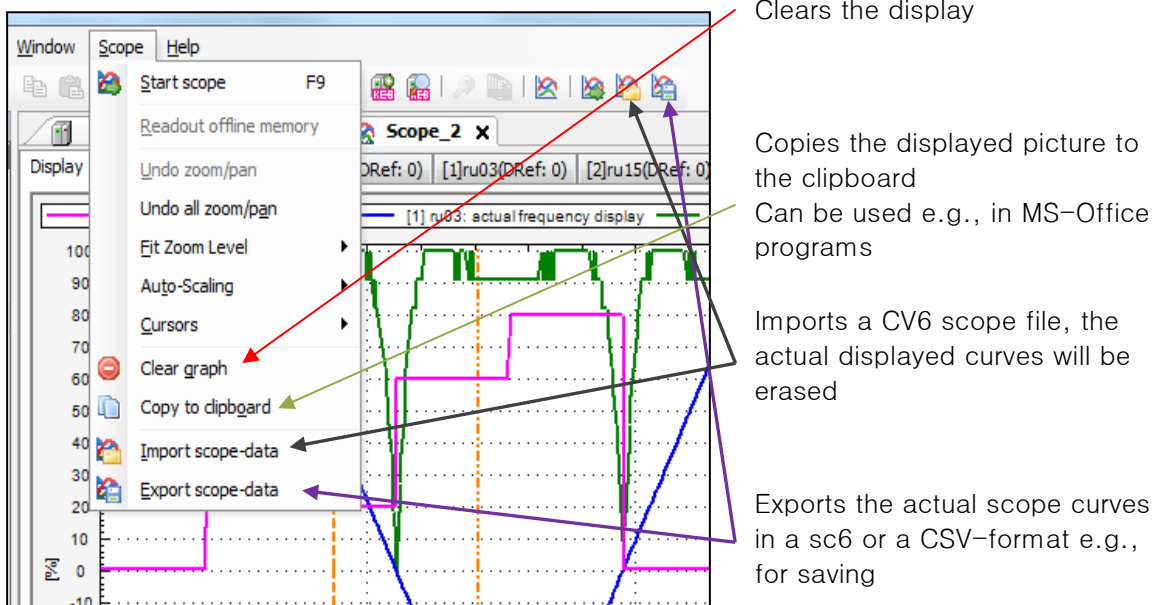
9.12 Save Recordings

Several scope recordings can be added to the project and saved with it. Each scope can save one recording (=> [9.2 Add Scope](#)).



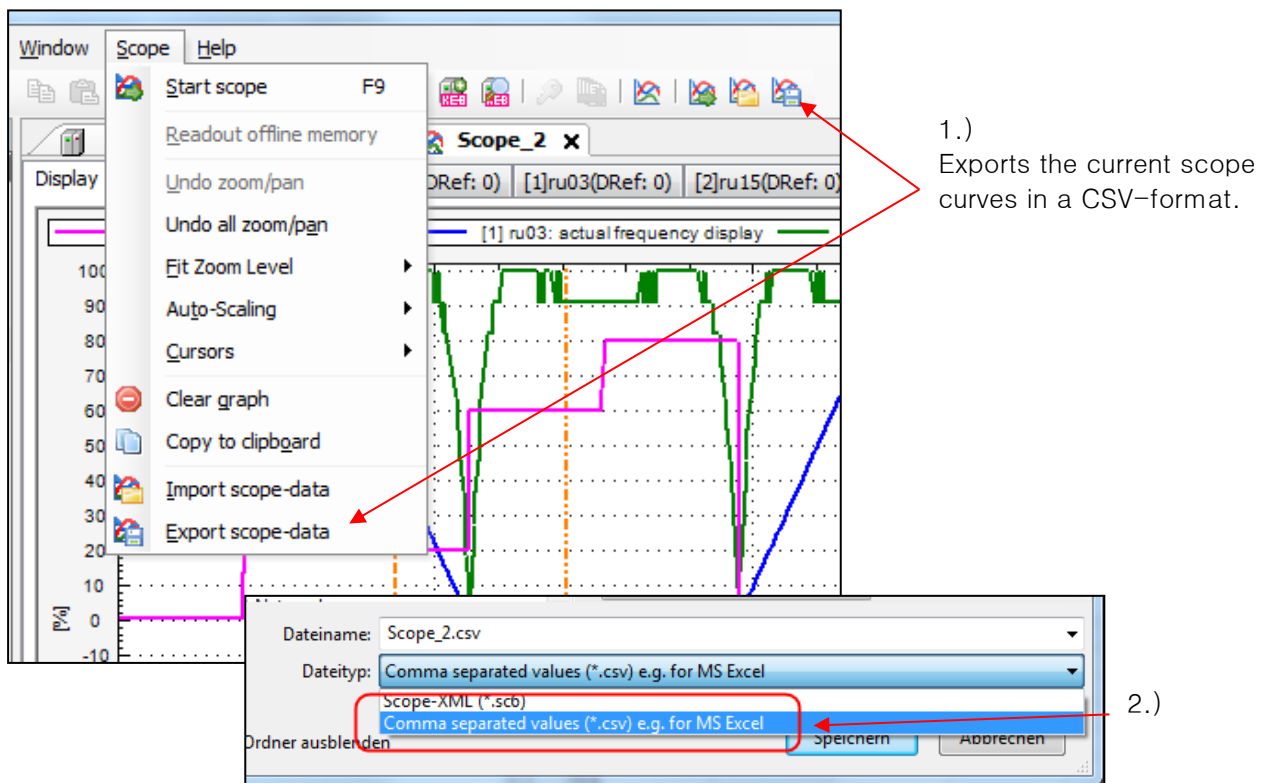
9.13 Import / Export

With the export and import function Scope records can be stored outside of the project or external files can be imported. The file extension is "sc6".



9.14 Export to CSV-Format

It exports the current diagram into a "CSV"-format. This allows importing the recorded curves in e.g., Excel program.



Adjustments of "CSV"-format by: "Tools" → "Options" → "KEB-Scope" → "Extended"

9.15 Trigger Function (Online)

Trigger function in online mode

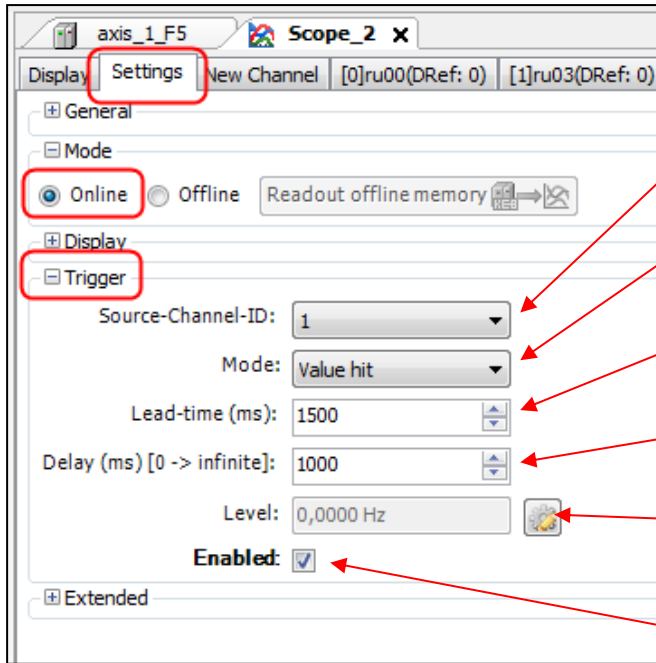
This function realizes in case of long-term recordings a limitation of the saved period (e. g. period around a defined error occurrence). Therefore a trigger event will be defined (e.g., a special drive controller status or a reached current level).

Around this event a predefined time domain will be saved. That results in a compact scope-file also for long term recordings.

This function will be adjusted and activated in the window "Scope" → "Settings".

The trigger event will be placed in scope display at 0 ms on the time axis.

Triggering (Online Mode)



Trigger channel: On which channel shall be triggered?

Which trigger pulse edge or level?

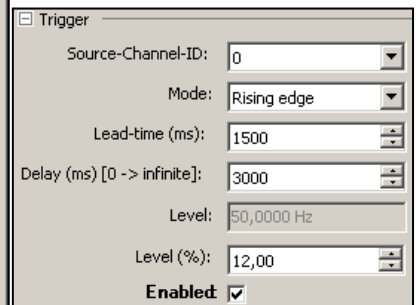
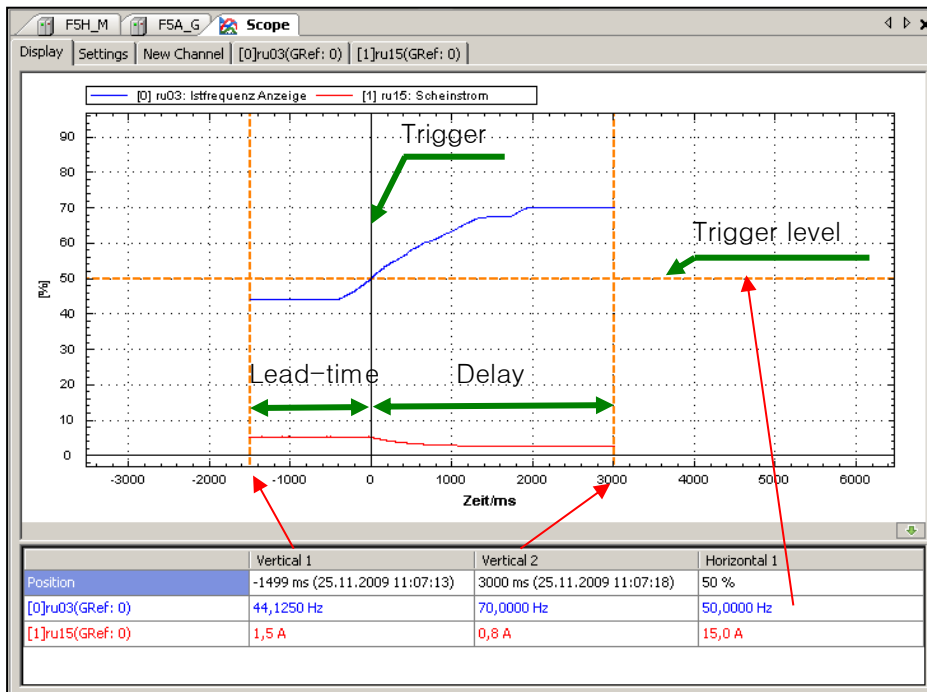
Lead time: Saved time before trigger event

Over travel time, saved time after trigger event

Level, absolute relating to unit or percentile relating to range of values

Activate trigger function

Example:



9.16 Offline Mode

The Offline mode uses the function of the fast Scope mode's 4 channels to buffer parameter values in the device. Therefore a part of the device's storage is reserved.

Via channel allocation recording and filling of storage will be generated. The storage works like a drum store, each new value overwrites the oldest one.

The store will be frozen by a trigger event and can be read-out by scope. Because of a faster data communication in the devices than to the PC it can be recorded with a shorter time grid.

Useful for:

- Shorter time grid, therewith better hit rate in short peaks
- Recording without PC
- Recording of sporadically events

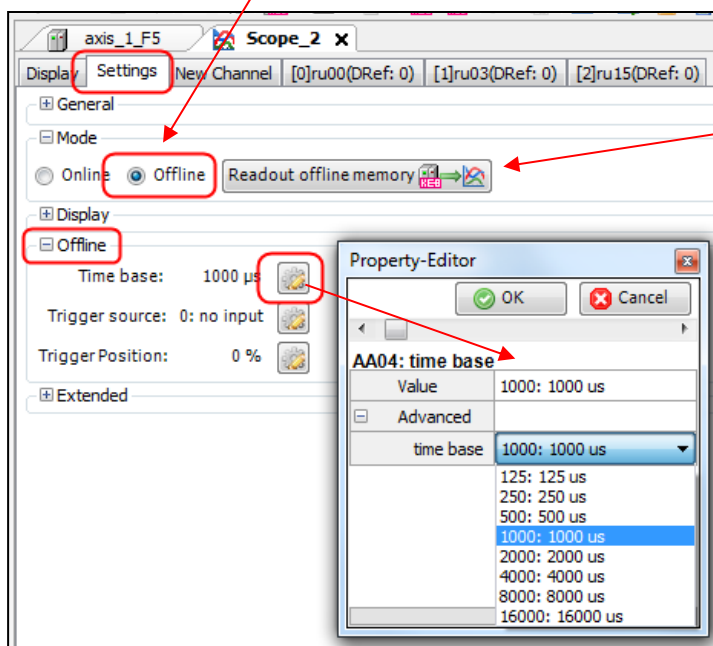
Characteristics:

- Available for COMBIVERT F5 but not F5-Basic, B6, F6, G6, H6, S6 and P6 drive controllers
- Contrary to online mode data won't be readout sequential from the drive controller and displayed but internally saved in the drive controller
- No dependency on communication time, therefore very short frames realizable
- Up to 4 channels in one device will be recorded with chronological synchronism and in a fixed frame (fast Scope mode)
- For data recording a connection drive controller to PC must not be active
- Flexible trigger conditions allow a selective recording of sequences
- Trigger will be released by a digital input.
- Also, after drive controller's power-off the trigger requirement will remain unaffected (only F5-A/M, -S, -H, -K, -L, -P, -E ≥ D-housing). In COMBIVERT G6 the trigger condition will be saved after Power-Off, stored date will be lost. It is possible to trigger intermittent effects over a long period.
- At COMBIVERT F5, B6 and G6 all Parameters are recorded only from set 0.

Note: With **COMBIVERT H6/F6/S6/P6** up to firmware 2.7, the index values of ARRAY and STRUCT parameters cannot be recorded. This function is only possible with COMBIVERT F6/S6 from firmware 2.8.

9.16.1 Switch On and Adjustment of Time Basis

Activating of Offline mode: "Scope" → "Settings" → "Mode"



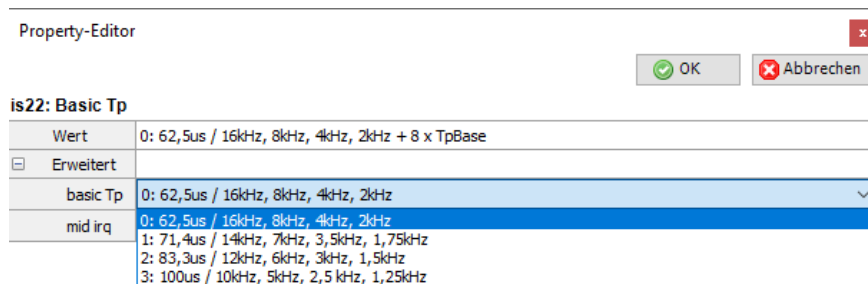
Read out of a stored recording.
Channel allocation will be read out automatically

Adjust scanning-frequency:

Maximum number of buffered values * scan time = stored time.
That means: the smaller time base the shorter recorded time.

Max. quantity of values depends on controller's data space (=>: [9.16.5 Offline-Storage Capacity](#)).

Note: For **COMBIVERT H6/F6/S6/P6/T6** the sampling rate depends on the setting in parameter is22 / time base Tp. Only multiples of the time base set in is22 can be used (rounded if necessary).



9.16.2 Adjusting of Trigger Source

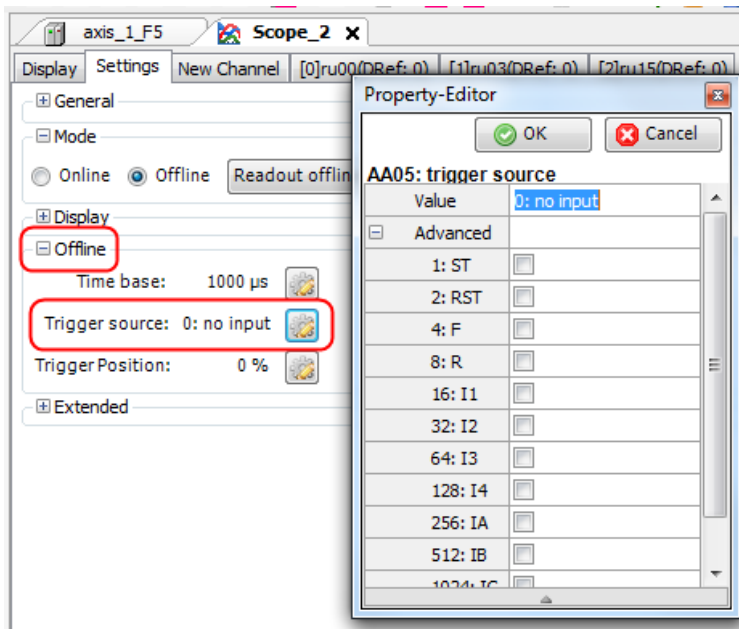
Digital inputs act as trigger source.

The activation of inputs initiates a saving of the scope recording.

Via software inputs IA ... ID complex trigger requirements can be indirectly realized by outputs OA ... OD (COMBIVERT F5/B6/G6).

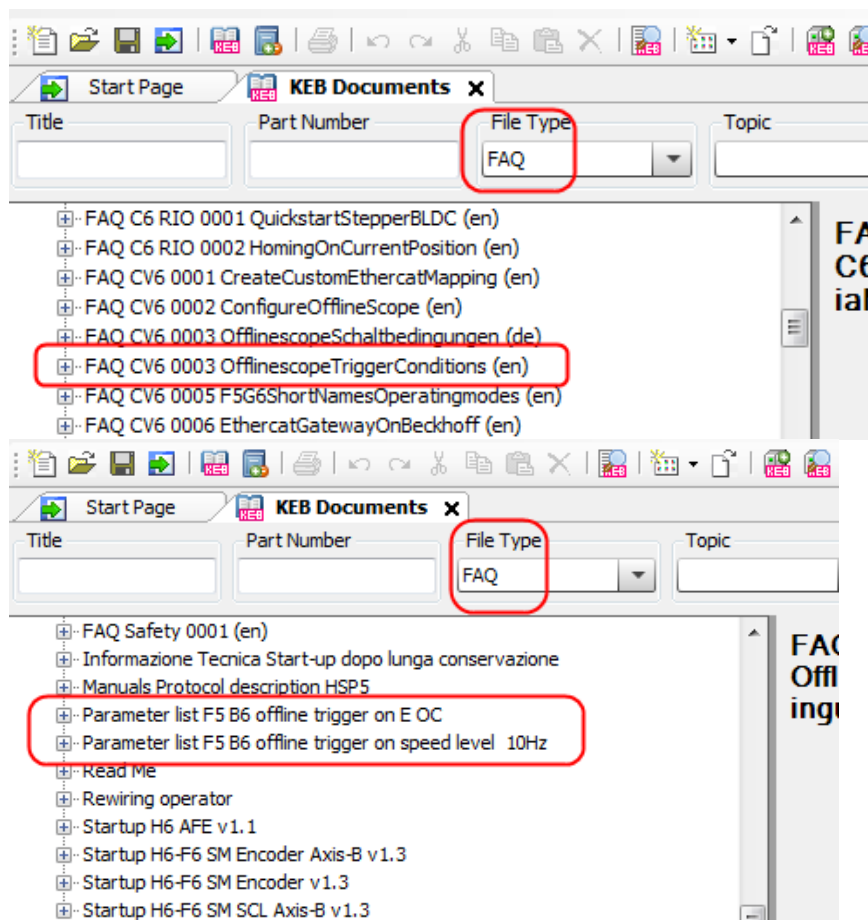
E.g., setting "F" for recording of acceleration

Or: by Out switching condition: "current > level" to input IA



Sample for COMBIVERT F5 (similar at G6):

A description and 2 samples can be found by menu "Help" → "Show "FAQ" Documents" → "FAQ CV6 0003 OfflinescopeTriggerConditions (en)". Also 2 sample parameter lists are included.

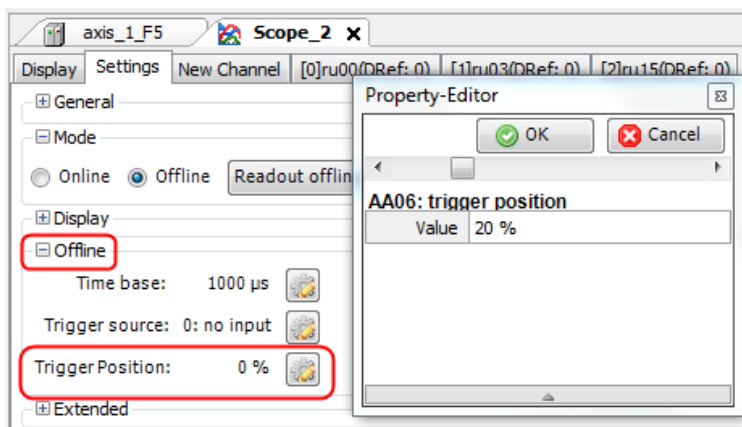


9.16.3 Adjusting of Trigger Position

Trigger position defines how many percent of the complete recording period before trigger event shall be displayed.

Example 20%:

= 20% of recording indicate the period before the trigger event.




Remark:



When the recording is started, the offline memory (ring memory / drum storage) is filled with values. Until the memory has finished the first loop values from previous records can be in. If, after the start of the recording,

the trigger still comes within the first “round” and has only a little delay, it may be that the previous values have not yet been overwritten and are displayed.

9.16.4 Applying Offline Mode

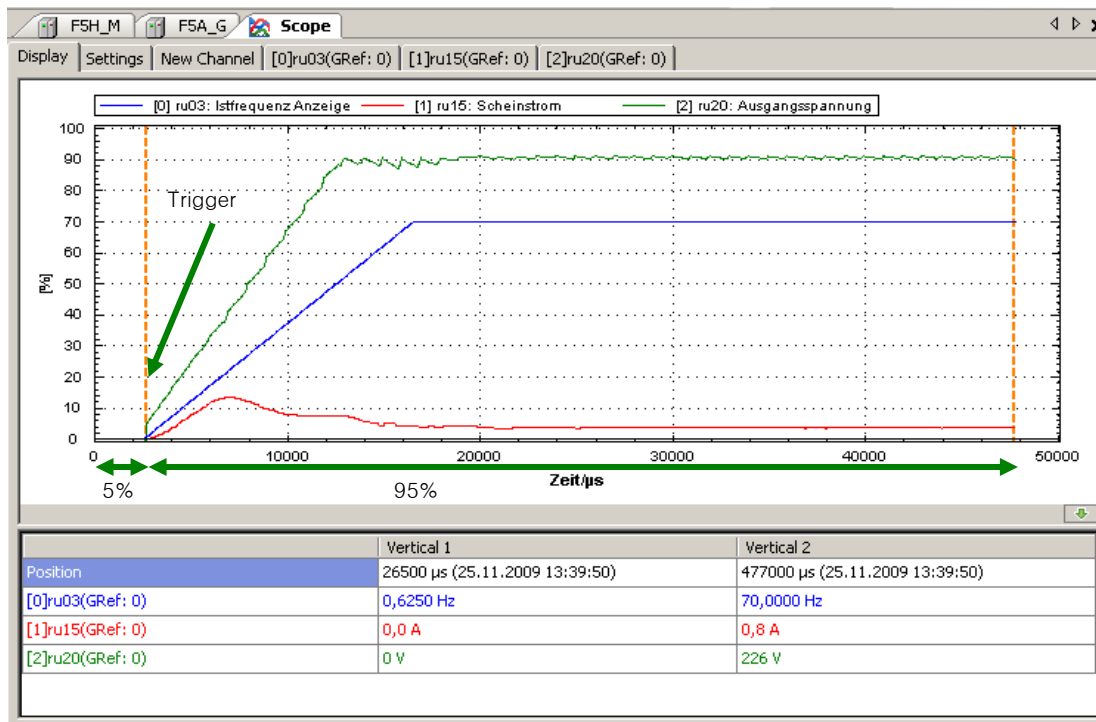
- Start offline recording via click on start/stop button  or tap key “F9”.
- In the bottom of the scope-window the flashing code “wait for trigger” appears. The drive controller waits for the trigger event.
- The code will change into “data recording” as soon as the trigger event occurs. The recording will be realized and saved.
- If the saving process is finished, the code will change into “offline data readout”. The saved data will be red out by Scope and displayed.
- After reading out the diagram can be handled like in online-mode.

Recording without connected PC and read out afterwards

- Start offline recording by start/stop button  or tap key “F9” → at the bottom of the display is shown blinking “Wait for trigger” → the device is waiting for the trigger condition
- Close COMBIVIS 6 without stopping the scope, if applicable save project.
- When the first trigger condition occurs, the curves will be saved in the device’s storage. Further will be ignored.
- Connect cables as shown before → start COMBIVIS 6 with the respective or with a new project → if needed get connection to the device → at “Scope” → “Settings” click on:  → the saved data will be read out of the device and displayed in Scope.
- The saved data will be erased at F5-A/-S/-E/-H; ≥D-housing only by a new starting of offline recording. The drive controller can also be switched of in the meantime. At G6/ H6/ F5-A-Servo (A-Housing) trigger requirements and saved data will be erased also by switching off the device or by overwriting.

For example:

Time base: 500µs / trigger source: F / trigger position: 5%



9.16.5 Offline-Storage Capacity

E.g., in KEB COMBIVERT F5.A Version 4.2: ≥ D-housing:

For 1x or 2x 16-bit-parameters: approx. 1900 values/channel

For 3x or 4x 16-bit-parameters: approx. 950 values/channel

For 1x or 2x 16- and 1x or 2x 32-bit-parameters: approx. 470 values/channel
(32-bit-parameters are e.g., position, torque, and control / status word long...)

Therewith 4 channels with 16-bit in 0.5ms time basis give approx. 0.47s recording time.

For the other drive controllers this might differ strongly.

For example: a KEB COMBIVERT G6-G has approximately 20% more space. COMBIVERT F5-C has approx. 70% less and COMBIVERT B6 approx. 86% less.

10 Start-up Assistants (Wizards)

Start-up wizards are tools for an easy creating of parameter lists and parameter adjustments.

Two procedures of start-up wizards can be found:

- Online start-up wizards – all adjustments are done directly in the device.
- Offline start-up wizards – creates a parameter list, which can be stored or directly downloaded to the device.
- Only the compatible wizards will be offered in the project.
- For “generation 5” drives (type F5, B6, G6) online and offline wizards can be found.
- For “generation 6” drives (type F6, H6, P6, S6, T6) an online wizard is offered. It can be used offline partly. At next connection to the drive the values will be transferred to the drive.

10.1 Online Start-Up Wizard

Online wizards need a connected device because all adjustments are done directly in the device parameters.

10.1.1 Online Start-Up Wizard COMBIVERT F6/ H6/ S6/ P6/ T6.

For the new “generation 6” drive controller a step by step start-up online wizard is implemented. It can be used also offline but then not all features can be handled.

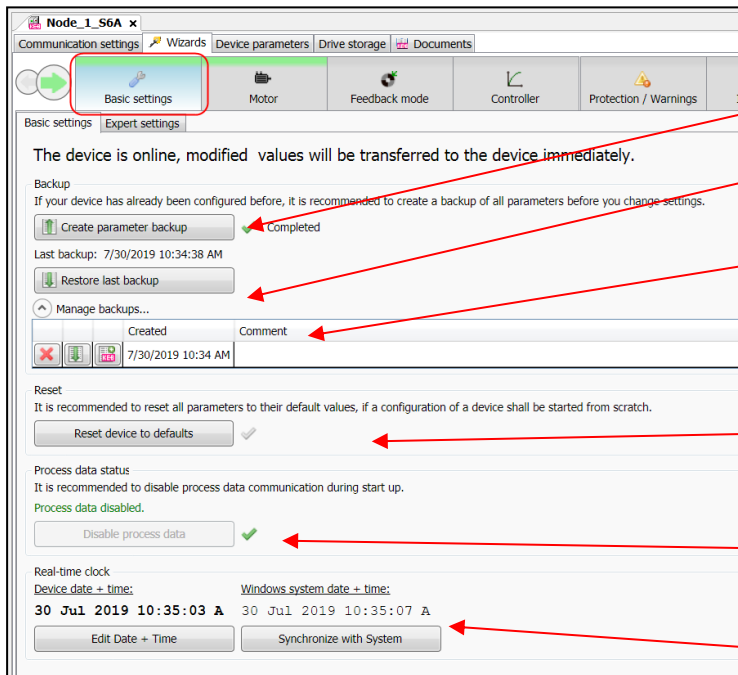
The idea is to start-up the drive with handling of all necessary adjustments step by step.

Depending on the functions available in the device type, parts of the wizard are masked.

For each function card there is a tab “expert settings”. There, the parameters belonging to the respective function are listed directly and allow advanced settings. The normal user is passed over it and normally does not need to set anything.

10.1.1.1 Basic Settings

- Backup / restore to backup
The backup is saved with the project. A saved backup file can be exported as parameter list to the navigator and from there exported out of the project.
- Device reset to factory default:
At reset the CPU is restarted, so COMBIVIS loses contact for a short time.
- Process data disabling, reconnect with former adjustments:
With active process data, the controller can overwrite certain parameters again and thus make a manual adjustment impossible. This function only works with COMBIVERT F6-K, S6-K and H6.
- Device clock:
The clock has no runtime reserve, also no connection to the clock of the safety module (option).



Create backup

Load backup to the device

Delete backup, download to the device or export to the navigator as parameter list

Set device to default

Disable process data (only F6–K, S6–K, and H6)

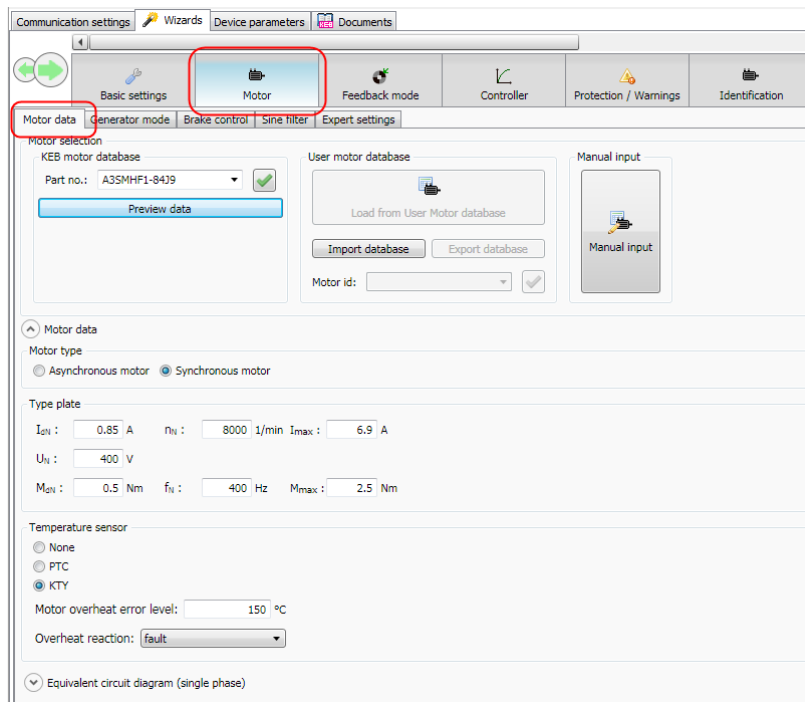
Set clock, manually or by PC clock

10.1.1.2 Motor

- Can be used for synchronous and asynchronous 3-phase motors
- Data of KEB Motors can be chosen by Part. No.
- Motor data can be adjusted manually, and the data can be stored in a motor data base (after identification in window "Identification")
- Data from user motor database can be chosen.
- User data base can load or exported
- Adjustment of braking transistor
- Adjustment of temperature sensor type and fault reaction
- Data of brake and sinusoidal filter can be adjusted optimally
-

Leaving of the window "motor" activates the motor data in the drive controller.

Start-up Assistants (Wizards)



10.1.1.3 Feedback Mode

Adjustment of

- Feedback mode (v/f-mode/open loop, closed loop, encoder less closed loop)
- Encoder interface
- Encoder type and data
- At encoders with electronic type plate motor the data can be read out of the encoder (KEB Motor)

At synchronous motors, the v/f-mode is not available

Communication settings | Wizards | Device parameters | Documents

Basic settings | Motor | **Feedback mode** | Controller | Protection / Warnings | Identification

Wizard | Expert settings

Control mode

V/f mode V/f mode is not recommended for synchronous motors.

Encoder with motor model

Encoderless (SCL)

System inversion

Inversion enabled

Inversion disabled

Speed control source

Encoder A

Encoder B

Position control source

Encoder A

Encoder B

Estimated Position

Encoder A

Encoder type: Hiperface

Invert position and speed

Encoder mounting position: 10923

signal periods per revolution: 128

Electrical type plate

Read Write

status encoder r/w: idle

Detected encoder type: Hiperface SKM 36 Multiturn

Status encoder interface: position value ok

Error encoder interface: no error

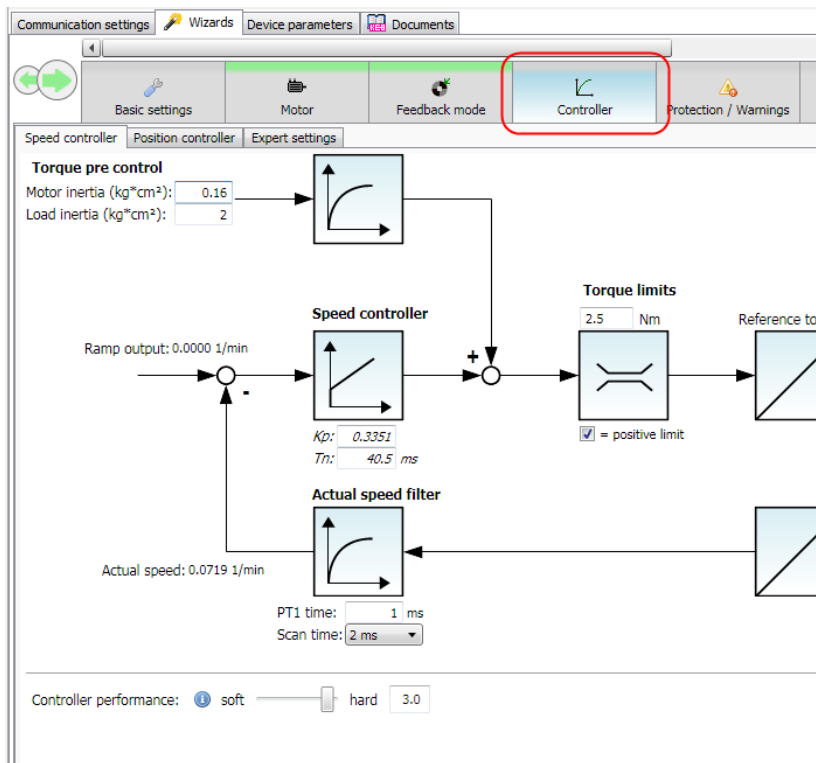
Warning encoder interface: no warning

Confirm

10.1.1.4 Controller

- Adjustments for speed controller
- Adjustments for position controller and position feedback.
- Pre adjustments depending on the inertia of motor and machine.

Start-up Assistants (Wizards)



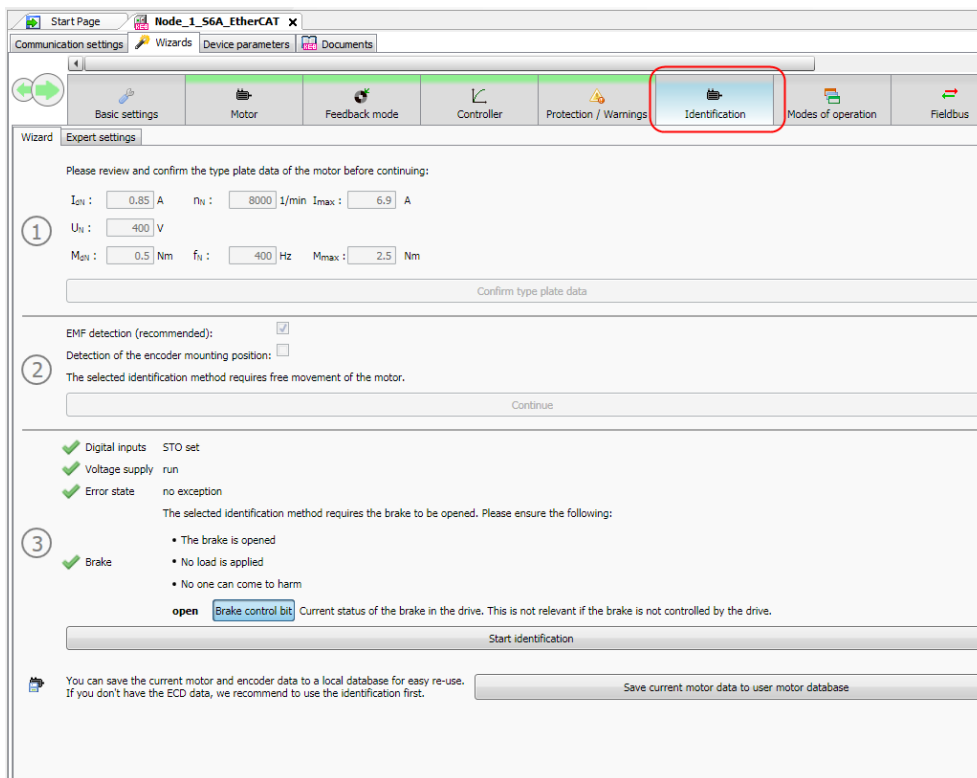
10.1.1.5 Protection / Warnings

- Adjustments for status word
- Adjustments for warning levels
- Application dependent warnings
- Adjustments of error reaction ramp

10.1.1.6 Identification

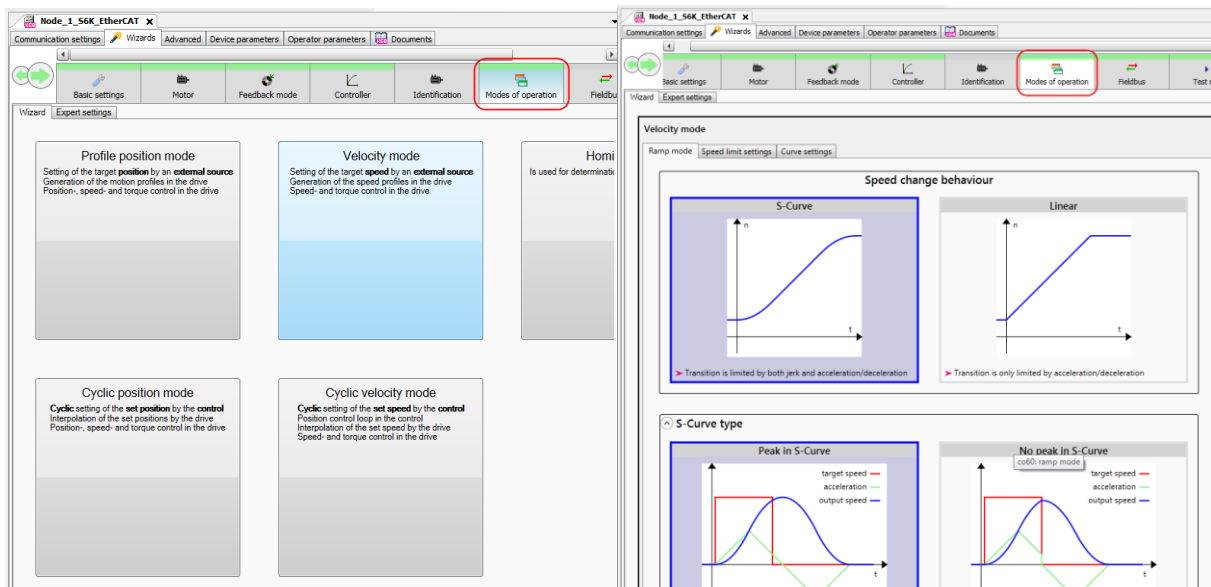
- Guided motor data identification
- Must not be done at KEB motors selected by KEB Motor database
- Identified motor data can be stored in user motor database

Start-up Assistants (Wizards)



10.1.1.7 Modes of Operation

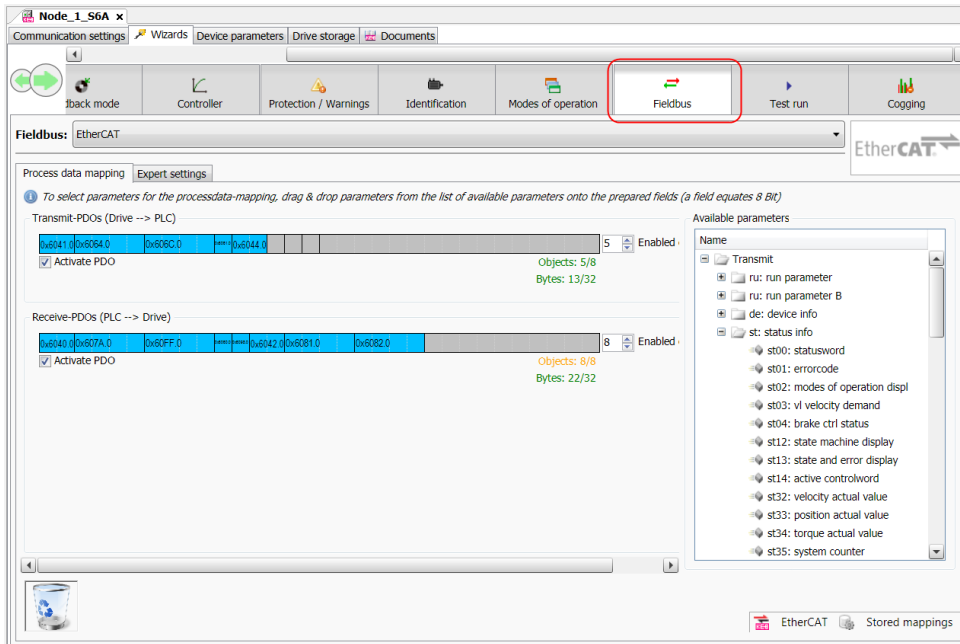
- Mode of operation regarding CiA 402 can be chosen.
- Adjustments depending on the chosen mode can be done. E.g., ramp mode, s-curves, speed limits, position curve settings, homing methods...



10.1.1.8 Fieldbus

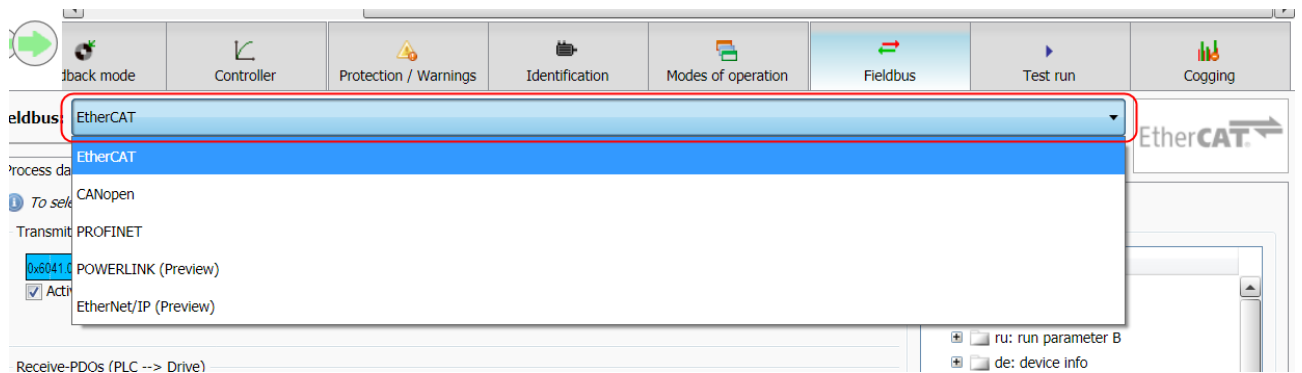
- Selection of bus system

- Size of process data
- Process data adjustments
- Bus diagnosis
- Create and export of device description
- Save and handle of self-created mappings

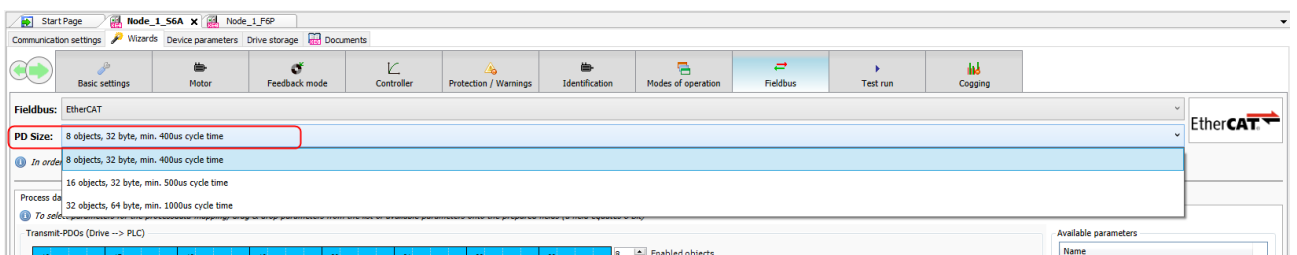


Selection of the bus system:

Depending on the hardware of the device the bus type can be selected:

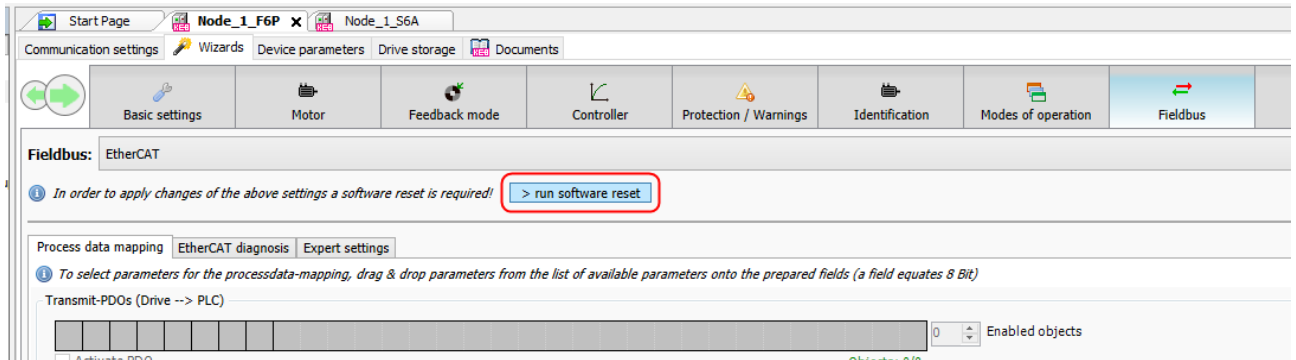


At EtherCAT and Profinet the process data size can be chosen (depending in firmware version):



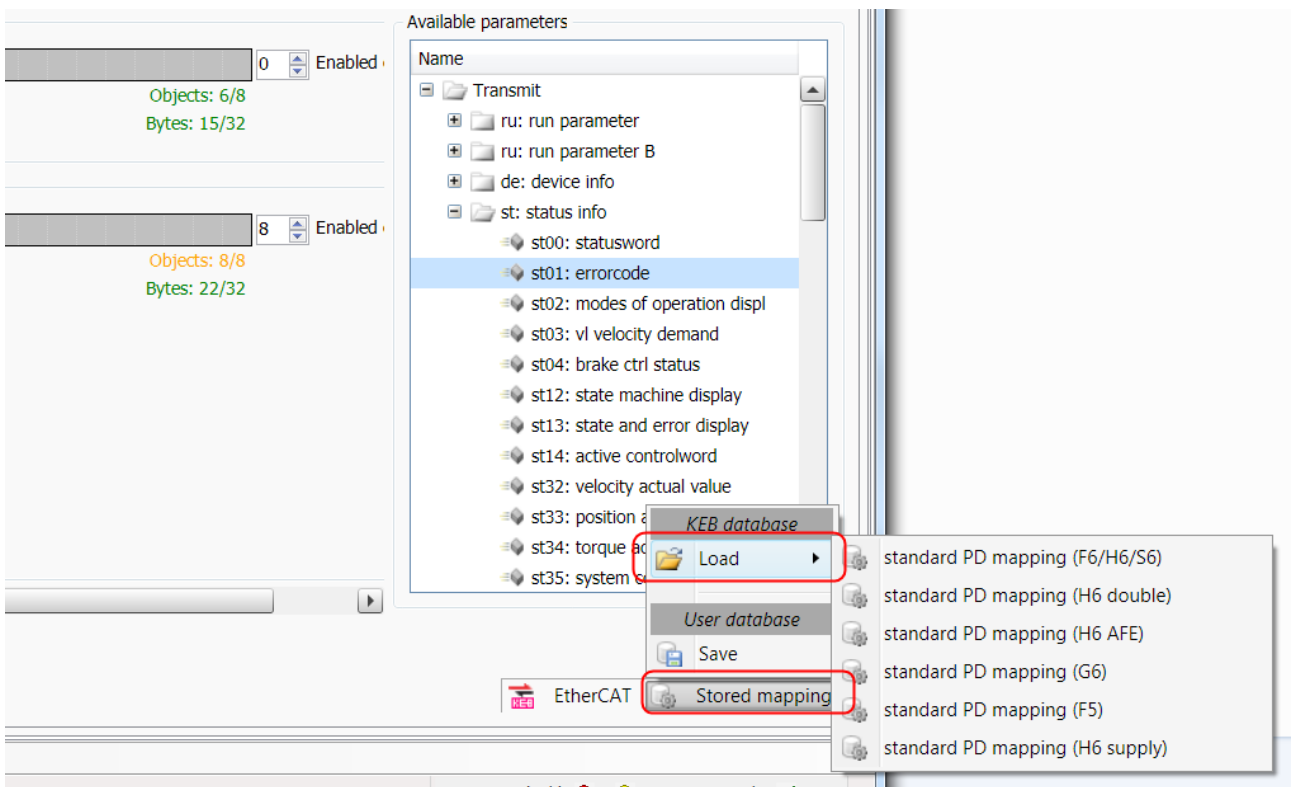


➤ If the bus type is changed, an error is triggered in the drive (ru01 = Error! fieldbus type changed). The change must be confirmed by pressing the "software reset" button or a power-on reset of the unit. Only then will the change be accepted!

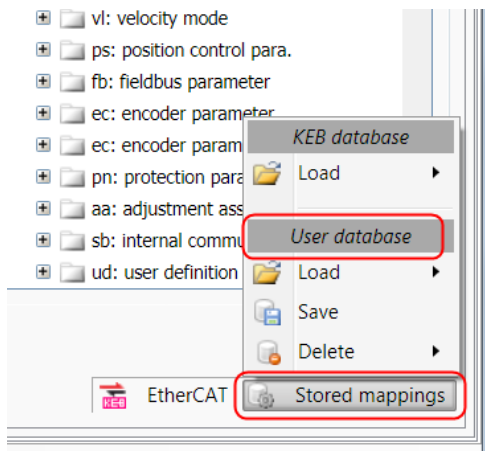


Assignment of process data:

The wizard offers a standard process data assignment:
 "Stored Mappings" → "KEB database" → "Load" → select device type
 The process data will be loaded and activated.



A customer specific assignment can be stored in the user data base and can be reloaded.
 "Stored Mappings" → "User database" → "Load/Save"



Manual assignment:

The process data must be disabled!

The right-hand window lists the parameters available for process data.

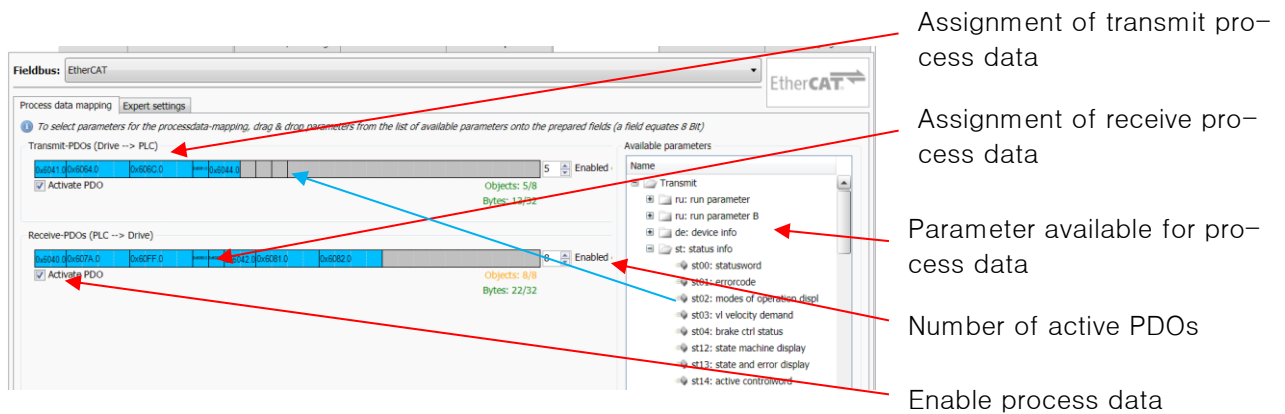
These can be copied with the mouse to the Transmit PDO field or the Receive PDO field using drag & drop.

The data length is taken over correctly.

Parameters can be deleted by dragging them to the waste basket at the bottom left via the mouse or marked and using the “Delete” key.

“Read only parameters” cannot be dragged into the Receive PDO field.

The number of transferred objects can be restricted. This allows certain objects to be excluded from data exchange from right to left.



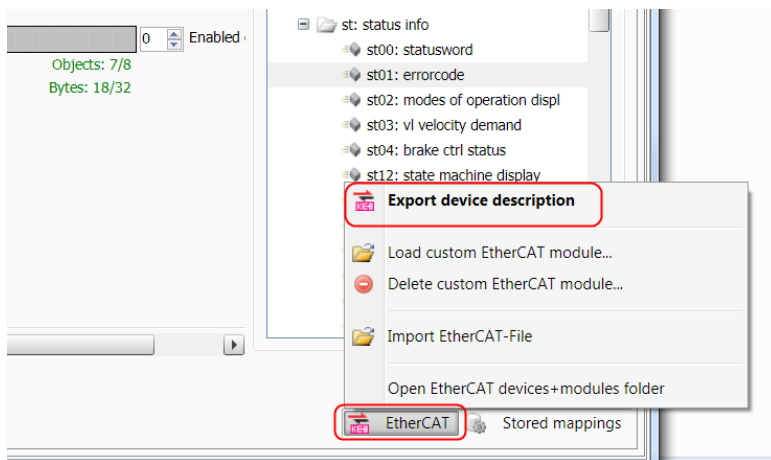
Device description file:

With the wizard, the device description file can be generated depending on the selected bus type. At CAN and EtherCAT, this contains the current process data assignment.

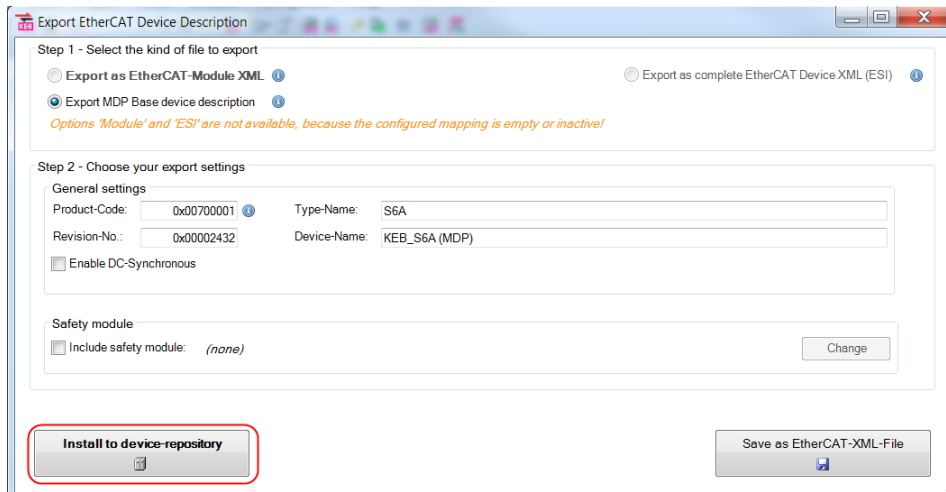
EtherCAT EDS:

“EtherCAT” → “Export device description”

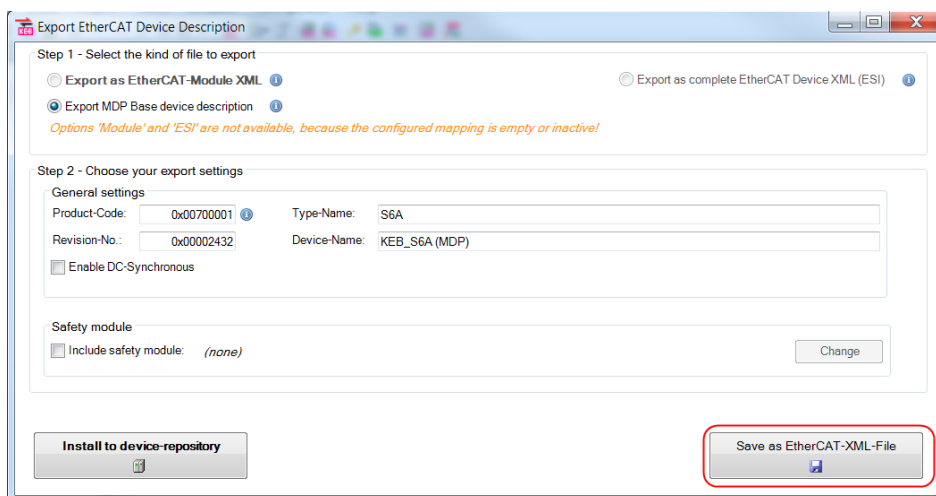
Start-up Assistants (Wizards)



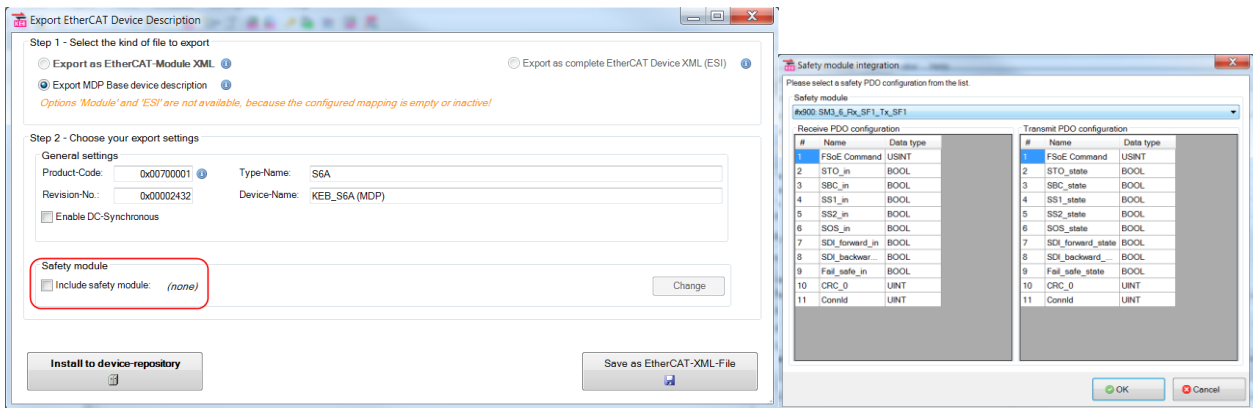
If the KEB COMBICONTROL is available, the description can be loaded directly:



For an EtherCAT PLC this can be generated and saved:

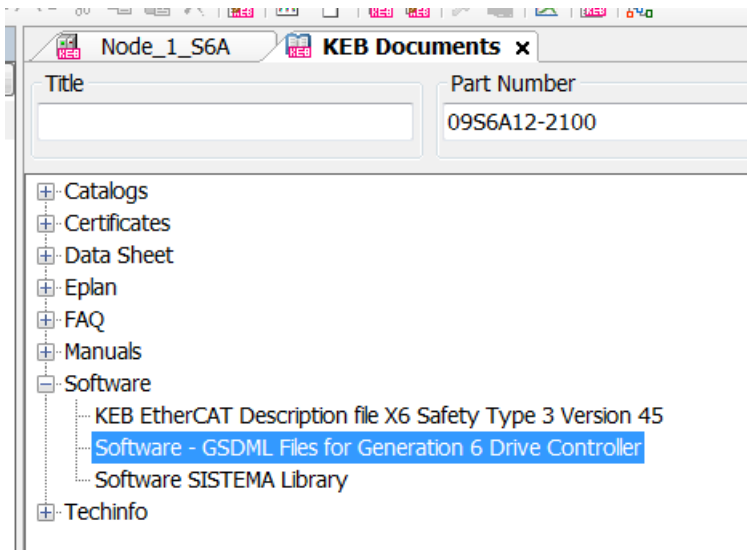


The FSOE process data description can additionally be selected for the KEB Safety Modules: (=> manual of the respective device)



Profinet:

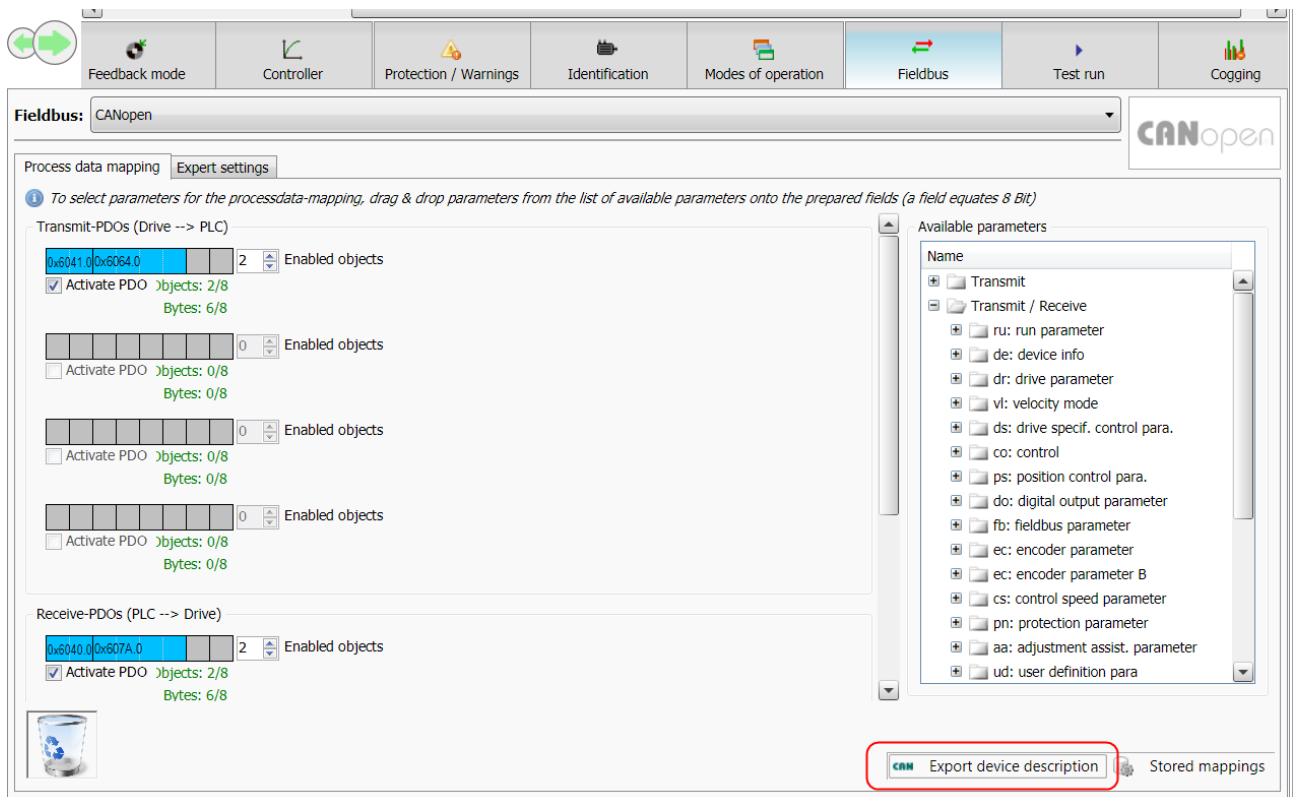
The device description file GSDML can be found in the KEB document database in the "Software" area under the part number of the COMBIVERT:



CAN EDS:

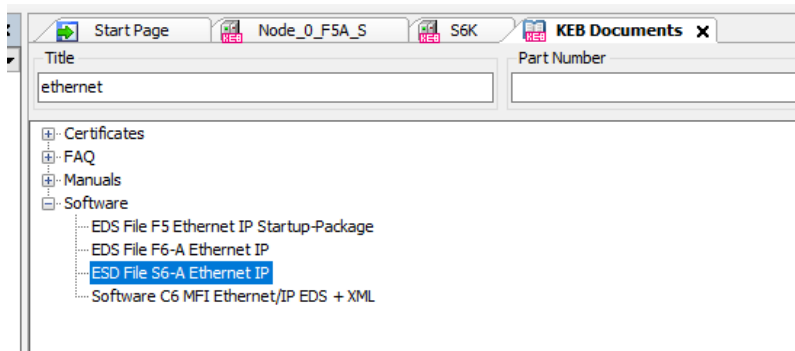
In the CAN process data wizard, an EDS device description file can be created and saved:

Start-up Assistants (Wizards)



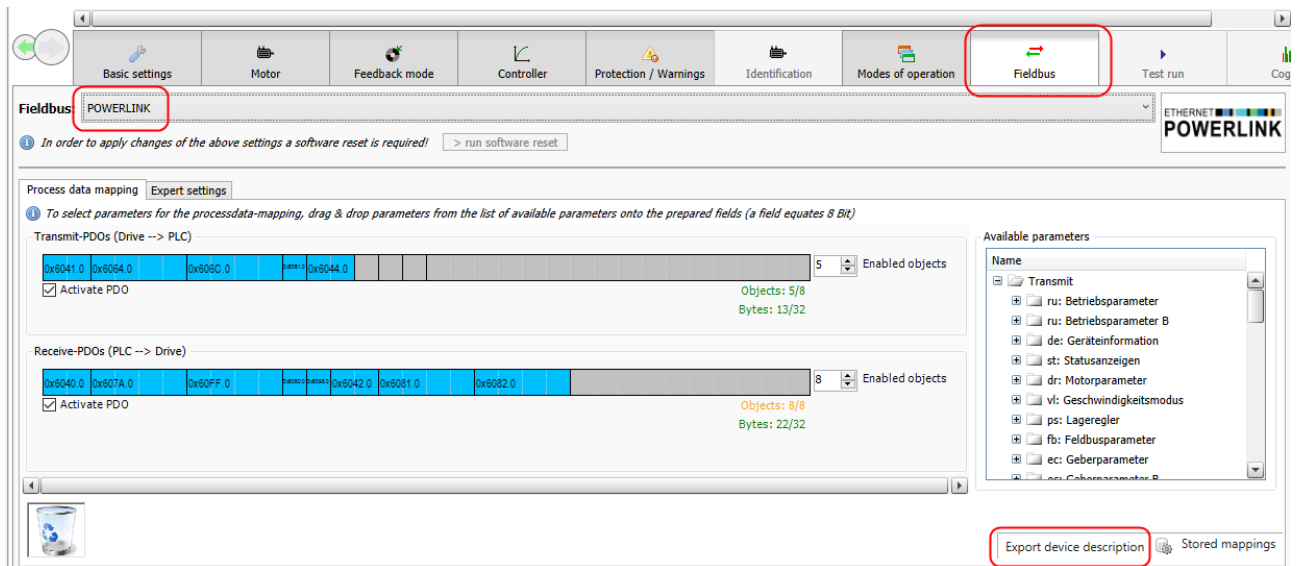
Ethernet IP EDS:

The EDS device description file can be found in the KEB document database in the "Software" area under the part number of the COMBIVERT or the term "Ethernet":



Powerlink xdd:

In the Powerlink process data wizard, the xdd device description file can be created and saved:



10.1.1.9 Test run

The Test run wizard can be opened in a separate window.

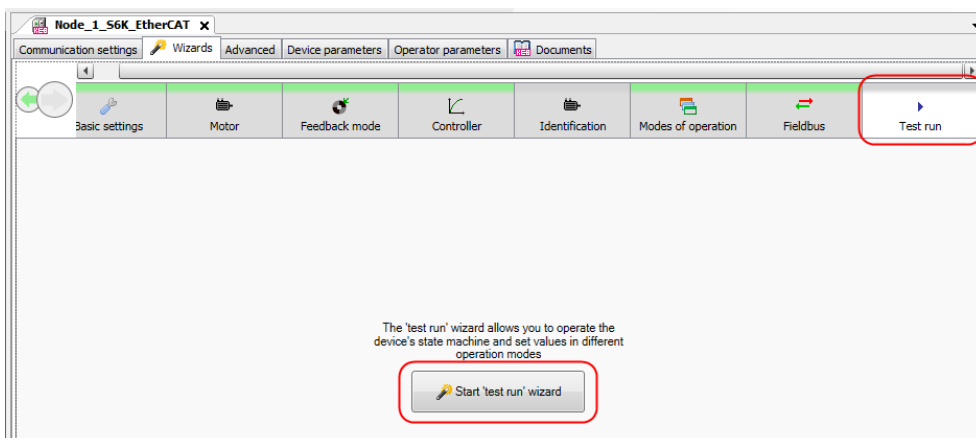
It enables a motor run or positioning step from the PC, without having to have a separate control. Likewise, the state of the state machine is graphically displayed.



The test run wizard does not have any watchdog functionality!

If the communication is lost due to cable interruption or program crash, the drive continues to run with its last set points!

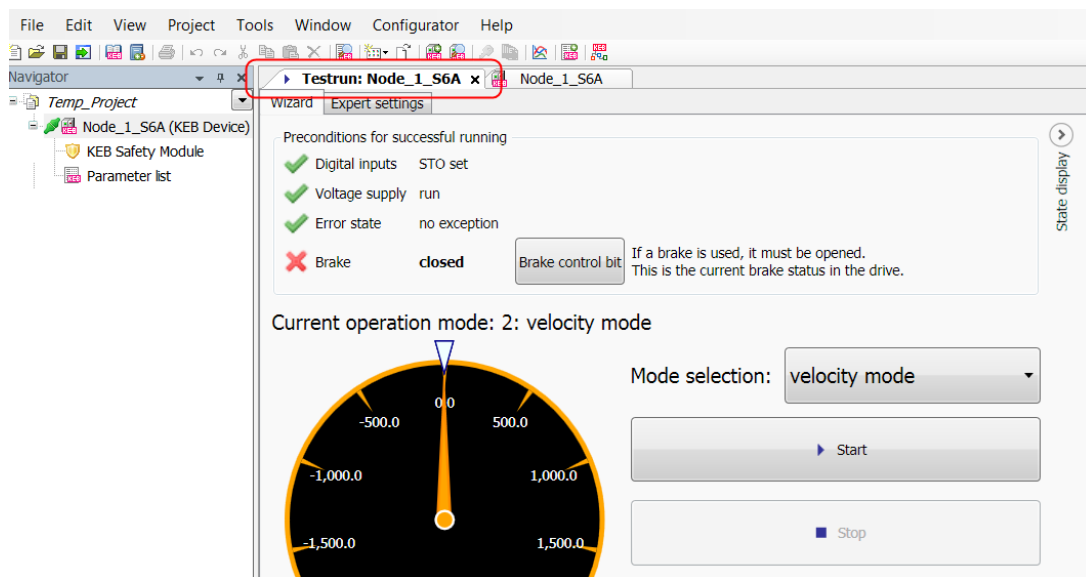
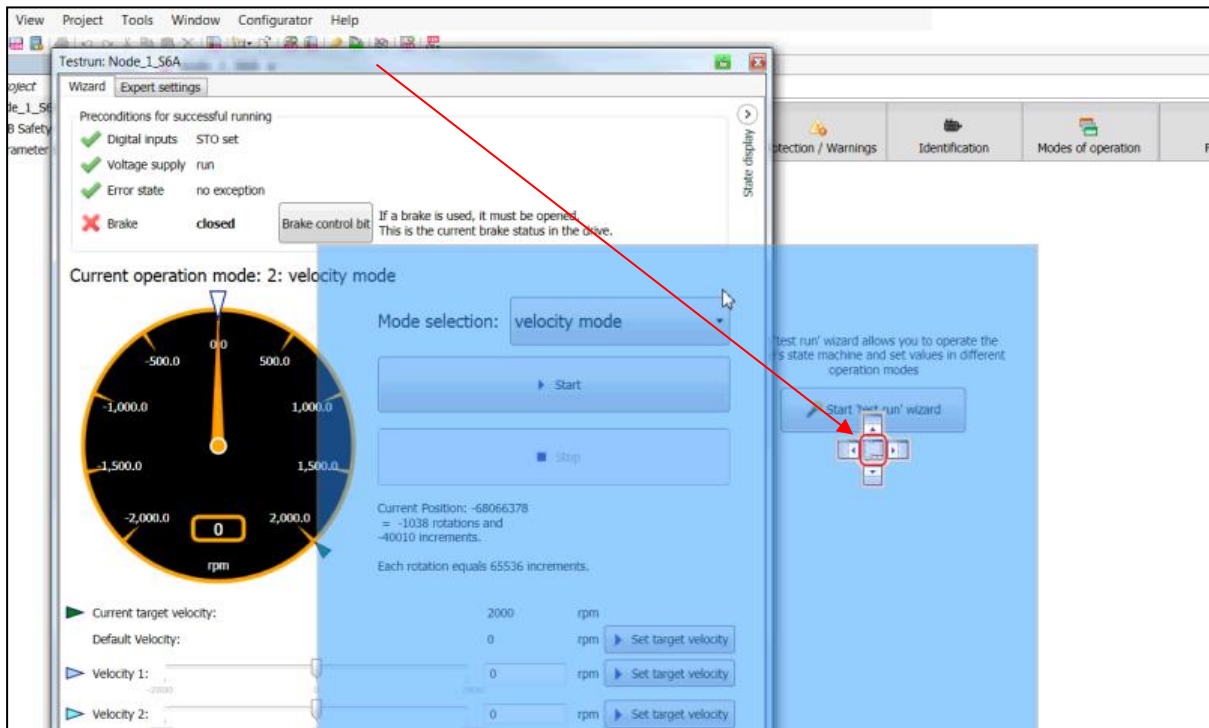
- Therefore always implement a separate, communication-independent, possibility to stop the drive. For example, by a separate, wired switch for control release or STO or mains voltage.



It can be arranged parallel to the device editors. You can then switch conveniently between e.g., Scope and the test run wizard:

Click the header with the left mouse button, hold it down and move the mouse pointer to the appearing arrangement cross, place it in the middle field and release the mouse pointer.

Start-up Assistants (Wizards)

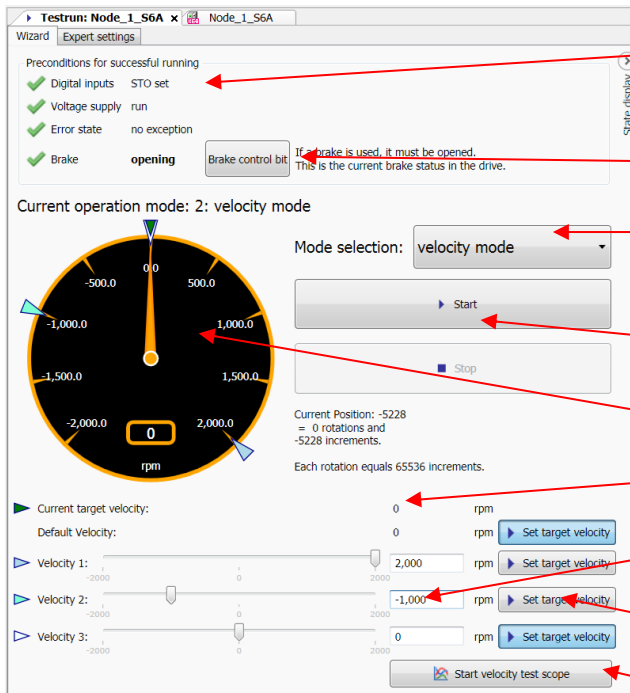


State machine

The view for the state machine can be opened with the field "status display" arranged in the top right corner.

Velocity mode:

- pre-set of 3 speeds
- setting of control word
- setting brake control bit
- start of pre-set scope



Display of current state like STO, fault, supply

Switch brake – Bit 15 in control word (parameter co00)

Adjustment of drive mode (parameter --04)

Start / Stop – Enable operation in the state machine

Actual speed

Actual set speed (parameter vl20)

Pre-adjust target speed, += right, -= left direction

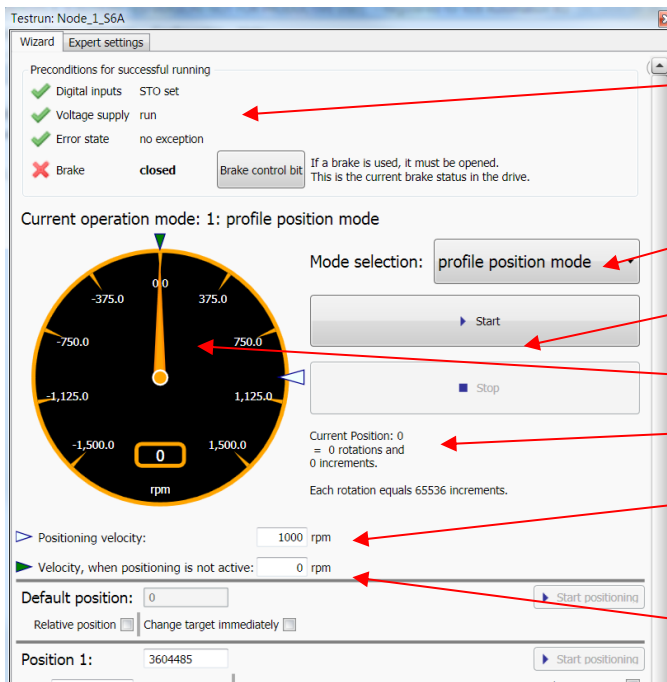
Activate pre-adjusted speed in (parameter vl20)

Start pre adjusted scope

Profile position mode

The drive can be moved in relative or absolute position profile:

- pre-set of 4 positions
- setting of control word
- setting brake control bit
- start of pre-set scope



Display of current state like STO, fault, supply.
Switch brake – Bit 15 in control word (parameter co00)

Adjustment of drive mode (parameter ps01)

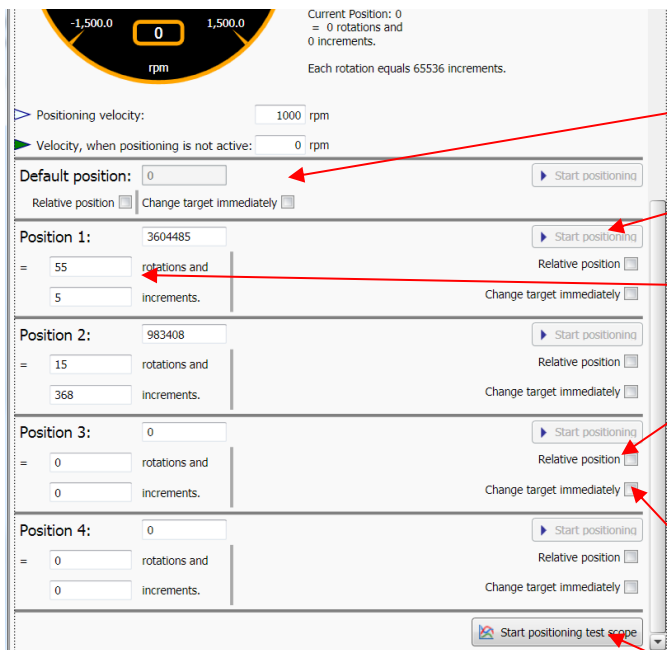
Start / Stop – Enable operation in the state machine

Actual speed

Actual position of the drive

Positioning speed for the next profile (parameter ps30)

If the drive must stand still before start of the positioning profile set "0" speed (parameter vl20)



Go to position "0"

Set pre-defined position into parameter co19: "target Position" and start positioning

Pre-defined target position

Hook: Relative positioning
No hook: Absolute positioning

Hook: The profile will be interrupted, and the new target will be headed
No hook: The current positioning profile is ended and then the new destination is activated.

Pre-defined Scope starts

Note: with "relative position" and "change target position immediately = off", a positioning profile is generated with each mouse click on the field "Start positioning" and then processed one after the other!

Homing Mode

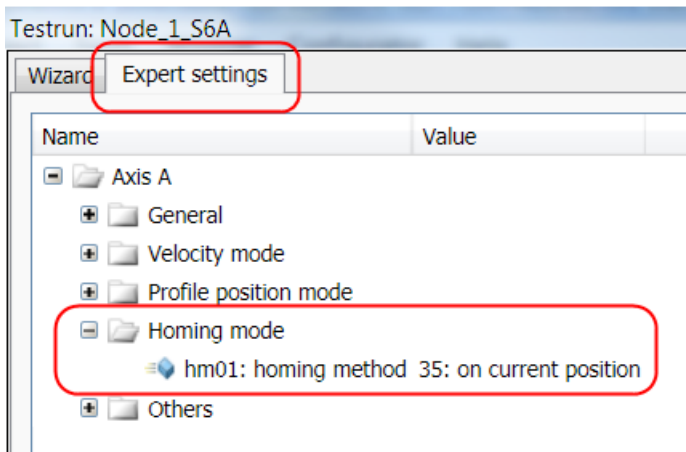
Set the current position to 0

Start-up Assistants (Wizards)

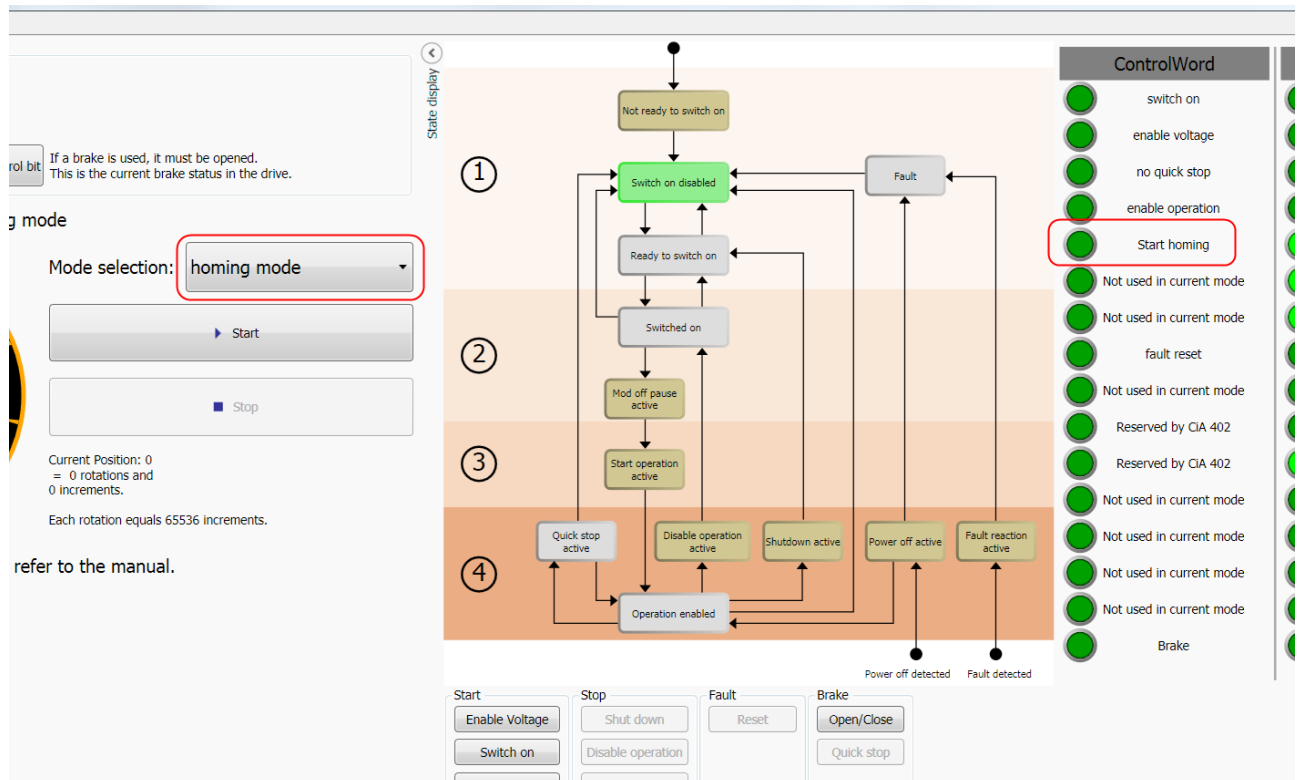
In many cases, the current mechanical position of the drive must / should represent the zero point. How to set the current position to 0:

Set mode to “homing mode”

- The homing method must be set to "35: on current position" (default). The parameter hm01 is included in the expert settings.



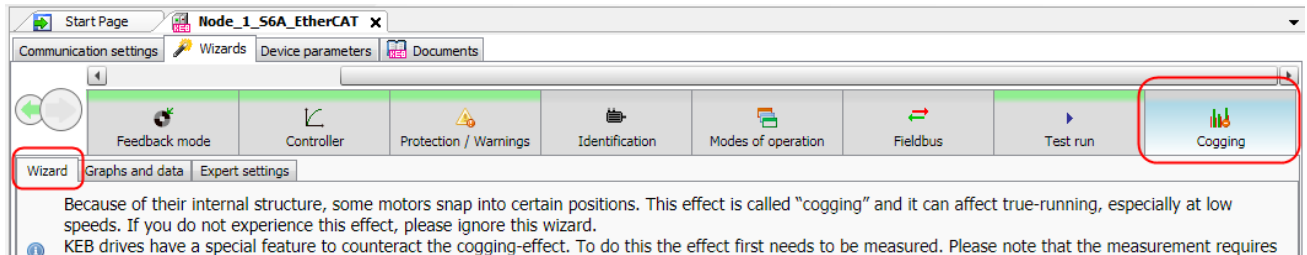
- Enable the bit “Start homing” in the Control Word and disable the bit.



The other modes cannot be used or only with restrictions by the test run wizard.

10.1.1.10 Cogging

The cogging compensation function minimizes the permanent magnet depending unequal speed in the range of low speed. Therefore the wizard measures a torque curve, calculates the offset curve, and saves the values in the drive controller.



- Useful only for permanent magnet linear drives and permanent magnet synchronous motors
- The calibration requires a motor encoder with position signal (e.g., resolver). The function itself can also work without an encoder with a loss of quality.
- The measurement may be done only after optimal adjustment of speed and position controller of the drive controller.
- The motor must run without load!
- Depending on the motor size and construction pre-adjustments in the wizard may be changed.
- During measurement, no value may be changed manually or by bus system
- The wizard uses the profile position mode
- The measurement takes 20-30 minutes
- After ending of the measurement, the result must be transmitted to the drive controller and the function must be enabled.
- The measurement procedure can be interrupted. If no value is transmitted and activated there is no influence on the drive controller.

The **"target reached"** mode controls the measurement via a positioning profile and ensures that really each measurement position is approached. That provides an accurate result but requires well-adjusted speed and positioning controls.

The **"time-based"** mode controls the measurement over a time sequence of measurements, regardless of whether the position has been reached or not. The result is not so accurate, but works more easily, because the movement does not have to be so precise.

Start-up Assistants (Wizards)

Start Page Node_1_S6A_EtherCAT x

Communication settings Wizards Device parameters Documents

Feedback mode Controller Protection / Warnings Identification

Wizard Graphs and data Expert settings

requires free movement of the motor. Based on the measurement the appropriate steps are calculated. Execute all necessary steps for you. If you want more information about the compensation, click on the 'Expert settings' tab.

Current status:
Inactive, measurement is in progress

Activate compensation

No compensation calculation is available. Please execute a measurement or load measurement data.

Measurement setup

Distance: 131072 Resolution: 128 Inc
= 2 rotations and Steps: 1024
0 increments.
No. of Measurements per step: 5

Measurement trigger:
 Target reached Time based

ps15: positioning window time: 0 ms Wait time: 500 ms

Estimated time: 22 min, 11 s

Measurement status

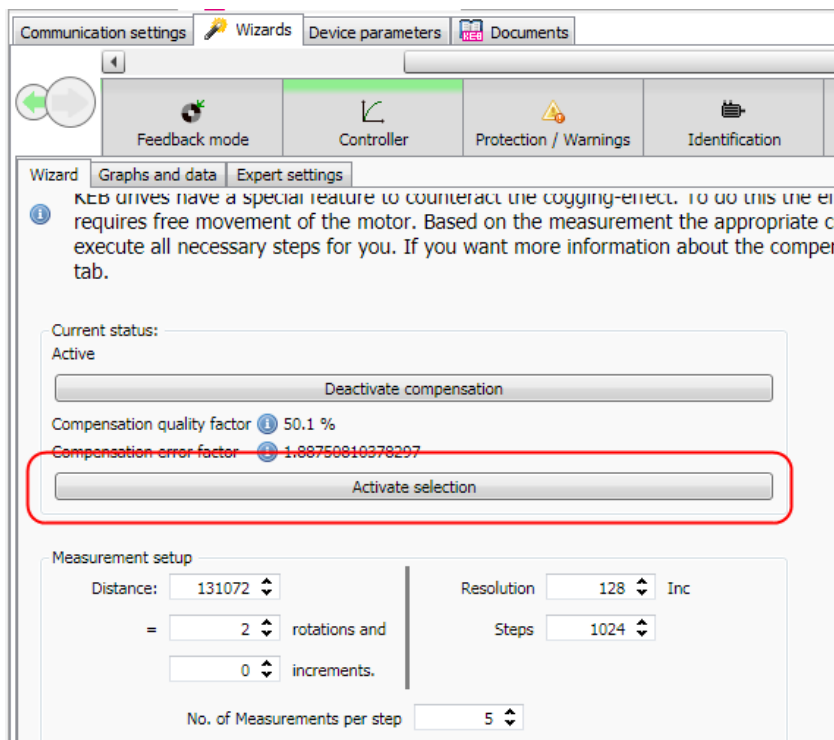
- ✓ Digital inputs STO set
- ✓ Voltage supply run
- ✓ Error state no exception
- ✓ Brake If a brake is used, it must be opened. This is the current brake status in the drive.

Start Measurement Abort

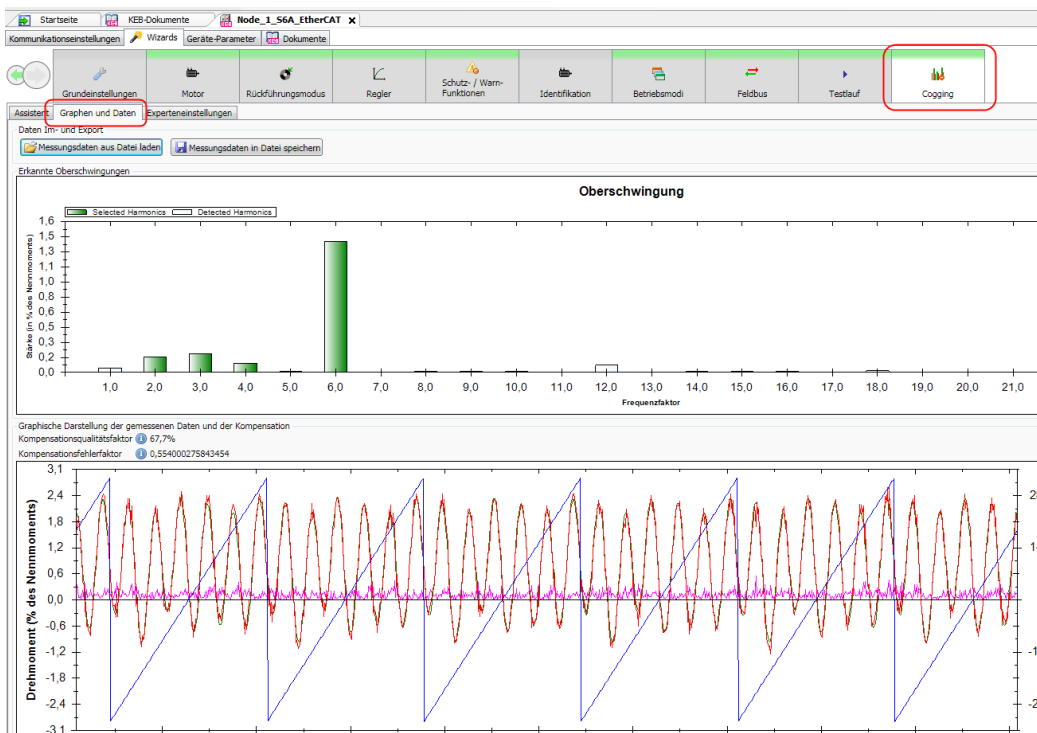
62 / 1024

Estimated remaining time: 19 min, 14 s

After the measurement is done, the data must be transferred to the drive and activated:

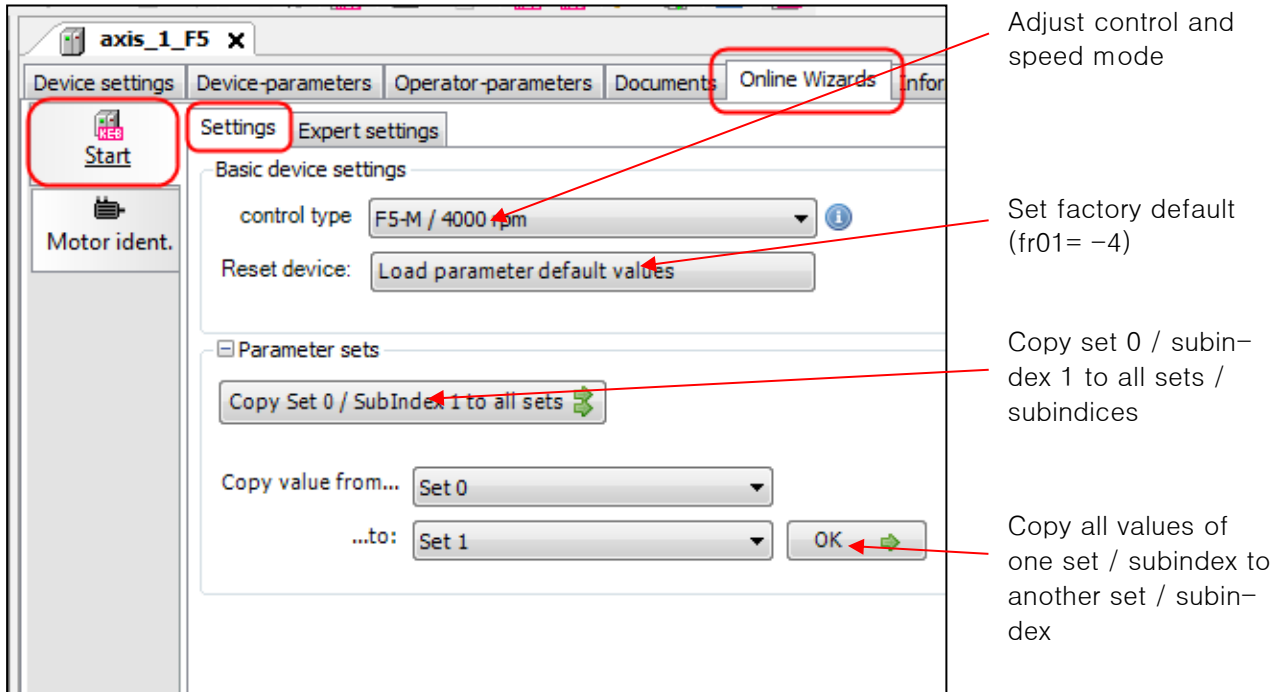


The result of the measurement is displayed in the editor “Graphs and data”. It can be stored in a separate file and reopened later.



10.1.2 Online Start-Up Wizard Basic COMBIVERT F5, B6 and G6.

For all COMBIVERT F5, B6 or G6 a small startup wizard is available:



10.1.3 Online Start-Up Wizard COMBIVERT F5.

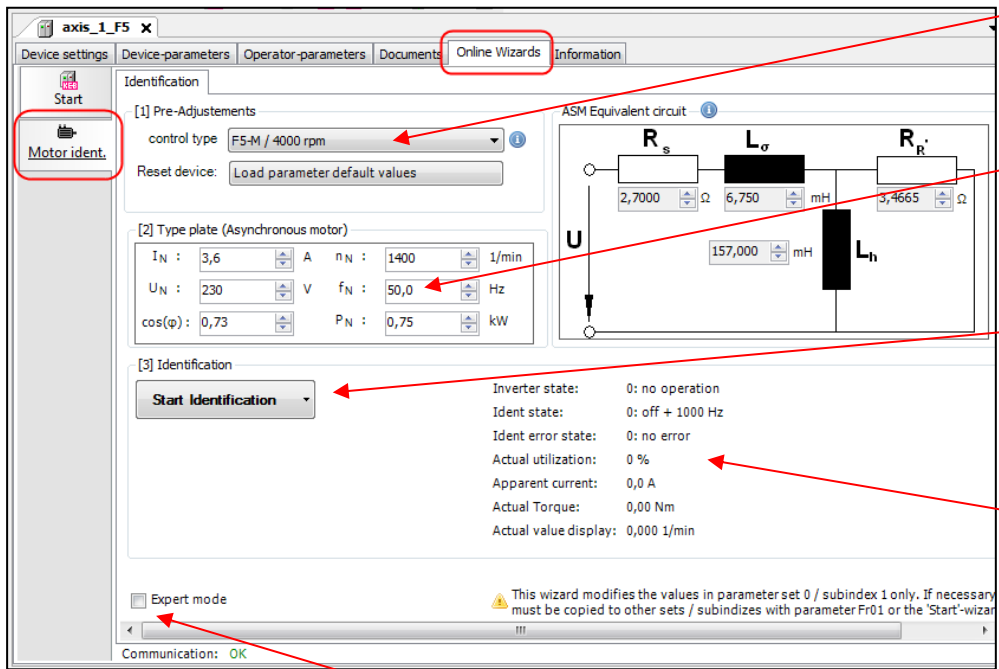
10.1.3.1 Motor Data Identification F5-A/ -K and F5-H/ -L (ASCL)

For driving with asynchronous motors, a wizard for motor data calculation and measurement is available. It works only with F5-A/ -M/ -K from V4.3 or F5-H /-L from V2.3. A standard mode and an expert mode are available. Specific values which are to be changed for measurement (set value...) are saved before and set back after finishing of the measurement.

The description of the motor identifying function can be found in the application manual F5-A (=> [13 Document Database](#)).

The control release terminal must be switched open and close while identifying runs. Switching by software is not possible.

Open in device editor:



Adjust speed mode

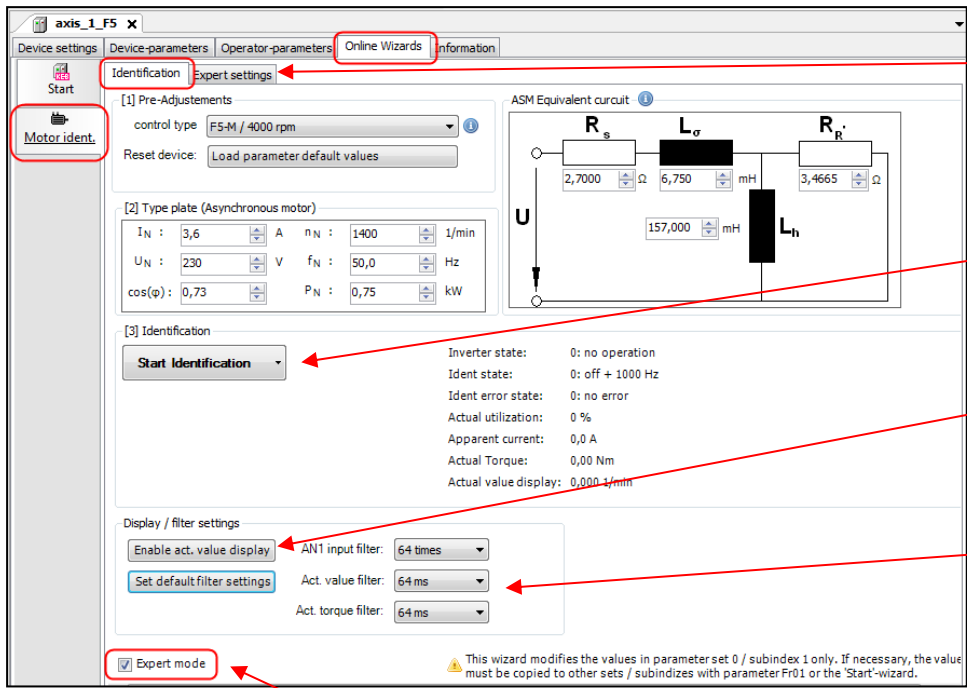
Adjust motor data

Start identification with automatic procedure

Display of actual measured data or status

Enable expert mode

With expert mode some useful adjustments are offered:



Open list with manually adjustable parameters

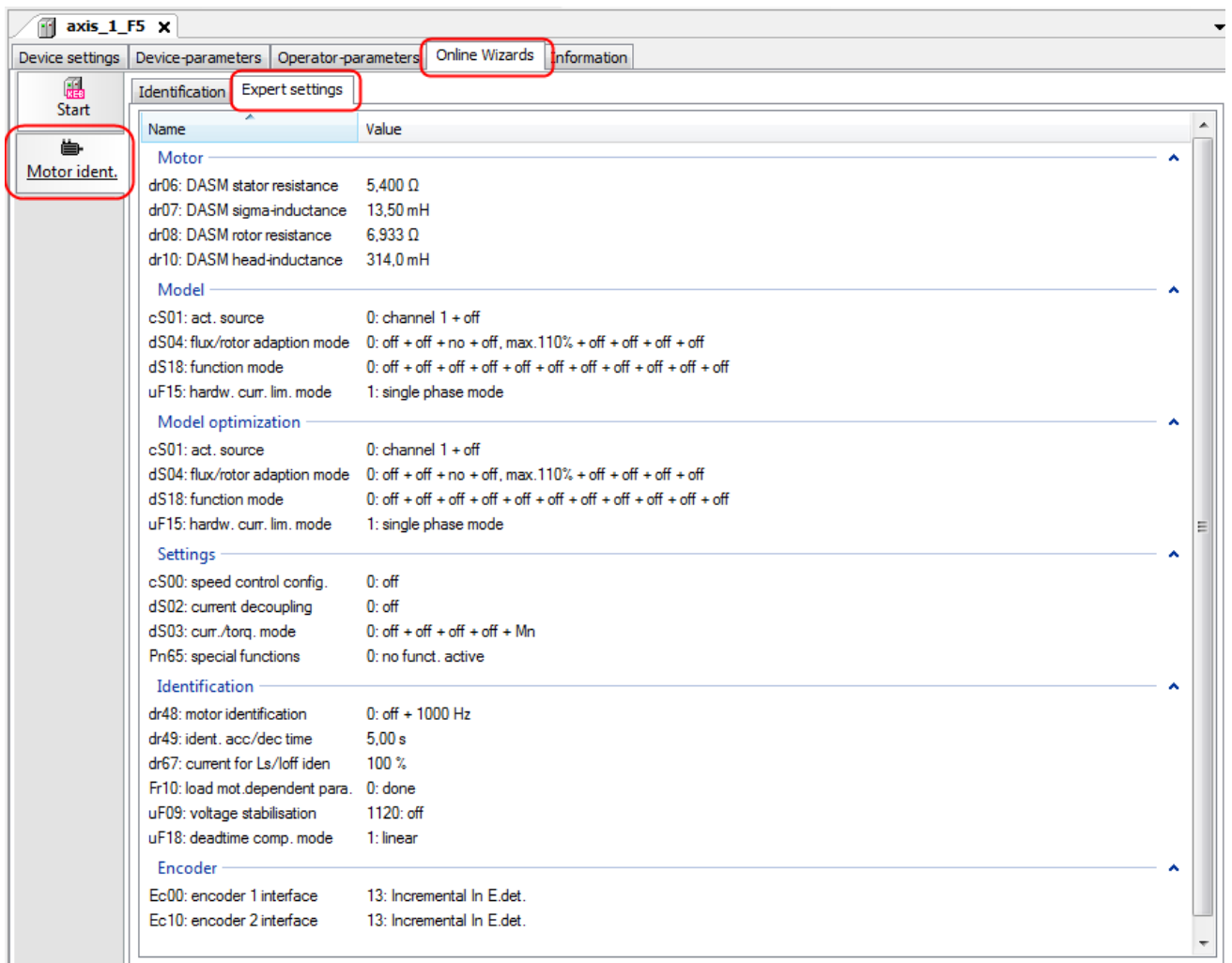
Full selection of identification options

Adopt best settings

Manually adaption of filter settings

Expert mode enabled

In the tab "Expert settings" all relevant parameters are available as an online list and can be adjusted manually if required such as the parameter editor:



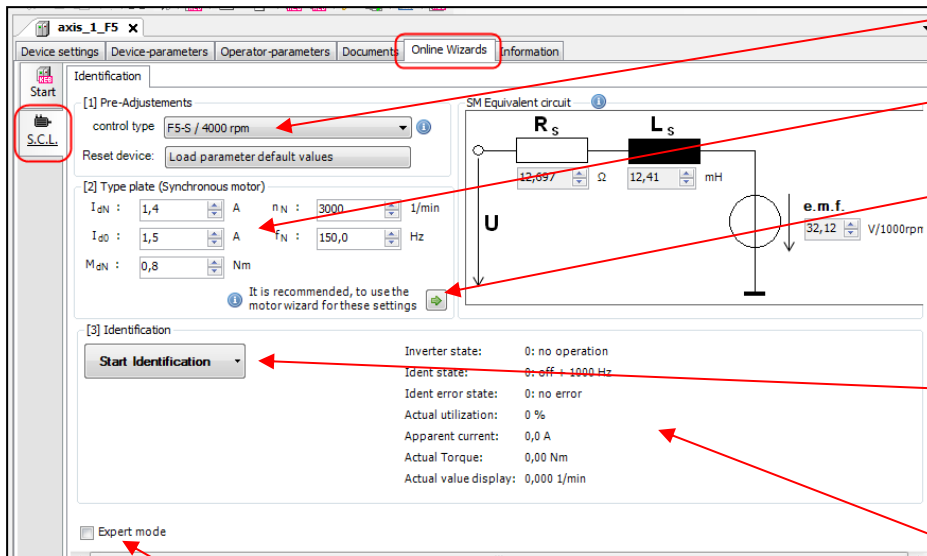
10.1.3.2 Motor Data Identification F5-A/ -S/ -K and F5-E/ -P (SCL)

For driving with PM-synchronous motors with and without encoder a wizard for motor data calculation and measurement is available. It works only with F5-A/ -S/ -K from V4.3 or F5-E /-P from V2.3. A standard mode and an expert mode are available. Specific values which are to be changed for measurement (set value...) are saved before and set back after finishing of the measurement.

The description of the motor identifying function can be found in the application manual F5-A. => [13 Document Database](#).

The control release terminal must be switched open and close while identifying runs. Switching by software is not possible.

Open in device editor:



Adjust speed mode

Adjust motor data
Or:

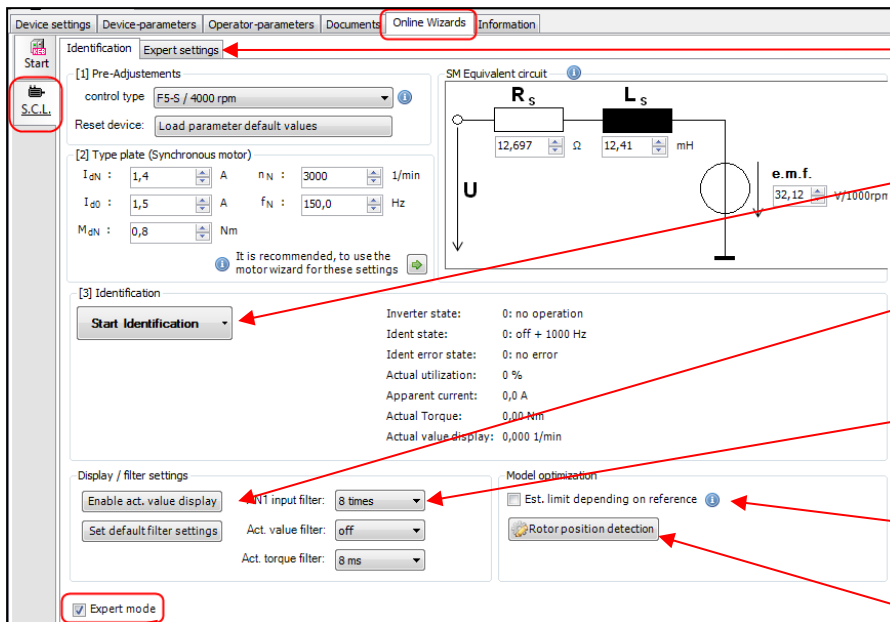
Routing to motor data assistant (see [10.2.1.1 Motor configuration](#))

Start identification with automatic procedure

Display of actual measured data or status

Enable expert mode

With expert mode some useful adjustments are offered:



Open list with manually adjustable parameters

Full selection of identification options

Adopt best settings

Manually adaption of filter settings

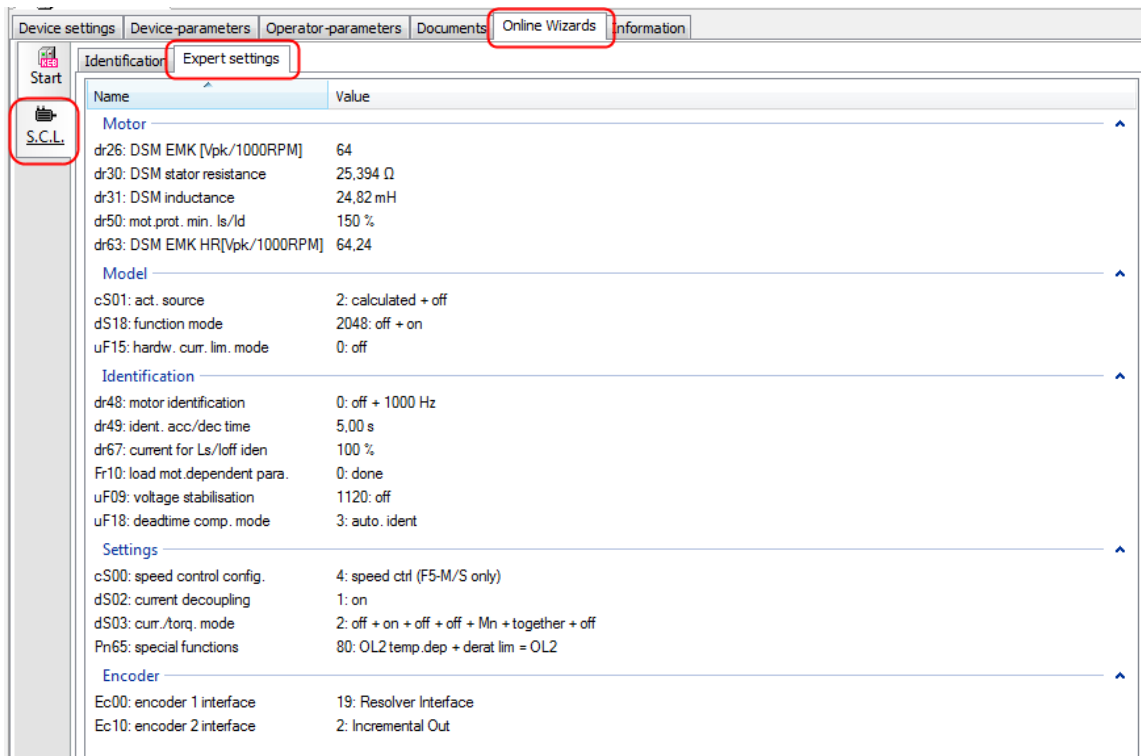
Stabilizes start

Extra menu for rotor position detection

Expert mode enabled

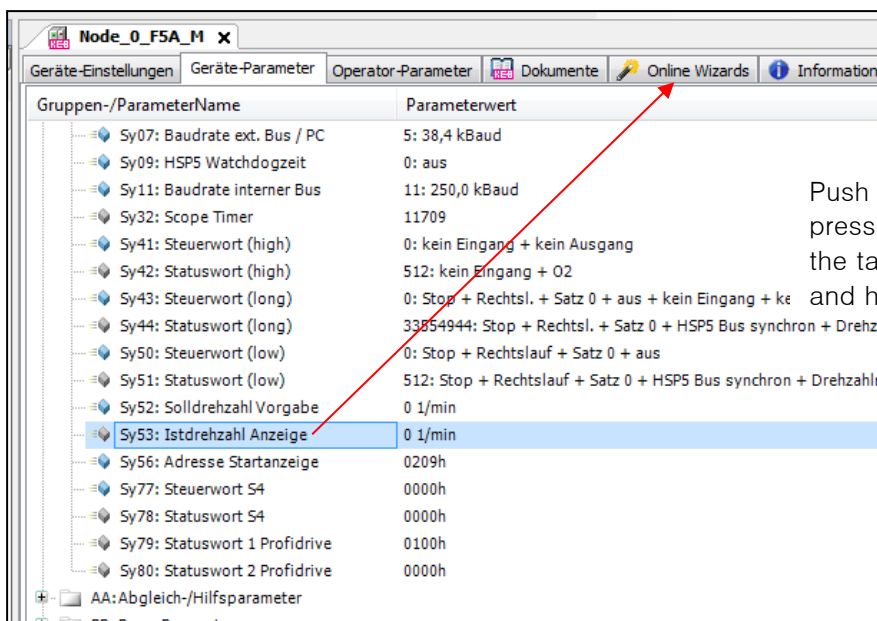
In the tab "Expert settings" all relevant parameters are available as an online list and can be adjusted manually if required such as the parameter editor:

Start-up Assistants (Wizards)

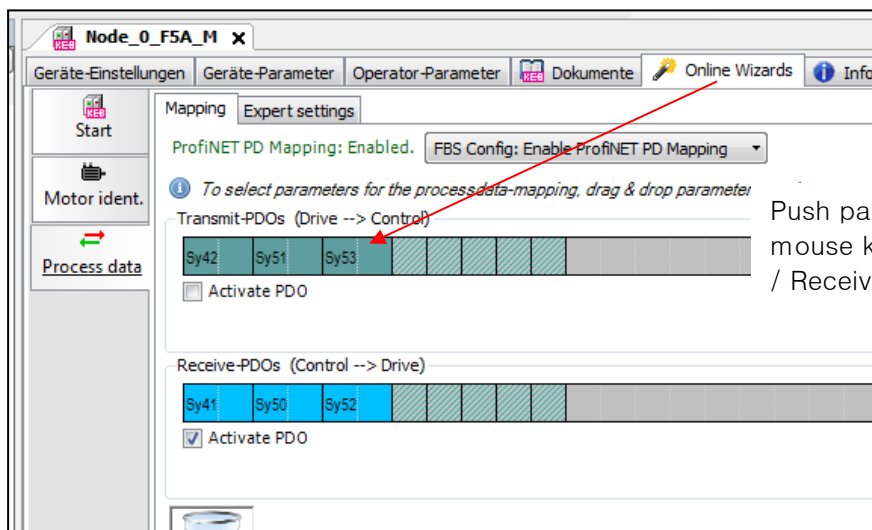


10.1.3.3 Start-Up assistant F5 with Profinet

By the assistant for process data adjustment on an easy way the PDO assignment can be done. In standard mode most device parameters can be placed by Drag&Drop from device editor to the assistant. Using the wizard for the process data assignment can be done in a simple way the PDO assignment. In standard mode, certain device parameters can be pushed by Drag&Drop from the Device Editor into the appropriate fields of the wizard. It is an operator firmware version 2.9ff required.



Push parameter with pressed left mouse key to the tab "Online Wizard" and hold...



Push parameter with pressed mouse key to the field “Transmit / Receive PDO” and lay down

A changing can be done only in condition “Inactive PDO”.

In **Expert mode** the PDO assignment can be done manually by hexadecimal addresses.
=> also: [10.2.1.4 Process data adjustment of F5 Profinet Operator](#)

10.1.4 Online Start-Up Wizard COMBIVERT G6.

10.1.4.1 Motor Data Identification G6-L (ASCL)

The online start up wizard basically works the same as [F5-ASCL: => section 10.1.3.1](#)
Because of no encoder can be connected, there will be no encoder parameter in the selection.

10.1.4.2 Motor Data Identification G6-P (SCL)

The online start up wizard basically works the same as [F5-SCL: => section 10.1.3.2](#)
Because of no encoder can be connected, there will be no encoder parameter in the selection.

10.1.5 Start-Up Wizard COMBIVERT T6.

A separate commissioning assistant will be published for the COMBIVERT T6 during the term of CV 6.6.0. This is only integrated in COMBIVIS studio 6, since the start-up works with the integrated embedded PLC. The “inverter-specific” parameters can be addressed with the online start-up wizard. The description is in [Online Start-Up Wizard COMBIVERT F6/ H6/ S6/ P6/ T6](#).

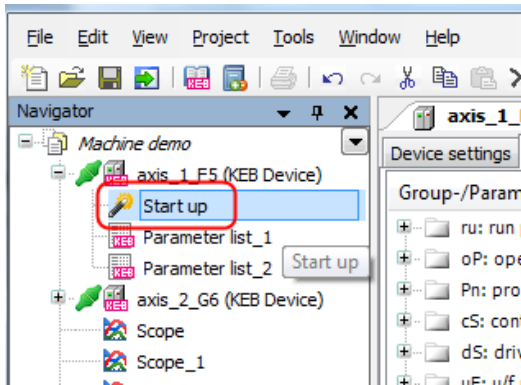
10.2 Offline Start-Up Wizard

For an offline Start-up wizard, it is not needed to connect a device.
The result can be loaded directly into a connected device, or a list of data (parameter list or another file) can be created, that can be saved and load into the device later.

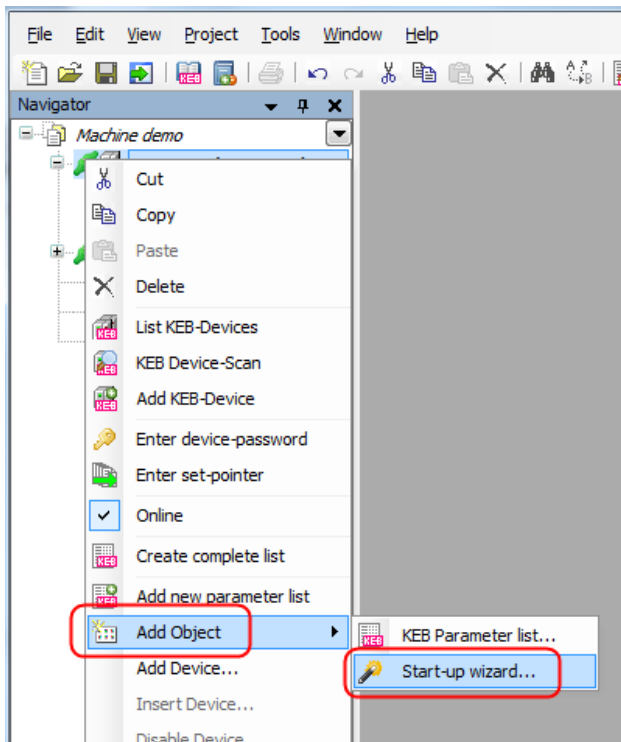
Open start-up wizards:


If there is a wizard for the device software offered, it will be shown direct in the navigator window.

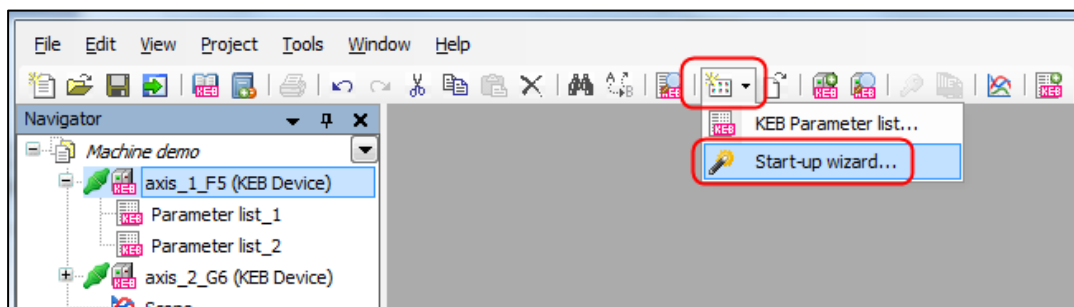
Start-up Assistants (Wizards)

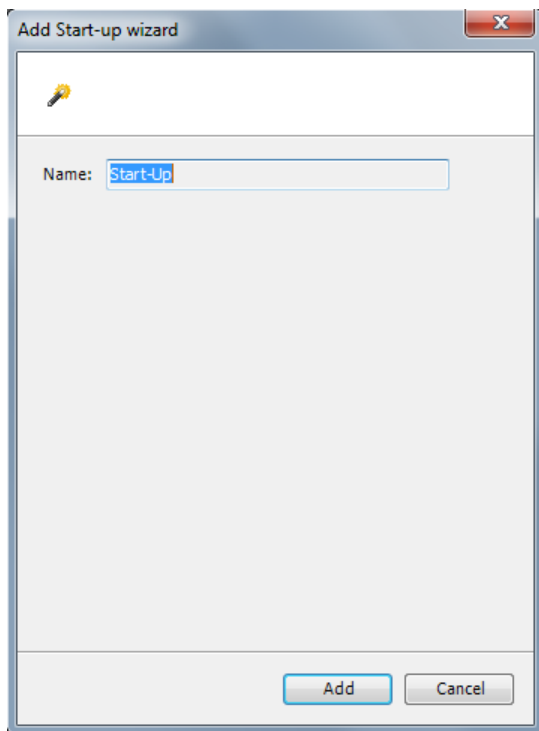


If it isn't shown because e.g., the software mode has switched, the start-up wizard can be opened manually:
Mark device → right mouse key → “Add object” → “Start-up Wizard”



Or: mark device → Tool bar: Icon  → “Start-up assistant”





Give name and add.

10.2.1 Offline Start-up Wizard for COMBIVERT F5.

10.2.1.1 Motor Configurator F5-S

The motor configurator is available in mode for Pm-servo motors F5-S, F5-P, F5-E und G6-P. It creates a parameter list with related motor data based on the KEB synchronous motors or self-defined data. This list can be stored or direct loaded to the device. Currently only synchronous motors are available.

The self-defined motors are stored in a separate file. This can be copied to other PCs:
C:\Program Files\KEB\COMBIVIS_6\KEB\UserMotors.xml

Motor from KEB-database:

Start-up Assistants (Wizards)

Reduction of list for design, voltage, speed, pole number

Series	Art.-Nr.	U _n	M _n	I _n	Id0	n _n	J _L	pole pairs
Dynamic Line I	A1SM000-6200	230	0.32	1	1.2	6000	0.17	3
Dynamic Line I	A2SM000-6200	230	0.48	1.5	1.5	6000	0.24	3
Dynamic Line I	A3SM000-6200	230	0.6	2	2	6000	0.31	3
Dynamic Line I	A4SM000-6200	230	0.8	2.9	3.2	6000	0.45	3
Dynamic Line I	B1SM000-4200	230	0.6	2	1.9	4000	0.22	3
Dynamic Line I	B1SM000-6200	230	0.5	2.5	2.6	6000	0.22	3
Dynamic Line I	B2SM000-4200	230	1.3	2.9	3.2	4000	0.36	3
Dynamic Line I	B2SM000-6200	230	1	4.4	5	6000	0.36	3
Dynamic Line I	B3SM000-4200	230	2	4.7	5.5	4000	0.57	3
Dynamic Line I	B3SM000-6200	230	1.5	6.6	7.7	6000	0.57	3
Dynamic Line I	C1SM000-3200	230	0.8	1.4	1.5	3000	1.2	3
Dynamic Line I	C1SM000-4200	230	0.75	1.8	2	4000	1.2	3

Forward

Choose motor, e.g., B1SM000-6200:

Adjust design of cooling type

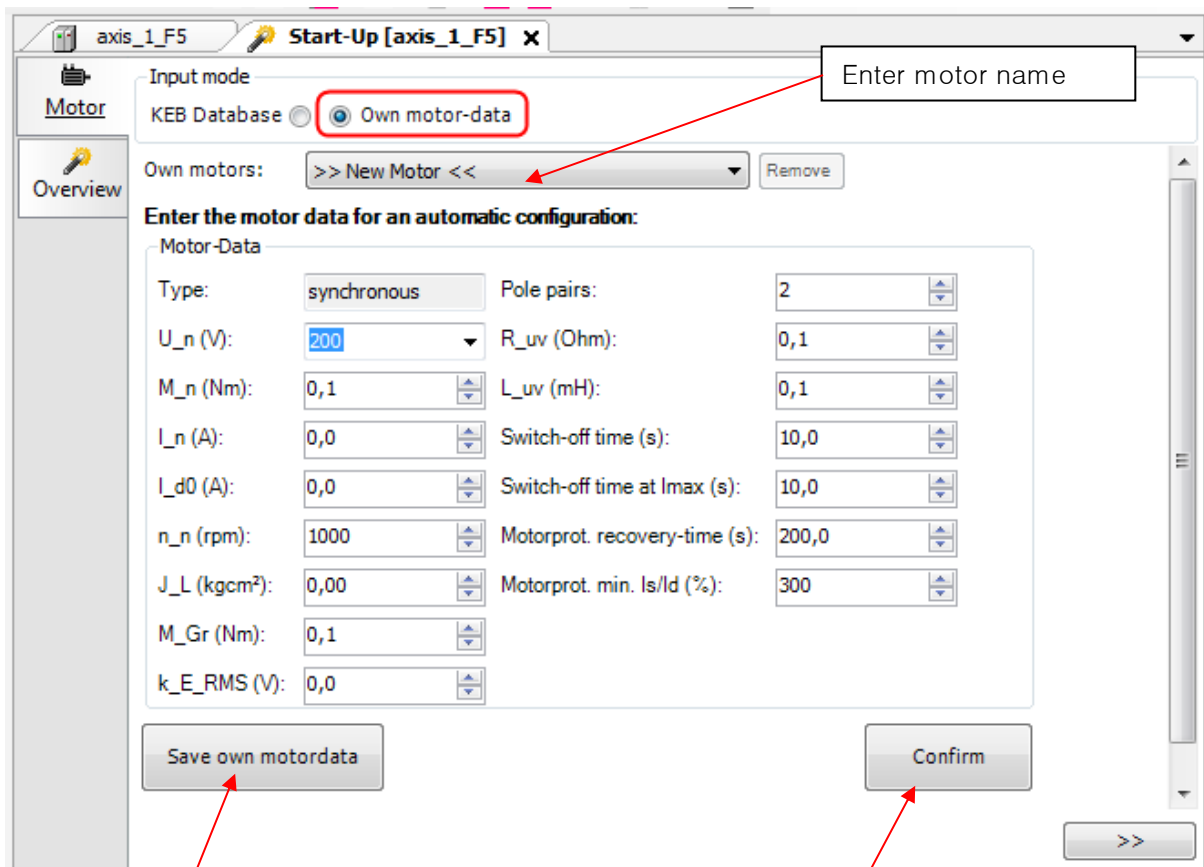
Adjust encoder type

Pre-adjustment of speed controller: 2=strong, 15=weak, (bases on motor inertia)

Back

Forward

Define your own synchronous motor:



Put motor data into
motor list

Use motor data directly for
parameterization

In → [Overview](#) it can be chosen if the parameter would be load directly into the device or if a parameter list shall be created.

10.2.1.2 Process Data Adjustment of F5 CAN Bus Operator

The F5-CAN bus wizard mainly may be used for creating the CAN EDS file. An adjustment of the process data can be done but a download of the settings into the device is not possible.

The function of the assistant is like the assistant of G6-CAN, => [10.2.2.1 Process data adjustment G6 CAN.](#)

10.2.1.3 Process Data Adjustment of F5 EtherCAT Bus Operator

The Process data assignment for the F5-CAN operator can be created and thus an XML- file. However, a download setting in the device is not possible.

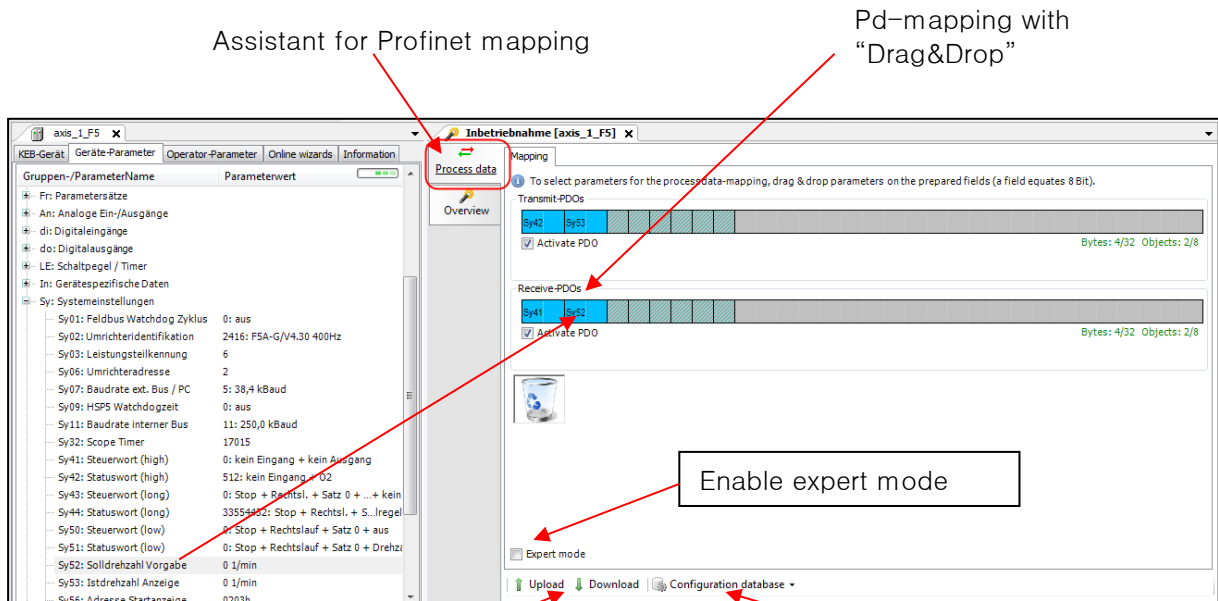
The function of the assistant is like the assistant of G6, => [10.2.2.2 Process data adjustment G6 EtherCAT.](#)

10.2.1.4 Process Data Adjustment of F5 Profinet Operator

Using the wizard for the process data assignment can be done in a simple manner the PDO assignment. In standard mode, certain parameters of the wizard can be dragged by "drag and drop" from the Device Editor in the appropriate fields. There is an operator firmware version 2.9ff required.

By **“Upload”** the adjustments of the device will be transmitted to the assistant and displayed.

By “Download” the adjustments of the assistant can be transmitted to the connected device.



Assistant for Profinet mapping

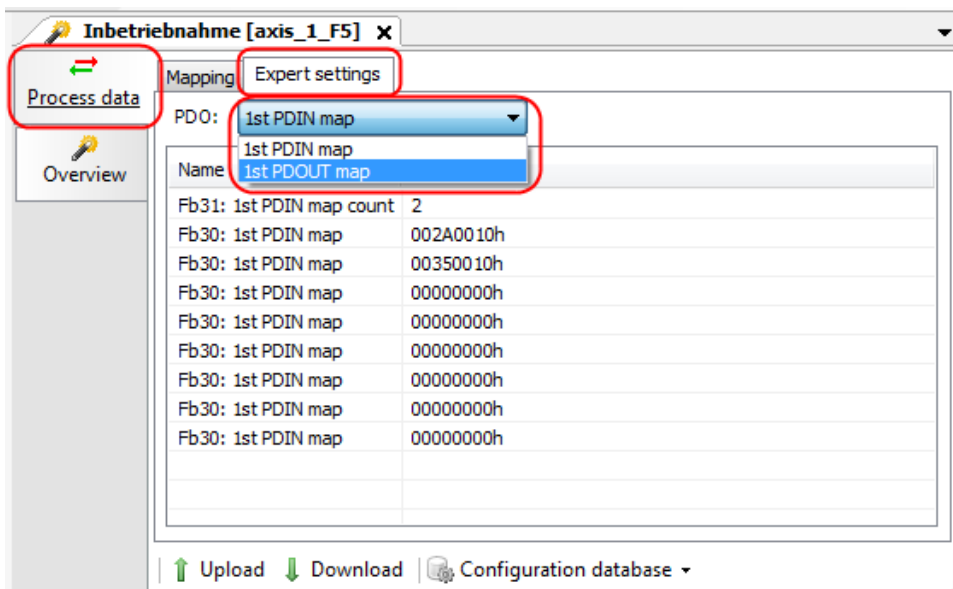
Pd-mapping with “Drag&Drop”

Enable expert mode

Load mapping from or into device

Own data sets can be created, red or deleted

In the **Expert mode** the PDO assignment can be done manually by hexadecimal addresses.



In → **Overview** it can be chosen if the parameter would be load directly into the device or if a parameter list shall be created.

10.2.2 Offline Start-up Wizard for COMBIVERT G6.

10.2.2.1 Motor data configurator G6-P

The Motor data configurator works in the same way as the [10.2.1.1 Motor data configurator F5-S](#). Because of no encoder can be connected, there will be no encoder parameter in the download list.

10.2.2.2 Process Data Adjustment G6-CAN

Using the wizard for the process data assignment can be done in a simple manner the PDO assignment. In standard mode, certain parameters of the wizard can be dragged by "drag and drop" from the Device Editor in the appropriate fields.

By **"Upload"** the adjustments of the device will be transmitted to the assistant and displayed.

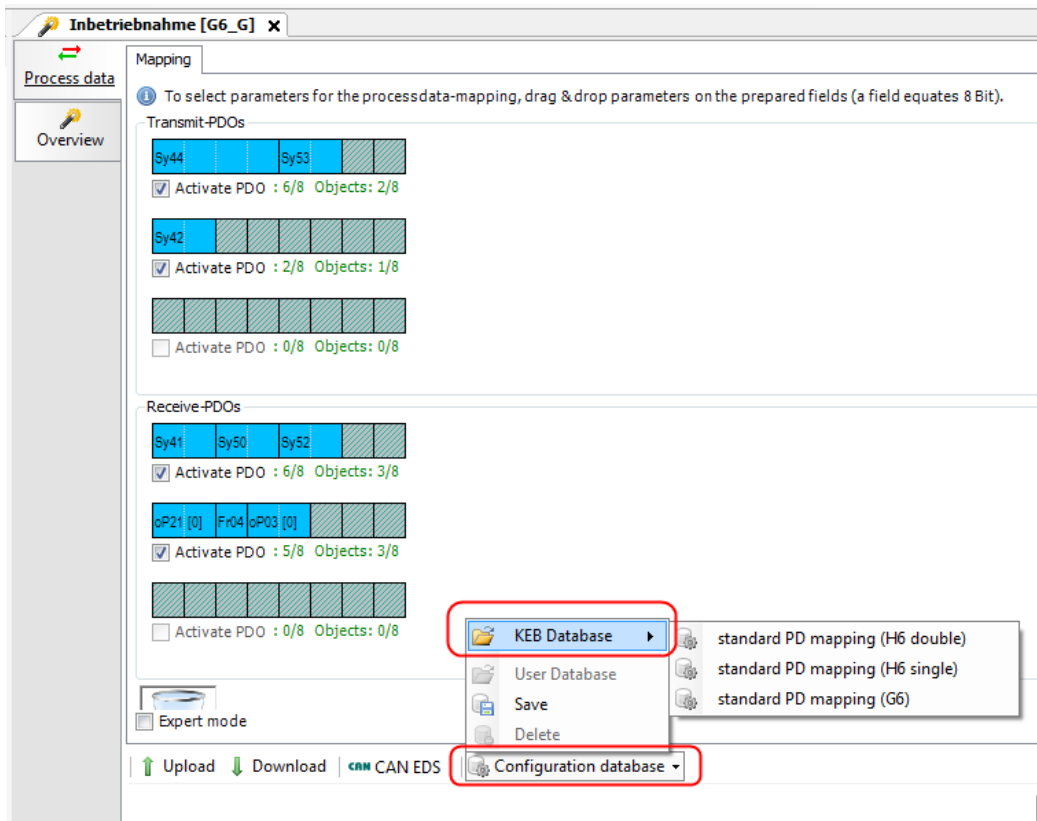
By **"Download"** the adjustments of the assistant can be transmitted to the connected device.

By **"CAN EDS"** an EDS-file matching to device and PDO assignment will be created.

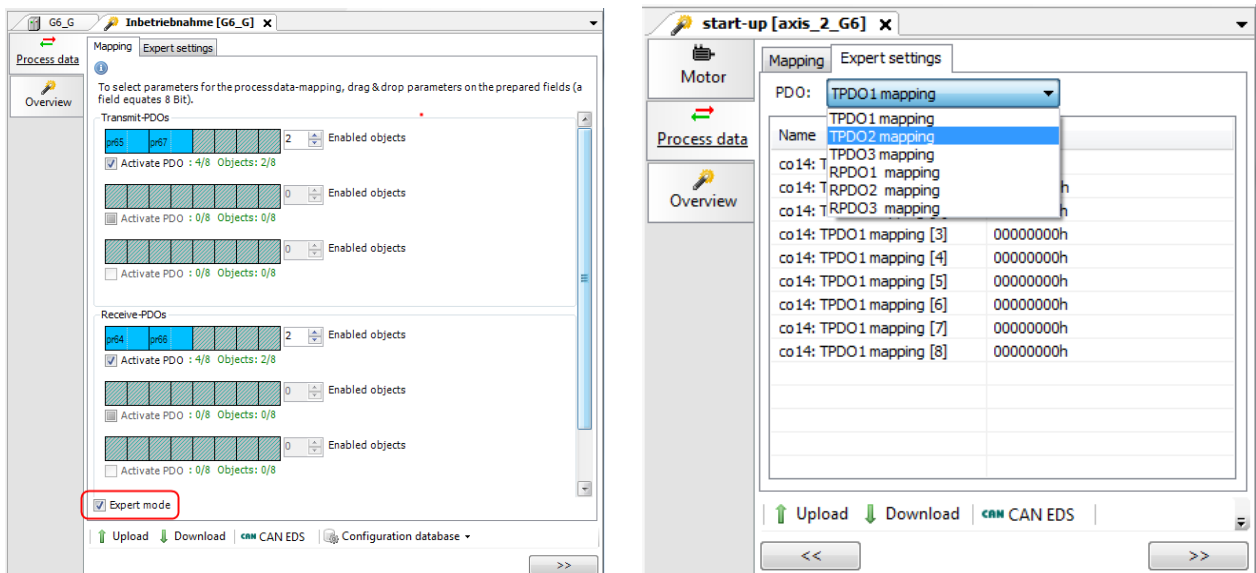
The screenshot shows the 'Inbetriebnahme [G6_G]' wizard window. The left pane displays a tree view of parameters under 'Sy: Systemparameter', with 'Sy41: Steuerwort (high)' selected. The right pane, titled 'Mapping', shows 'Transmit-PDOs' and 'Receive-PDOs' with checkboxes for 'Activate PDO' and 'Objects'. The 'CAN CAN EDS' button is highlighted with a red box. The bottom bar contains 'Upload', 'Download', and 'CAN CAN EDS' buttons, also highlighted with red boxes.

With "Configuration database" can be loaded into the wizard a previously saved setting or the KEB default. The KEB default loads the assignment for the CiA 402 profile in the wizard. "Save" can save an own assignment.

Start-up Assistants (Wizards)



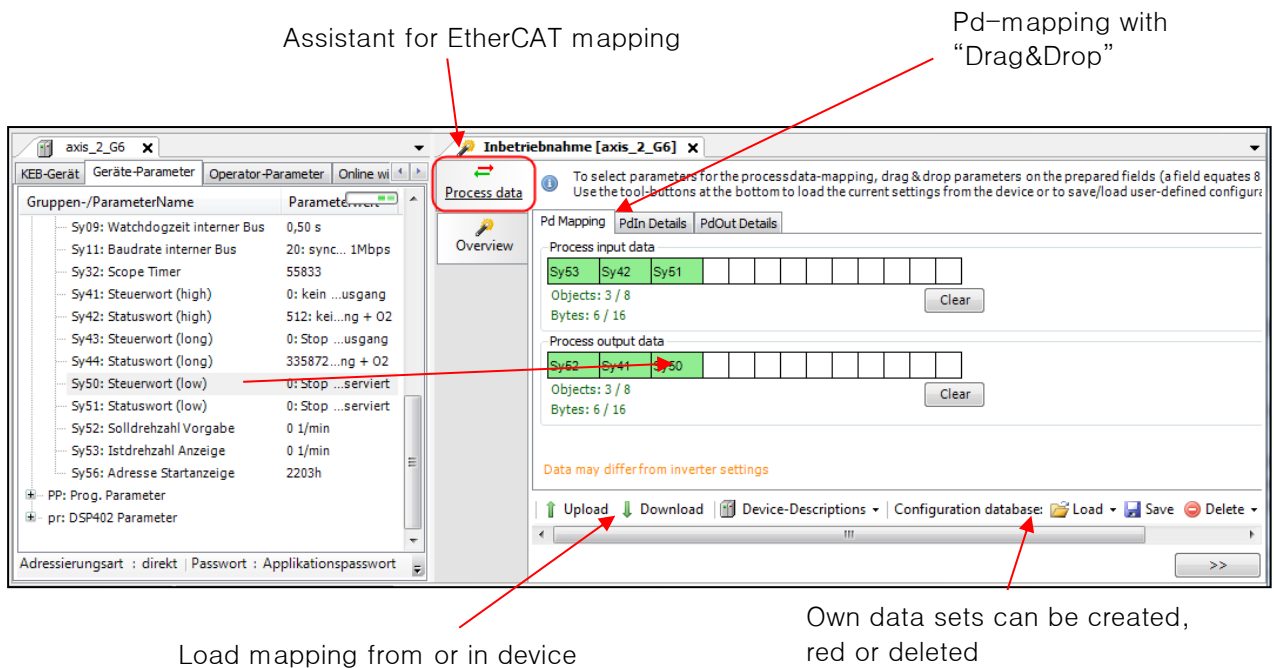
In the **Expert mode** the PDO assignment can be done manually by hexadecimal addresses.



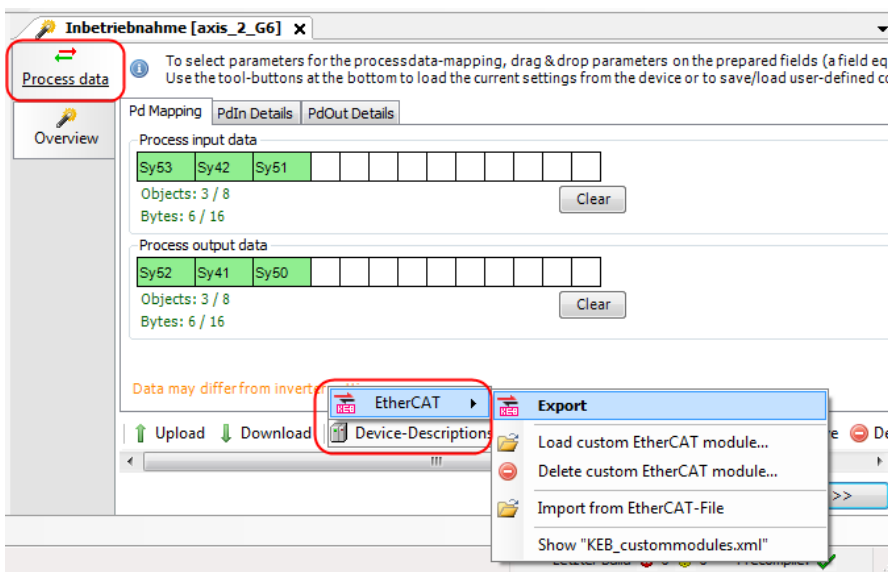
In → **Overview** it can be chosen if the parameter would be load directly into the device or if a parameter list shall be created.

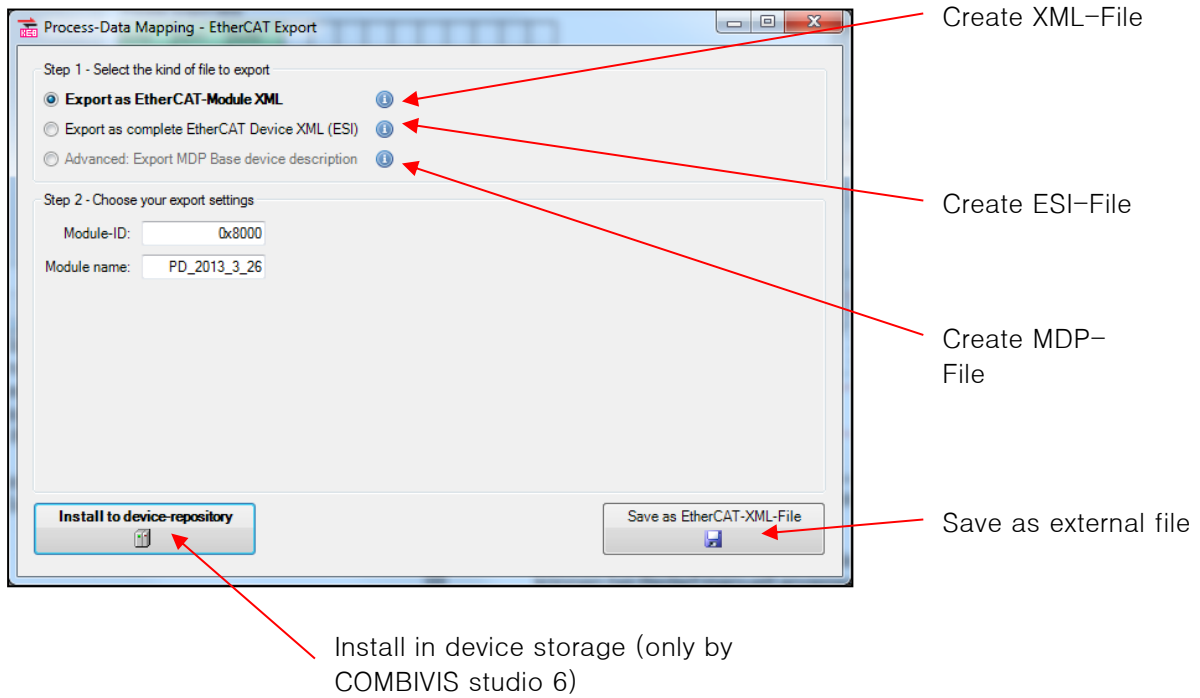
10.2.2.3 Process Data Adjustment G6-EtherCAT

Using the wizard for the process data assignment can be done in a simple manner the PDO assignment. In standard mode, certain parameters of the wizard can be dragged by "drag and drop" from the Device Editor in the appropriate fields.

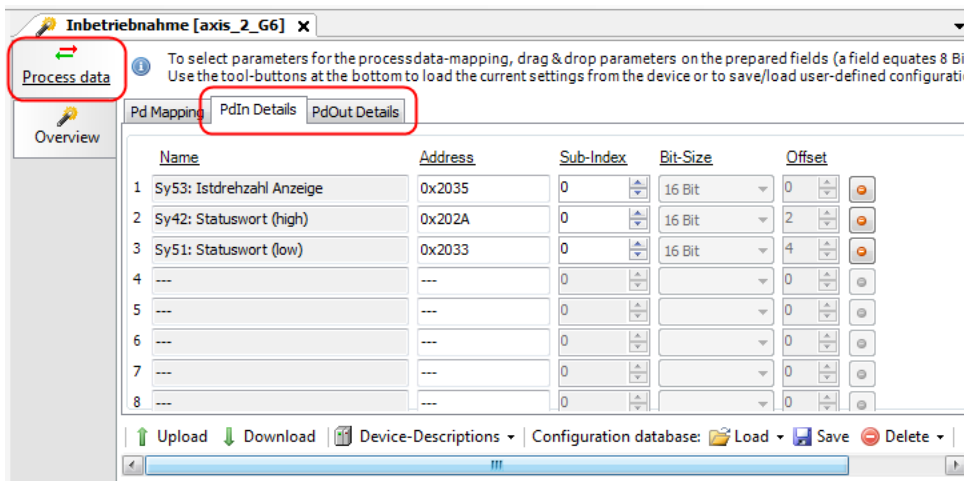


By **“Upload”** the adjustments of the device will be transmitted to the assistant and displayed.
 By **“Download”** the adjustments of the assistant can be transmitted to the connected device.
 By **“device description”** an XML or ESI-file matching to device and PDO assignment will be created.





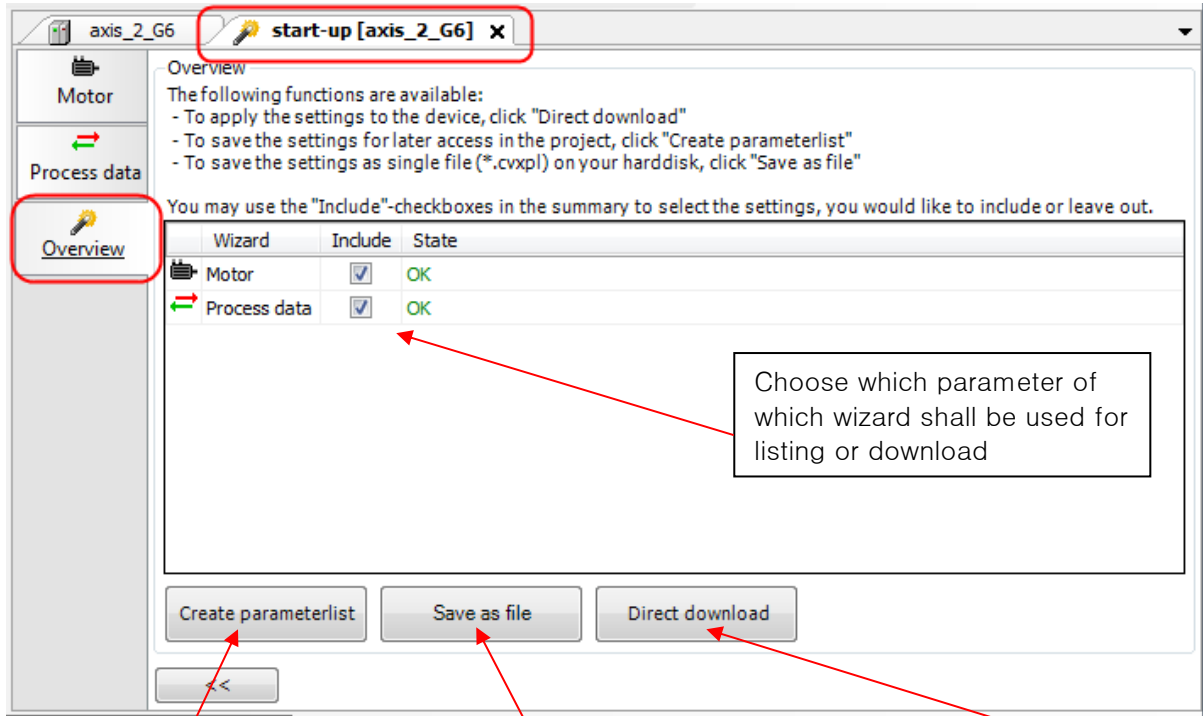
By “PdIn Details” und “PdOut Details” a detailed adjustment of Pd-mapping is possible.



10.2.3 Offline Start-up Wizard for COMBIVERT F6/ H6/ S6/ P6/ T6.

There are no offline wizards for COMBIVERT F6/ H6/ S6/ P6/ T6. The Online wizard can be use with restrictions also offline.

10.2.4 Offline Start-up Wizard Overview



Choose which parameter of which wizard shall be used for listing or download

Create a parameter list with all parameters of selected wizards

Create and export a parameter list with all parameters of selected wizards

Do a download to the device with all parameters of selected wizards

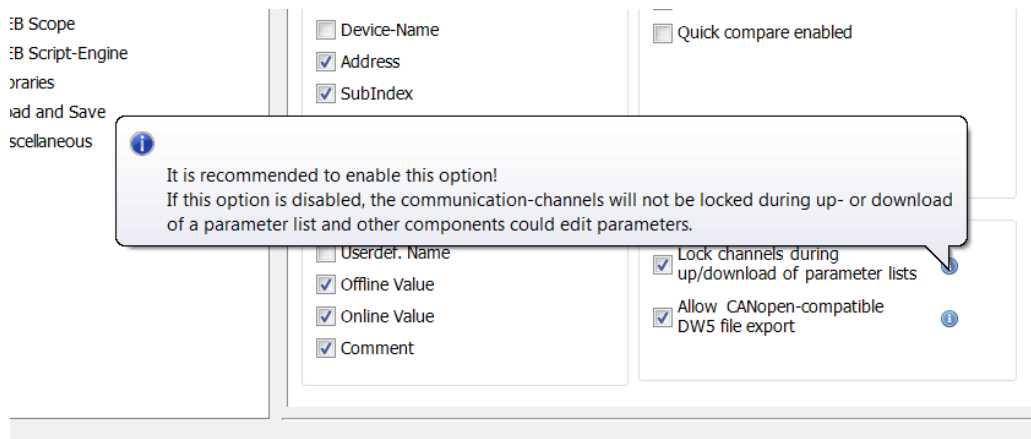
11 Help Area

There are 4 help areas:

- Help for specific COMBIVIS- or Device functions
- Help for COMBIVIS program functions
- Help for certain device functions (FAQ)
- Help for device parameter functions

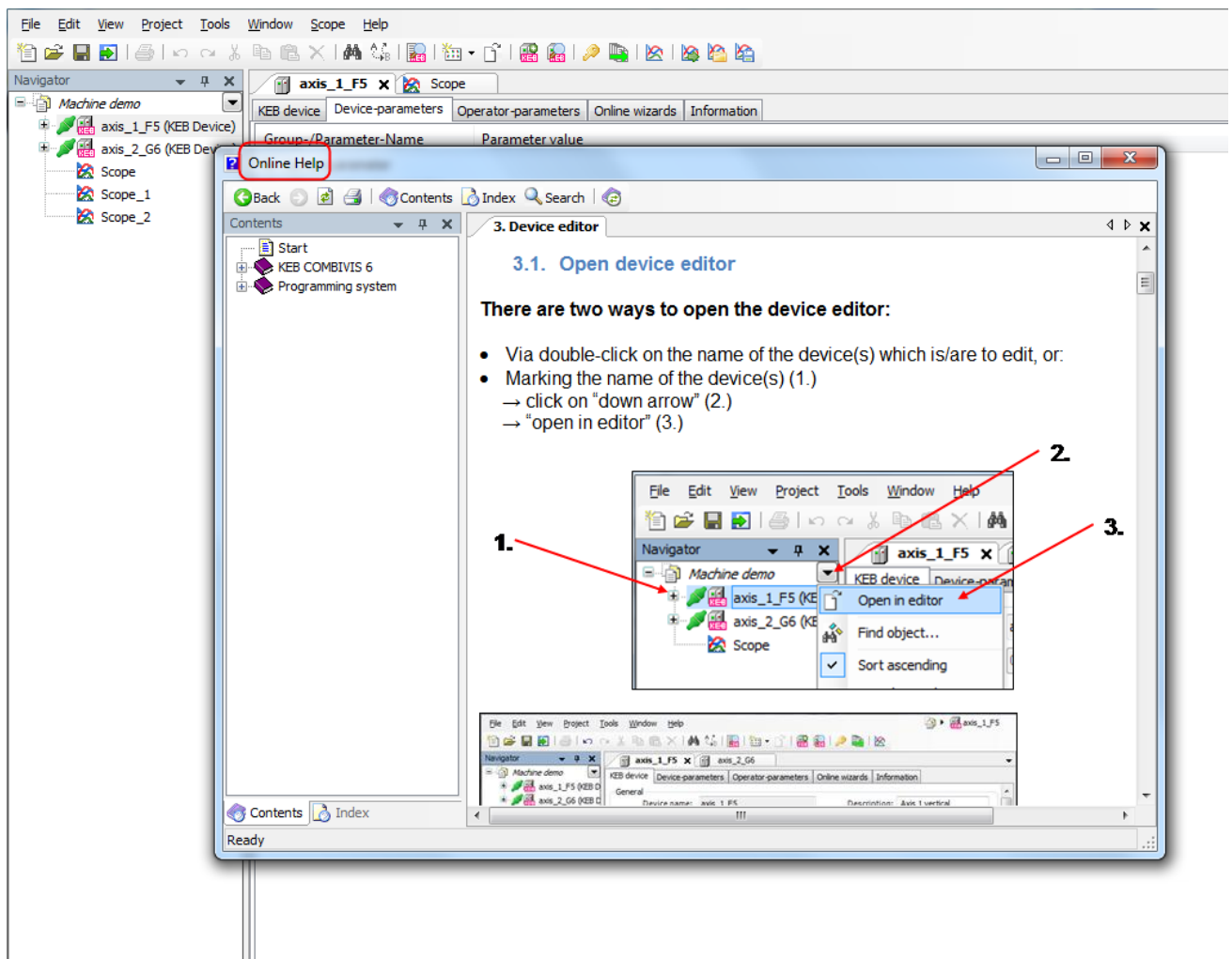
11.1 Help for Specific Functions

By touching with mouse on the sign  the corresponding help or explanation text is briefly displayed.

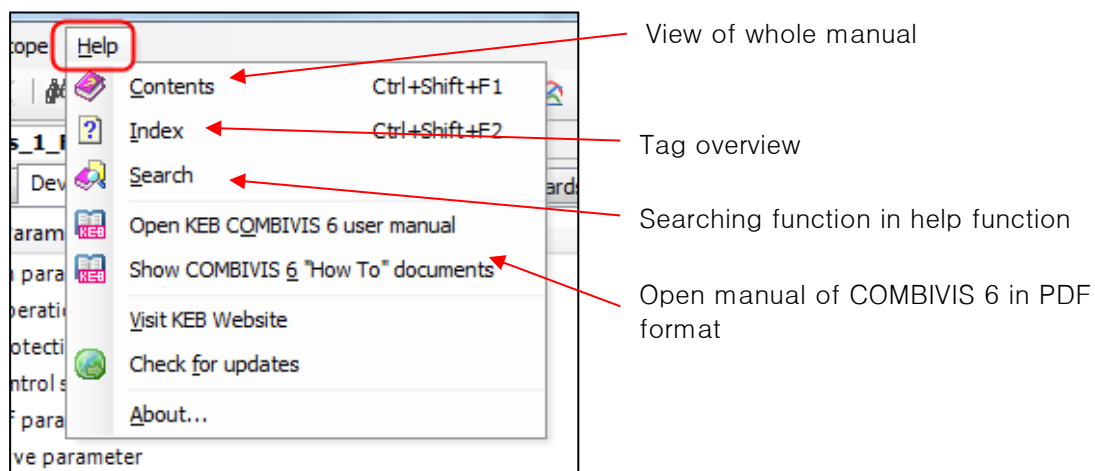


11.2 Help for Program Functions

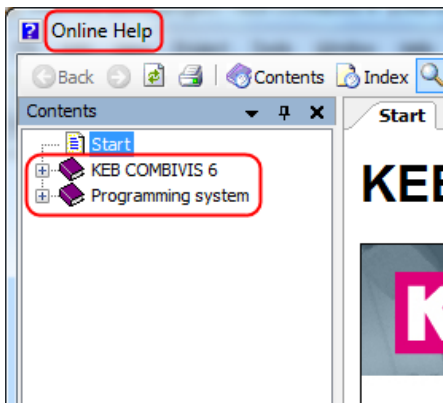
By pressing the F1 key in a particular program function the user will jump to the corresponding location in the manual.



In the menu bar under "Help" the help function can be opened in different display modes.

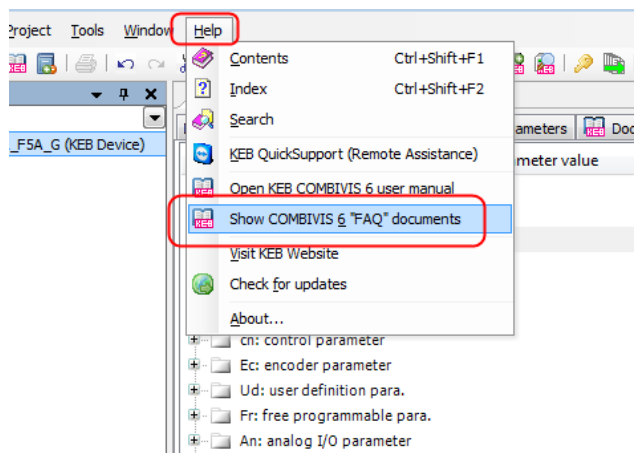


There is a distinction between function of COMBIVIS 6 and the programming system CODESYS.



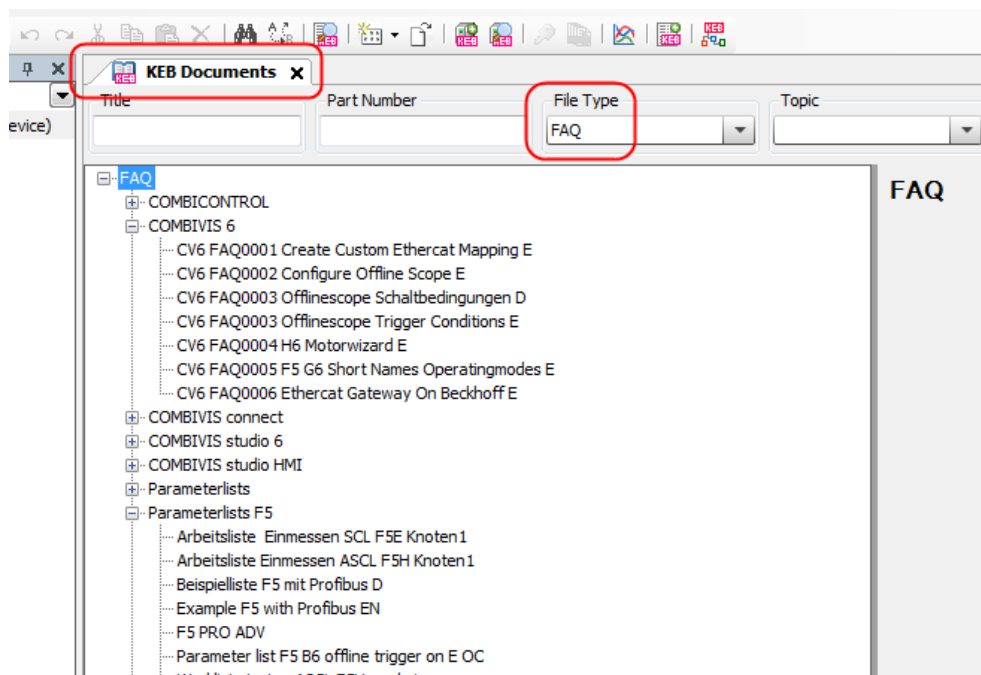
11.3 Help for Certain Device Functions (FAQ)

For certain procedures descriptions or samples are available.
Menu "Help" → "Show COMBIVIS 6 "FAQ" documents"



See special function descriptions

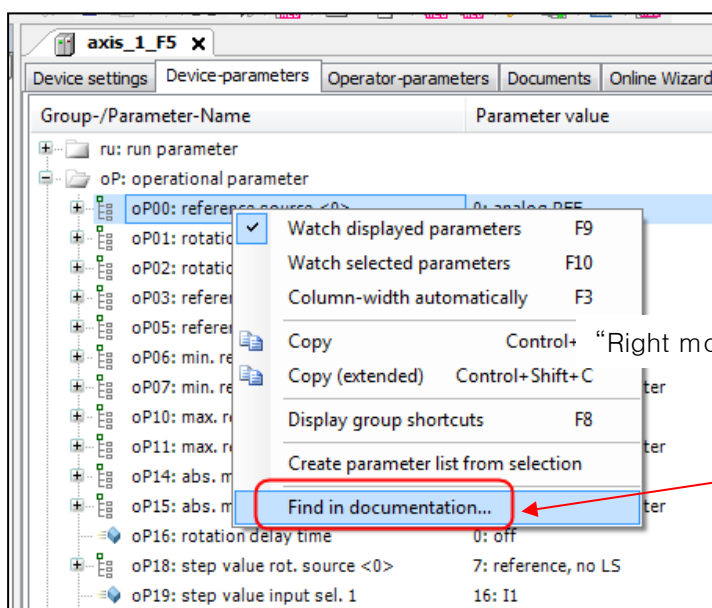
The KEB document database with file type FAQ opens. Depending on the program or device type descriptions or sample parameter lists are displayed. Files or sample lists can be opened directly by double-clicking.



11.4 Help for Parameter Functions

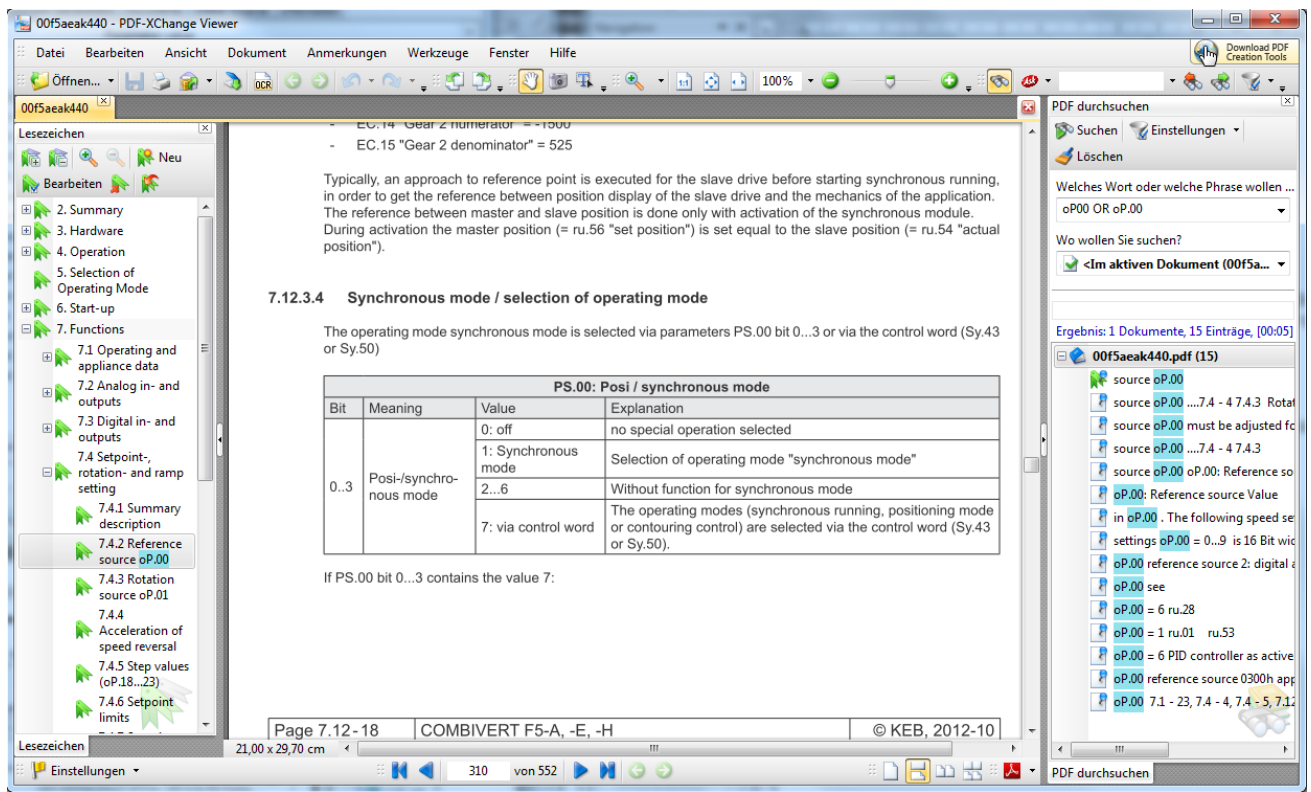
COMBIVIS 6 allows direct access to the device documentation. Requirement is that the documentation was imported from the KEB website into COMBIVIS 6. The feature is available only for registered COMBIVIS 6 or licensed COMBIVIS studio 6 versions. A PDF viewer is required. KEB suggests when installing COMBIVIS 6 free program PDF X-Change Viewer to installation.

When the corresponding Programmer's Guide is installed, with the function context menu - "Find documentation ..." the declaration of the parameter will be shown.



Control+ "Right mouse key"
 Show in KEB documents explanation for parameter

The programming manual of the device opens by PDF-X-Change Viewer:



In the right part of the window all digits are displayed where the selected parameter appears. The selection of a reference leads to a jump to the location in the PDF document.

The direct opening and the import of documentation are described in chapter [13 Document Database](#).

11.5 COMBIVIS Error Messages

COMBIVIS shows errors in message window or instead of the parameter value.

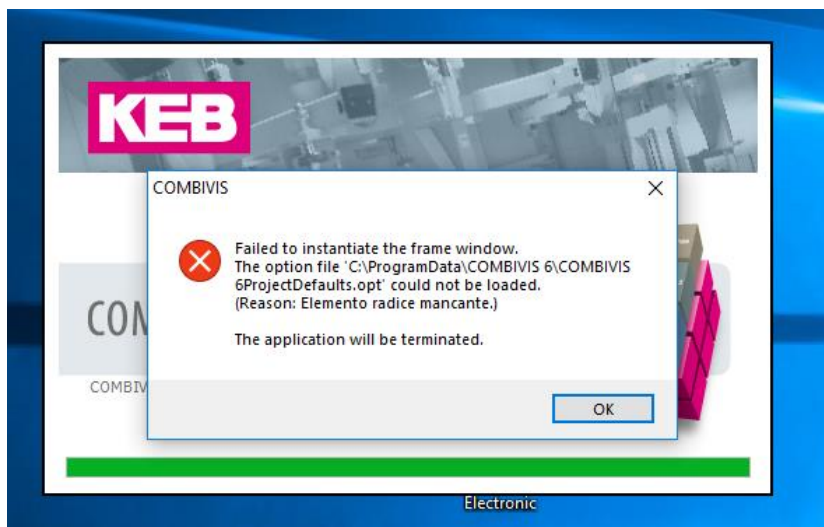
Value	Name	Source	Note
-200	Exception caught	Driver (COMBIVIS internal)	An unexpected error occurred in the telegram processing
-110	Invalid service parameter	Driver (COMBIVIS internal)	Invalid encoding of request
-109	Channel does not send	Driver (COMBIVIS internal)	Message could not be sent (e.g., port not available)
-108	Channel locked	Driver (COMBIVIS internal)	The channel is used by another component
-107	BCC error	Driver (COMBIVIS internal)	Transmission error (response of the device incorrectly received)
-106	Invalid protocol	Driver (COMBIVIS internal)	Invalid encoding of the response telegram
-105	Service decoding unsupported	Driver (COMBIVIS internal)	Invalid encoding of request
-104	Service encoding unsupported	Driver (COMBIVIS internal)	Invalid encoding of request

-103	Invalid node address	Driver (COMBIVIS internal) / Gateway	Invalid node address
-102	Invalid invoke id	Driver (COMBIVIS internal)	Invalid encoding of the response telegram
-101	Invalid response received	Driver (COMBIVIS internal)	Invalid encoding of the response telegram
-100	Channel closed	Driver (COMBIVIS internal)	Channel is closed / in parameter list: wrong device reference
-10	No Answer	Driver (COMBIVIS internal)	No response was received within the timeout period
0	OK	Target device	OK
1	Device not ready	Gateway	The target device cannot be reached (error code is typically reported by a gateway component, e.g., USB-converter, Operator, Port Expander ...)
2	Invalid address or password	Target device / Gateway	Password to access level is insufficient
3	Invalid data	Target device	Data are invalid (e.g., out of range)
4	Parameter read only	Target device	Parameter can be read only
5	BCC error	Target device	Transmission errors (The request is incorrectly received at the device)
6	Device busy	Target device	The device is reachable, but busy (e.g., reset, etc.) and will be available again soon
7	Service not available	Target device / Gateway	Service is not supported (may be reported by the device or a gateway component)
8	Invalid password	Target device / Gateway	Password level for access is insufficient
9	Invalid frame	Target device / Gateway	Invalid encoding of the telegram
10	Invalid character	Target device / Gateway	Invalid encoding of the telegram
11	Invalid set/subindex	Target device / Gateway	Set (at Service 0) / subindex (with Service 14) not available for this parameter
13	Invalid address	Target device	Invalid parameter address
14	Function not possible	Target device / Gateway	Function not possible (in the current state of the device) e.g., control release is enabled

Additional error messages:

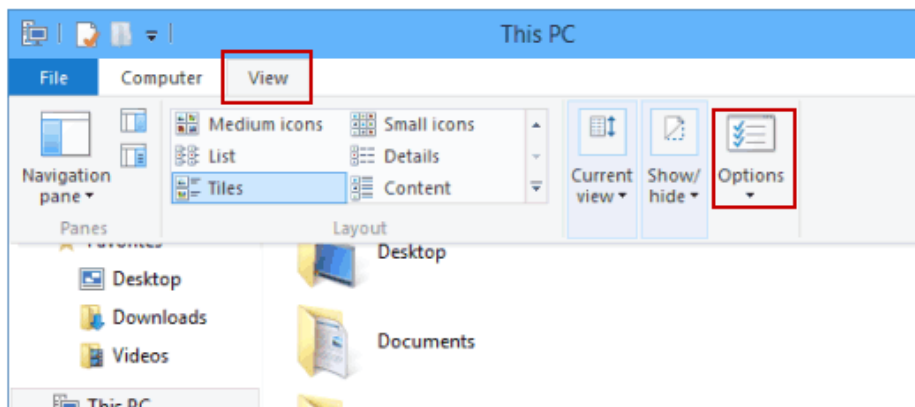
At opening of a project, a pop-up with following error message comes:

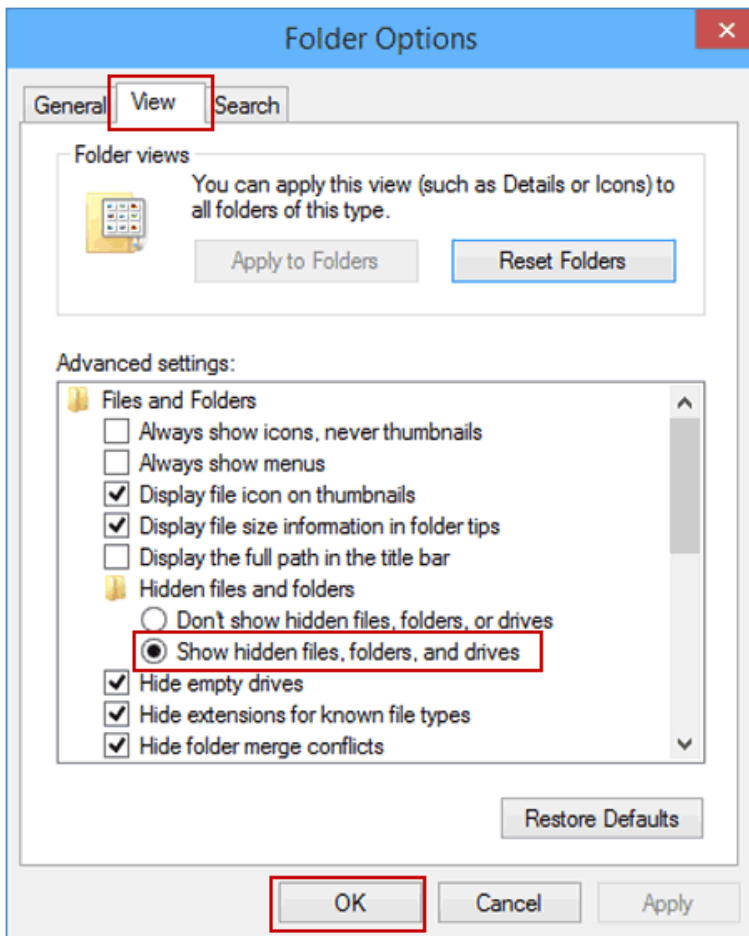
“.....C:\Programdata\COMBIVIS6\.....COMBIVIS6ProjectDefaults.opt could not be loaded”



At last saving of the project of the belonging “.opt”- files is damaged or empty. This file store the personal adjustments of the user (language, window size etc.) for this project. They do not influence the content of the project. The files are newly created at every storing of the project. Thus, they can be deleted: The path is shown in the error message. “Program Data” is a hidden folder. If it is not shown it must be made viewable in the folder options:

Windows 10:





A re-installation of COMBIVIS will not help, because the damaged file will not be deleted by the de-installation procedure!

11.6 TeamViewer

COMBIVIS provides a simple TeamViewer version. TeamViewer is a program with which a participant gets access to another PC over the Internet, sees the image surface, and can operate it. The computer with COMBIVIS must have a sufficiently fast internet connection.

The owner of the "observed" PC must explicitly start the program and agree to access. The remote access can only be made with a licensed full version with the same or higher version.

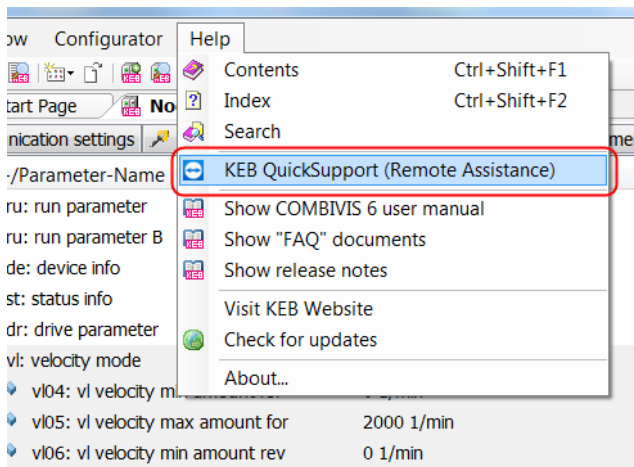
The COMBIVIS TeamViewer cannot access another PC.

Access is not limited to COMBIVIS.

Each time a new call is made, the password is changed.

Start:

Menu "Help" → "KEB Quick Support"



Agree to the disclaimer:

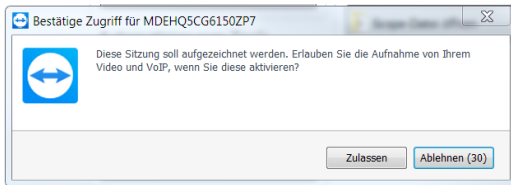


Tell ID and password to the user of the PC to be switched on:

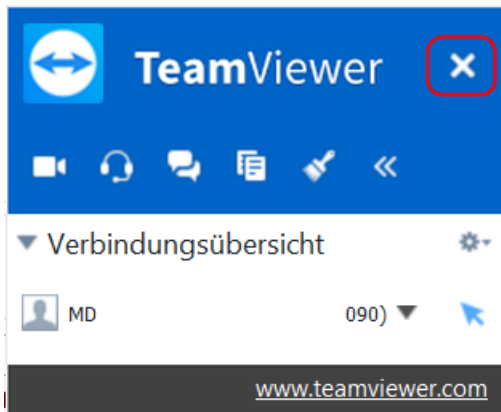


At the bottom the status of the connection is shown.

A recording of the session can be made:



The control and properties window is displayed:



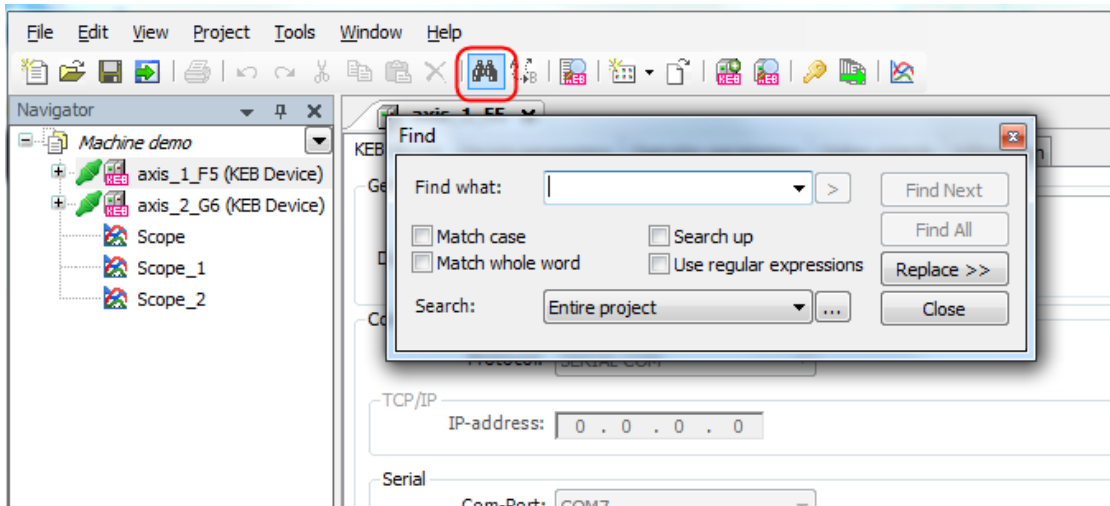
For quit and close click on the "X".

12 Search Function

COMBIVIS 6 offers two different search functions.

12.1 Searching for Text

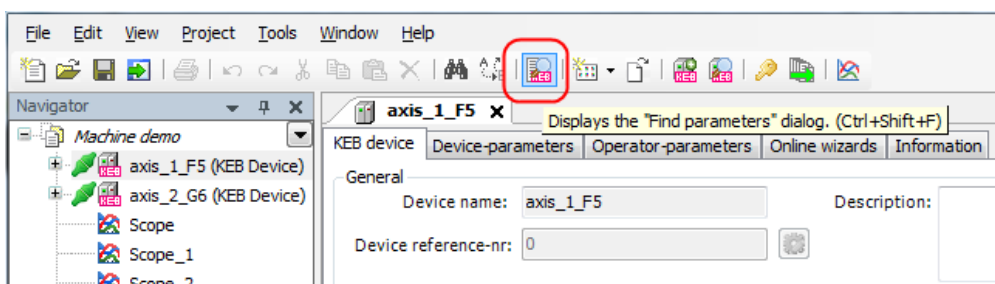
The general text search under the “binoculars” in the tool bar (only in COMBIVIS studio 6):



Here is just looking for texts in specific fields.

12.2 Searching for Parameters

The parameter search is opened with Ctrl + Shift + F or the icon in the toolbar. Parameters can be searched in the Device Editor and parameter lists in the project.



Text to search

Jumps to the next search result

Shows all results in separate window "Parameter search results" at the bottom of CV6 window

Text mode

Searching array

Terms for searching

Normally, the searching of parameters is done from the current cursor position is to the end. When the desired parameter is before it is not found. With the "end from the beginning" option the parameter will be found, but it may be in a loop and the user must decide at which point the loop is executed.

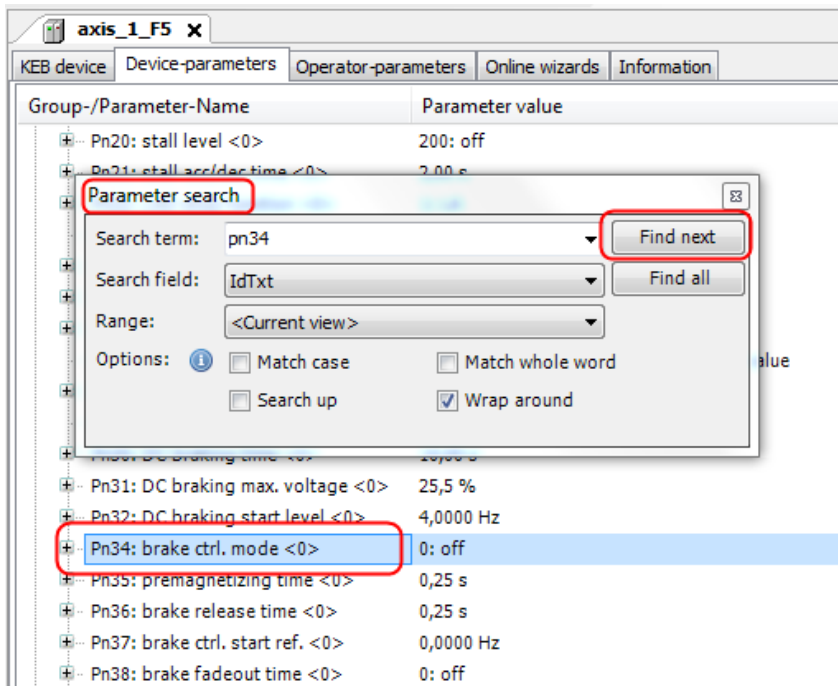
Can be searched by:

- Parameter ID (abbreviation). Search field must be set to "IdTxt". (Parameter Id without dot).
- By Parameter name: e.g., "current" all-the parameters will be found with the term "current" in the name
- By hexadecimal address: 1234h or 0x1234

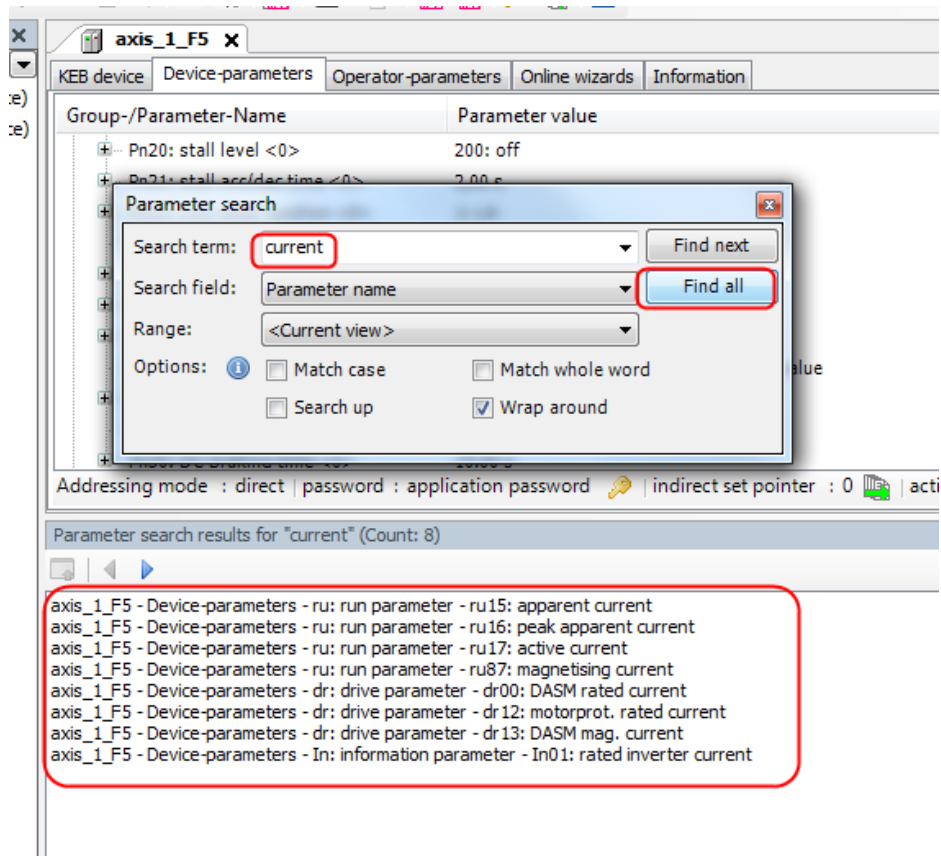
Search methods:

In "Find Next" will jump to the next location in the display window.

Search Function



In “Search All” a new result window will open with all the localities in the message window. Clicking the locality in the results executes a jump to the appropriate place in the editor or in the parameter list.



13 Document Database

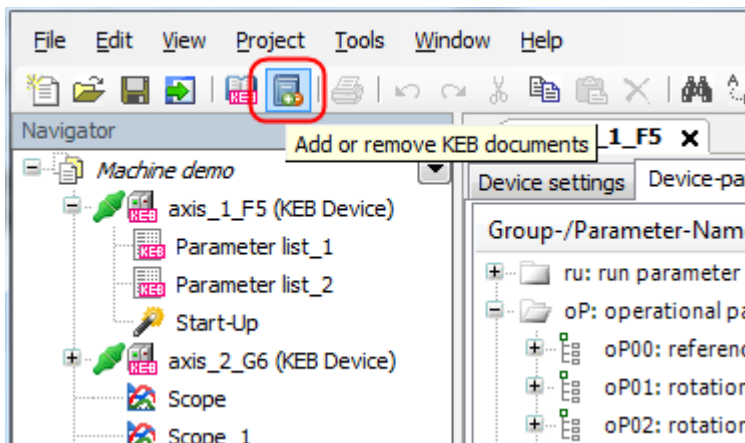
By the COMBIVIS internal document database all KEB documents can be displayed. In the basic equipment the programming manuals of COMBIVERT F5-A, G6 and F6/H6/S6 are integrated. Other documents (manuals, catalogues, E-Plan-data....) can be added via internet.

The using of the database requires the registration of COMBIVIS 6 or the licensing of COMBIVIS studio. The registration can be done via button on the bottom of the start page or via menu bar: "Help" → "Registration". The Registration is for free.

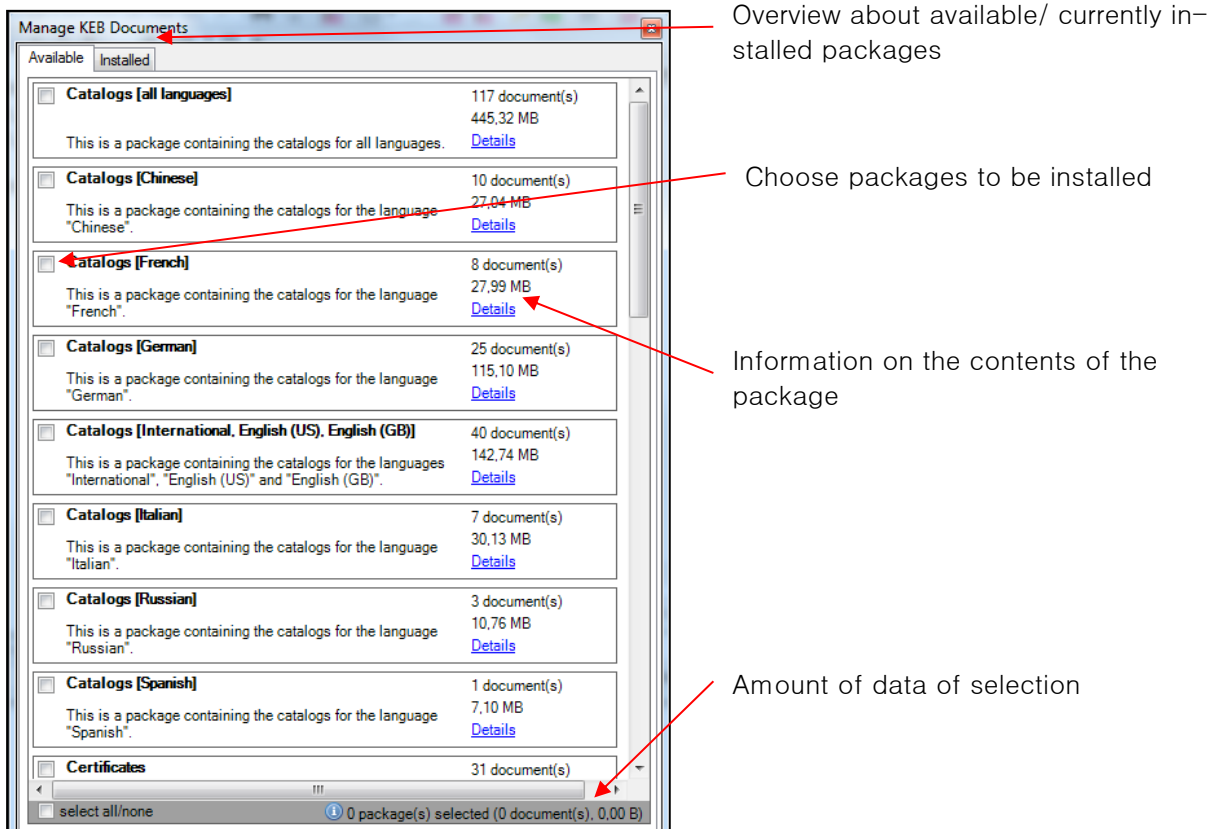
13.1 Add and Delete KEB Documents

The documents are grouped in packages. Documents are updated via the auto-update function. For the installation or update an Internet connection to KEB website www.keb.de is required.

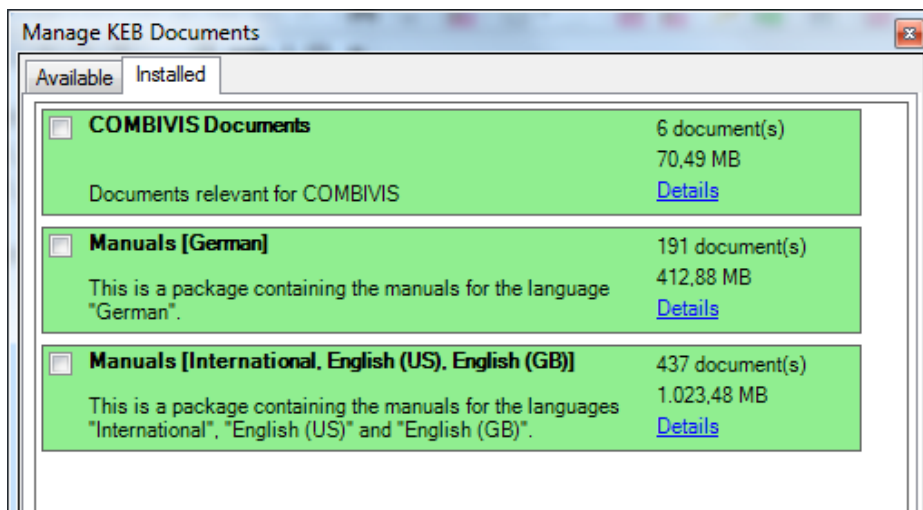
The database management can be opened by button on the start page: "Manage KEB documents" or via toolbar:



The document manager window opens:



In the tab “Installed” the documents available on the computer packages are displayed. A green background means that the package is up to date.

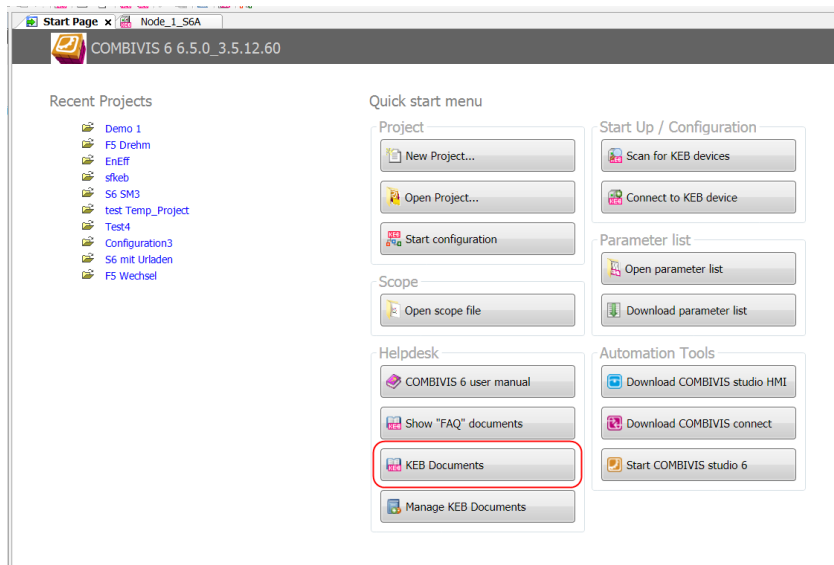


13.2 Use KEB Documents

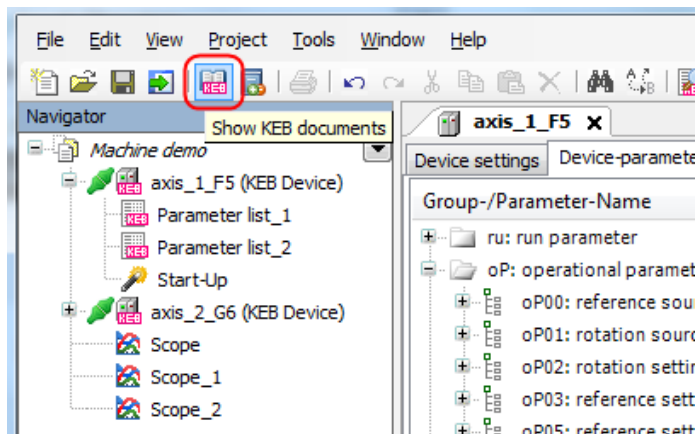
Two ways to access the documents are available:

Global access to all existing documents:

Database can be opened via start page “KEB Documents”

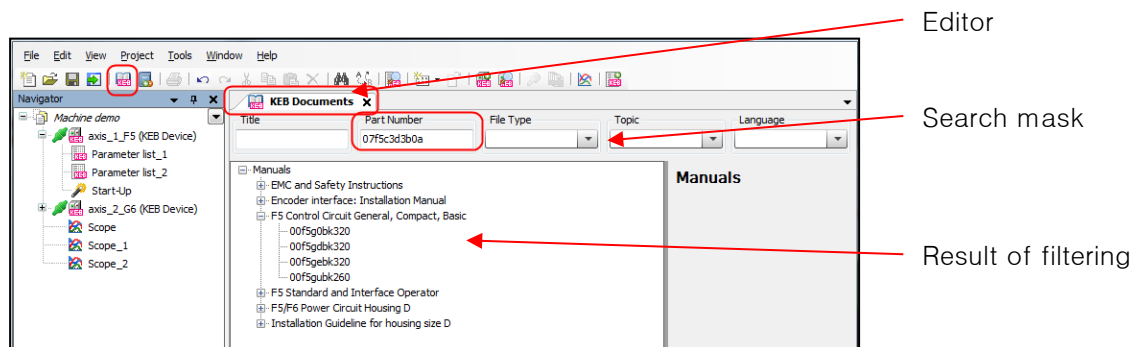


Or via the toolbar:

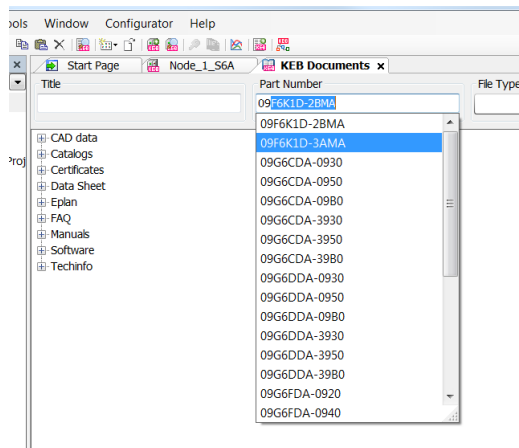


The editor "KEB-Documents" opens.

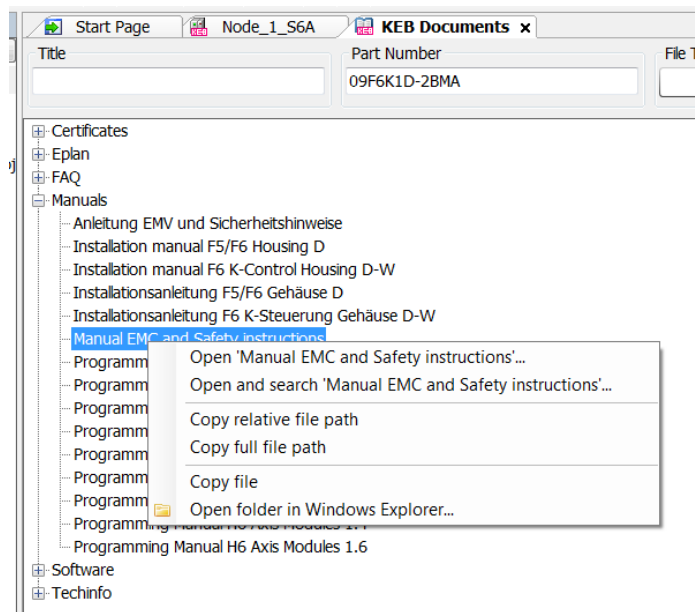
The searching can be done for part-No., data type, area, language.



When entering the part number, devices are proposed which are contained in the configurator database. Numbers of other KEB devices are also accepted.

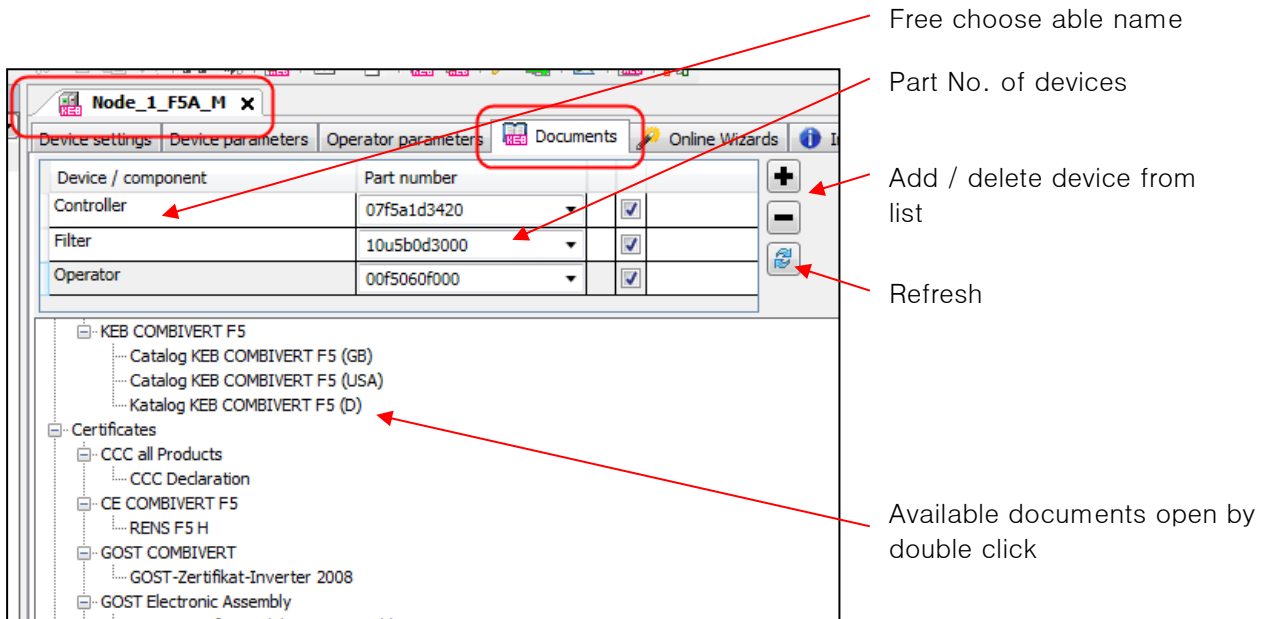


The document is opened by double-clicking on the document name. Via the context menu - right mouse button - on the document name different options are available.



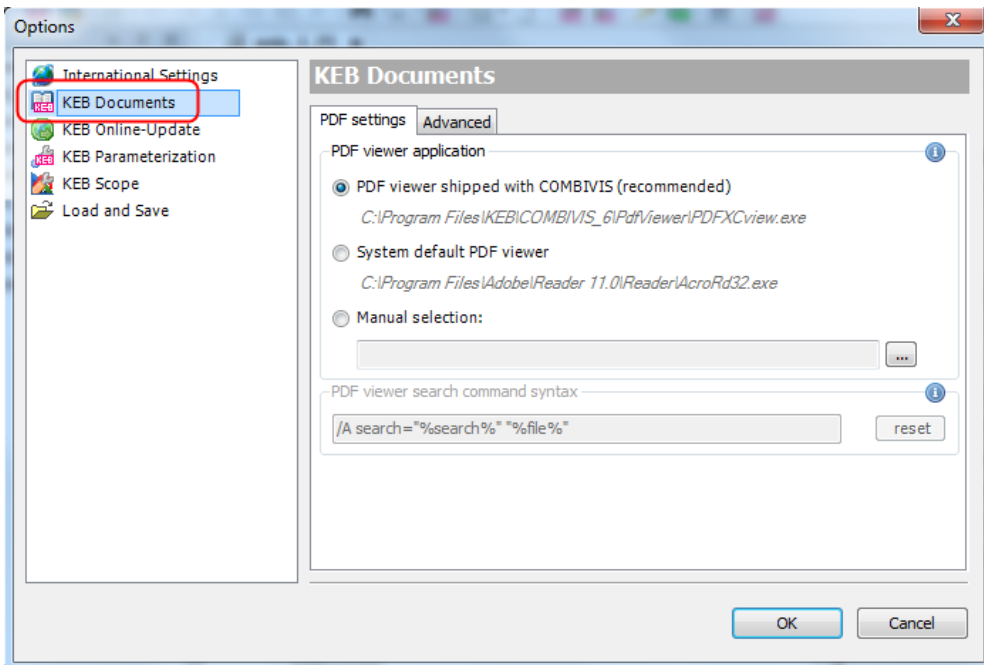
Device depending access to documents:

In the Device Editor there is the tab “Documents”. The documents can be searched by device part number. A part number you enter here will be permanently assigned to the unit in the project.



PDF-Viewer:

The used PDF Viewer can be set by menu “Tools” → “Options” → “KEB documents”. The proposed PDF X-Change Viewer offers some advantages compared to other commonly used PDF viewers.

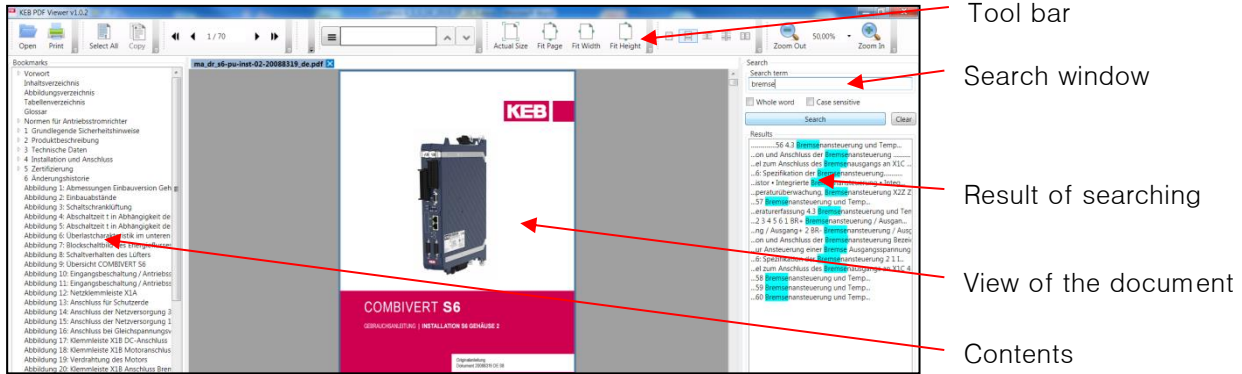


13.3 KEB PDF Viewer

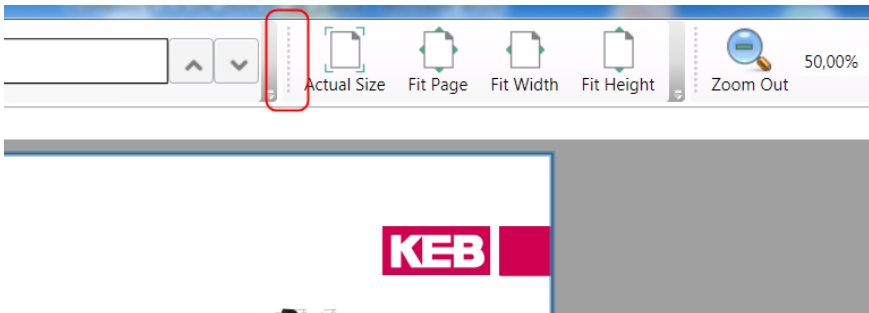
The KEB PDF Viewer is a simple program adapted to the KEB document database. It will be installed during the installation of CV6.

Other viewers can also be used but have partially limited functionality.

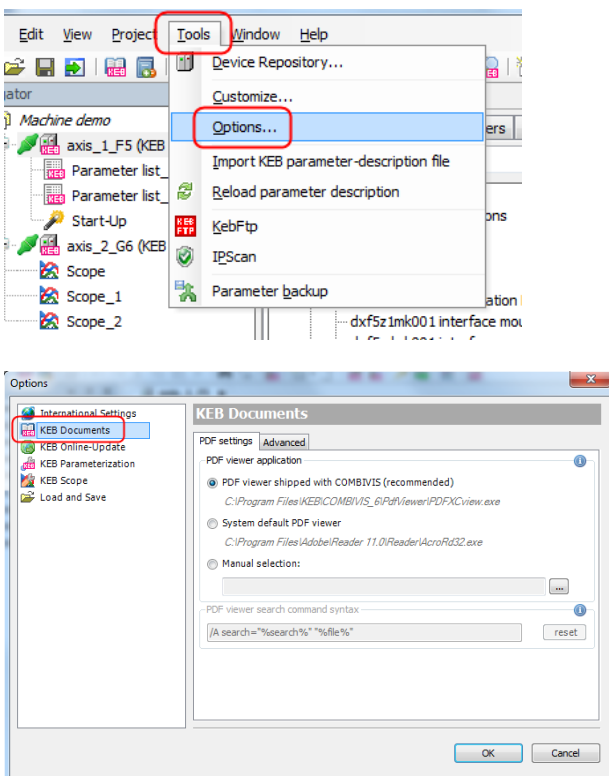
(For example: With Adobe Reader, the parameter search cannot be performed on the parameter if the document is already open.)



The toolbar can be customized by dragging and dropping the fields along the dashed line.



The used PDF viewer can be chosen under Toolbar "Tools" → "Options" → "KEB documents".



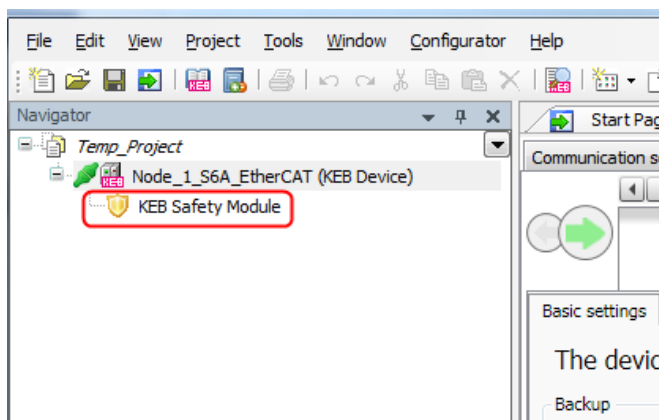
14 KEB Safety Module Editor

The KEB Safety Module Editor is used for parameterization and analysis of data in the KEB Safety Modules in COMBIVERT F6-A, H6 and S6-A.

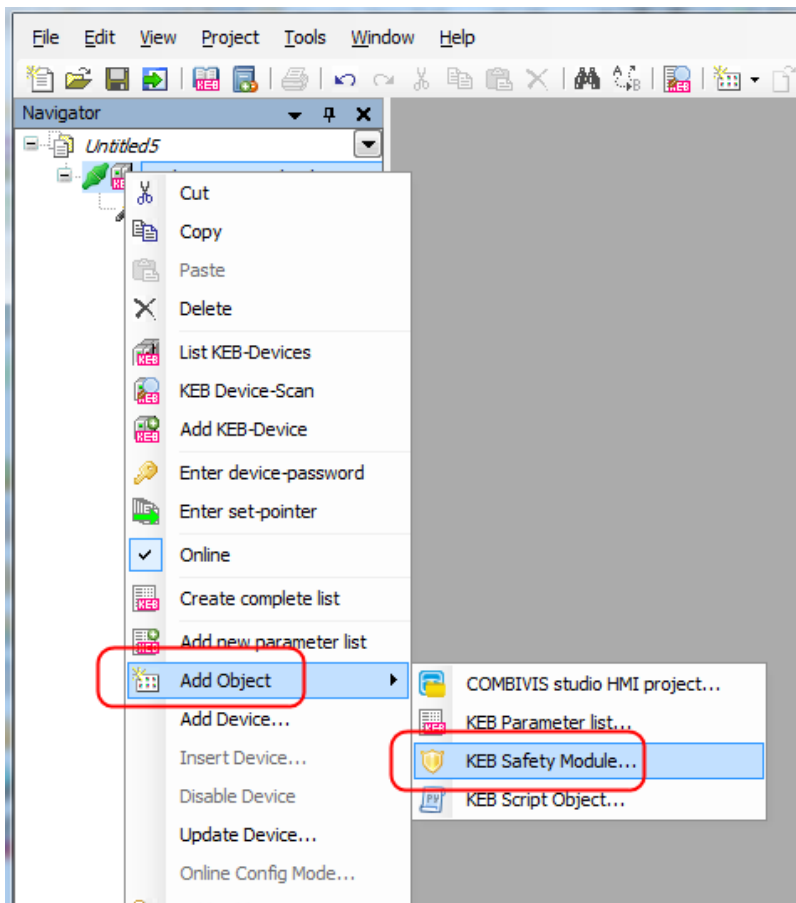
For the Safety Module Editor special system requirements apply, => [chapter 2.3](#).

14.1 Open Editor

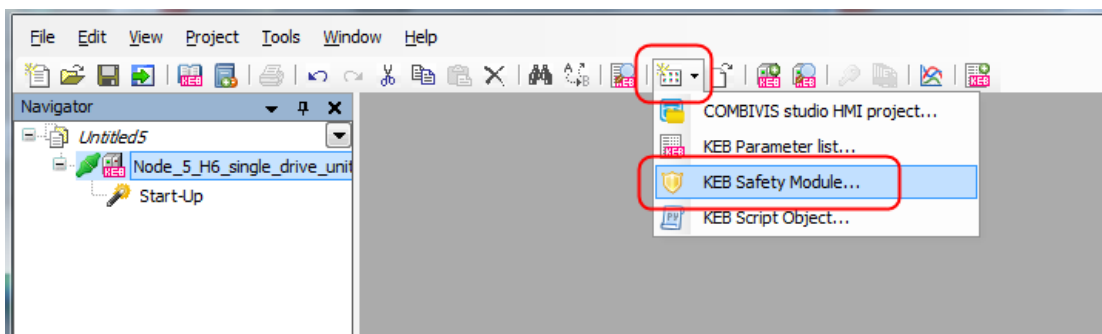
The Safety Module Editor is connected to the device and shown below the drive controller in the Navigator. It can be opened by double click with mouse on the name.



If not, please open KEB Safety Module Editor by
Right-mouse-key → choose “Add Object” → “KEB Safety Module” → “Add”:



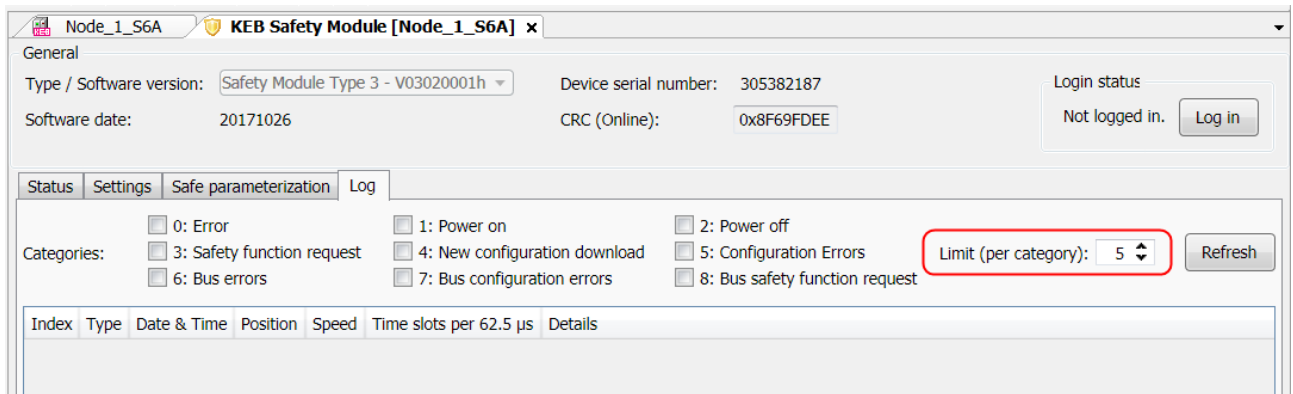
Or: in tool bar click on icon  → “KEB Safety Module” → “Add”





Please find the description of parameters and editor in the manual of the safety module.

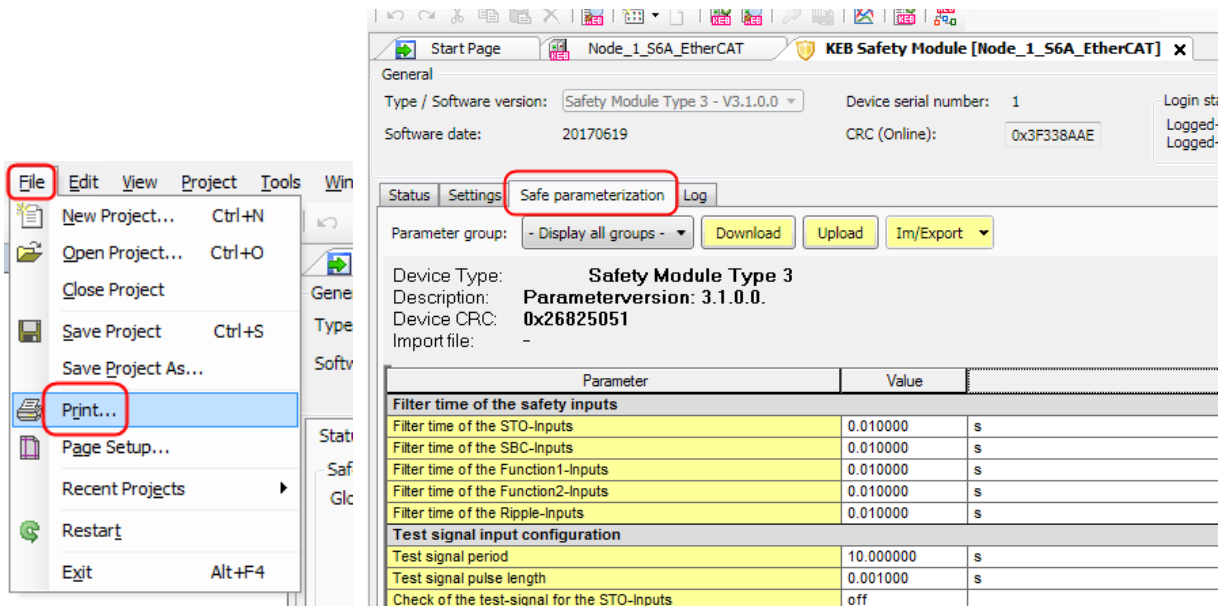
The number of read lines of the log file can be limited.



14.2 Print Configuration

The configuration of the safety module can be printed:

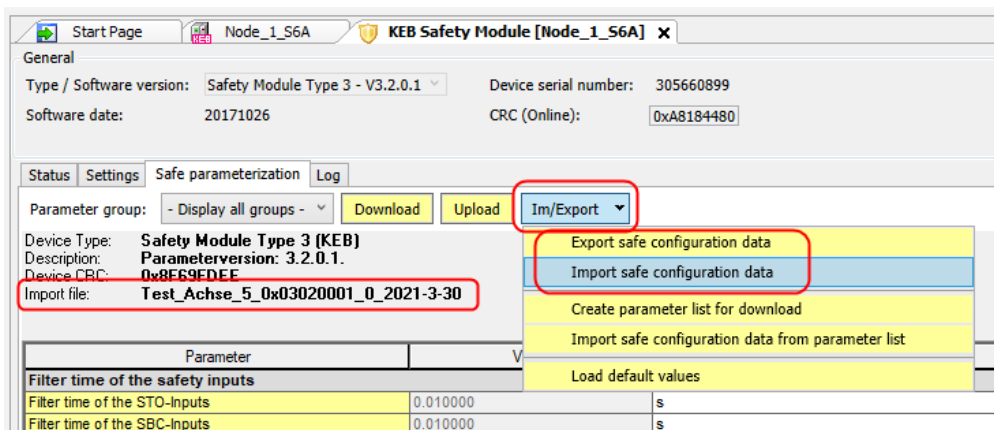
Open safety module editor → select tab “Safe parameterization” → menu: “File” → “Print”.
By PDF-creator program an image file can be created.



Sicherheitsmodul-Typ: Safety Module Type 3 (KEB)
 Beschreibung: Parameterversion: 3.2.0.1.
 CRC: 0x8F69DEE
 Importdatei: Test_Achse_5_0x03020001_0_2021-3-30

Parameter	Wert	Einheit
Filterzeit der Sicherheits-Eingänge	0.010000	s
Filterzeit der STO-Eingänge	0.010000	s
Filterzeit der SBC-Eingänge	0.010000	s
Filterzeit der Funktion1-Eingänge	0.010000	s
Filterzeit der Funktion2-Eingänge	0.010000	s
Filterzeit der Ripple-Eingänge	0.010000	s
Testsignal-Eingangskonfiguration		
Testsignal-Periodendauer	10.000000	s
Testpulslänge	0.001000	s
Auswertung des Testsignals für die STO-Eingänge	aus	
Auswertung des Testsignals für die SBC-Eingänge	aus	
Auswertung des Testsignals für die Funktion1-Eingänge	aus	
Auswertung des Testsignals für die Funktion2-Eingänge	aus	
STO Hardware Eingangskonfiguration		
Belastung der STO-Eingänge	STO Safe torque off	
Toleranzzeit der STO-Eingänge	0.010000	s
Status der STO-Eingänge	äquivalent	
SBC Hardware Eingangskonfiguration		
Belastung der SBC-Eingänge	SBC Sichere Bremsensteuerung	
Toleranzzeit der SBC-Eingänge	0.010000	s
Status der SBC-Eingänge	äquivalent	
Funktion1 Hardware Eingangskonfiguration		
Belastung der Funktion1-Eingänge	Hardware Eingang deaktiviert	
Toleranzzeit der Funktion1-Eingänge	0.010000	s
Status der Funktion1-Eingänge	äquivalent	
Funktion2 Hardware Eingangskonfiguration		
Belastung der Funktion2-Eingänge	Hardware Eingang deaktiviert	
Toleranzzeit der Funktion2-Eingänge	0.010000	s
Status der Funktion2-Eingänge	äquivalent	
Ripple Hardware Eingangskonfiguration		
Belastung der Ripple-Eingänge	Hardware Eingang deaktiviert	
Toleranzzeit der Ripple-Eingänge	0.010000	s
Konfiguration der Auslöse 1 und 2	0	
Auslöse1 Konfiguration	0	
Auslöse2 Konfiguration	0	
Einschleichen	0.000000	s
Ripple Ausgangskonfiguration	0	
Ripple Master	aus	
Zeitpunkt	0.000000	s
Zeit Ausgangskonfiguration	10.000000	s
Periodendauer der Fallauslösung	0.001000	s
Pulsanalog der Fallauslösung	0.001000	s
Geber Konfiguration		

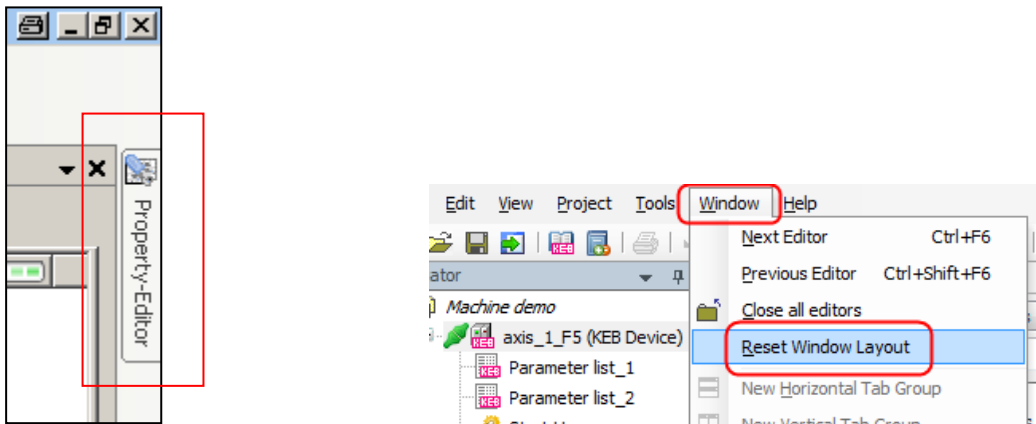
If the print shall include an individual file name, the configuration may be saved. The name can be assigned. After re-import, the file name appears in the line "Import file".



15 Frequently Asked Questions

15.1 FAQ General

- a) **Is it possible to use COMBIVIS 5 and COMBIVIS 6 in parallel?**
Both programs can be installed and opened at the same time. But each COM- and USB-interface can be used only by one of them. (e.g., CV5 by COM1/serial and CV6 by USB-COM6 will work)
- b) **Is it possible to use COMBIVIS 6 twice at the same time?**
CV6 can be open several times at the same time. But each COM- and USB-interface can be used only by one of them.
- c) **Is it possible to use parameter lists (.dw5), work lists (.wr5) and scope files (.sc5) of COMBIVIS 5 at COMBIVIS 6?**
With COMBIVIS 6 .dw5- and .wr5-files can be opened and saved. Sc5-files cannot be handled.
- d) **Is it possible to parameterize older KEB drive controllers (e.g., F4) with CV6?**
No, it is not intended.
- e) **After inserting a parameter list into the project, there is shown: “channel closed” in the online values.**
The device reference in the parameter list is not the same as in the actual device. → Adjust the device reference in the list.
- f) **Is it possible to open several projects with CV6 at the same time?**
CV6 can handle only one project at the same time. But CV6 can be opened several times with different projects (also in different languages).
- g) **Why will be found the same device several times by using the USB-Serial-Converter Part No. 0058060-0020 / -0040?**
Because of the not specified node addresses at HSP5 the F5/HSP5 or B6 drive controller will be found at each scanned node address. (HSP5 is a face to face communication with only 2 members)
→ Search only at one node address or, at manually searching, mark and open only one device (=>: [2.6.2 KEB USB Serial Converter](#)).
- h) **By using USB-Serial-Converter at a HSP5-interface of F5/B6, the device will be not or only by searching several times found.**
In default of CV6 the searching procedure starts with 9600 baud and counts upwardly afterwards. This needs a little time, so that the device may not be detected. → use CV6 at searching on HSP5 with fixed 38400 baud.
Note: on serial interface DIN66019 other, smaller baud rates may be used (F5, default= 9600 baud).
- i) **At handling of a parameter value, the property editor window is not shown. Or: Parameter value cannot be changed.**
Please try to open the property editor window in the toolbar menu “view”.
Afterwards search at the screen frame. May be the property editor window is collapsed.
If found, click into the property editor window, and open it. Clicking on the pin symbol fixes the window open.
A complete restoring of all windows can be done by toolbar: “Window” → “Reset window layout”.

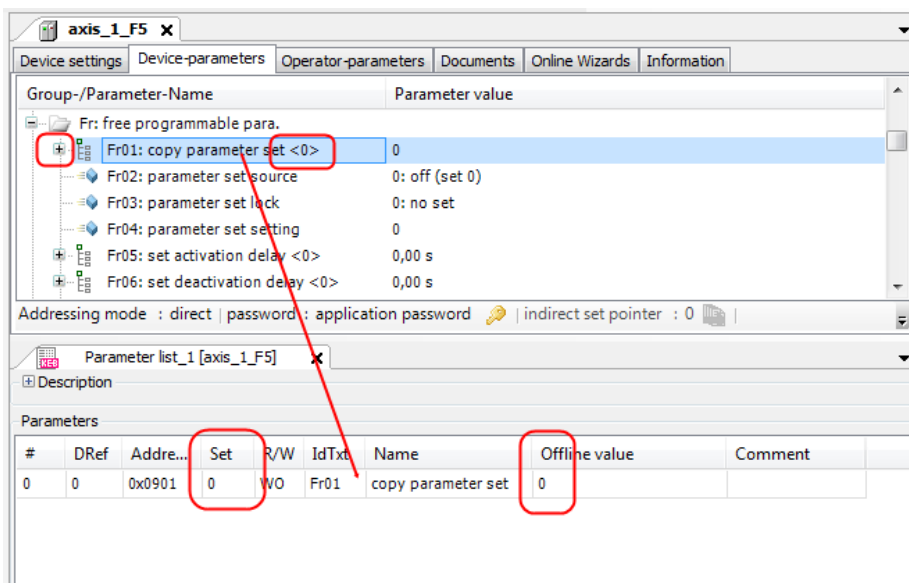


j) The copy function Fr01 at COMBIVERT F5/B6/G6 seems not to work.

With the parameter set copy function Fr01 at COMBIVERT F5 / B6 / G6 finished sets can be copied to other sets and then does not have to enter all the parameters again. The copy function runs in the drive controller and is triggered by COMBIVIS by entering the parameter Fr01 only.

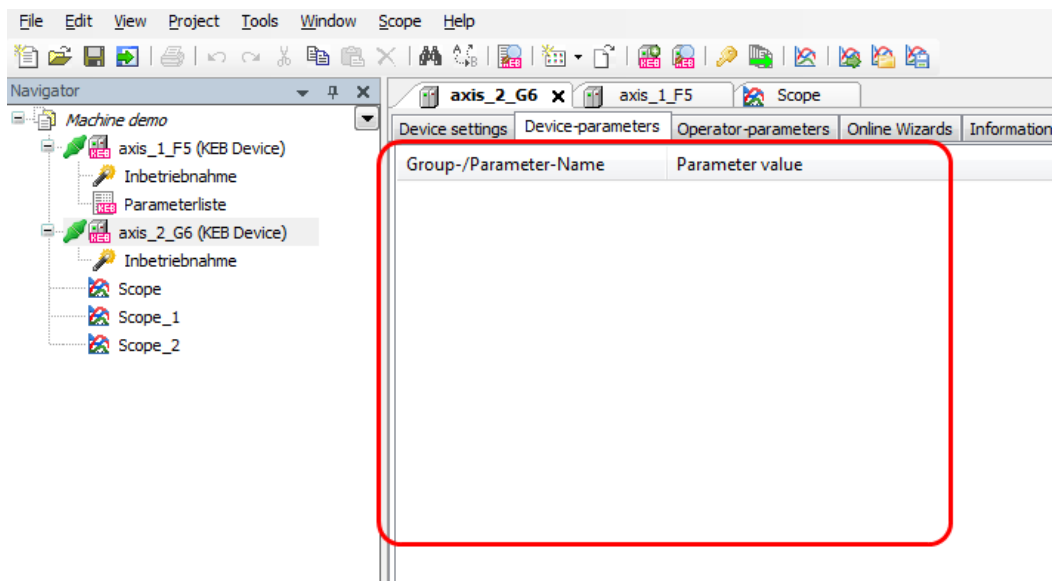
Because of the parameter "copy function" is set programmable, the set addressing mode plays an essential role in the process.

When copying the "collapsed" parameter the direct addressed set is the target (usually are then target and source set equal to 0):



Solution: Please adjust in column "set" the number of the set which is the target of the copying and adjust in the column "Offline/Online value" the number of the set which is to copy.

k) The editor window is empty / shows no parameter.



For every firmware of each KEB device a description of the parameters is needed in COMBIVIS. Parameter description for this firmware of the device is missing (=> [16 Update Function](#)).

- l) In editor is shown “service not available” at every parameter value.**
When operating with bus systems in "synchronous operation" only indirect addressing may be used (=> [4.7.1 Set Addressing](#)).

15.2 FAQ Scope

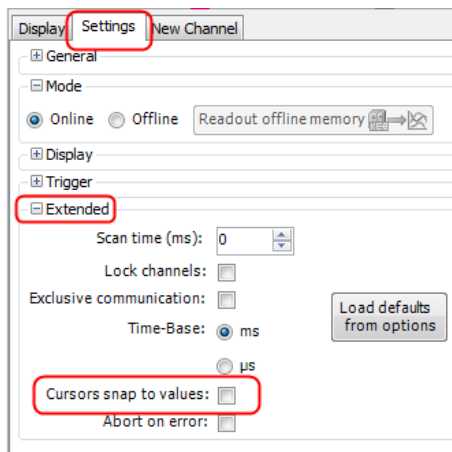
- a) Is it possible to record more than 16 channels?**
Each scope can handle max. 16 channels, but Scope can be opened several times in a project, each with 16 different channels.
- b) If a channel which is in the fast Scope mode will be disabled, does the 5th channel move up into the fast Scope mode or does the previous reservation persist?**
Yes. The channel “moves up”.
- c) Is it possible to save a CV6-scope in CV5 (.sc5) format?**
No, because of different and upgraded structures it is not possible.
- d) Is it possible to merge channels from different scope recordings?**
This is planned for a later COMBIVIS 6 version. Currently it is already possible, but only indirectly via export in an Excel-compatible format for example “CSV”. In Excel it is possible to merge curves as tables based on time-axis and compare them directly via diagram function.
- e) The externally stored Scope file ending .sc6 cannot be opened.**
With COMBIVIS 6 versions up to 6.2.2.0 only an XML file can be imported! The file extension .sc6 was introduced with version 6.2.3.0, to better distinguish Scope files of other XML files. The data format .sc6 continues to be an XML format. The .sc6 file extension can be changed to XML and thus imported into earlier versions COMBIVIS 6.

15.3 Known Malfunctions in Version 6.7.

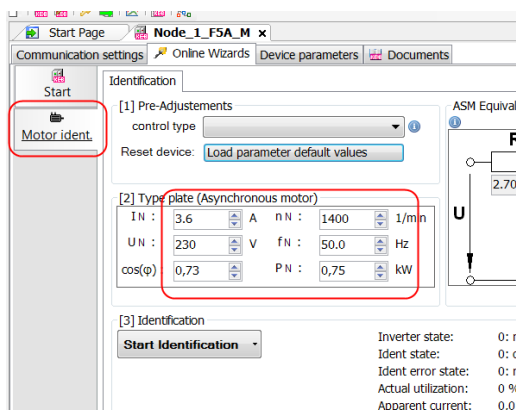
Regarding known malfunction of KEB COMBICONTROL please see the belonging manuals.

- a) The horizontal cursors in Scope locks only on the values of the first channel. The values of the other channels cannot be matched.

Workaround: By “Scope” → “Settings” → “Extended”: disable the hook at “Cursors snap to values”. Within the cursors can be placed freely by mouse.

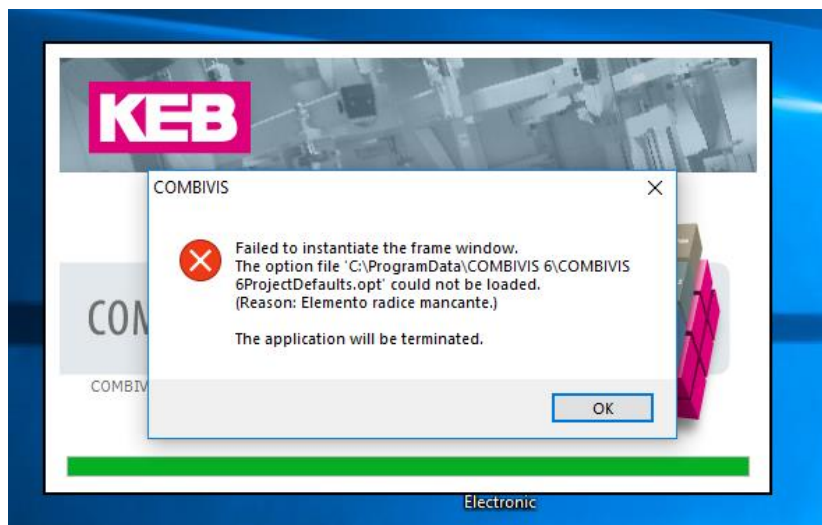


- b) At German Windows operating system and setting in English, the COMBIVERT G6 / F6 ASCL / SCL wizard has problems if the comma is used to separate the decimal place.



Workaround: If a value with decimal place is entered, the usual dot in English must be used. A comma will be ignored! In the display, however, "by default" can be a comma and then also applies. (The parameter editor can use either a dot or a comma, both are valid).

- c) At starting of COMBVIS or COMBVIS studio an error message pops up:
The file **C:\Programdata\COMBIVIS6\.....COMBIVIS6ProjectDefaults.opt** could not be loaded.



Please see => [11.5 Error Messages](#)

d) COMBIVIS Window does not open.

COMBIVIS minimized Icon is in the task bar, by click on this, the window does not open. Sometimes you can see the window flying out of the screen. This can happen when COMBIVIS was placed on the remote screen, and this was disconnected. COMBIVIS opens on the no longer existing screen. It is not a problem of COMBIVIS only. But we have seen this also on other programs (e.g., Microsoft Excel). The effect comes from the windows display handler.

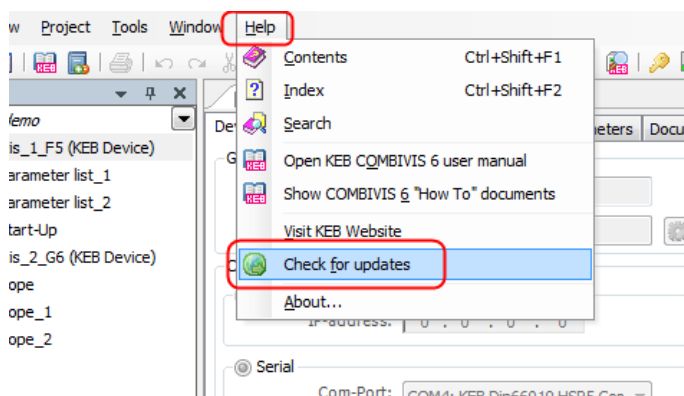
You can solve the effect by:

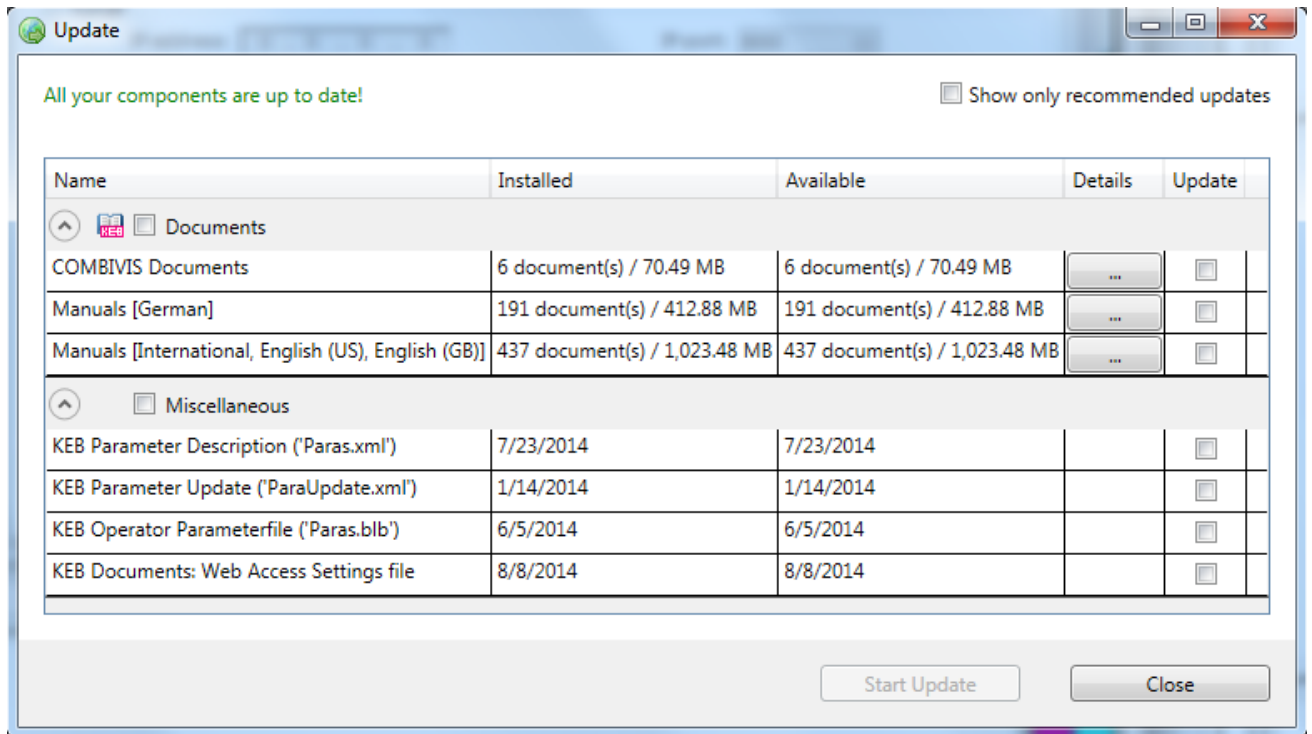
Push “shift key” and hold and push “right mouse key” on the minimized Icon of COMBIVIS in the task bar at the bottom of the screen. A window opens and select “maximise”. Then you see the COMBIVIS window. Then put the upper frame line by the mouse pointer and lower the size of the window. By this procedure windows orders the COMBIVIS window to the main screen.

16 Update Function

16.1 Manually Checking for Updates

With function “Check for updates” on the start page or in menu “Help” an automatically connection to the KEB-homepage is done if a connection to the internet is available. The parameter description file “paras.xml” is checked for a newer date and downloaded/integrated if desired.





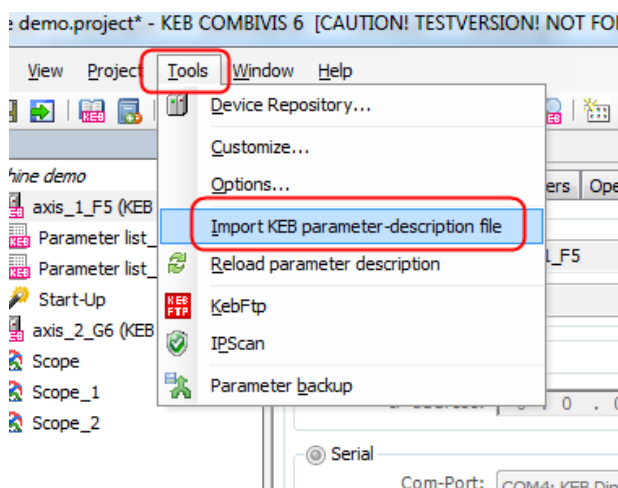
16.2 Automatically Checking for Updates

As background function COMBIVIS 6 can search automatically for an update if the internet connection is active (=> [6.4 Online Update](#)).

16.3 Manually Update for Parameter Description

If update by Internet will not work, the parameter description can be got from KEB-Homepage and copied by external storage (e.g., USB Stick) into COMBIVIS.

Search on www.KEB.de for the file "paras.xml" → store on the PC or stick → and integrate by: Menu "Tools" → "Import KEB parameter-description file".



After importing a reload must be done or the COMBIVIS must be restarted.

17 Drive Storage

17.1 Drive storage Wizard

The device storage wizard enables the transfer of recipe lists in the device memory of COMBIVERT F6 and S6 as of firmware V2.3.

The connection can be made via

- cable part. No. 0058025-001D (=> [2.7.1 Serial cable](#))
- KEB-USB serial converter Part. No. 0058060-0040 from version V2.4 and the designation "FTP ready" on the Type plate (=> [2.7.2 KEB USB converter](#))
- UDP Port 8002 on COMBIVERT F6/S6 Pro on the internal Ethernet interface

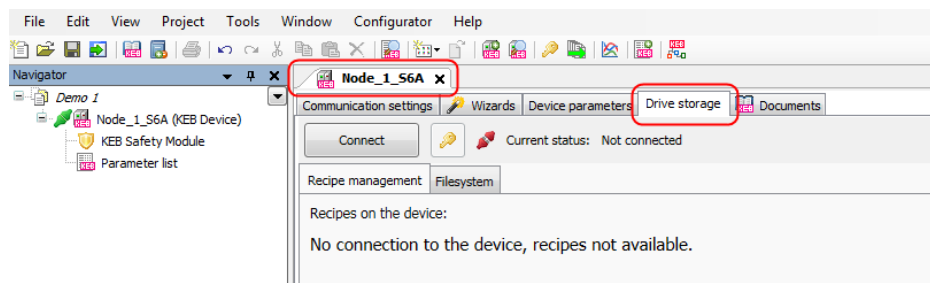
Note:

- Communication over the F6 Ethernet operator or the F6 USB operator opens only access to operator-internal store, not to the drive!
- Files in compressed form (zip files) cannot be loaded into the drive storage.
- Accessing the drive storage and loading recipes into the unit only works when the modulation is switched off (status voltage enabled, switched on, ready to switch on).

The function of the recipe management is described in the programming manual of the COMBIVERT (keyword: "recipe management"). It can be found in the [document data base](#).

With the drive storage wizard also other file types can be transferred (like firmware, description files etc.).

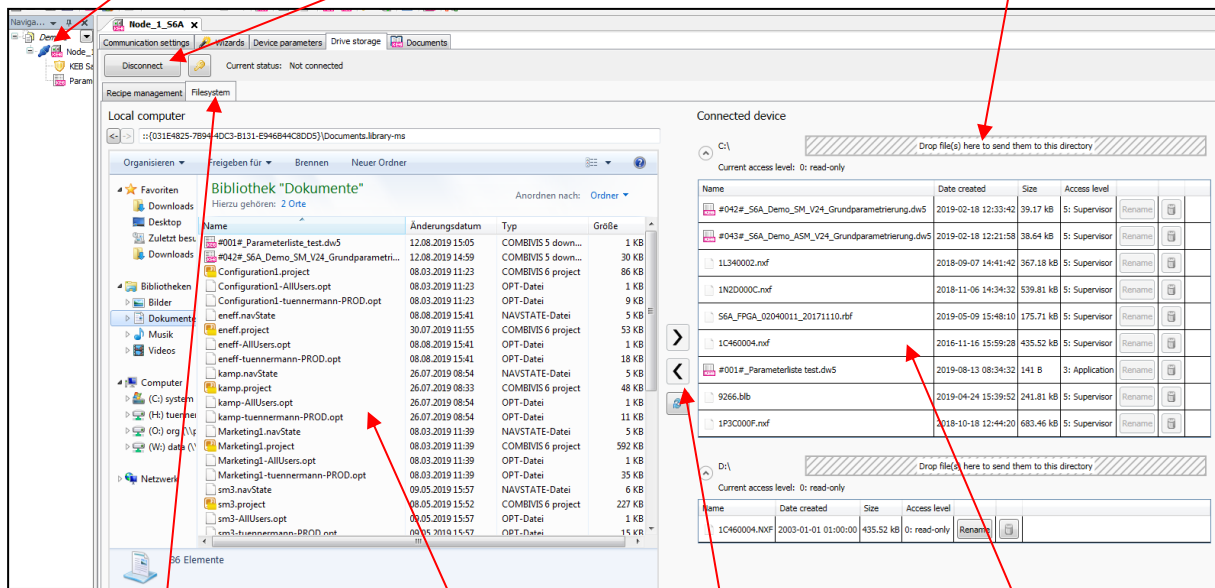
The drive storage is in the device editor:



Contactor blue = Commu-
nication with drive storage
green = with device,
red = offline

Open connection to
drive storage

Storage area for file transfer



Show file system

Files on the PC

Transfer files

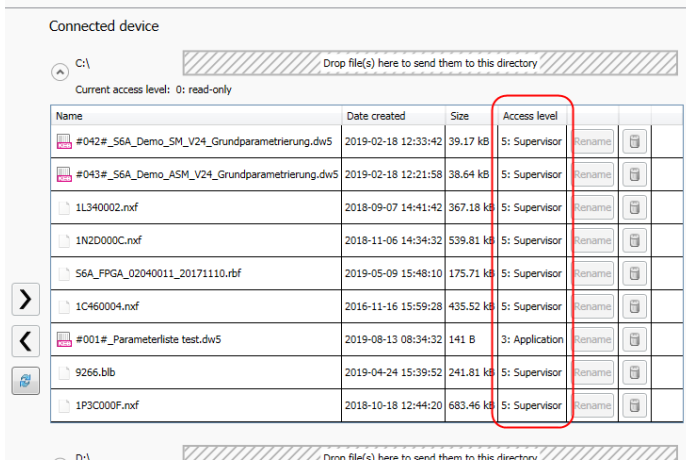
Files in the drive storage

Recipes have the file ending „.dw5“.

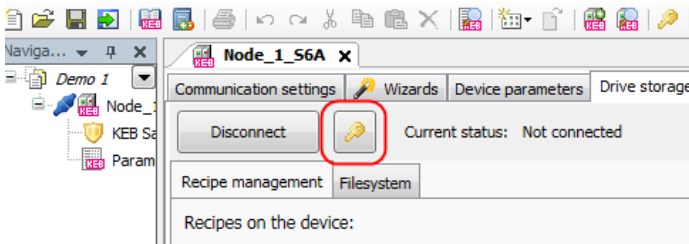
17.1.1 Access Level / Password

For transfer or deleting a specific access level is required, depending on the file function:

- No access: Level 0 = read-only
- User access: Level 3 or 4 = Application, Password: 440
- Service access: Level 5, 6 or 7 = Supervisor, Password ***
- Operating system: Level 10

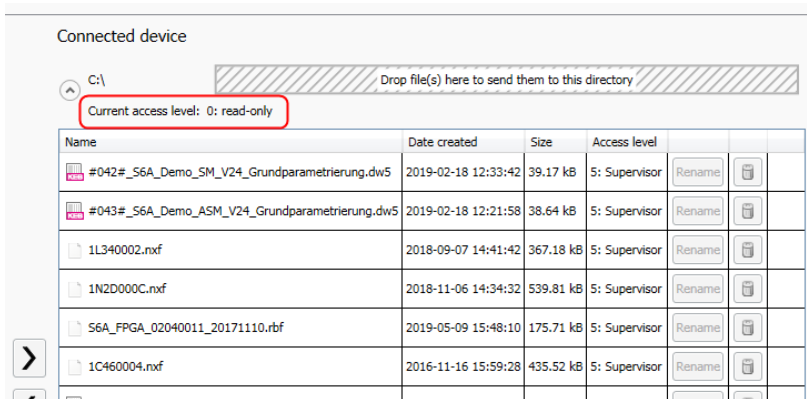


The password must be adjusted by the key symbol.



The key button in the tool bar or in the parameter editor at the bottom cannot be used for that!

The current access is displayed here:



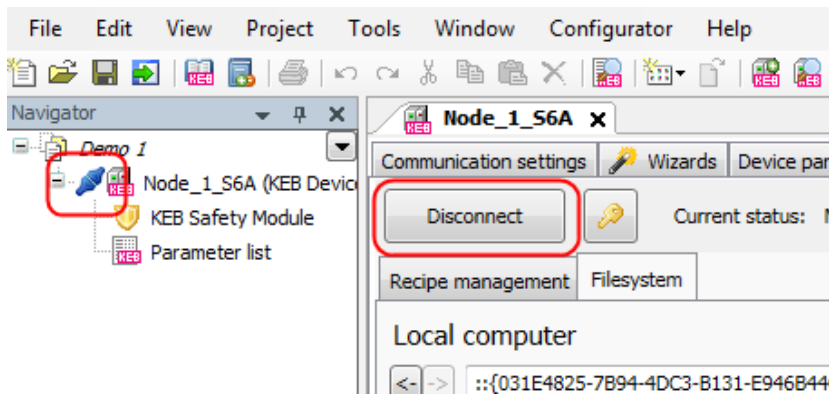
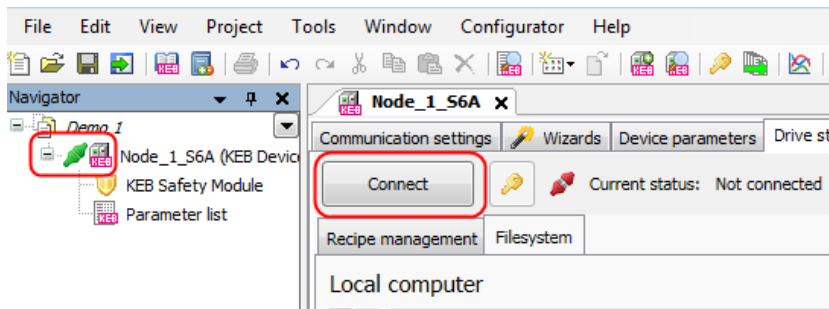
After Power-On-Reset the access level is 0: read-only.

17.1.2 Connect Drive Storage

Klick on the button “Connect”.

If needed enter the password.

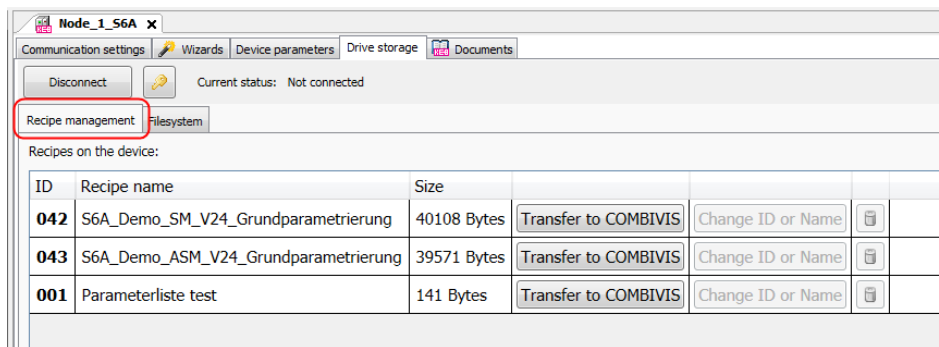
The connection to the parameter interface (green contactor in the navigator) is interrupted and `redirected` to the internal storage (blue contactor). The parameters are not accessible while using the drive storage wizard.



17.1.3 Show Stored Recipes

Tab Recipe management.

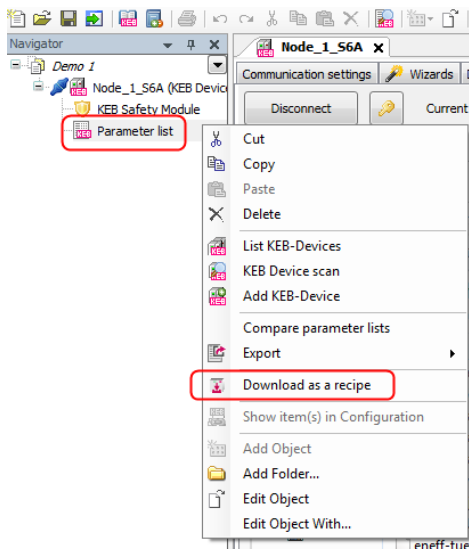
The recipes can be transferred to the Navigator as a parameter list.



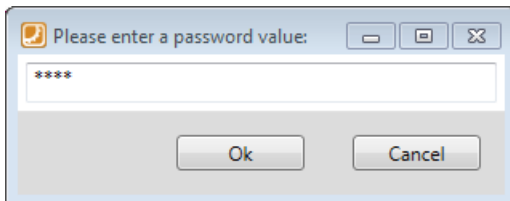
17.1.4 Create a Recipe

A parameter list can be loaded directly from the Navigator as a recipe into the COMBIVERT.

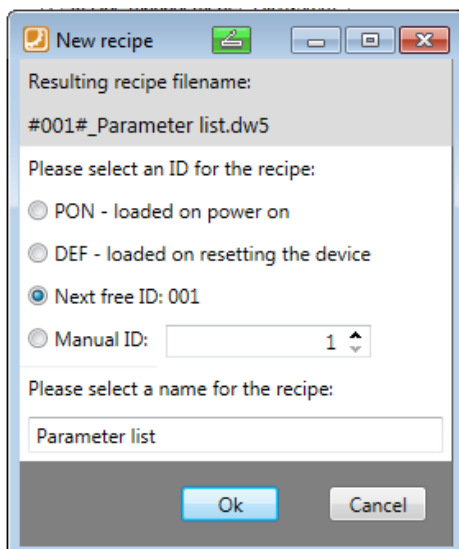
Select the parameter list → right mouse key → “Download as a recipe”.



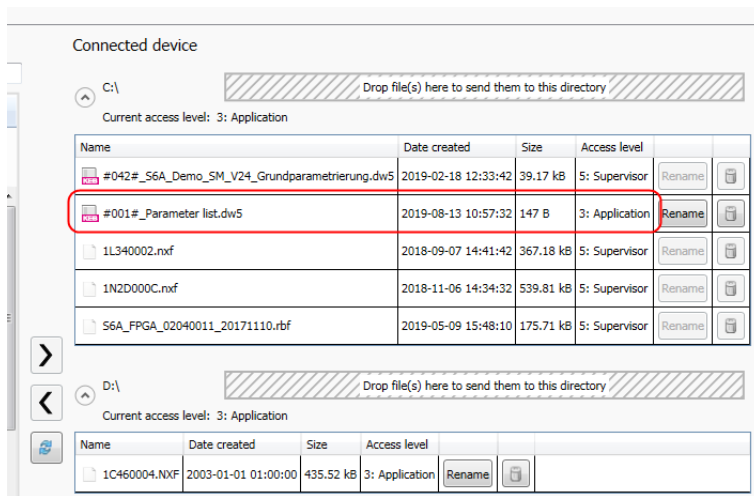
A Password is required. The user password is typically "440" (Level 3).



The file names of the recipes must meet certain criteria (=> Programming Manual). The function and the name can be selected.



With "OK" the list is transferred as a recipe to the device storage.



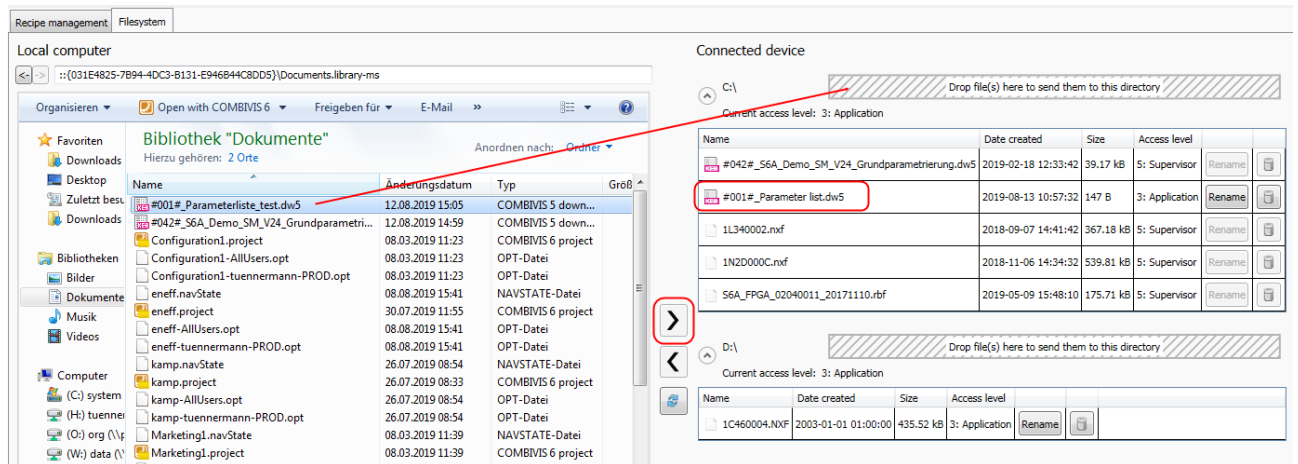
17.1.5 File System / Transfer File

In the "File system" card, the file system of the PC is shown in the left half of the window and the COMBI-VERT file system in the right half of the window.

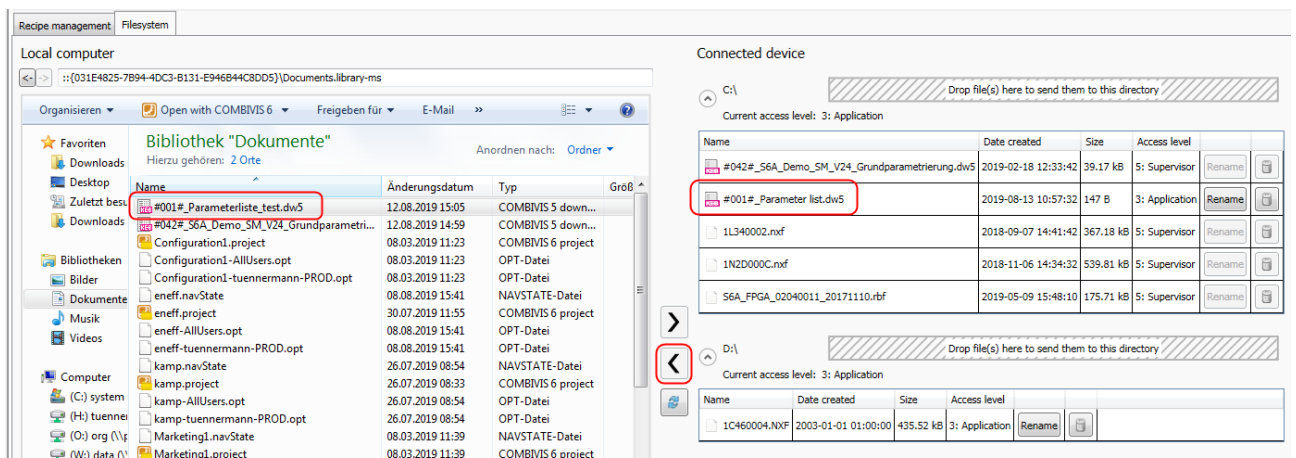
The drives C: and D: are available in COMBI-VERT. Normally, C: stores the user-specific files (recipes) and D: the system-relevant files (firmware, etc.).

The file names of the recipes must meet certain criteria (=> Programming Manual).

Transfer a recipe from the PC file system to the COMBI-VERT: Select files → by ">" transfer from one to the other file system or drag and drop the file from the PC file system onto the dashed area.

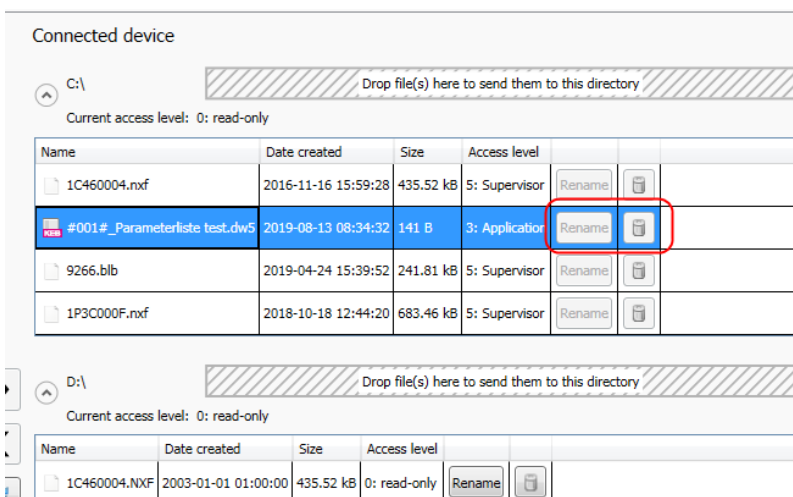


Transferring a recipe from the COMBI-VERT to the PC file system: Select files → Transfer by "<" from one file system to another.



17.1.6 Edit Recipe in the File System

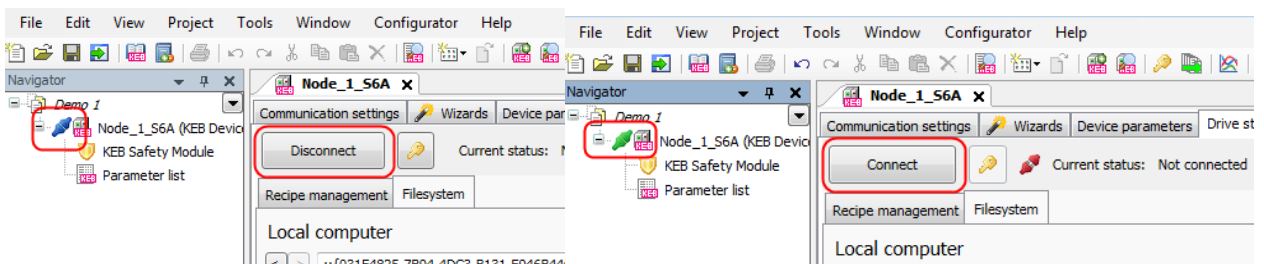
The recipe can be deleted from the file system (trashcan icon).
The recipe name can be changed.



The content of a recipe can be changed by transferring it as a parameter list to the Navigator and saving it again as a recipe after the change (=> [17.1.3 Recipe Management](#)).

17.1.7 Disconnect

After the connection has been disconnected, the connection to the parameterization interface of the COMBI-VERT opens again = green connector symbol in the Navigator.



17.2 KEB-FTP File Transport Program

By KEB File Transfer Program Files can be transferred between PC and KEB devices

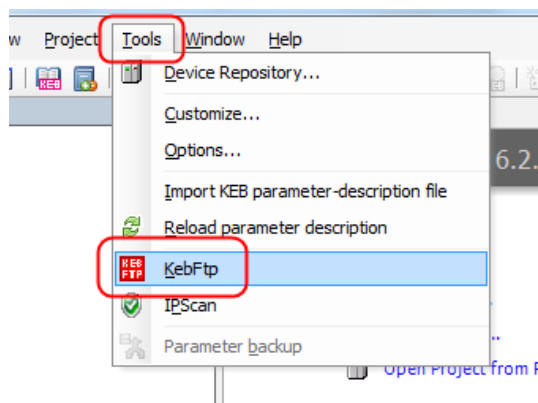
- PC and KEB Portable-Operator (Part No. 0058060-1010 /-1110) with USB cable
- PC and COMBICONTROL C5 / C6COMPACT I+II, H6CU, P6, T6MCU with LAN cable (not with KEB USB converter)
- PC and operator of COMBIVERT F6 with USB- or LAN cable
- PC and COMBIVERT S6 /F6 with cable Part No. 0058025-001D (=> [2.7.1 Serial cable](#)) or KEB-USB-Serial-converter Part No. 0058060-0040 from version V2.4 and signed as “FTP ready” on the type plate (=> [2.7.2 KEB USB converter](#))
- UDP Port 8002 on COMBIVERT F6/S6 Pro on the internal Ethernet interface

Note:

- Communication over the F6 Ethernet operator or the F6 USB operator opens only access to operator-internal store, not to the drive!
- Files in compressed form (zip files) cannot be loaded into the drive storage.
- Accessing the drive storage and loading recipes into the unit only works when the modulation is switched off (status voltage enabled, switched on, ready to switch on).
- Not useable for C6 IPC types!

Open:

Menu bar “Tools” → “KEBFTP”



Note:

KEB-FTP is a separate program running parallel to COMBIVIS 6. It is not possible for KEB-FTP and COMBIVIS 6 to serve the same COM-Port at the same time. So, the used COM Port in KEB-FTP must be inactive in COMBIVIS 6.

Adjustments:

IP-address or COM-Port and password if required (=> device manual) must be adjusted. Then click on Button “Connect”.

The password resets, depending on device, sometime after last serving.

For COMBIVERT F6/S6 the baud rate must be at 115200.

The file length is limited compared to Windows Explorer

COMBICONTROL C5 = 8 digits + file extension

COMBICONTROL C6 = 32 digits + file extension

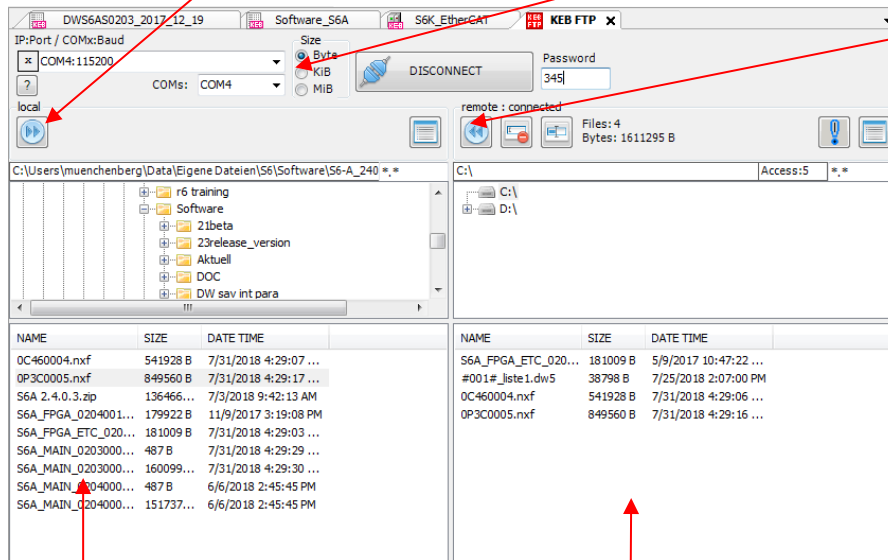
Portable Operator = 32 digits + file extension

Please consider the device manual

Transfer data from PC to device

Adjustments for communication

Transfer data from device to PC



Data in the PC

Data in the device

18 Configurator

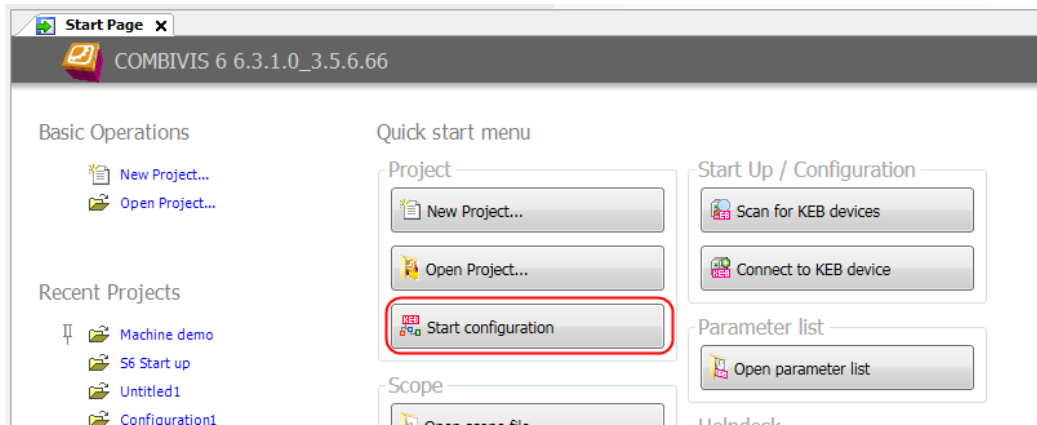
18.1 Properties

The KEB Configurator is a tool for easy modelling of KEB drive systems. While assembling these models you are supported by an intuitive Graphical User Interface (GUI) and different component selection wizards. You can use the created systems for documentation purposes. Furthermore, you can generate COMBIVIS (or COMBIVIS studio) projects and part lists, e.g., for requesting a quotation. The Configurator also provides easy access to the technical data of KEB devices and their documentation.

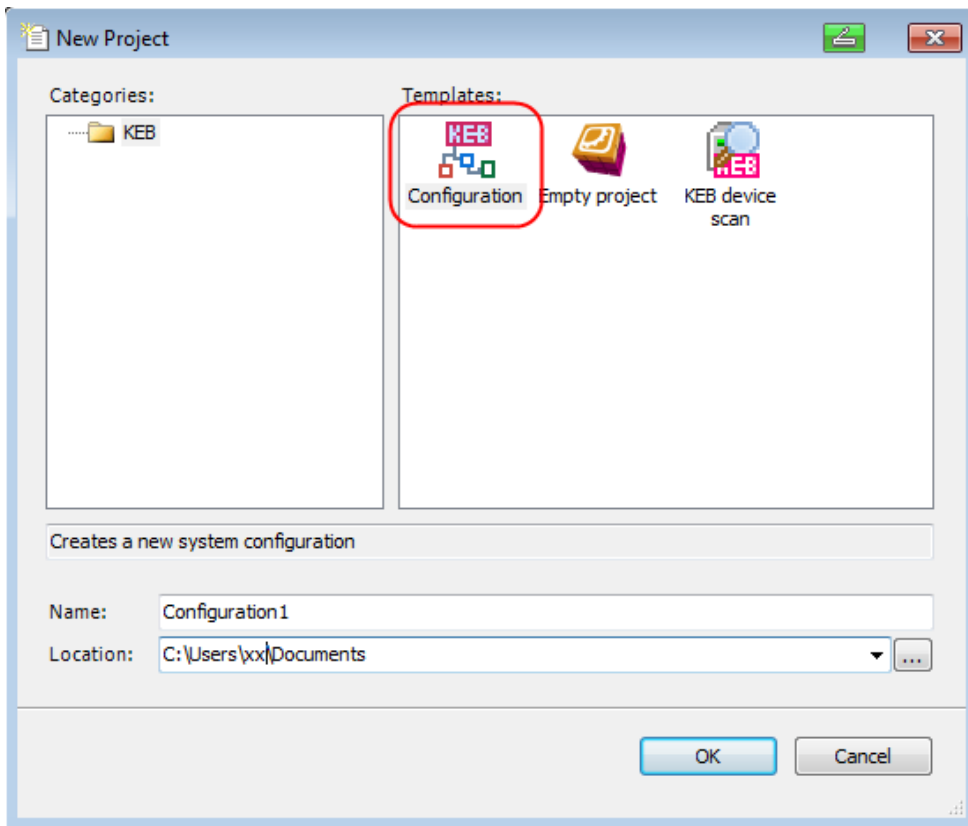
Please Note: In the Configurator, the standard portfolio of KEB is included. For special options, please contact directly to the KEB sales.

18.2 Start Configurator

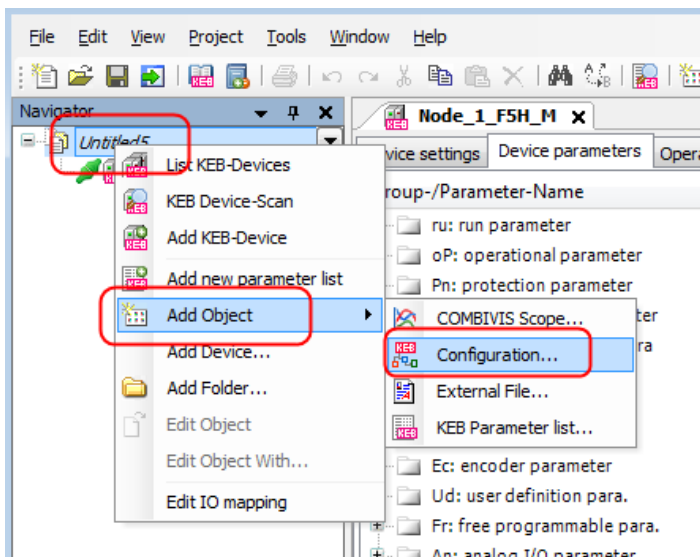
Open by Start page:



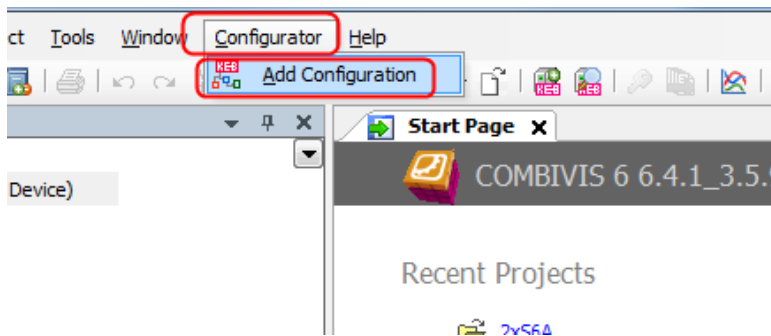
Or by “New project” and “Configuration”



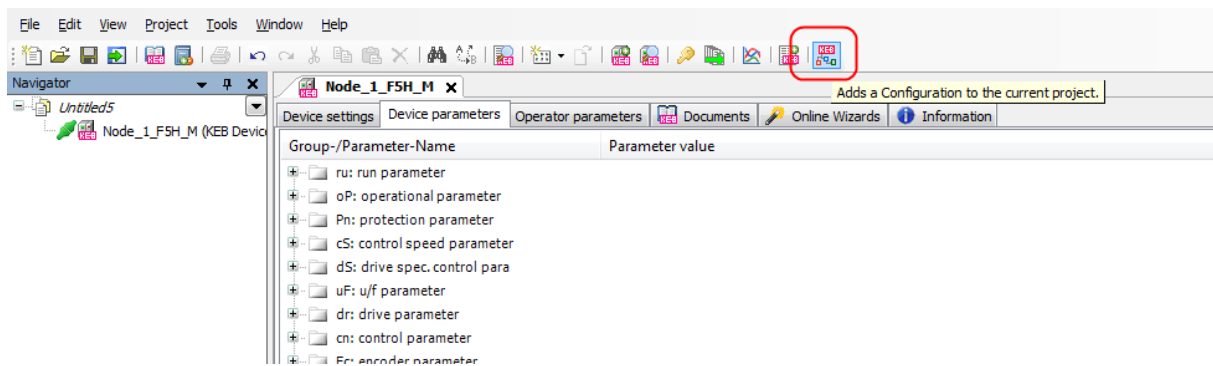
Or in an already existing project: Add by “Add object”:



Or via the menu:

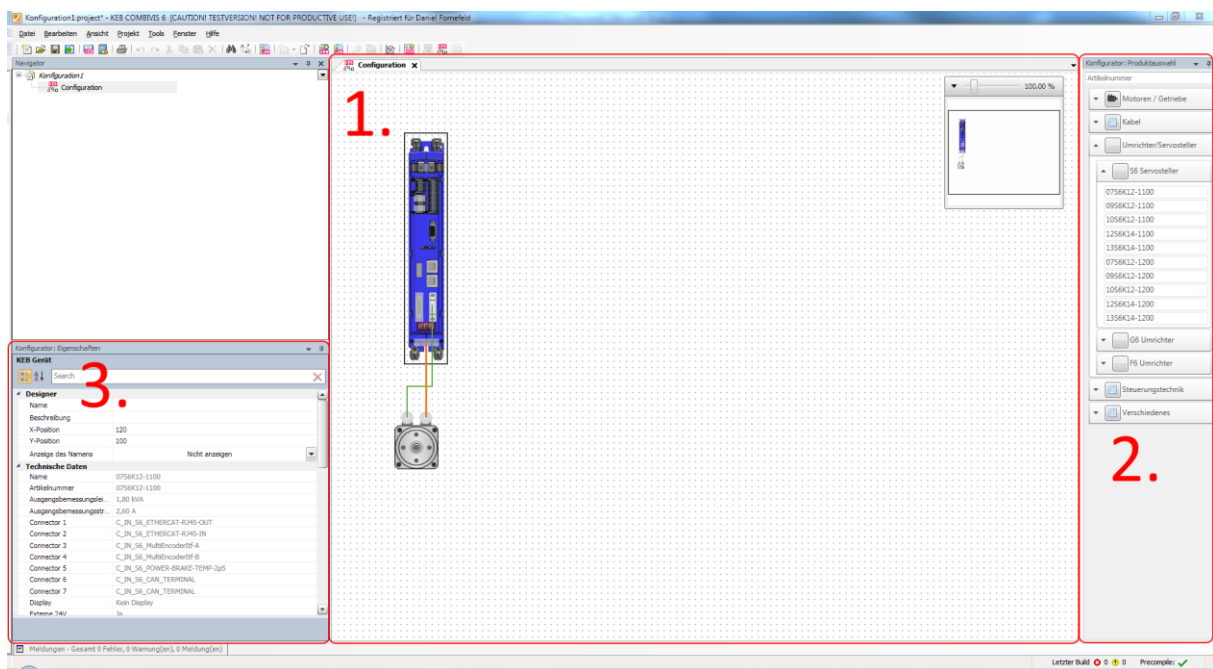


Or via tool bar:



18.3 Work with Configurator

The Configurators user interface consists of 3 main parts:



1. Workspace

Here all selected devices are shown, placed, and connected.

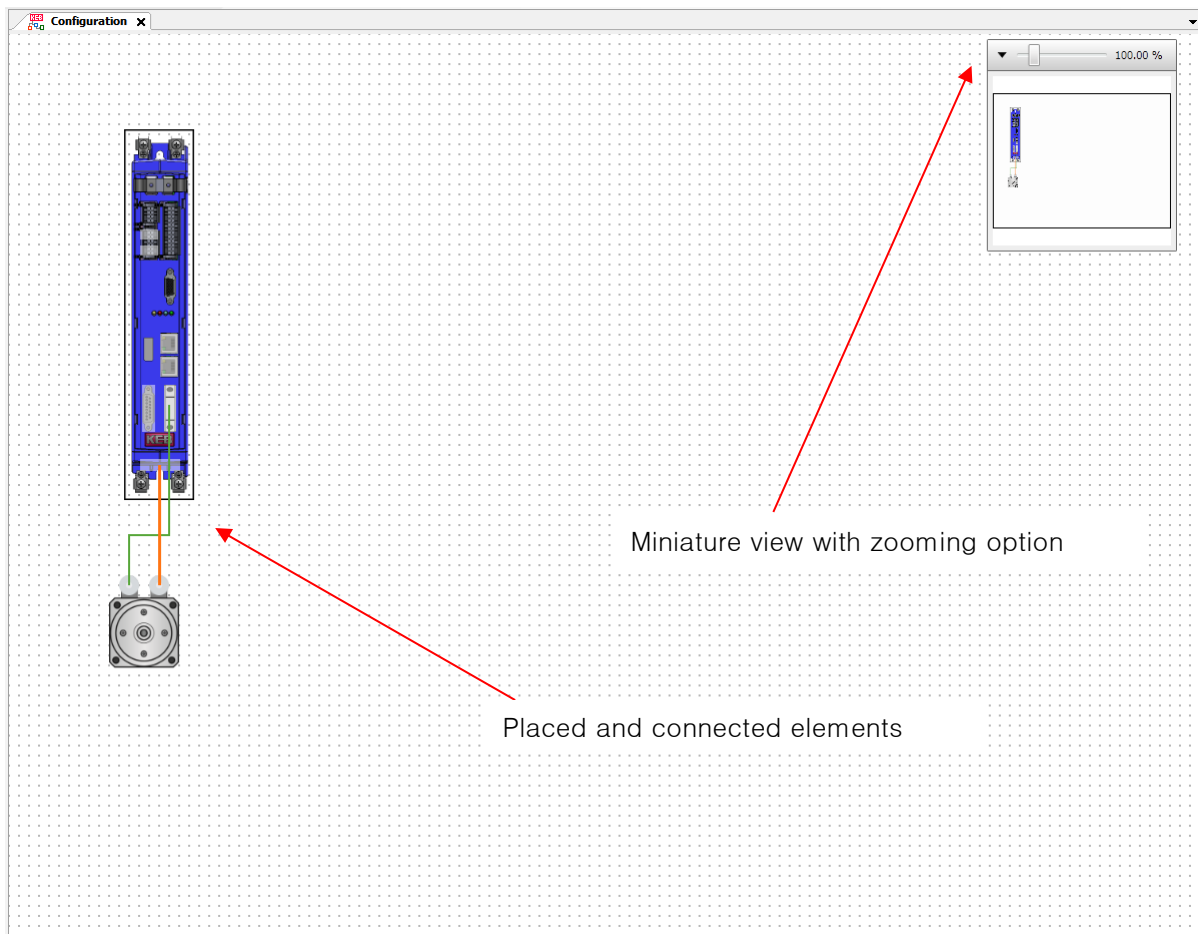
2. Product selection window

The elements are shown that can be used in the Configurator.

3. Properties window

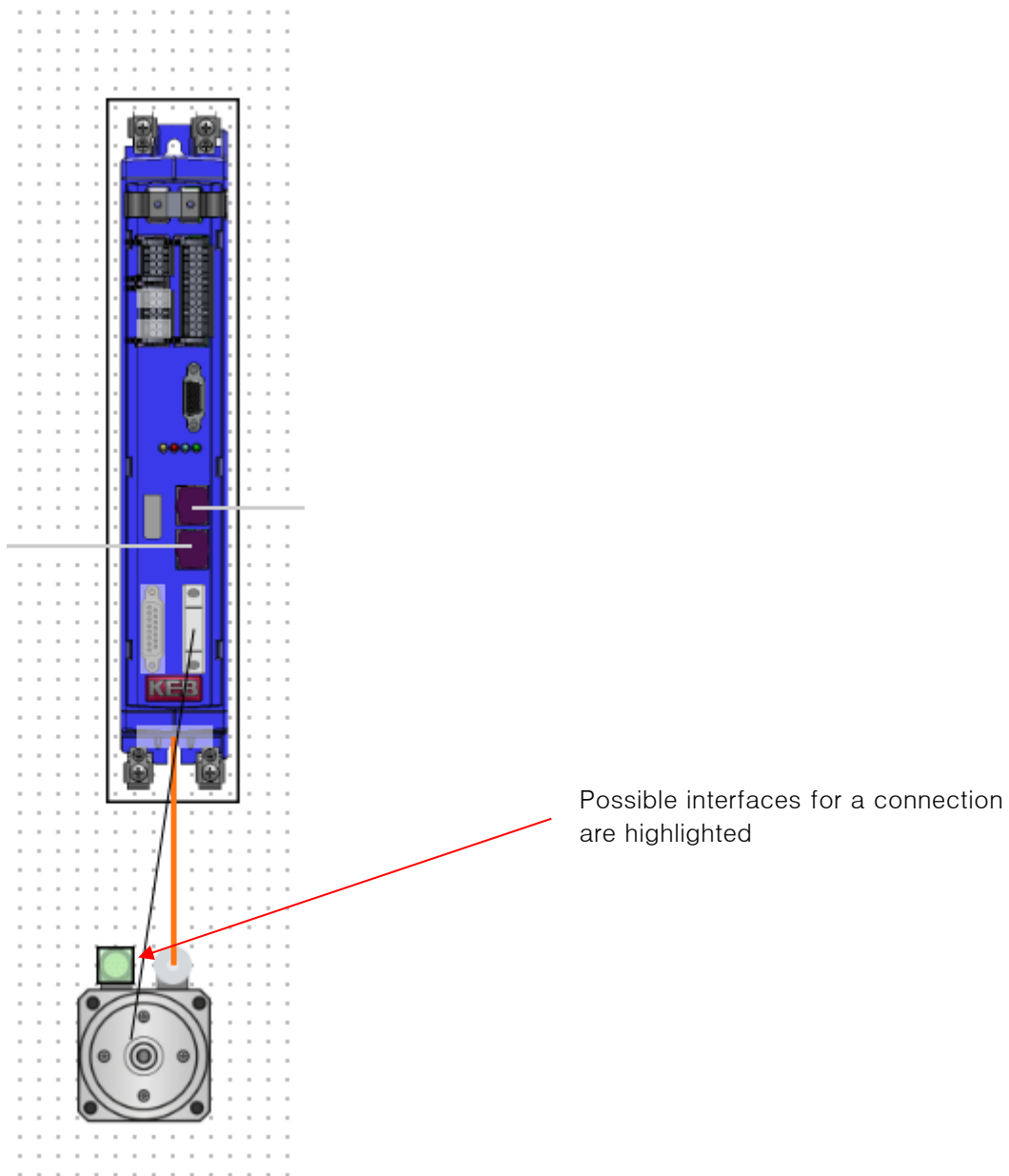
The properties of the elements selected in the workspace are shown.

18.3.1 Workspace



18.3.2 Connections

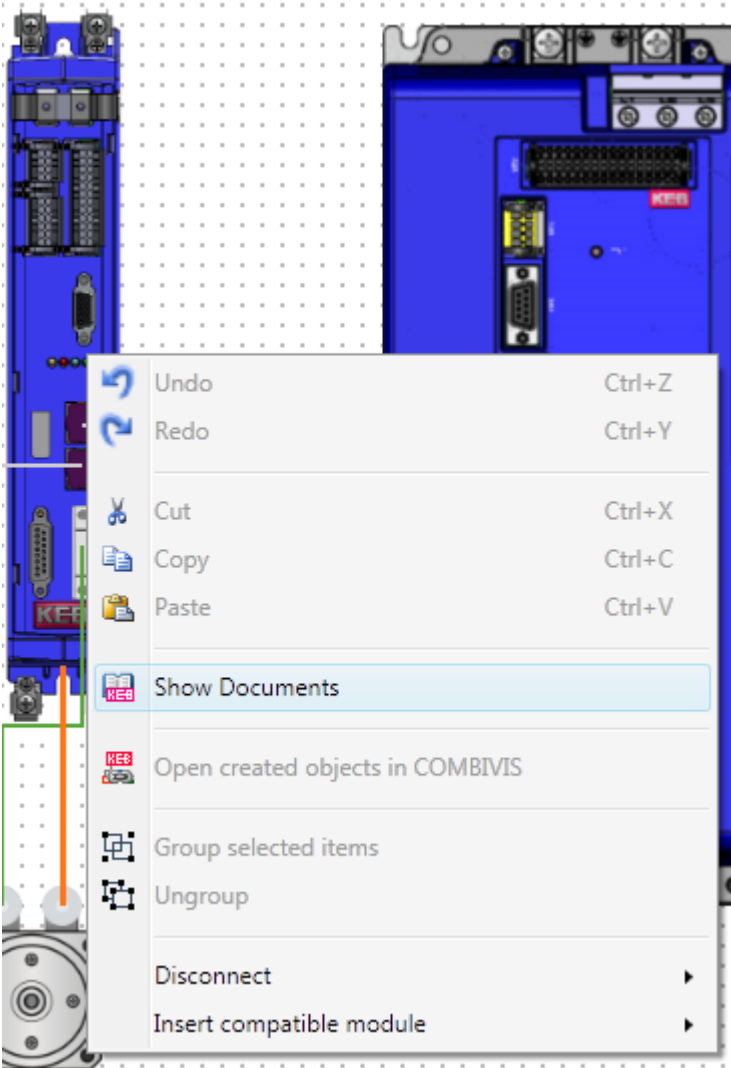
Connection (Cables) can be inserted from the product selection or by drawing a new connection from an interface with the mouse:



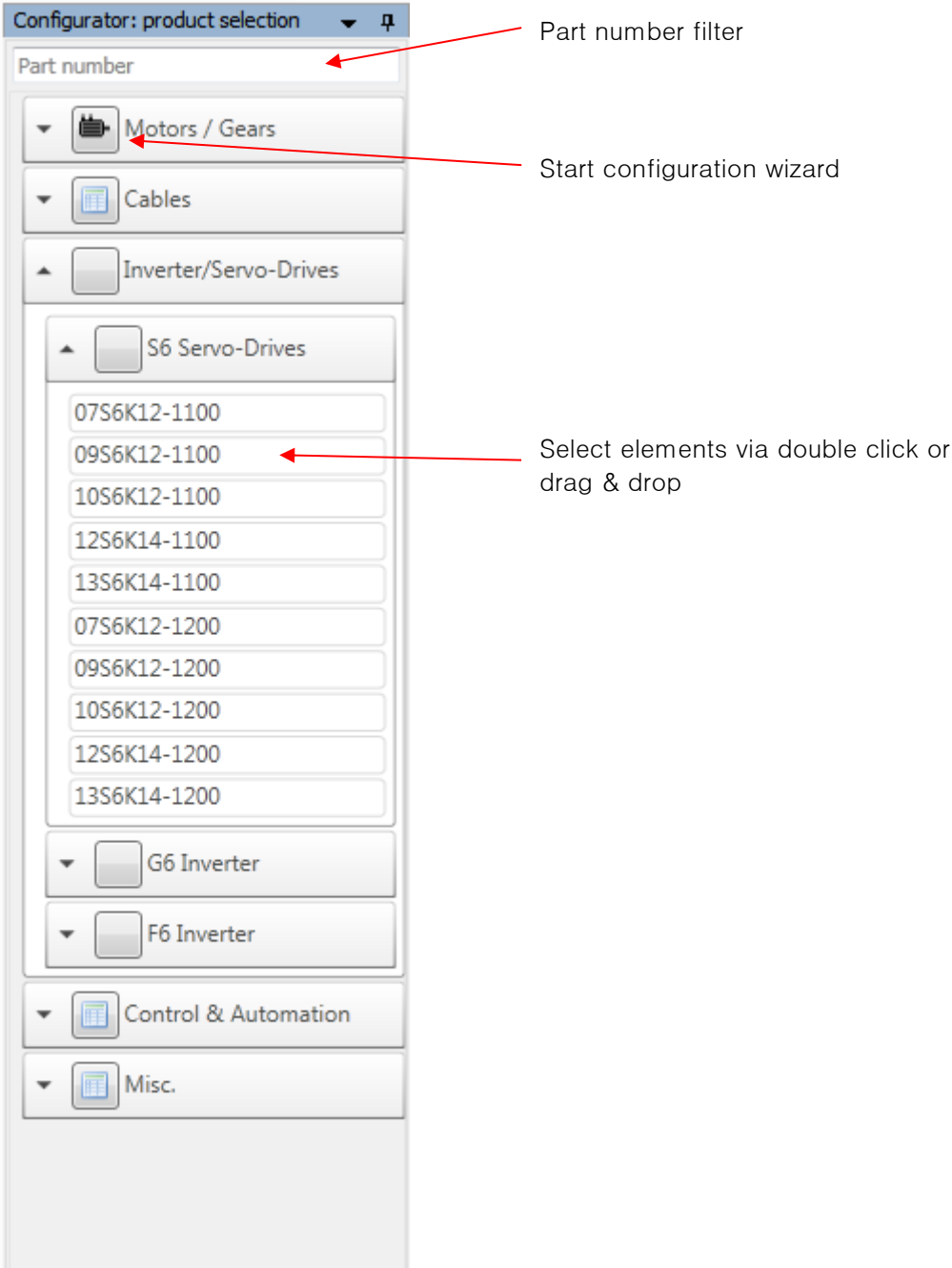
A fitting connection is automatically inserted. If multiple connections are possible, one must be selected from the dialog that will appear automatically in this case.

18.3.3 Document Access

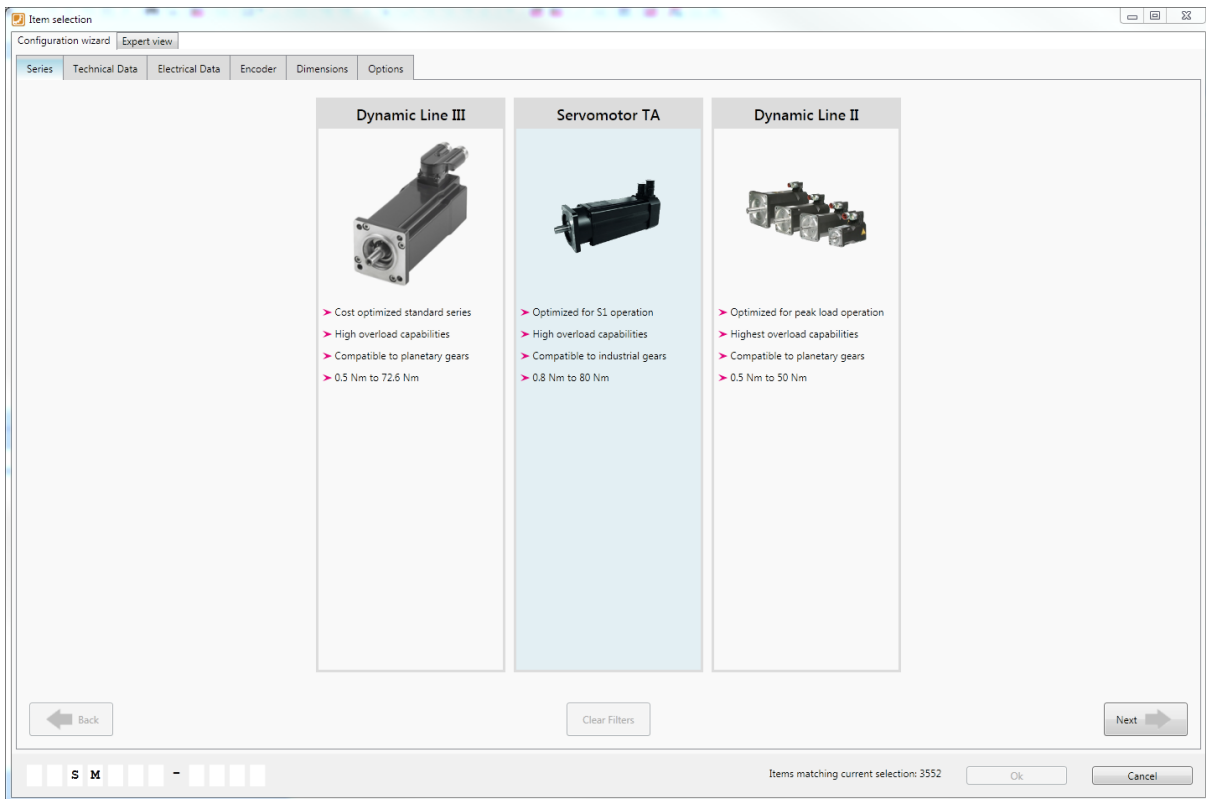
Using the context menu, it is possible to access all documents associated with that element:



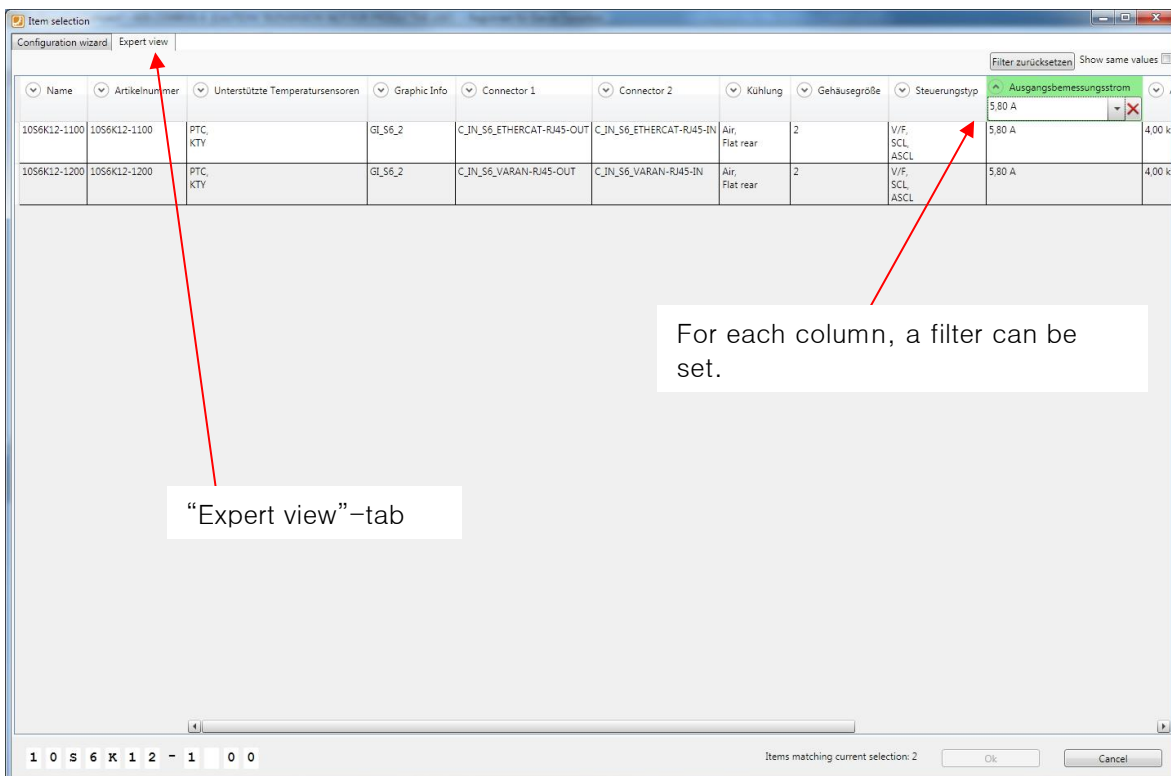
18.3.4 Product Selection Window



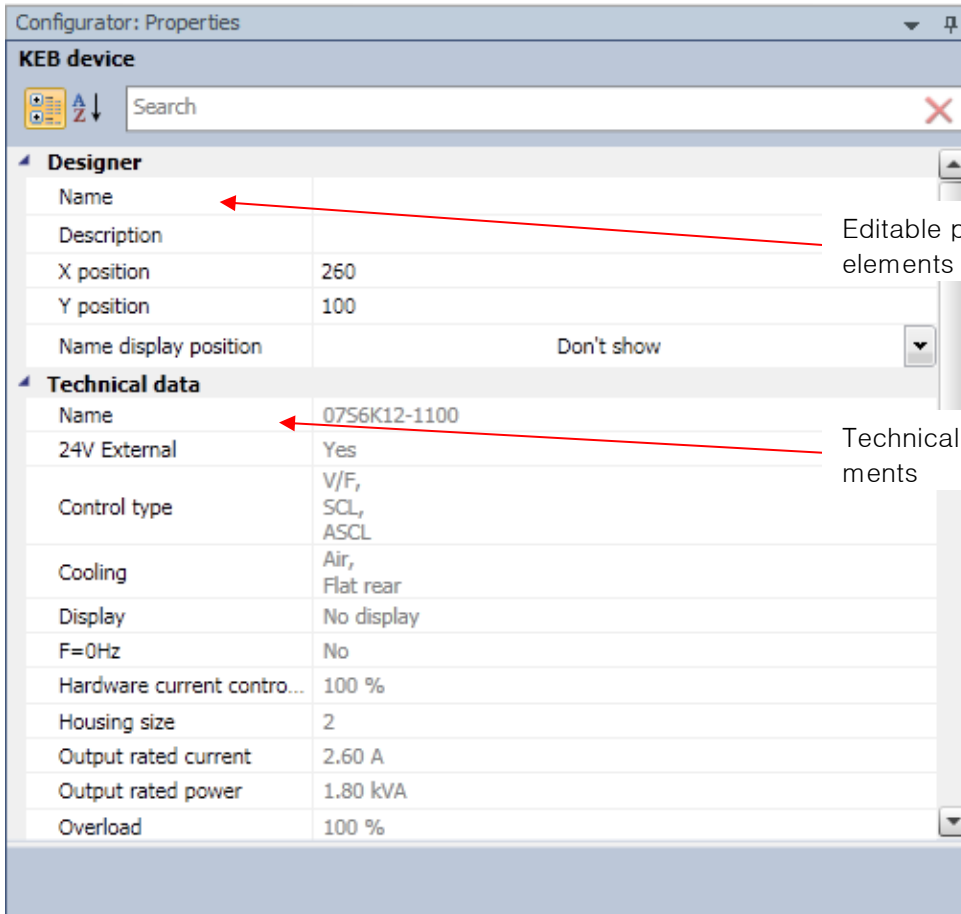
Example of a product selection wizard:



If no wizard is available, the elements will be shown in a table. This view is also available from a wizard using the “Expert view”-tab.



18.3.5 Properties Window

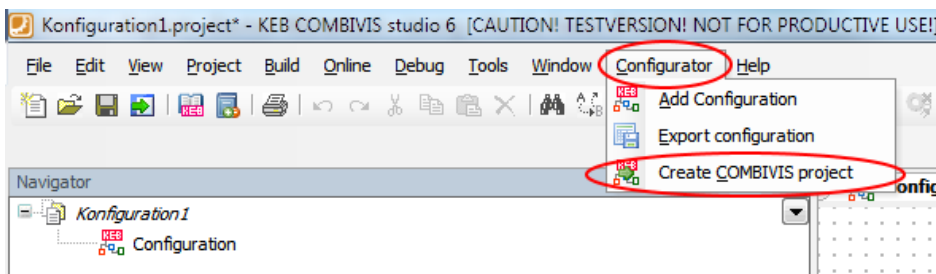


Editable properties of the selected elements

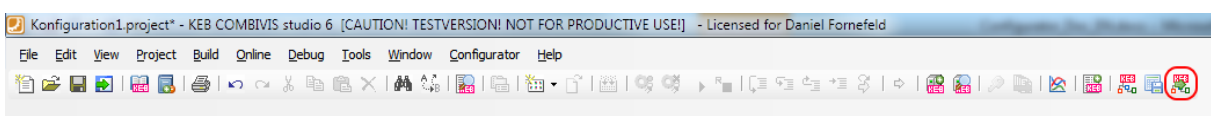
Technical data of the selected elements

18.4 Generate COMBIVIS Project

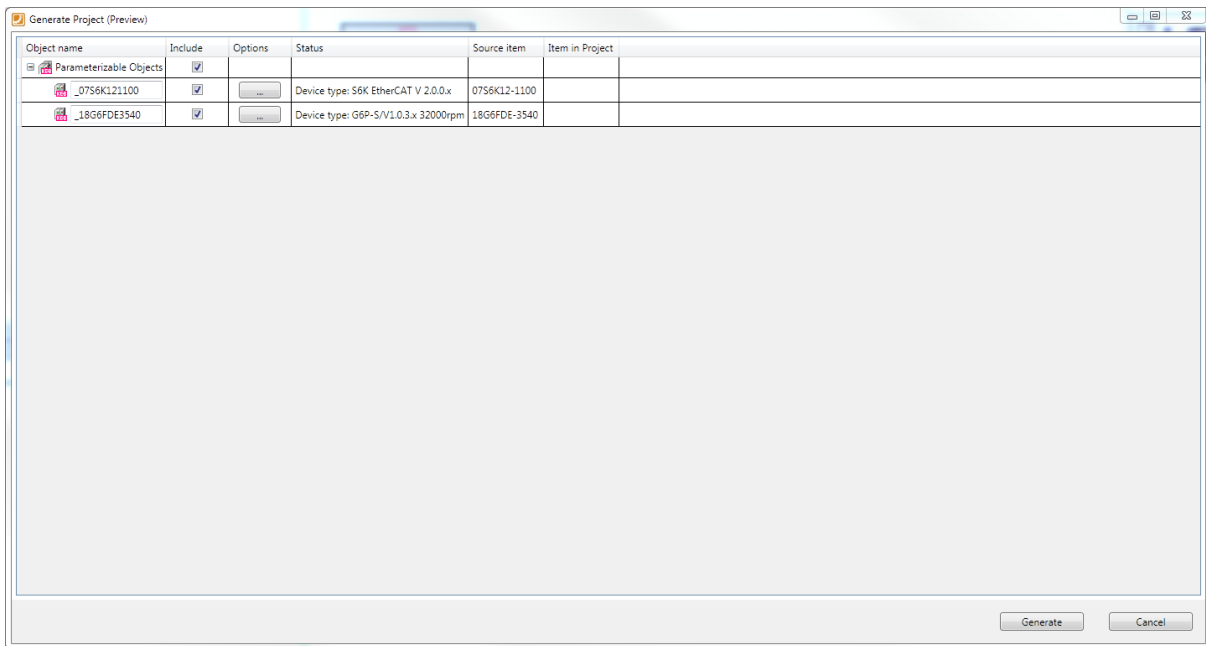
From a Configuration the contents of a COMBIVIS project can be generated. This is done via the menu:



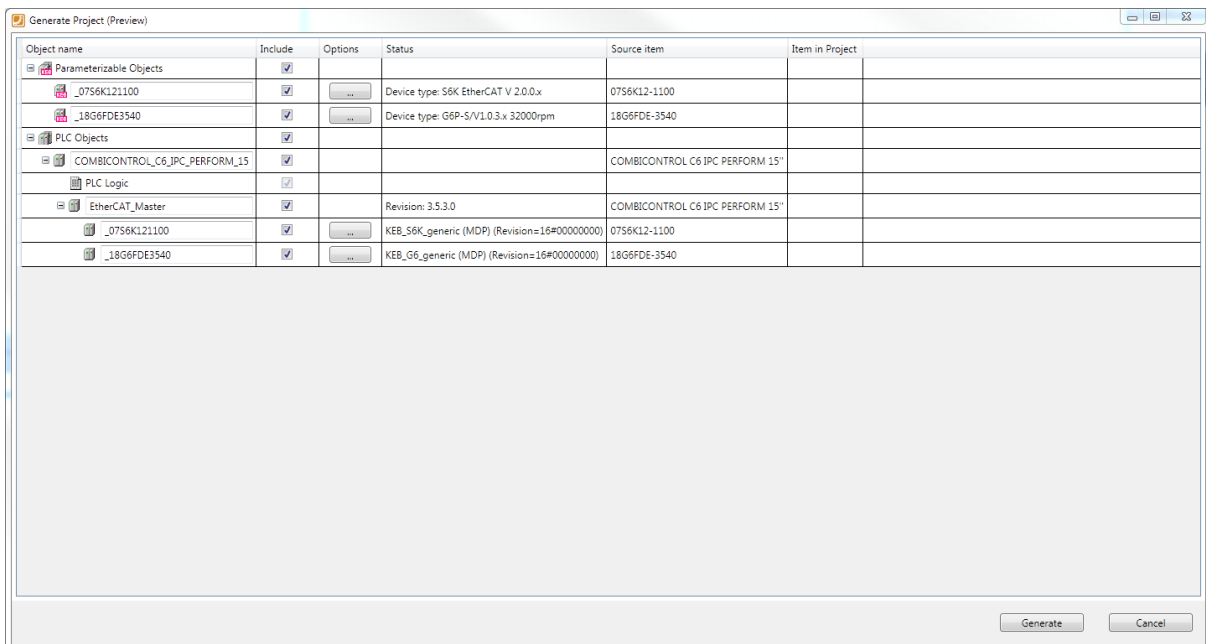
Or via tool bar:



This menu command opens a preview dialog where additional adjustments can be made:



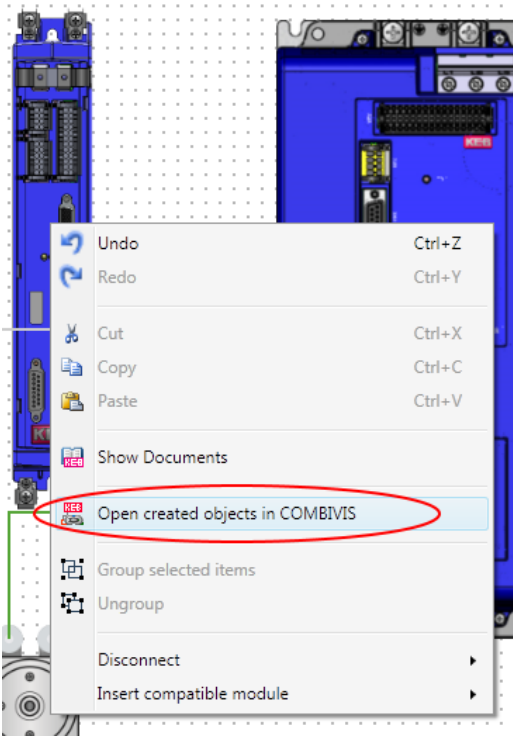
In COMBIVIS studio 6 in addition to the parameter based devices also PLC devices with complete EtherCAT or CAN-Bus topologies can be generated:



Depending on the size of the project to generate this might take a moment.

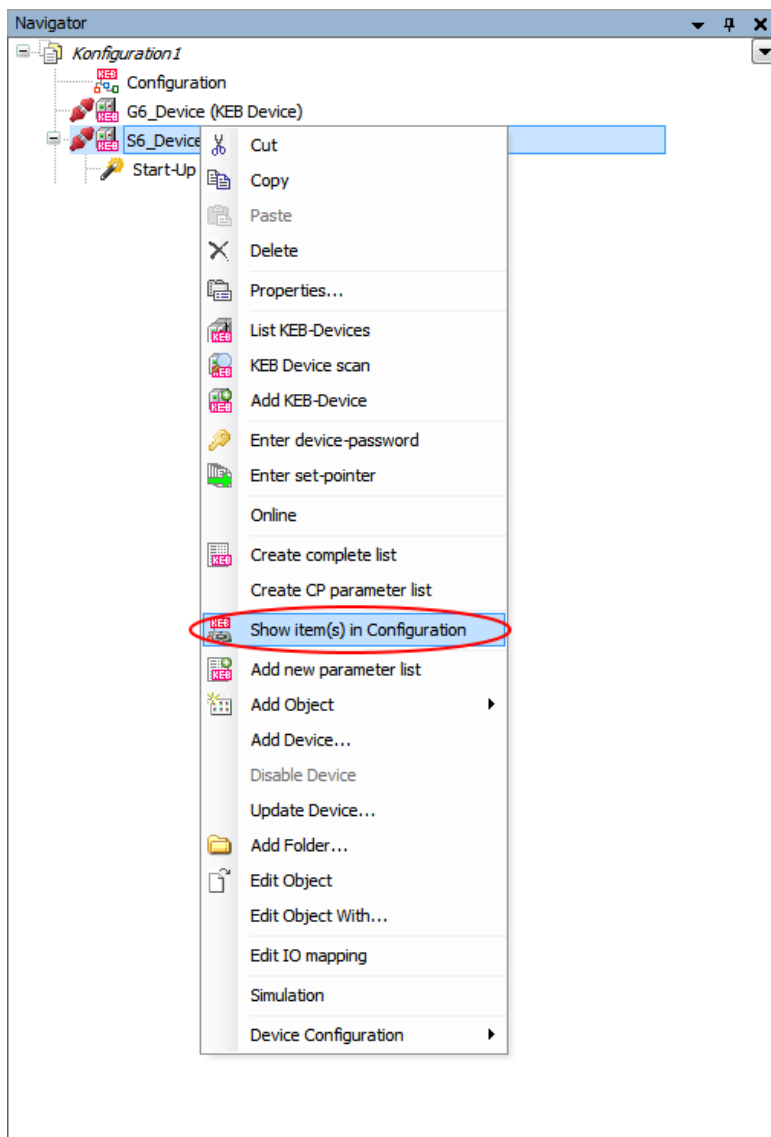
After the generation, the relation between the elements in the configuration and the created objects persists, which enables additional functionalities:

Open created objects:

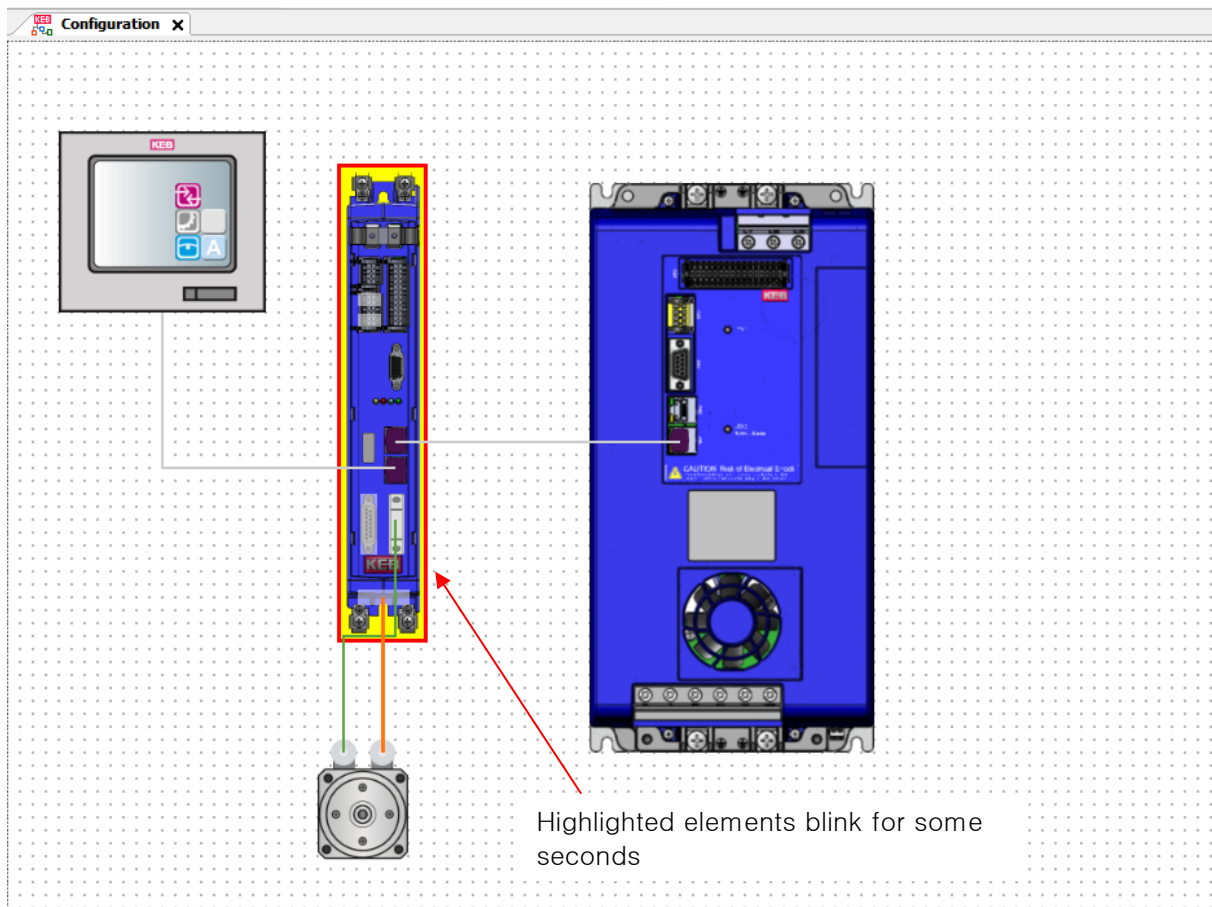


Using the context menu all generated objects can be opened.

Open in Configuration:

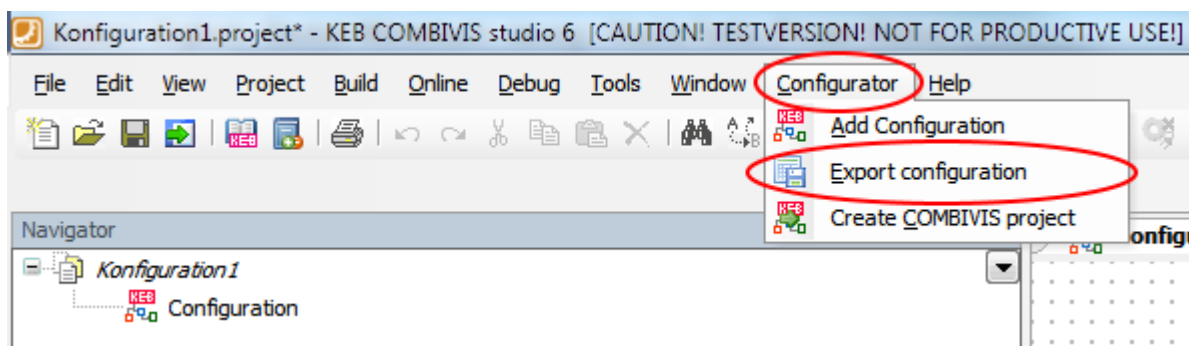


From the navigator the corresponding elements can be highlighted in the Configurator.

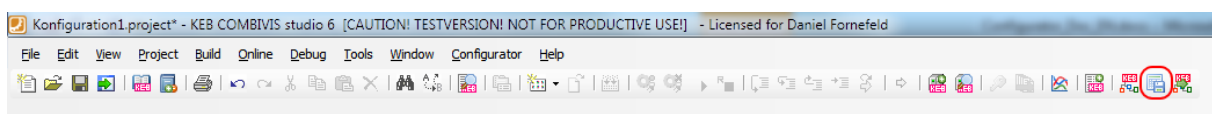


18.5 Part List / BOM

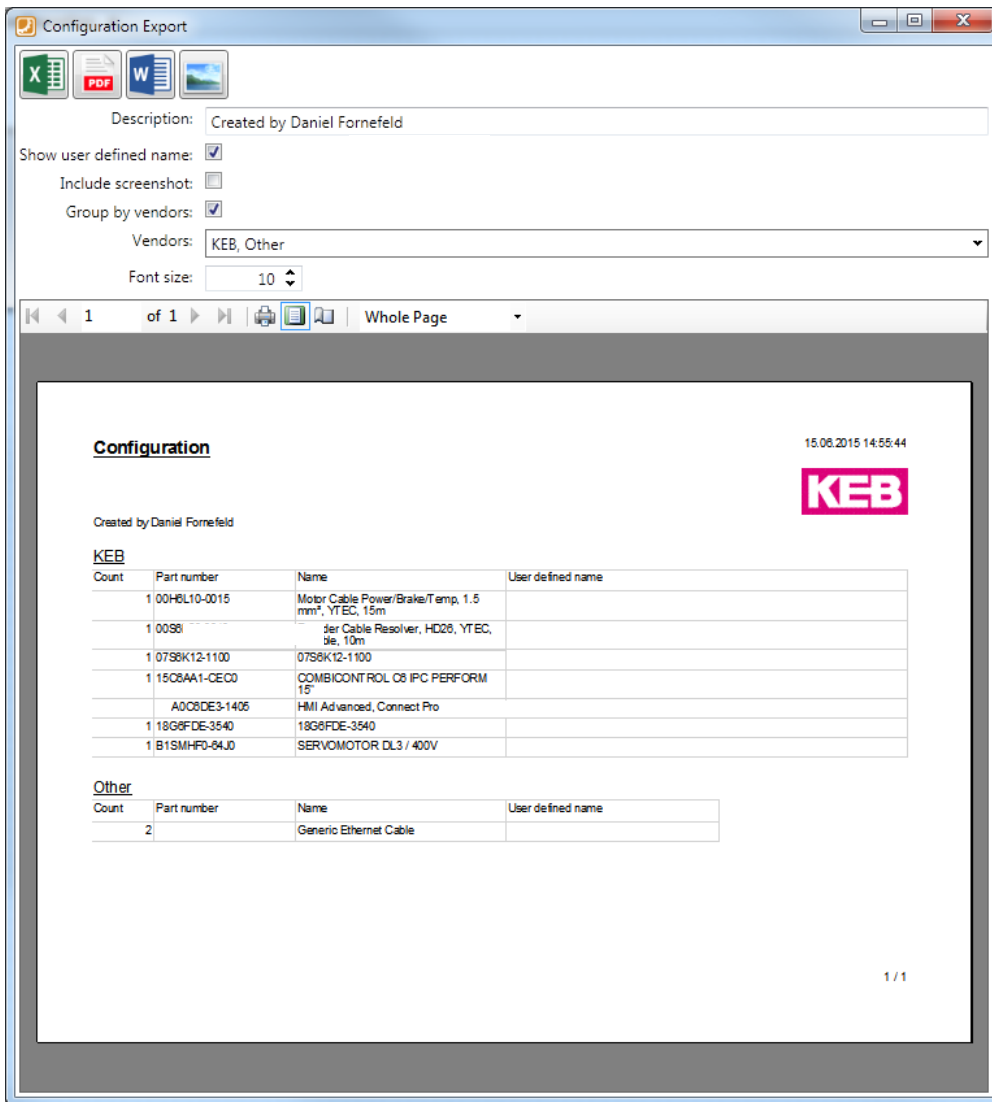
The part list is available using the menu:



Or via tool bar:

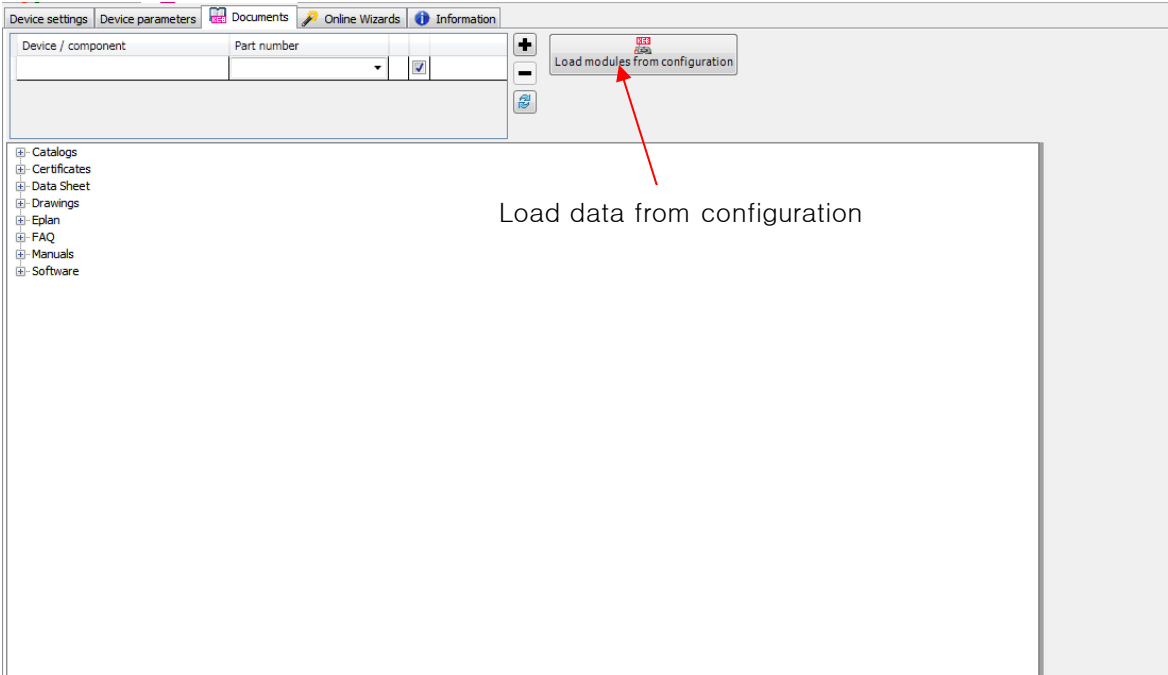


The part list contains all elements from the Configuration. There are options to customize the view. Different export formats are available as well as a print option.



18.6 Extended Document Search

Extended document search



In the “Documents”-tab of the editor for KEB devices all relevant documents for that device can be listed. This list contains for instance all documents for the device and the connected motor.

19 Registration and License

Registration: valid for COMBIVIS 6, free of charge, enables the access of the KEB document data bench.

License: valid only for COMBIVIS studio 6, fee required, disables the demo mode, includes the registration.

19.1 Registration

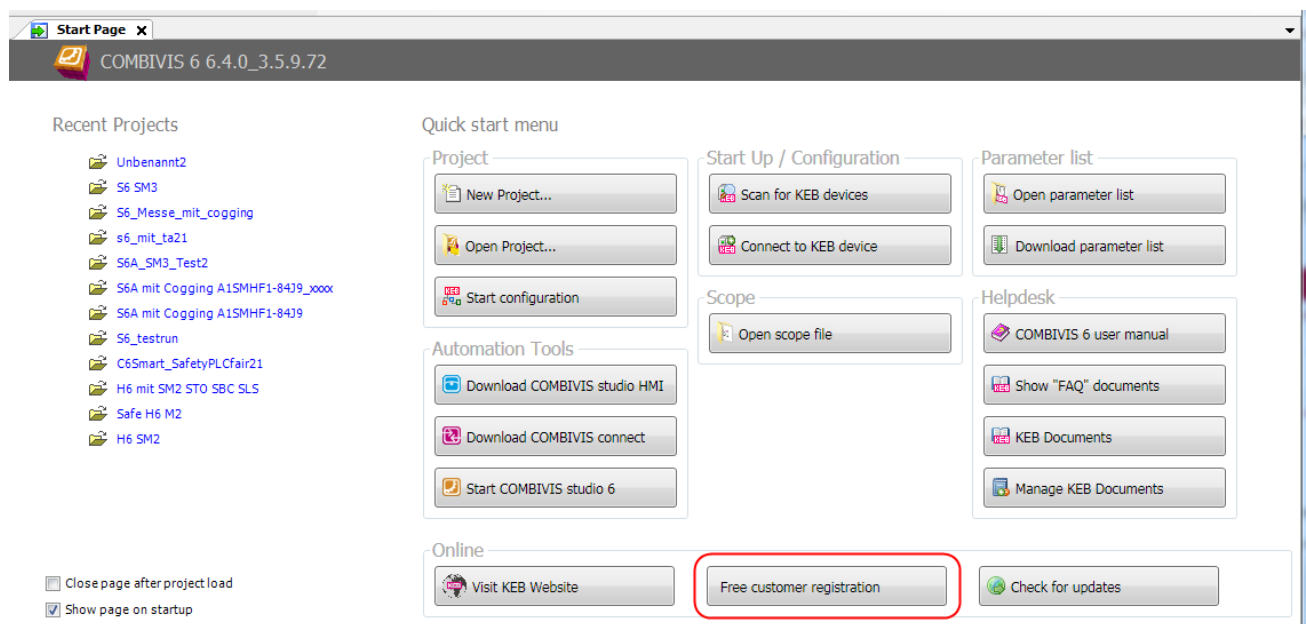
The free registration of COMBIVIS 6 allows access to the document database. Configurator, parameterization, data backup and scope work in demo version without restriction.

For registration, an Internet access must be available. Similarly, an account on the KEB homepage must be created. In the login-area the registration key can be generated.

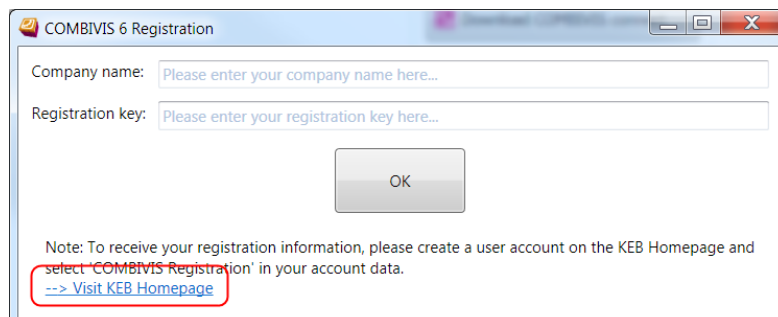
If you have a license for COMBIVIS studio 6 the registration is included.

Procedure:

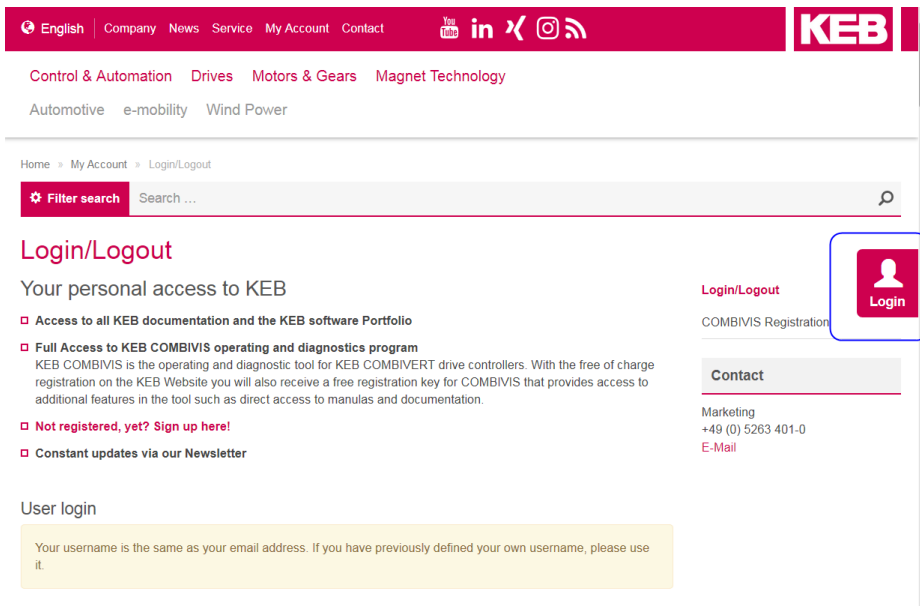
- An internet connection is needed.
- On the start page you find a link to the registration:



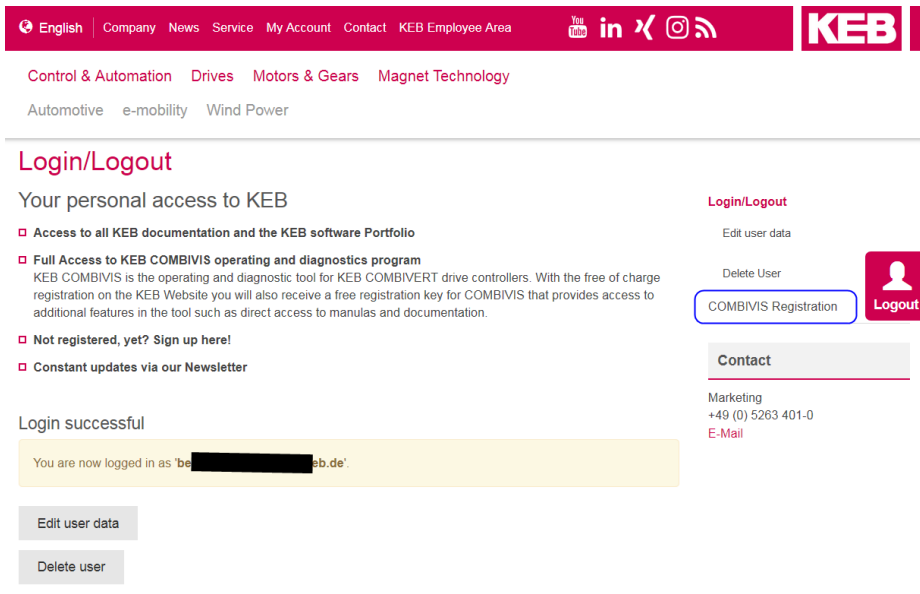
- You will be guided to the KEB homepage:



- Please log in your account or create a new:



- Then open “COMBIVIS registration”:



- Create the key by “Show registration key”:



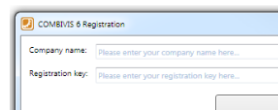
- Not registered, yet? Sign up here!

Your COMBIVIS registration key:

Registration key: [Redacted]

[Show registration key]

2. In the following COMBIVIS dialog enter the data and confirm with "OK"



- The registration key is a 40-digit letter-number combination:

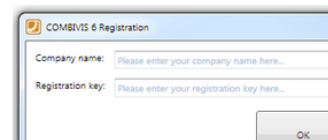
- not registered, yet? sign up here:

Your COMBIVIS registration key:

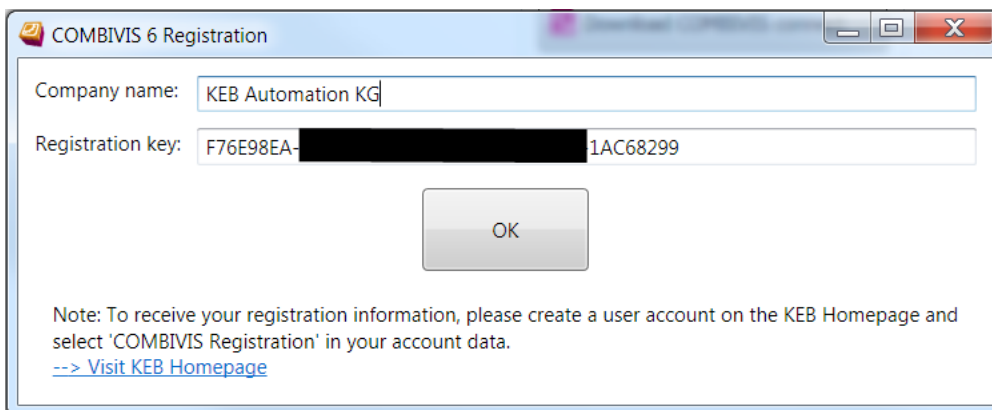
Company: KEB Automation KG

Registration key: F76E98EA-[Redacted]07-1AC68299

2. In the following COMBIVIS dialog enter the data and confirm with "OK"



- Copy company name and registration key to the window in COMBIVIS:

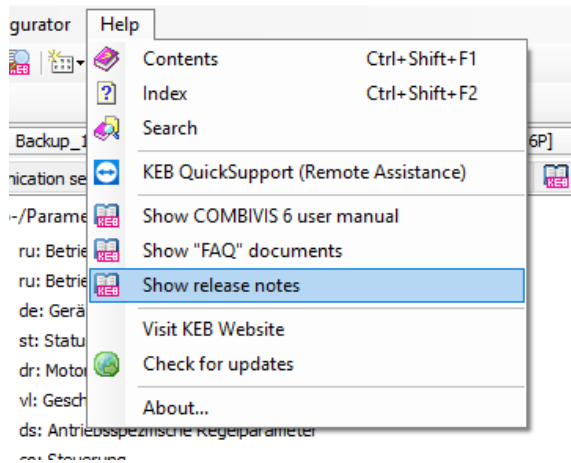


- After registration COMBIVIS 6 needs a new start.

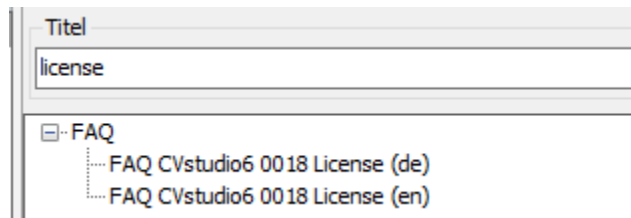
The registration is not related to the computer and can also be used on several computers. The key is stored as file "customer.nfo" on C:\Program Files (x86)\KEB\COMBIVIS_6\KEB or from V6.7.x alternatively on C:\ProgramData\COMBIVIS 6.

19.2 Licensing

The installed COMBIVIS studio 6 version is a demo version. This runs for a maximum of 1 hour and no boot projects can be created. After expiry, the demo version can always be restarted again. To obtain the full range of functions you need a licence. Please contact your KEB sales representative. The procedure for licensing COMBIVIS studio 6 is described in the Release Notes/ Chapter 7: Menu "Help" → "Show Release Notes".



Additionally, there is a manual in the document data bench => [13.2 use documents:](#)



The COMBIVIS studio 6 License includes the registration => [19.1 Registration.](#)

20 IPScan Tool

The IPScan tool makes it easy to find accessible devices in your own subnetwork.

20.1 General

KEB IPScan uses the UDP protocol to transfer a block of data to allow detecting KEB devices with Ethernet interface. The scan request is sent from a device called “*IPScanner*” via broadcast to reach all devices in the local network subnet range. All devices with IPScan functionality (KEB Kontiki based firmware) respond to the IPScanner with their name, location, and IP parameters. Also, any active instance of IPScan.exe software is found (e.g., IPScan running in C6-IPC).

20.2 Supported Devices

- Full support: embedded devices (C6-C,H6-CU, P6, T6) + F5 Ethernet operator, Port expander
- Limited support: C6 X86 based (ECON, PERFORM, E22, P3X)
- Not supported: arm based WEC7 devices (C6 SMART, C6 HMI LC)

20.3 Ports

The request port is 67 on the UDP protocol, the response port is 68. Sometimes the response port on the IPScanner is in use, so an alternative port can be used (devices with firmware after year 2014).

20.4 Scanning

By pressing the “Scan devices” button a call to the network is issued and the responding devices appear in the list below.

20.5 Wink

By pressing the “Wink this device” button the selected device from the list is asked to show a local response. This can be a blinking light or flashing header, depending on the specific hardware.

20.6 Assign

With the “Assign IP address” button, the selected device parameters and location may be changed. This highly depends on the selected device type and needs a specific password for that. It is primary used by service personnel.

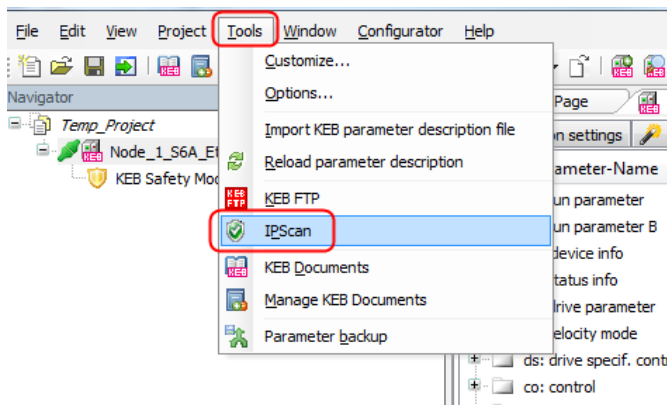
20.7 More Device Info

The ‘Info’ button shows additional information about the selected device (if available).

20.8 Use IP Scan

The program works independent from COMBIVIS, but is opened in COMBIVIS.

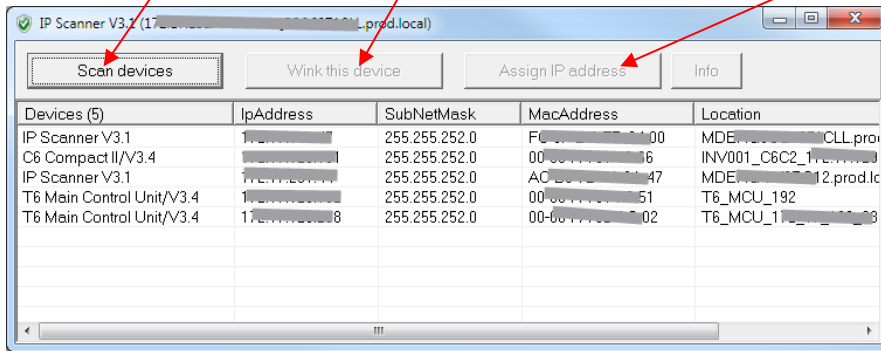
Menu bar “Tools” → “IPScan”



Start network scan

Device blinks (see device manual)

Reserved for KEB Service



21 Energy Efficiency Tool

Every manufacturer of drive technology is obliged to submit an energy efficiency declaration for their devices. With this plug-in the energy efficiency of different types of COMBIVERT can be classified and documented. The plug-in calculated absolute and relative power losses in eight different load levels in accordance with EN 61800-9-2. Users can also define up to 8 additional custom load points to determine the exact efficiency of the COMBIVERT.

For all KEB devices, even those which are not listed in the tool, the declaration can be obtained from the document database or from the KEB homepage www.keb.de as PDF (search for part number -> data sheets).

21.1 Function

This plug-in creates a PDF document for a specified KEB COMBIVERT. The KEB Configurator is the data base. Therefor only devices are offered which are parts of configurator.

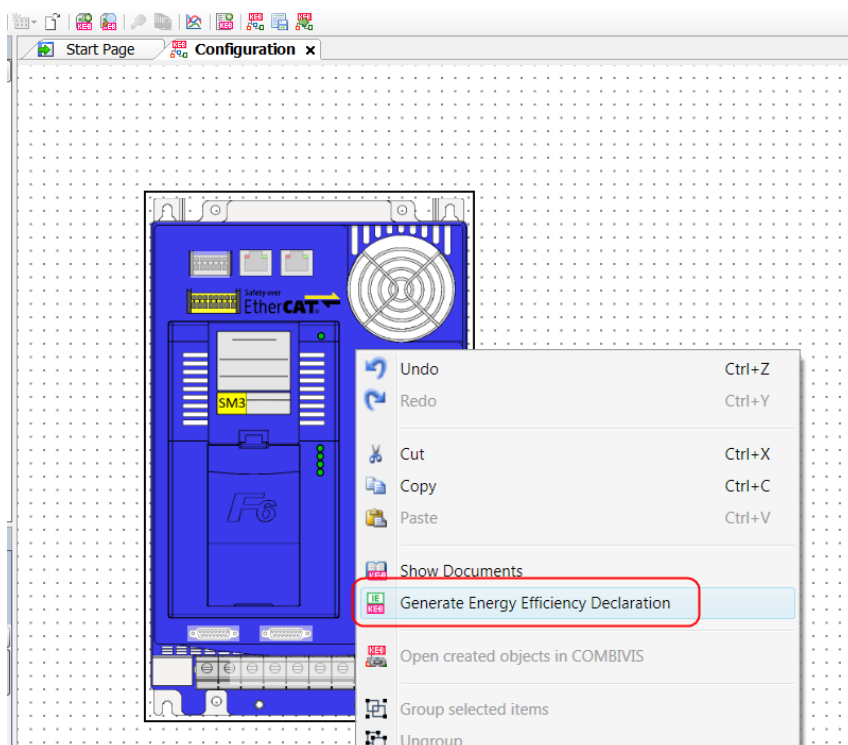
The operating points refer to the torque-generating current and the rated frequency of the motor.

The losses are related to the rated apparent power of the COMBIVERT.

The energy efficiency tool can be opened directly from the configurator or as an editor in the Navigator.

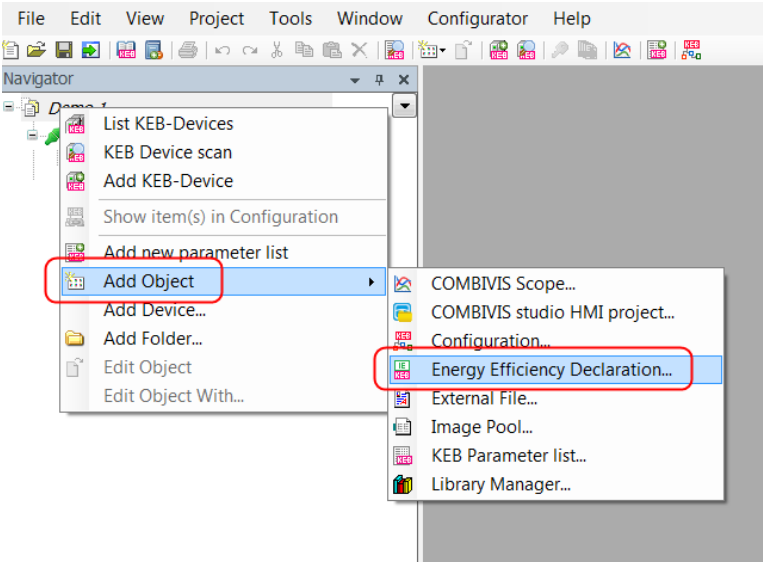
Configurator:

From the configuration project, select a specific COMBIVERT and right-click on it to go to the context menu. Then click on "Generate Energy Efficiency Declaration".

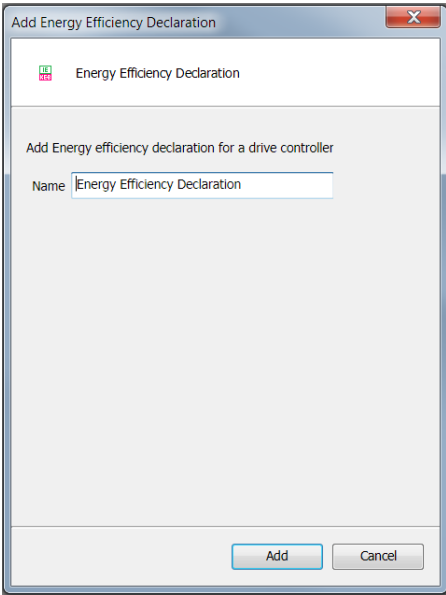


Navigator:

In the Navigator, right-click the project node and navigate to the Add Object item. Click on the "Energy Efficiency Declaration" button to open the editor.



Choose a name for the editor:



Activate the loss-time-profile

Choose device

Data points for losses calculation

User defined operating points

Losses at the operating points normative and user defined

Generate a document

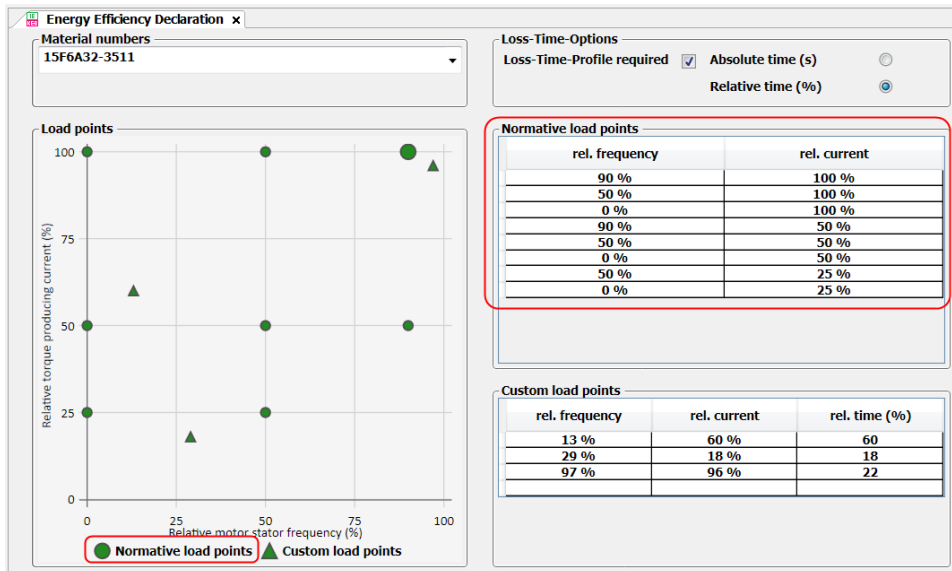
The screenshot shows the 'Energy Efficiency Declaration' window. It includes a 'Material numbers' dropdown menu, a 'Load points' graph, a 'Power Losses' table, and a 'Loss-Time-Profile' graph. Red arrows point from the text labels on the left to the corresponding elements in the software interface.

Coming from the Navigator, the COMBIVERT must be selected from the list. After opening the window, the 1st device is displayed in the list. Select the correct COMBIVERT based on the part number.

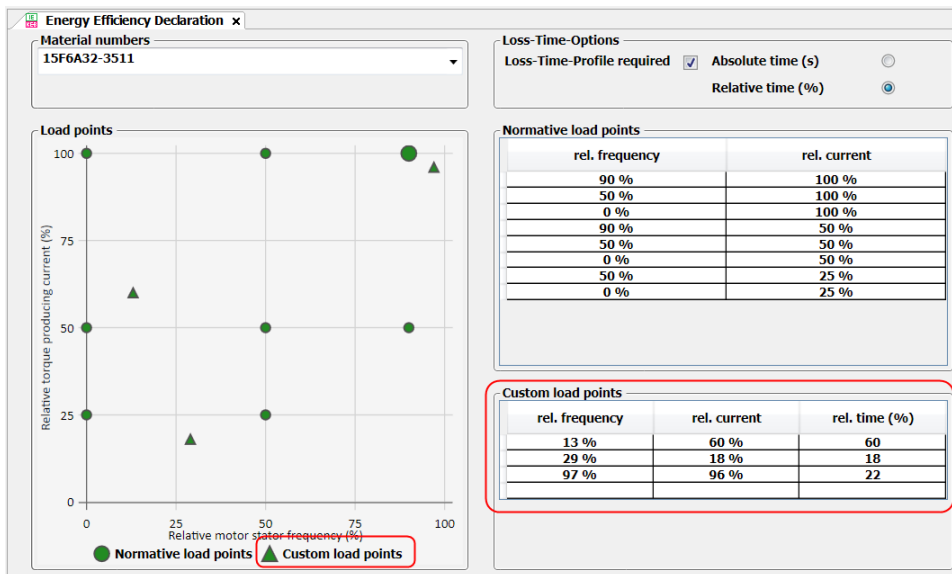
The screenshot shows a list of material numbers in the 'Energy Efficiency Declaration' window. The list is as follows:

- 15F6A32-3511
- 15F6A32-3511
- 12F6A32-3A11
- 13F6A12-3A11
- 13F6A12-3A13
- 13F6A32-3A11
- 13F6A32-3A13
- 14F6A12-3911
- 14F6A12-3913
- 14F6A32-3911
- 14F6A32-3913
- 15F6A12-3511
- 15F6A12-3513
- 15F6A32-3513
- 16F6A12-3411
- 16F6A12-3413

In the default setting, the relative and absolute losses are displayed for the operating points defined in EN 61800-9-2.



In addition, the user can define up to 8 own load points. The loss values are interpolated from the normative values. The points can be entered by a mouse double-click in the left-hand graph or manually in the table "Custom load points".



21.2 Loss-time profile

This can be used to create a curve that shows the losses over an operating cycle.

The profile is activated by setting the check mark in the field "Loss time options".

Energy Efficiency Declaration x

Material numbers
15F6A32-3511

Loss-Time-Options
Loss-Time-Profile required

Load points

Normative load points

rel. frequency	rel. current
90 %	100 %
50 %	100 %
0 %	100 %
90 %	50 %
50 %	50 %
0 %	50 %
50 %	25 %
0 %	25 %

The cycle time can be entered absolutely in seconds or relative.

The profile is generated exclusively from the table of "Custom load points".
To integrate normative load points, these can be pulled down from the above table "Normative load points" by mouse. The time values must be entered manually.

Loss-Time-Options
Loss-Time-Profile required Absolute time (s)
Relative time (%)

Normative load points

rel. frequency	rel. current
90 %	100 %
50 %	100 %
0 %	100 %
90 %	50 %
50 %	50 %
0 %	50 %
50 %	25 %
0 %	25 %

Custom load points

rel. frequency	rel. current	rel. time (%)
13 %	60 %	60
29 %	18 %	18
97 %	96 %	22
90 %	50 %	0

Loss-Time-Profile

21.3 Create Declaration / Data Sheet


After defining the work points and optionally the loss-time profile, the user can create a PDF report. The report contains all the important device data, the normative and custom defined loss values, and the loss-time profile (if selected).

ENERGIEEFFIZIENZ NACH EN 61800-9-2 **KEB**

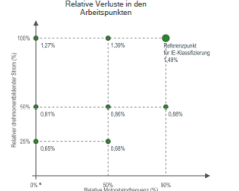
Energieeffizienzdaten¹ 15F6A12-3511

Effizienzklasse **KEB IE2**

Arbeitspunkt	rel. Frequenz ²	rel. Strom ²	rel. Verlust ³	abs. Verlust ⁴
1	90 %	100 %	1,49 %	247 W
2	50 %	100 %	1,39 %	230 W
3	0 %	100 %	1,27 %	213 W
4	90 %	50 %	0,88 %	148 W
5	50 %	50 %	0,86 %	143 W
6	0 %	50 %	0,81 %	134 W
7	50 %	25 %	0,88 %	112 W
8	0 %	25 %	0,85 %	108 W
Verlustleistung Standby	-	-	-	29,41



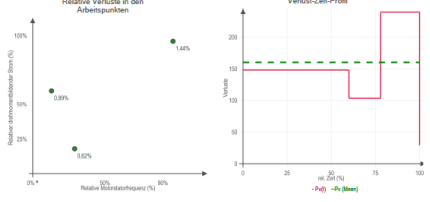
Relative Verluste in den Arbeitspunkten



Gerätedaten

Modellnummer	15F6A12-3511
Produktreihe	FS
Gehäusegröße	2
Gerätegröße	15
Eingangsbemessungsspannung	400 V
Motorbemessungsleistung	11 kW
Ausgangsbemessungsleistung	16,8 kVA
Ausgangsbemessungsstrom	24 A
Bemessungshäufigkeit	4 kHz

Verlust-Zeit-Profil



1) Alle Verlustdaten gelten für eine Umgebungstemperatur von 45 °C und beziehen sich auf den Betrieb bei Bemessungsfrequenz und maximaler Kühlung. Die Daten sind für das Bauelement mit Luftkühlung gültig. Alternative Kühlkonzepte können die Verlustleistung beeinflussen.
2) Die Arbeitspunkte werden normativ vorgegeben und definieren sich nach dem „normierten Betriebsbereich Steuert“ und der „realen Motorstromfrequenz“. Ziel der Verwendung dieser Parameter ist es, die Verluste von Frequenzumrichter und Motoren in vergleichbaren Betriebspunkten abzubilden.
3) Die relativen Verluste beziehen sich auf die Bemessungsbemessung des Frequenzumrichters und sind unabhängig für die normative Klassifizierung nach EN 61800-9-2.
4) Alle Verlustangaben sind lediglich beispielhaft, die der Veränderung unterliegen.
5) Nach EN 61800-9-2 ist es zulässig, die Verluste in den Punkten mit 0 % relativer Motorstromfrequenz bei einer absoluten Frequenz von 0 Hz zu messen.

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ENERGIEEFFIZIENZ NACH EN 61800-9-2 **KEB**

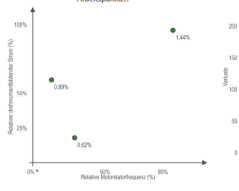
Energieeffizienzdaten¹ 15F6A12-3511

Effizienzklasse **KEB IE2**

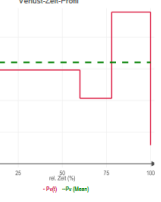
Arbeitspunkt	rel. Frequenz ²	rel. Strom ²	rel. Verlust ³	abs. Verlust ⁴	rel. Zeit (%)
1	13 %	40 %	0,39 %	148 W	82 %
2	29 %	18 %	0,82 %	103 W	18 %
3	97 %	96 %	1,44 %	240 W	22 %



Relative Verluste in den Arbeitspunkten



Verlust-Zeit-Profil



1) Alle Verlustdaten gelten für eine Umgebungstemperatur von 45 °C und beziehen sich auf den Betrieb bei Bemessungsfrequenz und maximaler Kühlung. Die Daten sind für das Bauelement mit Luftkühlung gültig. Alternative Kühlkonzepte können die Verlustleistung beeinflussen.
2) Die Arbeitspunkte werden normativ vorgegeben und definieren sich nach dem „normierten Betriebsbereich Steuert“ und der „realen Motorstromfrequenz“. Ziel der Verwendung dieser Parameter ist es, die Verluste von Frequenzumrichter und Motoren in vergleichbaren Betriebspunkten abzubilden.
3) Die relativen Verluste beziehen sich auf die Bemessungsbemessung des Frequenzumrichters und sind unabhängig für die normative Klassifizierung nach EN 61800-9-2.
4) Alle Verlustangaben sind lediglich beispielhaft, die der Veränderung unterliegen.
5) Nach EN 61800-9-2 ist es zulässig, die Verluste in den Punkten mit 0 % relativer Motorstromfrequenz bei einer absoluten Frequenz von 0 Hz zu messen.

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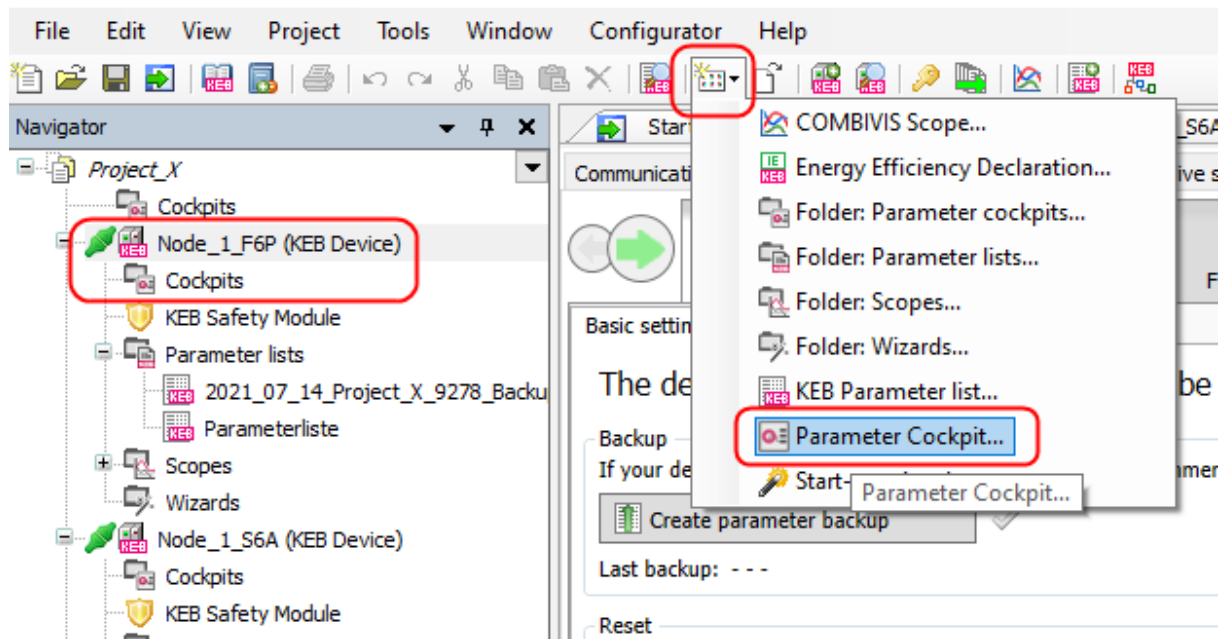
22 Parameter Cockpit

The function Parameter Cockpit is a tool to display parameter values in separate window and bigger size.

Parameter Cockpit can be opened at project or node/device.

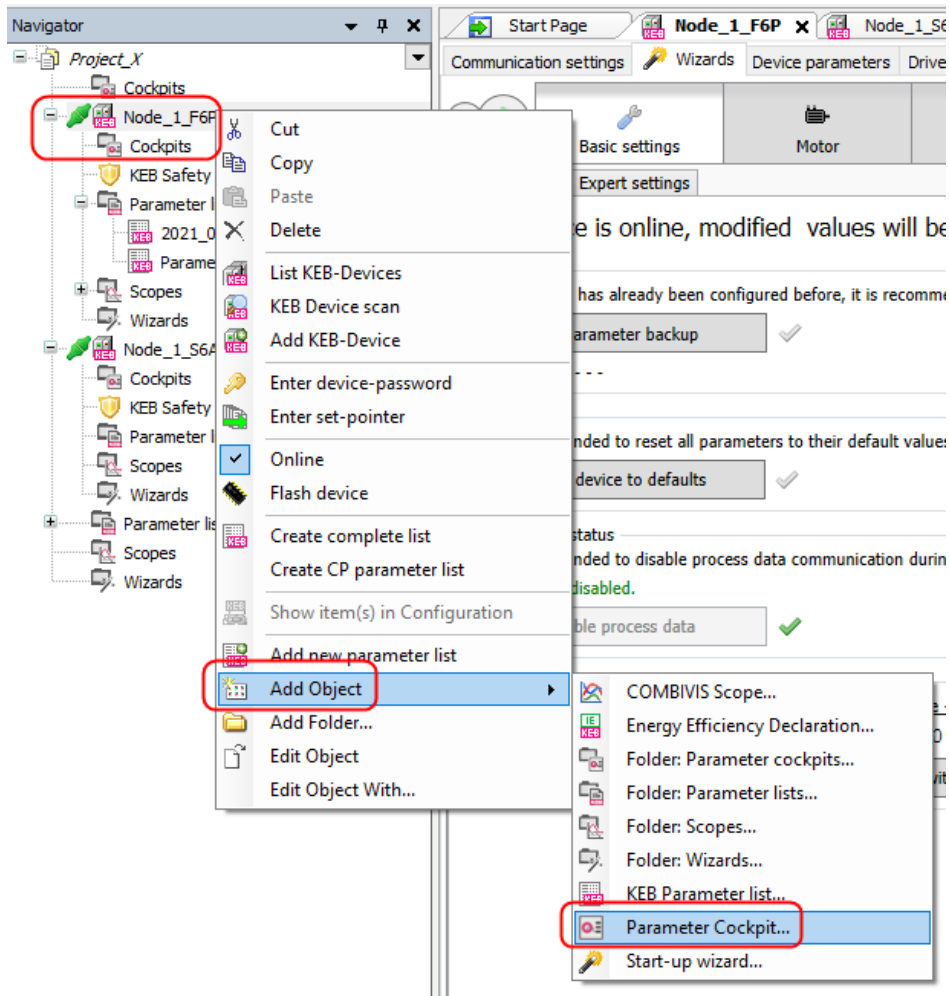
When the cockpit is opened on the project, parameters of several units can be inserted. If it is opened on a specific unit, only from that unit.

Open by menu bar icon “add object”:

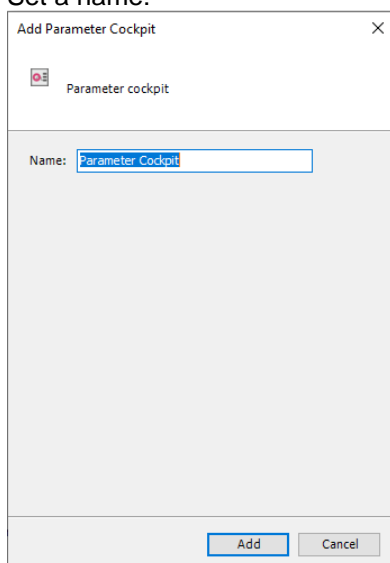


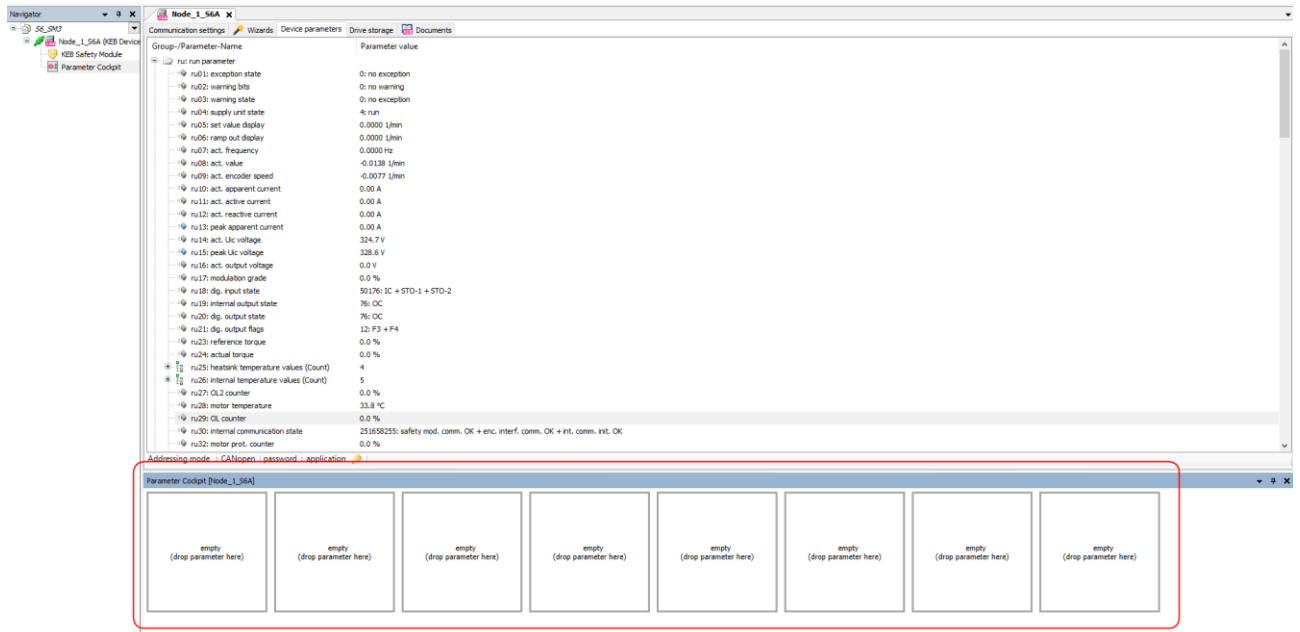
Or in the navigator with right mouse click:

Parameter Cockpit



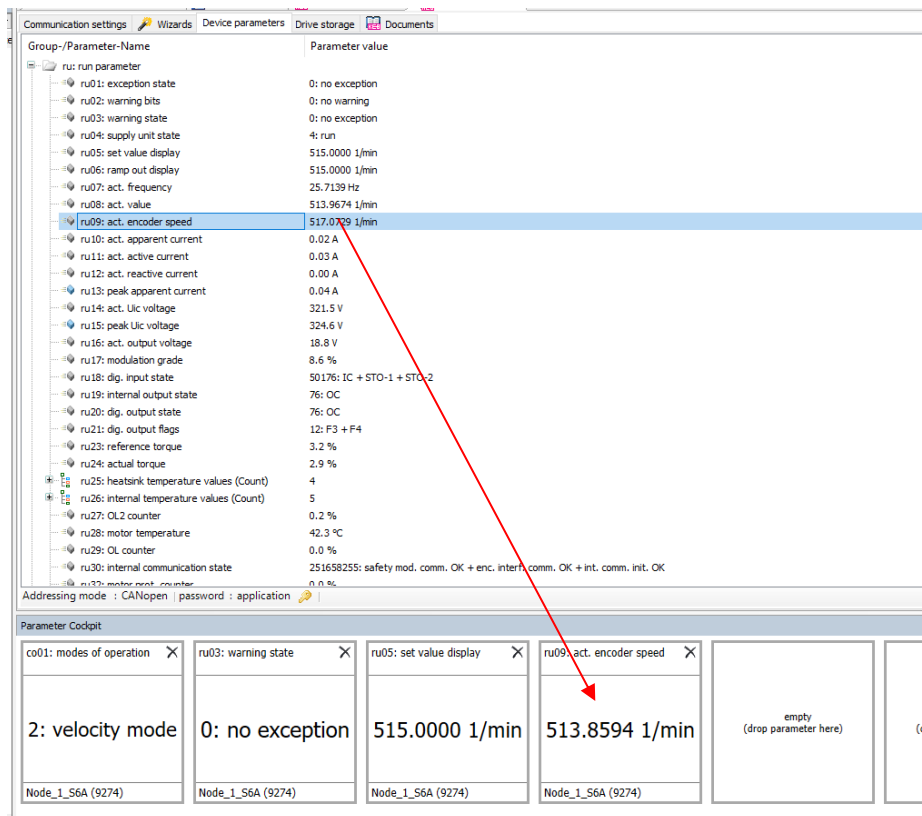
Set a name:





The Parameter Cockpit includes 8 view boxes.

Parameters can be set by Drag&Drop from the device parameter editor or from a parameter list to one of the view boxes.



The Parameter Cockpit is placed at the bottom of the editor window. It can be placed also on other sides (=> [7 Window Layout](#))

Parameter Cockpit

The screenshot displays a software interface for a motor drive, featuring a 'Parameter Cockpit' window. The cockpit is divided into several sections:

- Preconditions for successful running:** A list of status indicators for Digital inputs, Voltage supply, Error state, and Brake.
- Current operation mode:** A speedometer showing 515 rpm and a mode selection dropdown set to 'velocity mode'. Below it are 'Start' and 'Stop' buttons.
- Control Panel:** A set of buttons for 'Start', 'Stop', 'Fault', and 'Brake', each with sub-buttons for 'Enable/Disable' and 'Open/Close'.
- State Machine Diagram:** A flowchart showing the drive's operational states (e.g., 'Not ready to switch on', 'Switched on', 'Operation enabled') and transitions between them.
- ControlWord and Status:** Two columns of green indicator lights representing different control signals and their current states.
- Parameter Cockpit List:** A scrollable list of parameters with their current values, such as '2: velocity mode', '0: no exception', and '515.0000 1/min'.

Parameter Cockpit can be added several times.

Parameters from several units can be placed together in a Parameter Cockpit if it is attached to the project and not to a specific unit.

23 Plug-ins – Additional Modules

Additional modules for COMBIVIS 6 and / or COMBIVIS studio 6 can be published during the term of the release. These are either integrated via the update function or as a separate installation. The description for the additional modules is published separately in the KEB document database (=> [13 document database](#)).

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