COMBIVERT

F5/F6

GB INSTRUCTION MANUAL

Power Unit Housing R

18.5 ...45 kW 230 V

22 ...90 kW 400 V

Mat.No.	Rev.
00F50EB-KR00	2K

KEB

1. Preface

1.1 General

First we would like to welcome you as a customer of the company KEB Automation KG and congratulation to the purchase of this product. You have decided for a product on highest technical level.

The described hard- and software are developments of the KEB Automation KG. Die beigefügten Unterlagen entsprechen dem bei Drucklegung gültigem Stand. Misprint, mistakes and technical changes reserved.

The instruction manual must be made available to the user. Before working with the unit the user must become familiar with it. This especially applies to the knowledge and observance of the following safety and warning indications. The pictographs used in this instruction manual have following meaning:

	Danger Warning Caution	Is used when the life or health of the user is in danger or considerable damage to property can occur.

	Attention observe at all costs	Is used, if a measure is necessary for safe and trouble-free operation.

	Information Aid Tip	Is used, if a measure simplifies the handling or operation of the unit.

1.2 Safety Instructions

	Observe safety and operating instructions	Precondition for all further steps is the knowledge and observance of the safety-, EMC- and operating instructions (Part 1 „Before Starting“ 0000NEB-0000“). This instruction is provided with the unit or by download of www.keb.de.

Non-observance of the safety instructions leads to the loss of any liability claims. The safety and warning instructions specified in this manual do not lay claim on completeness. This list is not exhaustive.

1.3 Validity and liability

The use of our units in the target products is outside of our control and therefore lies exclusively in the area of responsibility of the machine manufacturer.

The information contained in the technical documentation, as well as any user-specific advice in spoken and written and through tests, are made to best of our knowledge and information about the application. However, they are considered for information only without responsibility. This also applies to any violation of industrial property rights of a third-party.

Selection of our units in view of their suitability for the intended use must be done generally by the user.

Tests can only be done within the application by the machine manufacturer. They must be repeated, even if only parts of hardware, software or the unit adjustment are modified.

Unauthorised opening and tampering may lead to bodily injury and property damage and may entail the loss of warranty rights. Original spare parts and authorized accessories by the manufacturer serve as security. The use of other parts excludes liability for the consequences arising out of.

The suspension of liability is especially valid also for operation interruption loss, loss of profit, data loss or other damages. This is also valid, if we referred first to the possibility of such damages.

If single regulations should be or become void, invalid or impracticable, the effectivity of all other regulations or agreements is not affected.

1.4 Copyright

The customer may use the instruction manual as well as further documents or parts from it for internal purposes. Copyrights are with KEB and remain valid in its entirety. All rights reserved.

KEB®, COMBIVERT®, KEB COMBICONTROL® and COMBIVIS® are registered trademarks of KEB Automation KG.

Other wordmarks or/and logos are trademarks (TM) or registered trademarks (®) of their respective owners and are listed in the footnote on the first occurrence.When creating our documents we pay attention with the utmost care to the rights of third parties. Should we have not marked a trademark or breach a copyright, please inform us in order to have the possibility of remedy.

1.5 Specified application

The KEB COMBIVERT serves exclusively for stepless open loop / closed-loop speed control of three-phase a.c. motors.

The operation of other electric consumers is prohibited and can lead to the destruction of the unit.

The used semiconductors and components of KEB are developed and dimensioned for the use in industrial products. If the KEB COMBIVERT is used in machines, which work under exceptional conditions or if essential functions, life-supporting measures or an extraordinary safety step must be fulfilled, the necessary reliability and security must be ensured by the machine builder. The operation of the KEB COMBIVERT outside the indicated limit values of the technical data leads to the loss of any liability claims.

Units with safety function are limited to a service life of 20 years. After this time the units must be replaced.

1.6 Product description

This instruction manual describes the power circuits of the following units:

Unit type:	Frequency inverter
Series:	COMBIVERT F5/F6
Power range:	18.5…45 kW / 200 V
	22…90 kW / 400 V
Housing size:	R

Features of the power circuits :

- only slight switching losses due to IGBT
- low noise development due to high switching frequency
- extensive safety device for current, voltage and temperature
- voltage and current monitoring in static and dynamic operation
- conditionally short circuit proof and earth-fault proof
- hardware current limit
- integrated cooling fan

1.7 Part code

18	F5	C	1	R	-	9	7	0	A

Cooling

0, 5, A, F	heat sink (standard)
1, B, G	Flat rear
2, C, H	Water cooling
3, D, I	convection

Encoder interface

0: none

Switching frequency; short time current limit; overcurrent limit

0	2 kHz; 125 %; 150 %	5	4 kHz; 150 %; 180 %	A	8 kHz; 180 %; 216 %	F	16 kHz; 200 %; 240 %
1	4 kHz; 125 %; 150 %	6	8 kHz; 150 %; 180 %	B	16 kHz; 180 %; 216 %	G	2 kHz; 400 %; 480 %
2	8 kHz; 125 %; 150 %	7	16 kHz; 150 %; 180 %	C	2 kHz; 200 %; 240 %	H	4 kHz; 400 %; 480 %
3	16 kHz; 125 %; 150 %	8	2 kHz; 180 %; 216 %	D	4 kHz; 200 %; 240 %	I	8 kHz; 400 %; 480 %
4	2 kHz; 150 %; 180 %	9	4 kHz; 180 %; 216 %	E	8 kHz; 200 %; 240 %	K	16 kHz; 400 %; 480 %

Input identification

0	1ph 230 VAC/DC	5	400 V class DC	A	6ph 400 VAC		
1	3ph 230 VAC/DC	6	1ph 230 VAC	B	3ph 600 VAC		
2	1/3ph 230 VAC/DC	7	3ph 230 VAC	C	6ph 600 VAC		
3	3ph 400 VAC/DC	8	1/3ph 230 VAC	D	600 V DC		
4	230 V class DC	9	3ph 400 VAC				

Housing type A, B, D, E, G, H, R, U, W, P

Accessories (A...D with safety relay)

0, A	none
1, 5, B	Braking transistor (5 with braking transistor monitoring)
2, C	integrated filter
3, 7, D	Braking transistor and integrated filter (7 with braking transistor monitoring)

Control type

A	APPLICATION	K	like A with safety technology
C	COMPACT (controlled frequency inverter)		
E	SCL	P	like E with safety technology
G	GENERAL (controlled frequency inverter)		
H	ASCL	L	like H with safety technology
M	MULTI (regulated, field-oriented frequency inverter for three-phase asynchronous motors)		
S	SERVO (regulated frequency inverter for synchronous motors)		

Series F5/F6

Inverter size

The type code is not used as order code, but only for identification!

1.7 Installation instructions

1.7.1 Cooling systems

The KEB COMBIVERT F5/F6 is available for different cooling systems:

Heat sink with cooling fan (mounted version)
The standard version is delivered with heat sink and cooling fan.

Special versions
The dissipation of power loss must be guaranteed by the machine builder.

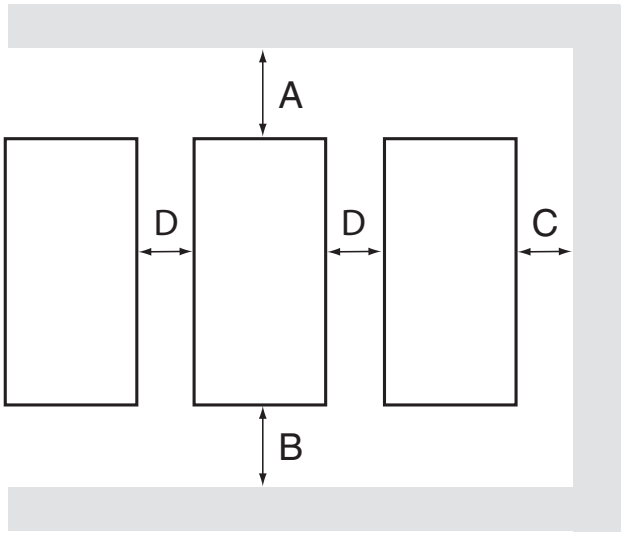
Flat rear
There is no heat sink at this version. The unit must be mounted on an appropriate ground for heat dissipation.

Water cooling
This version is dimensioned for the connection to an available cooling system. The dissipation of the power loss must be ensured by the machine builder. In order to avoid moisture condensation, the minimum inlet temperature may not decrease the ambient temperature. The max. inlet temperature may not exceed 40°C. No aggressive coolant shall be used. Measures against contamination and calcination must be done externally. We recommend a pressure of 4 bar on the cooling system.

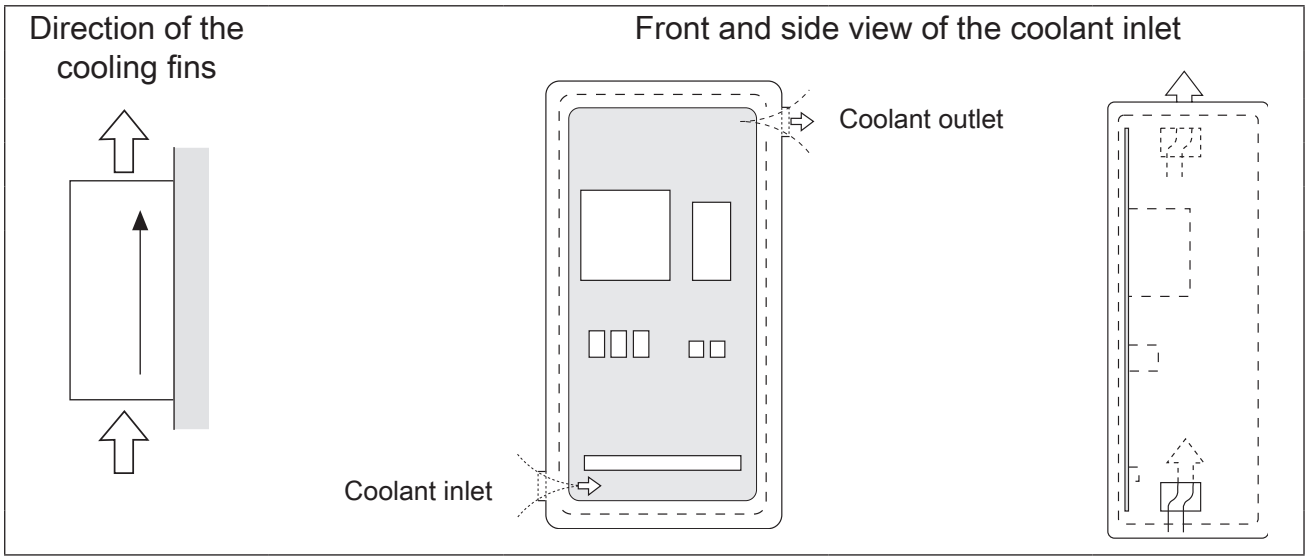
Convection (trough-mount version)
In this version the heat sink is placed externally with a cutout in the control cabinet.

Heat sinks can reach temperatures, which can cause burns when touching. If in case of structural measures a direct contact cannot be avoided, a warning notice "hot surface" must be mounted at the machine.

1.7.2 Control cabinet installation

Mounting distances	Dimen-sion	Distance in mm	Distance in inch
	A	150	6
	B	100	4
	C	30	1.2
	D	30	1.2
	X [1]	50	2

1) Distance to preceding elements in the cabinet door.



See annex C for instructions of water-cooled units.

1.8 Safety and application notes

Safety and application notes for drive converter
(in accordance with: Low-Voltage Directive 2006/95/EC)

1. General
In operation, drive converter depending on their degree of protection, may have live, uninsulated and possibly also moving or rotating parts, as well as hot surfaces.
In case of inadmissible removal of the required covers, of improper use, wrong installation or maloperation, there is the danger of serious personal injury and damage to property.
For further information, see documentation.
All operations serving transport, installation and commissioning as well as maintenance are to be carried out by skilled technical personnel (Observe IEC 364 or CENELEC HD 384 or DIN VDE 0100 and IEC 664 or DIN/VDE 0110 and national accident prevention rules!).
For the purposes of these basic safety instructions, „skilled technical personnel“ means persons who are familiar with the installation, mounting, commissioning and operation of the product and have the qualifications needed for the performance of their functions.

2. Specified application
Drive converter are components which are intended for the installation in electric systems or machines.
In case of installation in machinery, commissioning of the drive converter (i.e. the starting of normal operation) is prohibited until the machinery has been proved to conform to the provisions of the directive 2006/42/EC (Machinery Directive). Account is to be taken of EN 60204.
Start-up (i.e. the starting of normal operation) is only permitted in compliance with the EMC directive (2004/108/EC).
The drive converter meet the requirements of the Low-Voltage directive 2006/95/EC. The harmonized standards of the series EN 50178/DIN VDE 0160 in connection with EN 60439-1/DIN VDE 0660 part 500 and EN 60146/DIN VDE 0558 were used for drive converter.
The technical data as well as information concerning the supply conditions shall be taken from the rating plate and from the documentation and shall be strictly observed.

3. Transport, storage
The instructions for transport, storage and proper use shall be complied with.
The climatic conditions shall be in conformity with prEN 50178.

4. Installation
The installation and cooling of the appliances shall be in accordance with the specifications in the pertinent documentation.
The drive converter shall be protected against excessive strains. In particular, no components must be bent or isolating distances altered in the course of transportation or handling. No contact shall be made with electronic components and contacts.
Drive converter contain electrostatic sensitive components which are liable to damage through improper use. Electric components must not be mechanically damaged or destroyed (potential health risks).

5. Electrical connection
When working on live drive converter, the applicable national accident prevention rules (e.g. VBG 4) must be complied with.
The electrical installation shall be carried out in accordance with the relevant requirements (e.g. cross-sectional areas of conductors, fusing, PE connection). For further information, see documentation.
Instructions for the installation in accordance with EMC requirements, like screening, earthing, location of filters and wiring, are contained in the drive converter documentation. They must always be complied with, also for drive converter bearing a CE marking. Observance of the limit values required by EMC law is the responsibility of the manufacturer of the installation or machine.

6. Operation
Installations which include drive converter shall be equipped with additional control and protective devices in accordance with the relevant applicable safety requirements, e.g. act respecting technical equipment, accident prevention rules etc. Changes to the drive converter by means of the operating software are admissible.
After disconnection of the drive converter from the voltage supply, live appliance parts and power terminals must not be touched immediately because of possibly energized capacitors. In this respect, the corresponding signs and markings on the drive converter must be observed.
During operation, all covers and doors shall be kept closed.

7. Maintenance and servicing
The manufacturer’s documentation shall be followed.
KEEP SAFETY INSTRUCTIONS IN A SAFE PLACE!

2. Technical Data

2.1 Operating conditions

		Standard	Standard/ class	Instructions
Definition acc.		EN 61800-2		Inverter product standard: **rated specifications**
		EN 61800-5-1		Inverter product standard: **general safety**
Site altitude				max. 2000 m above sea level[3)] With site altitudes over 1000 m a derating of 1 % per 100 m must be taken into consideration.
Ambient conditions during operation				
Climate	Temperature	EN 60721-3-3	3K3	extended to -10…45 °C (use frost protection for water cooling systems and temperatures below zero)
	Humidity		3K3	5…85 % (without condensation)
Mechanical	Vibration		3M1	
Contamination	Gas		3C2	
	Solids		3S2	
Ambient conditions during transport				
Climate	Temperature	EN 60721-3-2	2K3	Drain heat sink completely
	Humidity		2K3	(without condensation)
Mechanical	Vibration		2M1	
	Surge		2M1	max. 100 m/s²; 11 ms
Contamination	Gas		2C2	
	Solids		2S2	
Ambient conditions for the storage				
Climate	Temperature	EN 60721-3-1	1K4	Drain heat sink completely
	Humidity		1K3	(without condensation)
Mechanical	Vibration		1M1	
	Surge		1M1	max. 100 m/s²; 11 ms
Contamination	Gas		1C2	
	Solids		1S2	
Type of protection		EN 60529	IP20	
Environment		IEC 664-1		Pollution degree 2
Definition acc.		EN 61800-3		Inverter product standard: **EMC**
EMC emitted interference (see instruction manual)				
Cable-based interferences		–	C3[1)2)]	Earlier limit value A (B optional) according to EN55011
Radiated interferences		–	C3[2)]	Earlier limit value according to EN55011
EMC interference immunity				
ESD		EN 61000-4-2	8 kV	AD (air discharge) and CD (contact discharge)
Burst - Ports for process measurement control lines and signal interfaces		EN 61000-4-4	2 kV	
Burst - power interfaces		EN 61000-4-4	4 kV	
Surge - power interfaces		EN 61000-4-5	1 / 2 kV	Phase-phase / phase-ground
Electromagnetic fields		EN 61000-4-3	10 V/m	
Cable-fed disturbances, induced by high frequency fields		EN61000-4-6	10 V	0.15-80 MHz
Voltage variation / voltage drop		EN 61000-2-1		+10 %, -15 %, 90 %
Voltage unsymmetries / Frequency changes		EN 61000-2-4		3 %, 2 %

1)	This product can cause high frequency disturbances in residential areas (category c1) which require noise suppression measures.
2)	The specified value is only meet in connection with a corresponding filter.
3)	Above 2000 m there is no "safe isolation" of the control.

2.2 Technical data of the 230V class

Inverter size			17	18	19	20	21
Housing size			R	R	R	R	R
Phases			3	3	3	3	3
Output rated power		[kVA]	33	40	46	59	71
Max. rated motor power		[kW]	18.5	22	30	37	45
Output rated current		[A]	84	100	115	145	180
Max. short time current	1)	[A]	126	150	172	217	270
OC-tripping current		[A]	151	180	206	261	324
Input rated current		[A]	92	116	126	165	198
Max. permissible main fuse gG	8)	[A]	100	160	160	200	315
Rated switching frequency	6)	[kHz]	8	8	8	8	8
Max. switching frequency	11)	[kHz]	16	16	16	16	16
Power dissipation at nominal operating		[W]	850	1020	1200	1350	1620
Power dissipation at DC operating		[W]	790	950	1100	1230	1470
Standstill current at 4 kHz	2)	[A]	92	110	126	159	198
Standstill current at 8 kHz	2)	[A]	84	100	115	145	180
Standstill current at 16 kHz	2)	[A]	50	70	69	101	90
Min. frequency at continuous full load		[Hz]	3	3	3	3	3
Max. heat sink temperature		[°C]	90°C (194°F)				
Motor cable cross-section	3)	[mm²]	35	50	50	95	95
Min. braking resistor	4)	[Ω]	4.7	4.0	3.0	2	2
Max. braking current	4)	[A]	85	100	132	160	160
Overload characteristic (see annex)			1				
Input rated voltage		[V]	230 (UL: 240)				
Input voltage range		[V]	180...260 ±0				
Input voltage at DC operation		[V]	250...370 ±0				
Mains frequency		[Hz]	50 / 60 ±2				
permitted mains forms			TN, TT, IT[9], Δ-mains[10]				
Output voltage	7)	[V]	3 x 0...Uin				
Output frequency	6)	[Hz]	0 - max. 599				
Cooling mode (L=air; W=water)			L				
Max. motor line length shielded		[m]	50				

1) With the regulated systems 5% are to be subtracted as overmodulation capacity.
2) Max. current before the OL2 function triggers (not in operating mode F5 GENERAL).
3) Recommended minimum cross section of the motor line for rated power and a cable length of upto 100 m (copper).
4) This data is only valid for units with internal brake transistor GTR 7 (see "Unit identification").
5) –
6) The output frequency is to be limited in such way that 1/10 of the switching frequency is not exceeded. Units with higher max. output frequency are subject to export restrictions and are only available on request.
7) The voltage of the motor is depending on units which are connected upstream and on the control method (example see chapter 3.3 in the annex).
8) Protection in accordance with UL see annex "Certification“.
9) Restrictions when using HF filters.
10) Phase conductor grounded mains are only permissible without HF filters
11) with COMPACT only 8 kHz, with F6-K only 8 kHz.

The technical data are for 2/4-pole standard motors. With other pole numbers the inverter must be dimensioned onto the motor rated current. Contact KEB for special or medium frequency motors.

2.2.1 Technical data of the 400 V class

Inverter size			18	19	20	21		22		23	24
Housing size			R								
Phases			3								
Output rated power		[kVA]	35	42	52	62		80		104	125
Max. rated motor power		[kW]	22	30	37	45		55		75	90
Output rated current		[A]	50	60	75	90		115		150	180
Max. short time current	1)	[A]	75	90	112	135		172		225	270
OC-tripping current		[A]	90	108	135	162		207		270	324
Input rated current		[A]	65	66	83	100		127		165	198
Max. permissible main fuse gG	8)	[A]	80	80	100	160		160		200	315
Rated switching frequency		[kHz]	16	8	8	4	8	4	8	2	2
Max. switching frequency	11)	[kHz]	16	16	16	16		16		8	8
Power dissipation at nominal operating		[W]	850	750	900	1000	1100	1200	1500	1300	1700
Power dissipation at DC supply		[W]	810	695	830	915	1015	1100	1400	1160	1530
Standstill current at 4 kHz	2)	[A]	55	66	82.5	99	99	126	115	127	144
Standstill current at 8 kHz	2)	[A]	50	66	75	81	90	80	115	90	108
Standstill current at 16 kHz	2)	[A]	40	36	34	45	63	46	51	–	–
Min. frequency at continuous full load		[Hz]	3								
Max. heat sink temperature		[°C]	90								
Motor cable cross-section	3)	[mm²]	25		35	50				95	
Max. motor line length shielded		[m]	100		50						
Min. braking resistor	4)	[Ω]	9					8		6	5
Max. braking current	4)	[A]	88					100		133	200
Overload characteristic (see annex)			1								
Input rated voltage	5)	[V]	400 (UL: 480)								
Input voltage range U_{in}		[V]	305…528 ±0								
Input voltage range at DC supply		[V]	420…746 ±0								
Mains frequency		[Hz]	50 / 60 ±2								
permitted mains forms			TN, TT, IT[9], Δ-mains[10]								
Output voltage	6)	[V]	3 x 0…U_{in}								
Output frequency	7)	[Hz]	0 - max. 599								
Cooling mode (L=air; W=water)			L	L/W							
Cooling water content			-	0.4 liter							

1) With the regulated systems 5% are to be subtracted as overmodulation capacity.
2) Max. current before the OL2 function triggers (not in operating mode F5 GENERAL).
3) Recommended minimum cross section of the motor line for rated power and a cable length of upto 100 m (copper).
4) This data is only valid for units with internal brake transistor GTR 7 (see "Unit identification").
5) At rated voltages ≥ 460 V multiply the rated current with factor 0.86.
6) The voltage of the motor is depending on units which are connected upstream and on the control method (example see chapter 3.3 in the annex).
7) The output frequency is to be limited in such way that 1/10 of the switching frequency is not exceeded.Devices with higher max. output frequency are subject to export restrictions and are only available on request.
8) Protection in accordance with UL see annex "Certification".
9) Restrictions when using HF filters.
10) Phase conductor grounded mains are only permissible without HF filters
11) with COMPACT only 8 kHz, with F6-K only 8 kHz.

The technical data are for 2/4-pole standard motors. With other pole numbers the inverter must be dimensioned onto the motor rated current. Contact KEB for special or medium frequency motors.

From size 23 the use of a input choke is absolutely necessary.

The response threshold of the braking transistsor (Pn.69) for all other controls without safety technology (A, E, G, H, M) must be adjusted at least to 770 Vdc (see annex D).

2.3 DC supply

2.3.1 Calculation of the DC input current

The **DC input current** of the inverter is basically determined by the used motor. The data can be taken from the motor name plate.

230V class :

$$I_{DC} = \frac{\sqrt{3} \bullet \text{rated motor voltage} \bullet \text{rated motor current} \bullet \text{Motor cos}\varphi}{\text{DC voltage (310 V)}}$$

400V class :

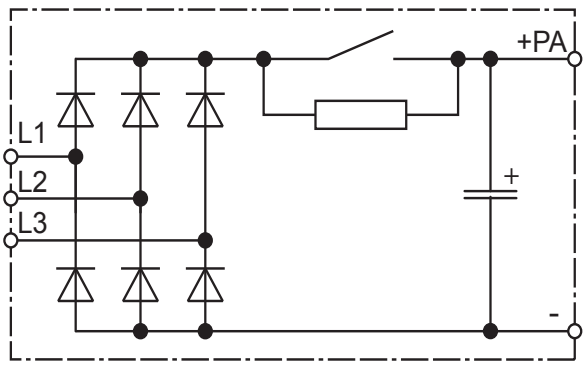
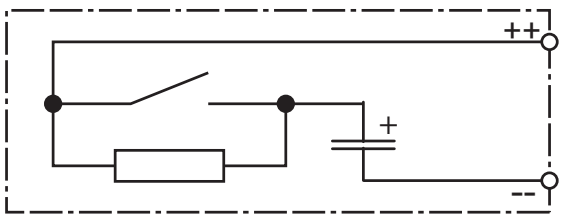
$$I_{DC} = \frac{\sqrt{3} \bullet \text{rated motor voltage} \bullet \text{rated motor current} \bullet \text{Motor cos}\varphi}{\text{DC voltage (540 V)}}$$

The **DC input peak current** is determined by the operating range.

- If you accelerate on the hardware current limit, the short-time current limit of the inverter must be used in the formula above (instead of the rated motor current).
- If the motor in normal operation is never stressed with rated torque, it can be calculated with the real motor current.

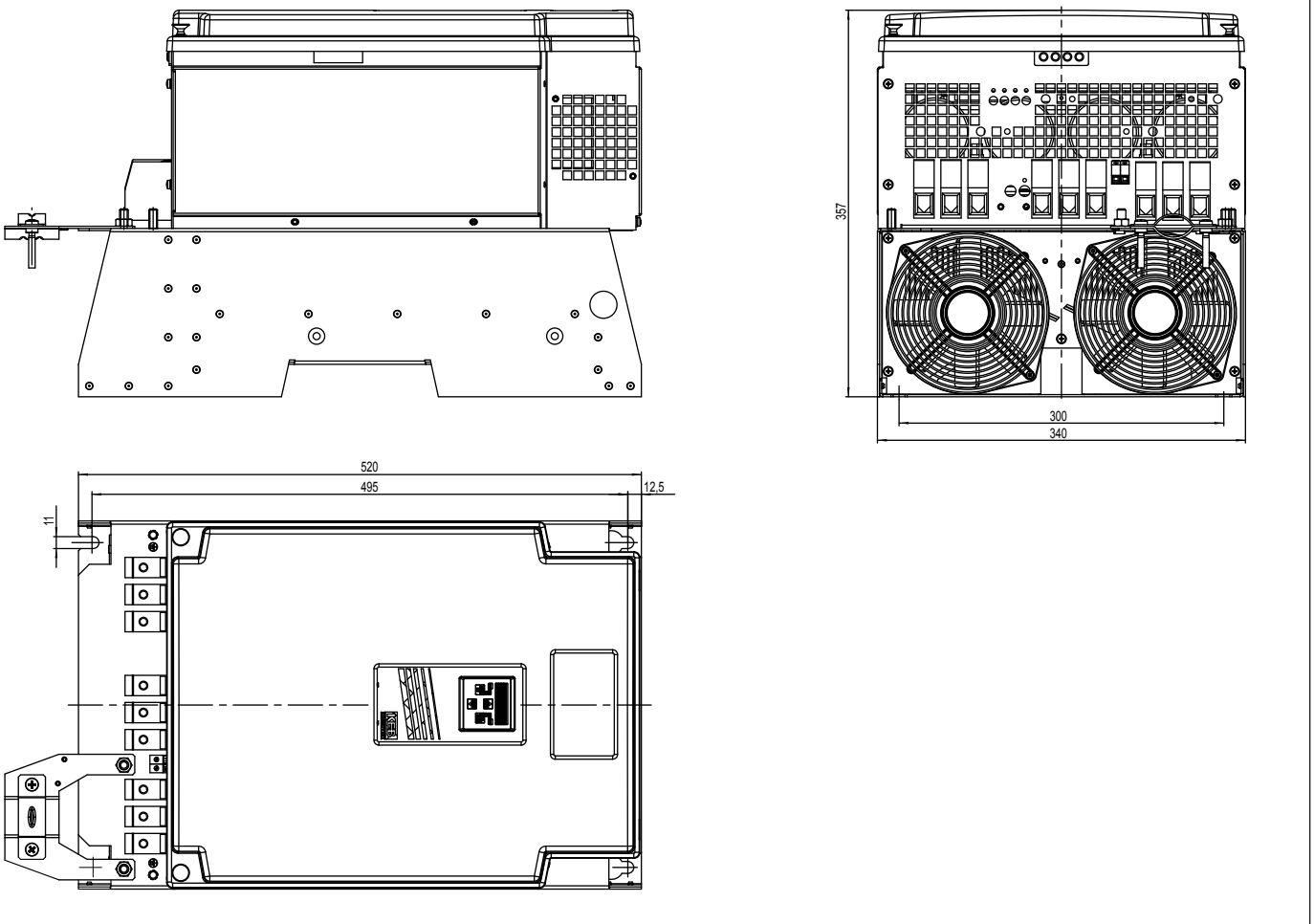
2.3.2 Internal input circuit

The COMBIVERT in R housing corresponds to the inverter type B1. Pay attention to the inverter type in DC interconnection and in operation at regenerative units.

Inverter types for COMBIVERT in R housing:	
Type B1	Type C1
	

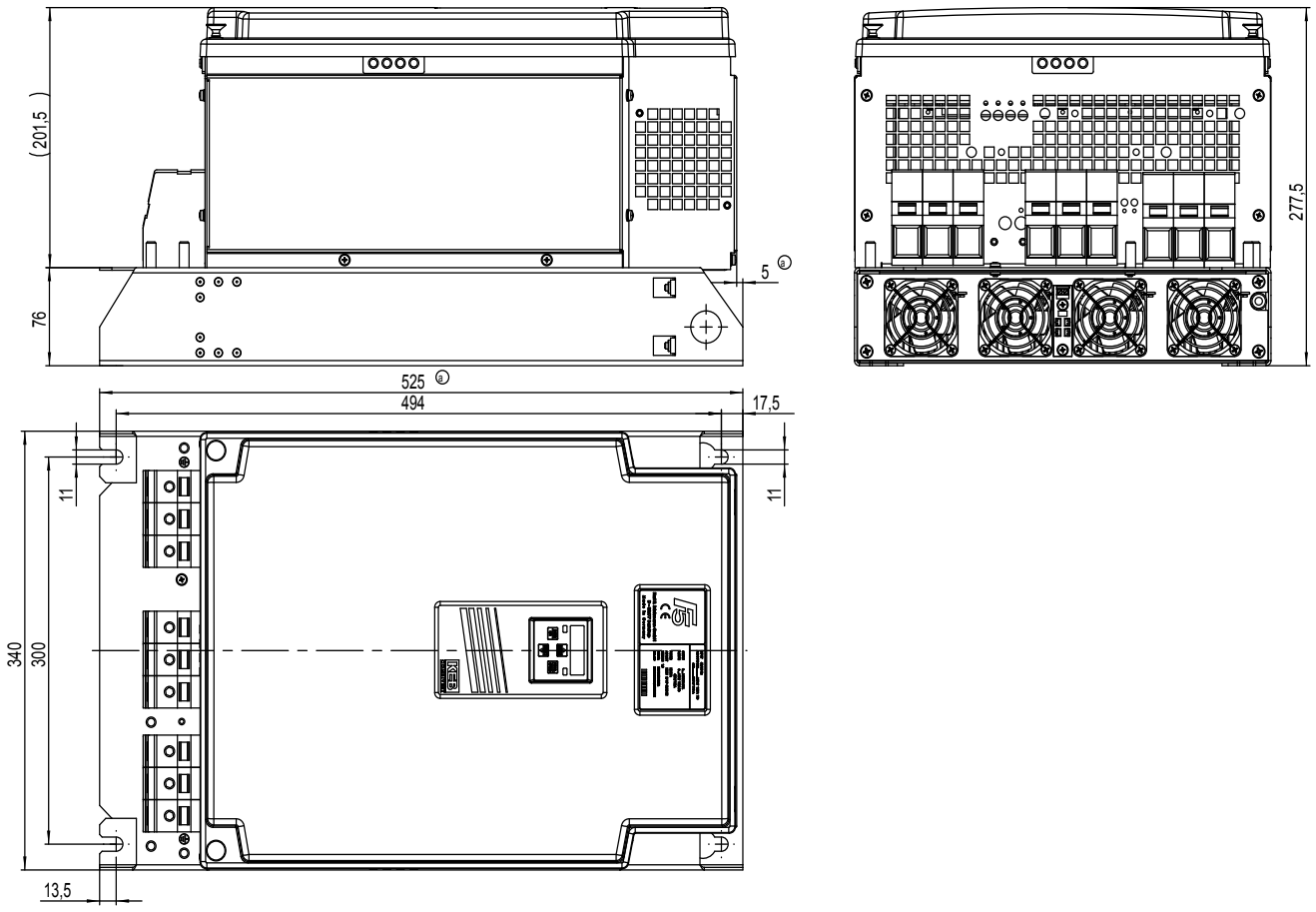
2.4 Dimensions and Weights

2.4.1 Dimensions air-cooling mounted version 1



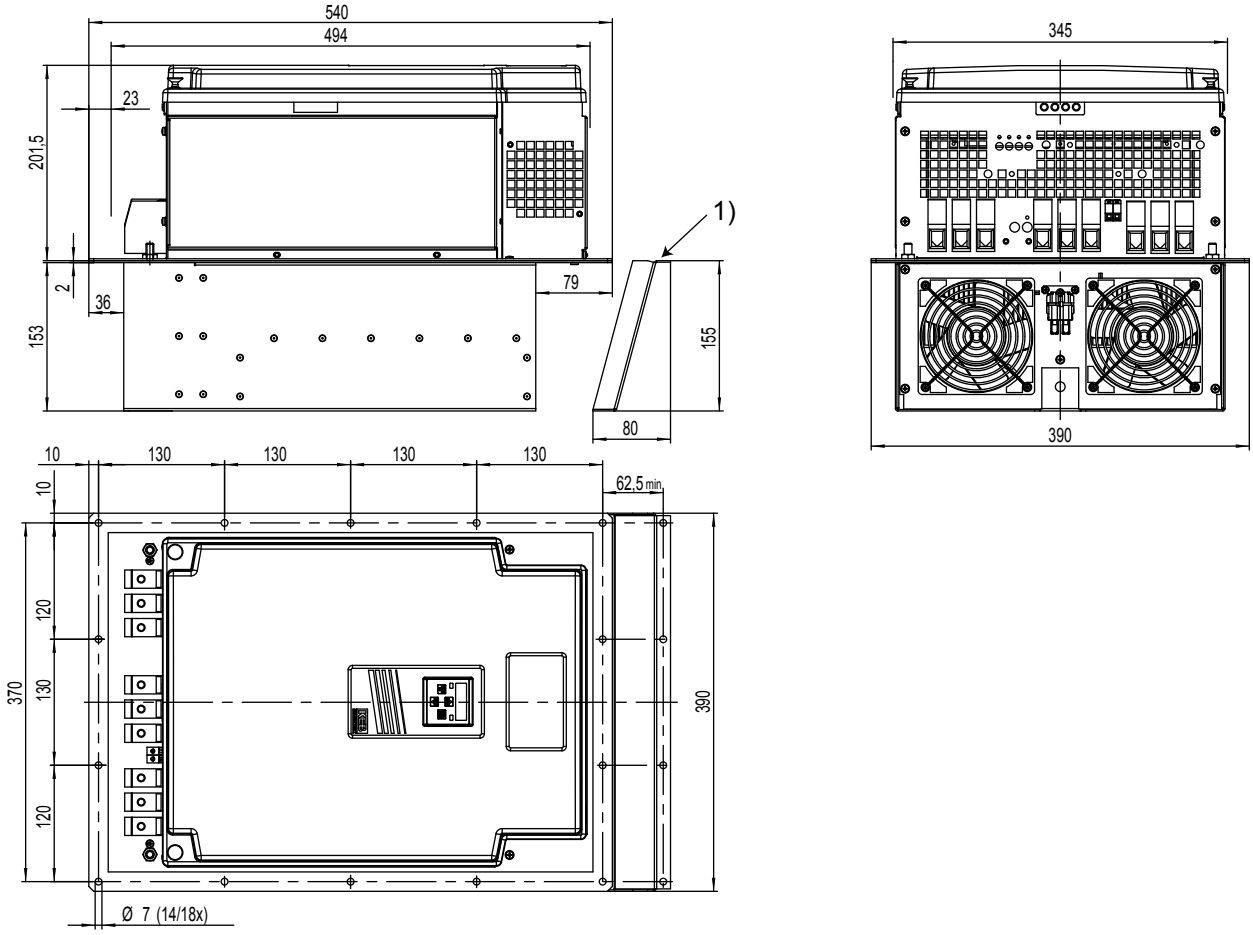
Housing type	Weight
Air-cooling mounted version with sub construction (2 fans)	32 kg

2.4.2 Dimensions air-cooling mounted version 2



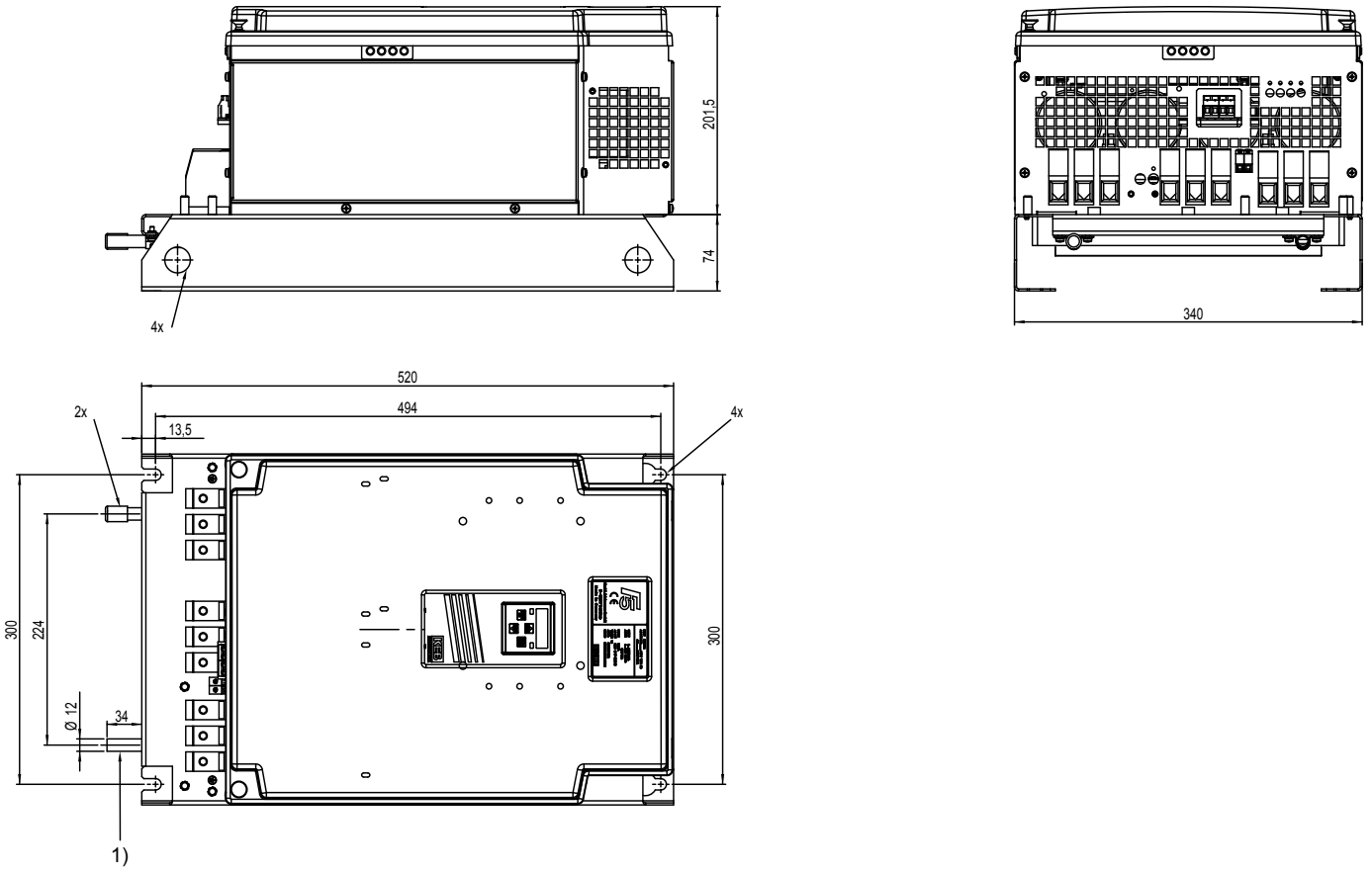
Housing type	Weight
Air-cooling mounted version with sub construction (4 fans)	33 kg

2.4.3 Dimensions air-cooling through-mount version



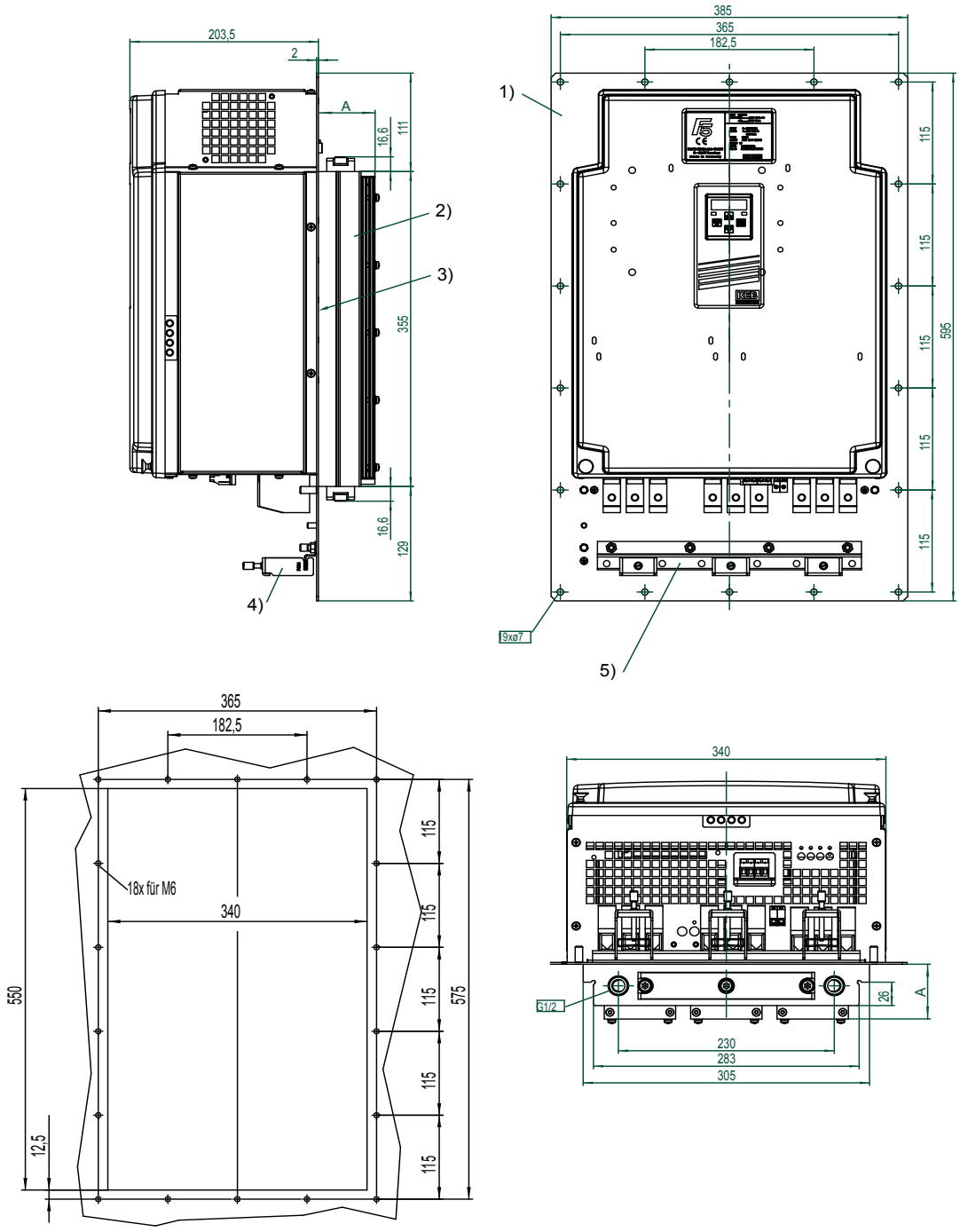
Housing type	Weight
Air-cooling through-mount version	28 kg
1) Optional: Cover plate R0F5T32-0057	

2.4.4 Dimensions water cooling mounted version



Housing type		Weight
Water cooling mounted version		32 kg
1)	An usual compression type fitting can be used for the coolant connection.	
	Series: light (315 bar) or very light (100 bar)	
	Outside pipe diameter: 12 mm	
	Material: stainless steel	
	Gain sockets are required in case of hard operating conditions (vibrations).	
	The assembly instructions of the manufacturer company are to be observed!	

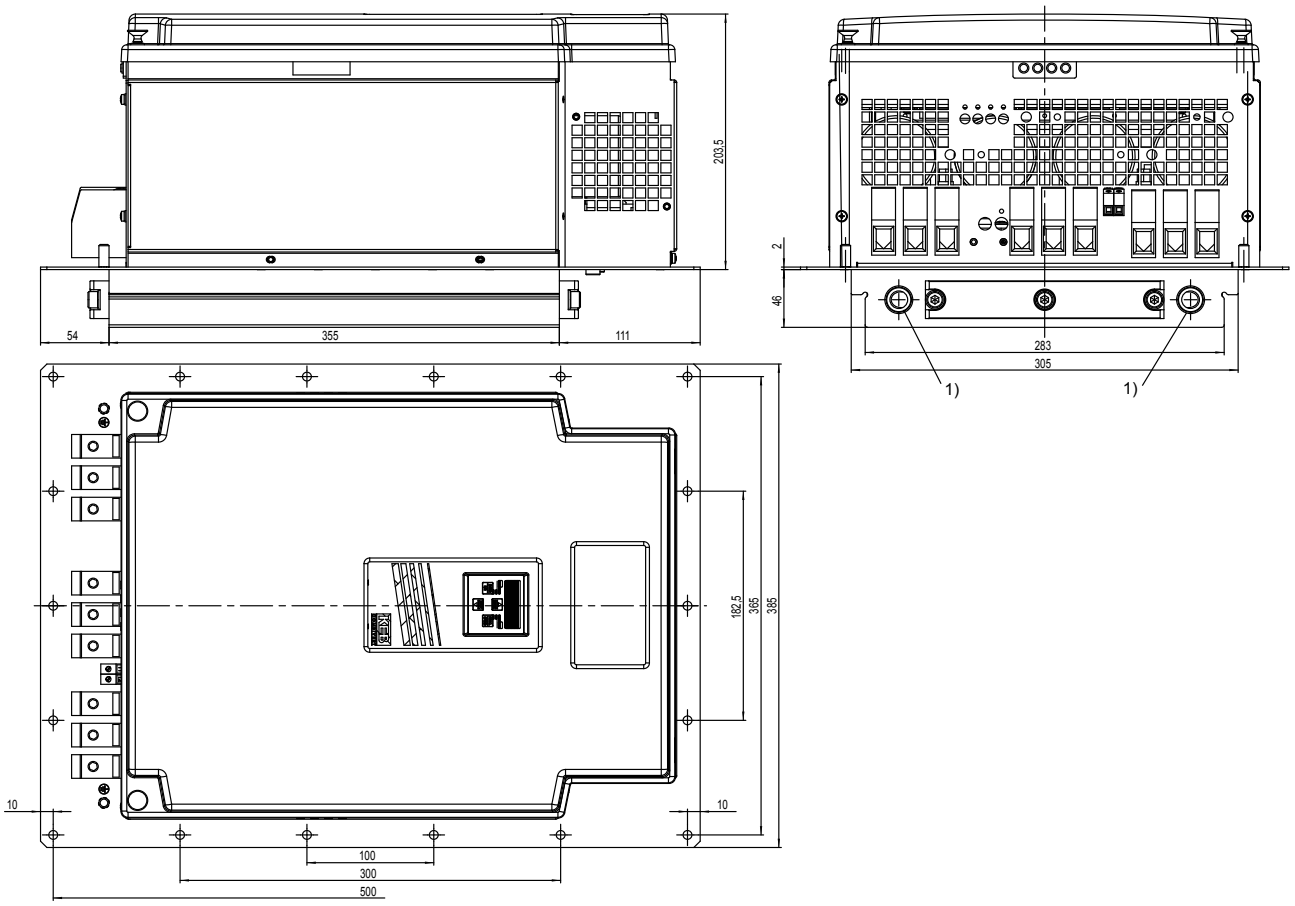
2.4.5 Dimensions water cooling through-mount version



Housing type	A	Weight
Water cooling through-mount version	46	35 kg
Water cooling through-mount version with braking resistor	61	45 kg

1)	Sub construction
2)	Heat sink
3)	Seal
4)	Shielding clamp
5)	Shield sheet

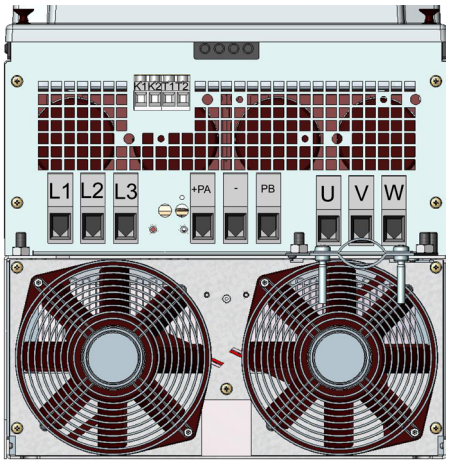
2.4.6 Dimensions water cooling through-mount version



Housing type	Weight
Water cooling through-mount version (max. 10 bar)	34 kg
1) Connection thread G1/2“	

2.5 Terminal strips of the power circuit

All terminal strips following the requirements of the EN 60947-7-1 (IEC 60947-7-1)

230 V AC housing size 17...18 400 V AC housing size 18...22	Terminal in acc. with table 2.5.1		
	**Name**	**Function**	**No.**
	L1, L2, L3	3-phase mains connection	1
	U, V, W	Motor connection	
	+PA, PB	Connection for braking resistor	
	+PA, –	Connection for braking module Regenerative unit 420…720 V VDC	
	T1, T2	Connection for temperature sensor	3
	K1, K2	GTR7 monitoring (optional)	
	⏚	Connection for shielding /earthing	4

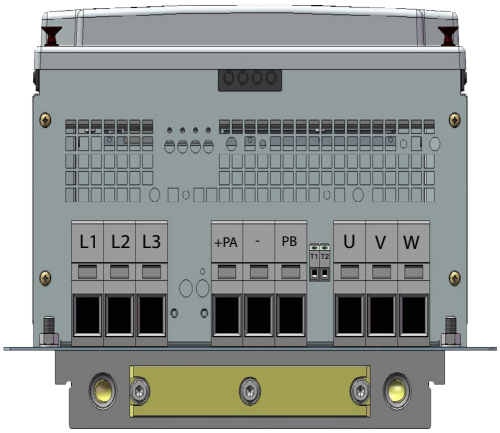
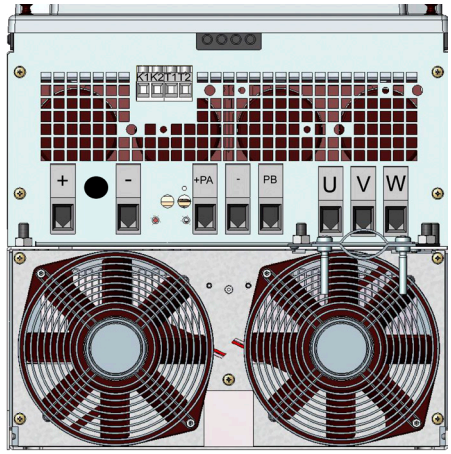
230 V AC housing size 19...21 400 V AC housing size 23...24	Terminal in acc. with table 2.5.1		
	**Name**	**Function**	**No.**
	L1, L2, L3	3-phase mains connection	2
	U, V, W	Motor connection	
	+PA, PB	Connection for braking resistor	
	+PA, –	Connection for braking module Regenerative unit 420…720 V VDC	
	T1, T2	Connection for temperature sensor	3
	K1, K2	GTR7 monitoring (optional)	
	⏚	Connection for shielding /earthing	4

Table 2.5.1 Permissible cable cross-sections and tightening torques of the terminals

No.	permissible cross-section flexible with wire-end ferrule				Maximum tightening torque	
	mm²		AWG/MCM		Nm	lb inch
	min	max	min	max		
1	16	50	6 AWG	0 MCM	6…8	75
2	35	95	4 AWG	000 MCM	15…20	175
3	0.2	4	24 AWG	10 AWG	0.6	5.3
4	8 mm stay bolt for ring thimble				13	115

400 V DC housing size 19	Terminal in acc. with table 2.5.1		
	**Name**	**Function**	**No.**
	+, -	DC-supply connection	1
	U, V, W	Motor connection	
	+PA, PB	Connection for braking resistor	
	+PA, –	Connection for braking module Regenerative unit 420…720 V VDC	
	T1, T2	Connection for temperature sensor	3
	K1, K2	GTR7 monitoring (optional)	
	⏚	Connection for shielding /earthing	4

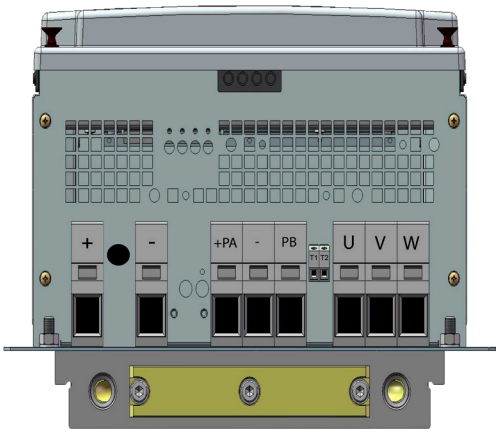
230 V DC housing size 20 400 V DC housing size 20...22	Terminal in acc. with table 2.5.1		
	**Name**	**Function**	**No.**
	+, -	DC-supply connection	2
	U, V, W	Motor connection	
	+PA, PB	Connection for braking resistor	
	+PA, –	Connection for braking module Regenerative unit 420…720 V VDC	
	T1, T2	Connection for temperature sensor	3
	K1, K2	GTR7 monitoring (optional)	
	⏚	Connection for shielding /earthing	4

Table 2.5.1 Permissible cable cross-sections and tightening torques of the terminals

No.	permissible cross-section flexible with wire-end ferrule				Maximum tightening torque	
	mm²		AWG/MCM		Nm	lb inch
	min	max	min	max		
1	16	50	6 AWG	0 MCM	6…8	75
2	35	95	4 AWG	000 MCM	15…20	175
3	0.2	4	24 AWG	10 AWG	0,6	5.3
4	8 mm stay bolt for ring thimble				13	115

2.6 Connection accessories

2.6.1 Filter and chokes

Voltage class	Inverter size	Filter	Mains choke 50 Hz / 4 % Uk	Motor choke 100 Hz / 4 % Uk
230 V	17	20E4T60-1001	17Z1B03-1000	21Z1F04-1010
	18	22E4T60-1001	18Z1B03-1000	22Z1F04-1010
	19	22E4T60-1001	19Z1B03-1000	22Z1F04-1010
	20	22E4T60-1001	20Z1B03-1000	upon request
	21	23E4T60-1001	21Z1B03-1000	upon request

Voltage class	Inverter size	Filter	Mains choke 50 Hz / 4 % Uk	Motor choke 100 Hz / 4 % Uk
400 V	18	20E4T60-1001	18Z1B04-1000	18Z1F04-1010
	19	20E4T60-1001	19Z1B04-1000	19Z1F04-1010
	20	20E4T60-1001	20Z1B04-1000	20Z1F04-1010
	21	22E4T60-1001	21Z1B04-1000	21Z1F04-1010
	22	22E4T60-1001	22Z1B04-1000	22Z1F04-1010
	23	22E4T60-1001	23Z1B04-1000	upon request
	24	23E4T60-1001	24Z1B04-1000	upon request

- The service life of the frequency converter/ servo drive with intermediate voltage circuit depends on the current load of the electrolytic capacitors in the intermediate circuit. The use of mains chokes can increase the service life of the condensators to a considerable extent, especially when connecting to „hard“ power systems or when under permanent drive load (continuous duty).
  For continuous duty (S1) drives with a medium duty of >60%, KEB recommends the use of mains chokes with a terminal voltage (Uk) of 4%.
  The term “hard” mains can be defined as follows:

$$k = \frac{Smains}{Sn} >> 200$$

  The rated power of the inverter (Sn) is very low compared to the nodal point power (Smains). Example:

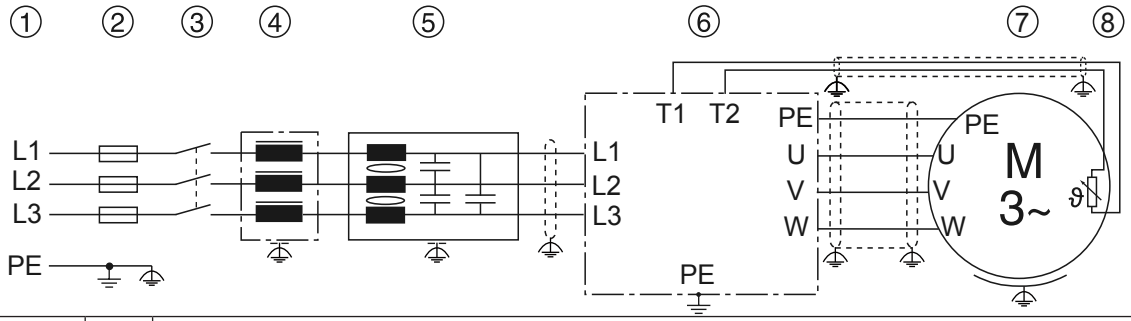
$$k = \frac{Smains}{Sm} = \frac{2\,MVA\ (supply\ transformer)}{6.6\,kVA\ (12.F5)} = 303 \quad \text{-> Choke required}$$

- When using a mains choke, it should usually be mounted on the mains side of the interference suppression filter.

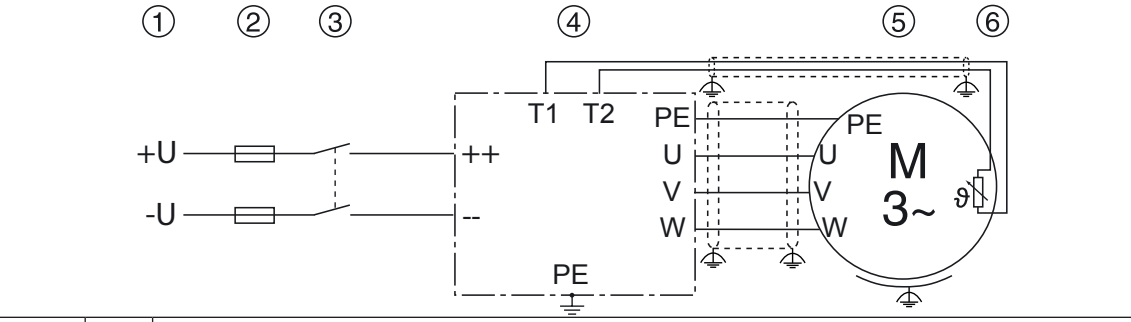
2.7 Connection Power Unit

2.7.1 Mains and motor connection

⚠	Absolutely pay attention to the supply voltage of the KEB COMBIVERT. A 230-V unit at 400-V mains is destroyed immediately.
⚠	Exchanging mains and motor connection leads to immediate destruction of the unit.
⚠	Pay attention to the supply voltage and the correct polarity of the motor!



Legend	1	Mains supply
	2	Mains fuse
	3	Mains contactor
	4	Mains choke
	5	HF filter
	6	KEB COMBIVERT
	7	Motor (see also 2.7.3)
	8	Motor protection temperature sensor (also see 2.7.4)

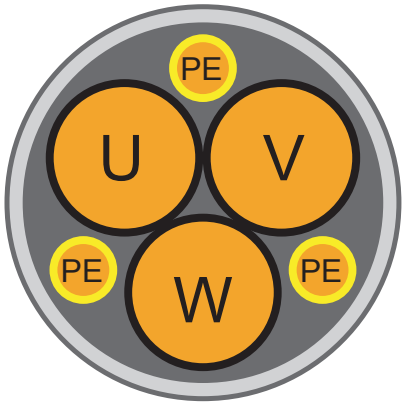


Legend	1	DC supply
	2	DC fuses
	3	Mains contactor
	4	KEB COMBIVERT with DC input
	5	Motor (see also 2.7.3)
	6	Motor protection temperature sensor (also see 2.7.4)

2.7.2 Selection of the motor cable

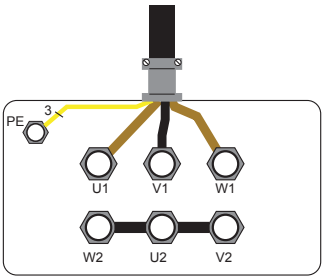
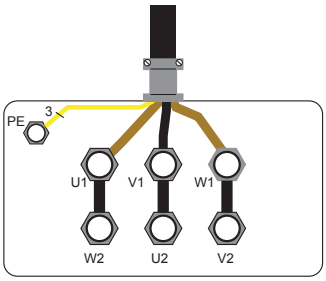
Correct selection and wiring of the motor cable is very important for high motor ratings:

- lower abrasion of the motor bearings by leakage currents
- improved EMC characteristics
- lower symmetrical operating capacities
- less losses by transient currents

Cross section of a shielded motor cable with tripartited protective earth conductor	
	It is recommended to use symmetric shielded motor cables at high motor ratings (>30 kW). At these cables the protective earth conductor is tripartited and uniformly placed between the phase lines. A cable without protective earth conductor can be used if the local regulations allow this. Then this protective earth conductor must be placed externally. Certain cables accept also the shielding as protective earth conductor. Pay attention to the data of the cable manufacturer!

2.7.3 Connection of the motor

As a standard the connection of the motor must be carried out in accordance with the following table:

Connection of the motor			
230/400 V motor		400/690 V motor	
230 V	400 V	400 V	690 V
Delta	Star	Delta	Star
Motor connection in star connection		Motor connection in delta connection	
			
The connecting-up instructions of the motor manufacturer are generally valid!			

Protect motor against voltage peaks!	Inverter switch at the output with a du/dt of approx. 5kV/µs. Voltage peaks that endanger the insulation system at the motor can occur especially in case of long motor cables (> 15 m). A motor choke, a du/dt filter or sine-wave filter can be used to protect the motor.	

2.7.4 Temperature detection T1, T2

Parameter In.17 displays in high byte the installed temperature input of the inverter. The KEB COMBIVERT F5/F6 is delivered as standard with switchable PTC/KTY evaluation. The desired function is adjusted with Pn.72 (dr33 at F6) and operates in accordance with the following table:

In.17	Function of T1, T2	Pn.72 (dr33)	Resistance	Display ru.46 (F6 => ru28)	Error/Warning [1]
5xh	KTY84	0	< 215 Ω	Detection error 253	x
			498 Ω	1°C	– [2]
			1 kΩ	100°C	x [2]
			1.722 kΩ	200°C	x [2]
			> 1811 Ω	Detection error 254	x
	PTC (in accordance with DIN EN 60947-8)	1	< 750 Ω	T1-T2 closed	–
			0.75…1.65 kΩ (reset resistance)	T1-T2 closed	–
			1.65…4 kΩ (tripping resistance)	T1-T2 open	x
			> 4 kΩ	T1-T2 open	x
6xh	PT100	–	upon request		
1)	The column is valid at factory setting. The function must be programmed accordingly with parameters Pn.12, Pn.13, Pn.62 and Pn.72 for F5 in operating mode GENERAL.				
2)	Disconnection is depending on the adjusted temperature in Pn.62 (F6 => pn11/14).				

The behaviour of the inverter in case of error/warning is defined with parameters Pn.12 (CP.28), Pn.13 (F6 =>pn12/13).

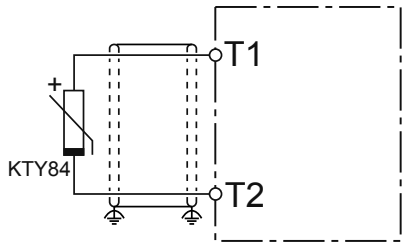
Dependent on the application the temperature input can be used for the following functions:

Function	Mode (F5 => Pn.72; F6 => dr33)
Motor temperature display and monitoring	KTY84
Motor temperature monitoring	PTC
Temperature control for water-cooled motors [1]	KTY84
General fault sensing	PTC
1) If the temperature input is used for other functions, the motor temperature control at water-cooled inverters can be done indirectly via the water cooling circuit of the inverter.	

- Do not lay KTY or PTC cable of the motor (also shielded) together with control cable!
- KTY or PTC cable only permissible with double shielding within the motor cable!

The error message E.dOH should never be disabled, otherwise the load shunt is no longer evaluated. This can cause damage to the hardware!

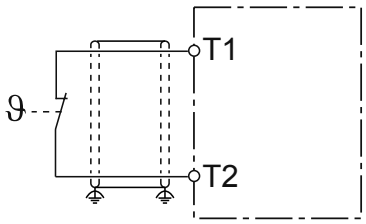
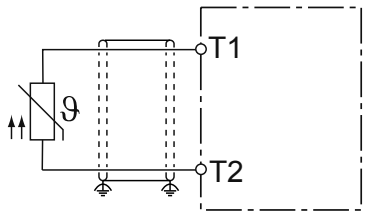
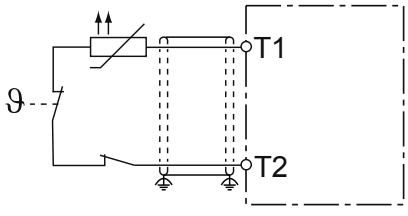
2.7.4.1 Use of the temperature input in KTY mode

Connection of a KTY sensor	
	KTY sensors are poled semiconductors and must be operated in forward direction! Connect anode to T1! Non-observance leads incorrect measurement in the upper temperature range. Protection of the motor winding is no longer guaranteed.
	• KTY sensors may not be combined with other devices. Otherwise wrong measurements would be the consequence. • The control type COMPACT does not support KTY sensors.

	Examples for the construction and programming of a temperature control with KTY84 evaluation can be taken from the application manual.

2.7.4.2 Use of the temperature input in PTC mode

If the temperature input is operated in PTC mode, all possibilities are available for the user within the specified resistance range. This can be:

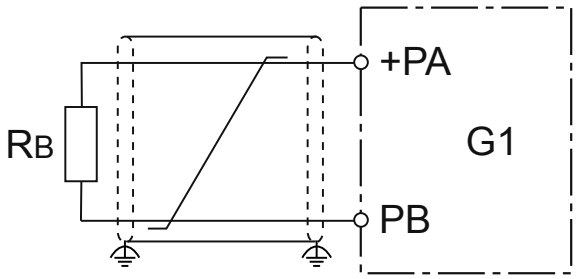
Wiring example in PTC mode	
Thermal contact (NC contact)	
Temperature sensor (PTC)	
Mixed sensor chain	

The function can be switched off with Pn.12="7" (CP.28) if no evaluation of the input is desired (standard in operating mode GENERAL). Alternatively a bridge can be installed between T1 and T2.

2.7.5 Connection of a braking resistor

	Braking resistors dissipate the produced energy of the motor into heat during generatoric operation. Thus braking resistors can cause very high surface temperatures. During assembly pay attention to appropriate protection against contact and fire.
	The use of a regenerative unit is reasonable for applications which produce a lot of regenerative energy. Regeneration of excess energy into the mains.
	The mains voltage must always be switched off in order to guarantee fire protection in case of a defective braking transistor.
	The frequency inverter remains in operation in spite of switched off power supply in generatoric operation. An error must be released by external wiring which switches the modulation off in the inverter. This can occur e.g. at terminals T1/ T2 or via digital input. The frequency inverter must be programmed accordingly in each case.
	The response threshold of the braking transistsor (Pn.69) for all other controls without safety technology (A, E, G, H, M) must be adjusted at least to 770 Vdc (see annex D).

2.7.5.1 Braking resistor without temperature monitoring

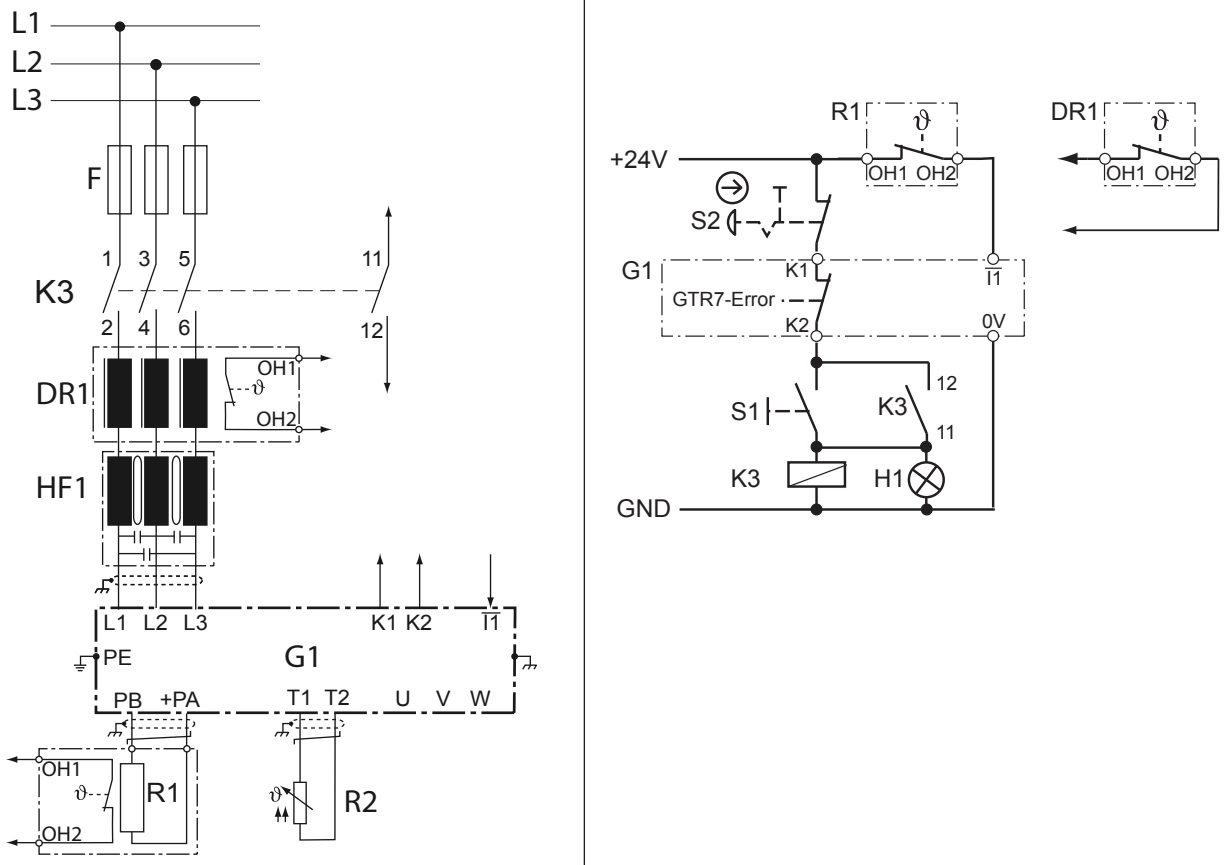
Intrinsically safe braking resistor without temperature monitoring

 Only "intrinsically safe" braking resistors are permissible for operation without temperature monitoring.

2.7.5.2 Braking resistor with over-heat protection and GTR7 monitoring (water-cooled inverters)

This circuit offers a direct protection with defective GTR7 (braking transistor). At defective braking transistor an integrated relay opens the terminals K1/K2 and error „E.Pu“ is released. Terminals K1/K2 are integrated into the holding circuit of the input contactor, so the input voltage is switched off in error case. Regenerative operation is also secured by the internal fault disconnection. All other errors of the braking resistor and the input choke are intercepted via a digital input. The input must be programmed to "external error".

	If the PTC/KTY evaluation of the motor at terminals T1/T2 is not used, these terminals can be used instead of the programmable input. The temperature input must be operated in PTC mode.

Connection example: Braking resistor with over-heat protection and GTR7 monitoring



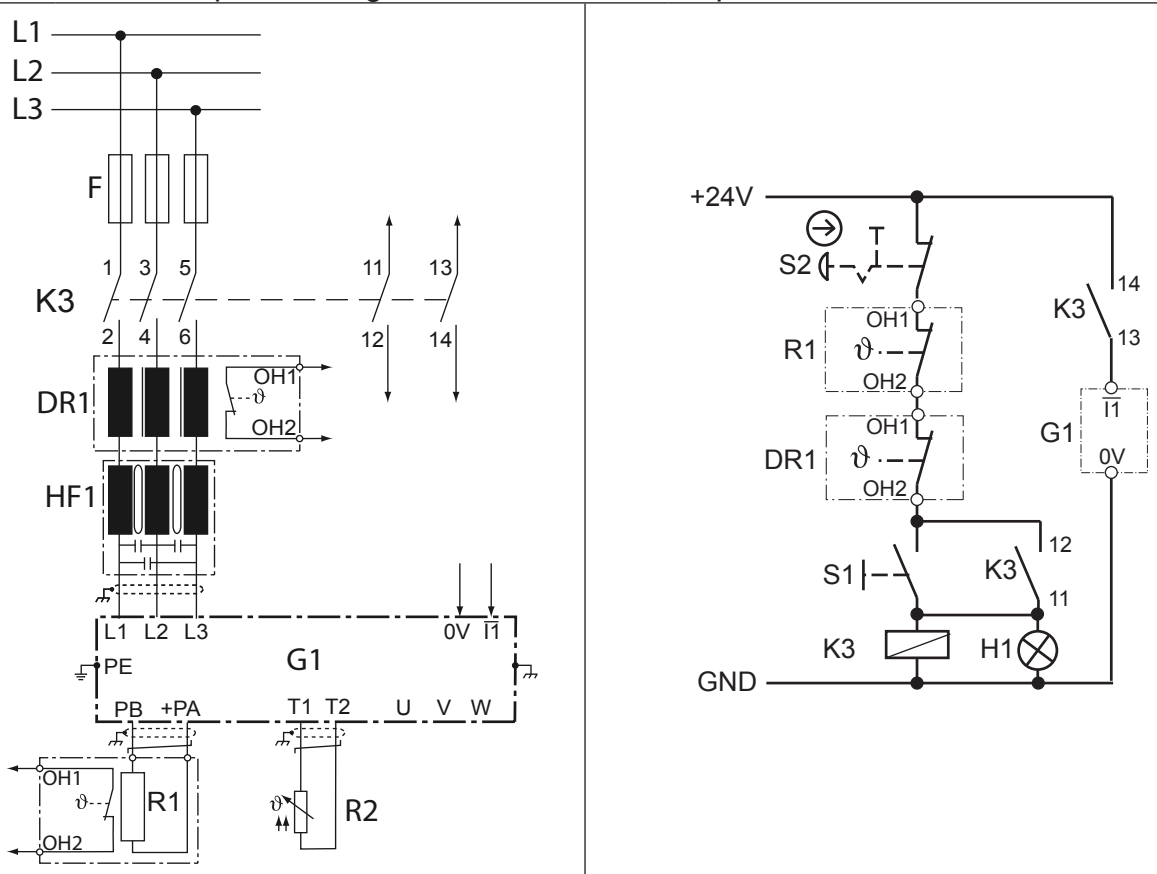
K3	Line contactor with auxiliary contacts	R1	Braking resistor with temperature switch
S1	Key for switch on	R2	PTC or KTY84 sensor e.g. of the motor
S2	Emergency stop circuit braker for switch off	DR1	Mains choke with temperature switch (optional)
H1	Tripping control	HF1	HF filter
G1	Inverter with GTR7 evaluation (relay 30 V DC/ 1 A) and programmable input I1		

2.7.5.3 Braking resistor with over-heat protection and GTR7 monitoring (air-cooled inverters)

This circuit offers a direct protection with defective GTR7 (braking transistor). The braking resistor overheats and opens the OH terminals with defective GTR7. The OH terminals open the holding circuit of the input contactor, so that the input voltage is switched off in error case. An error in inverter is released by opening the auxiliary contacts of K3. Regenerative operation is also secured by the internal fault disconnection. The input must be programmed and inverted to "external error". Automatic restarting after cooling of the braking resistor is prevented by the self-holding circuit of K3.

	If the PTC/KTY evaluation of the motor at terminals T1/T2 is not used, these terminals can be used instead of the programmable input. The temperature input must be operated in PTC mode.

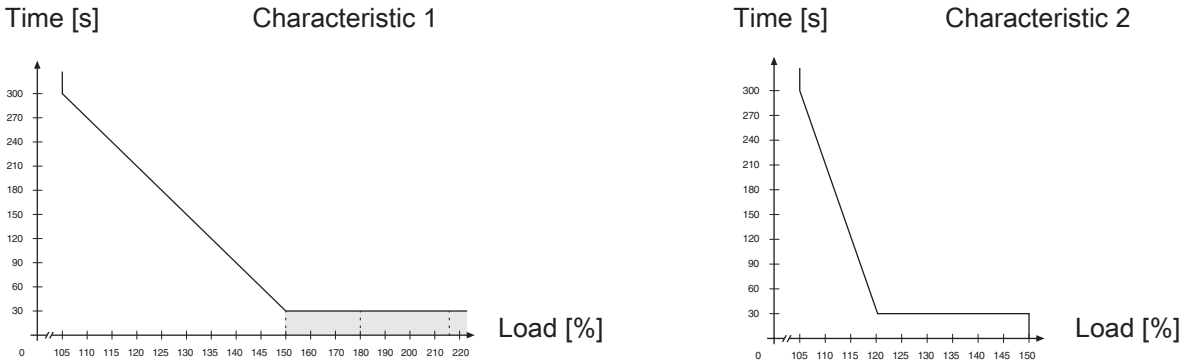
Connection example: Braking resistor with over-heat protection without GTR7 monitoring



K3	Line contactor with auxiliary contacts	R1	Braking resistor with temperature switch
S1	Key for switch on	R2	PTC/KTY84 sensor e.g. of the motor
S2	Emergency stop circuit braker for switch off	DR1	Mains choke with temperature switch (optional)
H1	Tripping control	HF1	HF filter
G1	Inverter with programmable input I1		

Annex A

A.1 Overload characteristic

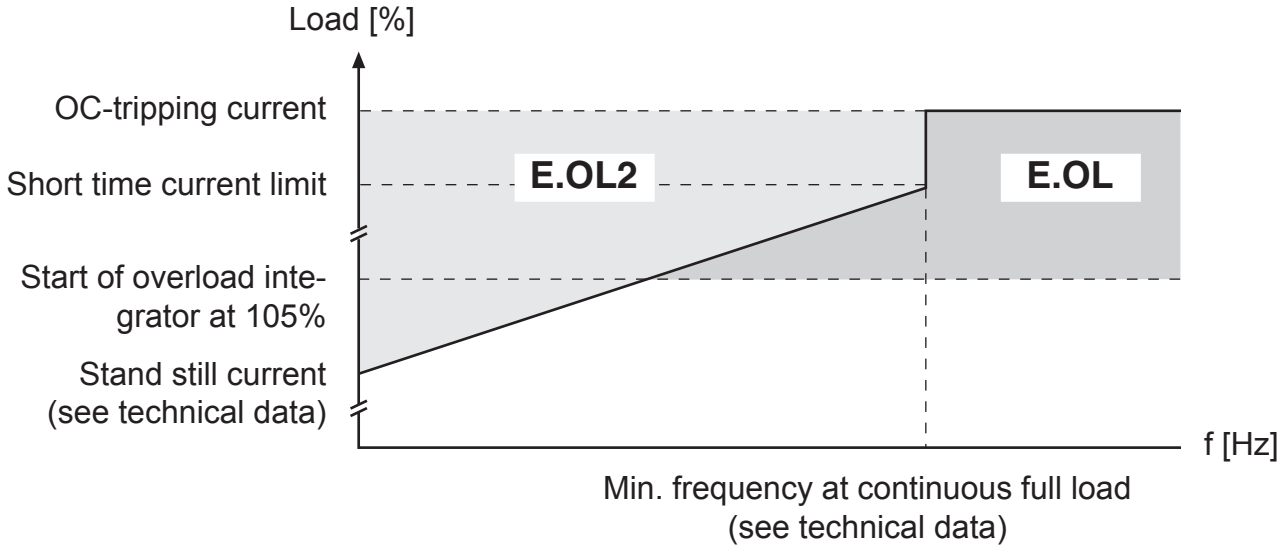


The characteristic declines device-dependently in this range (see unit identification).

On exceeding a load of 105% the overload integrator starts. When falling below the integrator counts backwards. If the integrator achieves the overload characteristic that corresponds to the inverter, the error E.OL is triggered.

A.2 Overload protection in the lower speed range

(only operating mode MULTI and SERVO)



A PT1-element ($\tau = 280$ ms) starts if the permissible current is exceeded. After its sequence of operation the error E.OL2 is triggered.

A.3 Calculation of the motor voltage

The motor voltage for dimensioning of the drive is depending on the used components. The mains voltage reduces according to the following table:

Mains choke Uk	4 %	Example:
Inverter open loop	4 %	Closed loop inverter with mains- and motor choke at non-rigid supply system: 400 V mains voltage - 15 % = 340 V motor voltage
Inverter closed loop	8 %	
Motor choke Uk	1 %	
Non-rigid supply system	2 %	

A.4 Maintenance

All work may only be done by qualified personnel. The security must be ensured as follows:

- Disconnect power supply at MCCB
- Secure against restarting
- Await discharge time of capacitors (if necessary controlling by measurement at „+PA“ and „-“, respectively “++“ and „--“)

- Ensure loss of voltage by measurement

In order to avoid premature ageing and avoidable malfunctions, the measures mentioned below must be carried out in the appropriate cycle.

Cycle	Function
Constant	Pay attention to unusual noises of the motor (e.g. vibrations) as well as of the frequency inverter (e.g. fan).
	Pay attention to unusual smells of the motor or frequency inverter (e.g. evaporation of capacitor electrolyte, braise of the motor winding)
Monthly	Check unit for loose screws and plugs and if necessary tighten up.
	Clean frequency inverter from dirt and dust deposits. Pay attention especially to cooling fins and protective grid of the fans.
	Examine and clean extracted air filter and cooling air filter of the control cabinet.
	Examine function of the fans of the KEB COMBIVERT. The fans must be replaced in case of audible vibrations or squeak.
Annual	Check the connecting ducts for corrosion and change it if necessary for units with water cooling.

A.5 Storage

The DC link of the KEB COMBIVERT is equipped with electrolytic capacitors. If the electrolytic aluminium capacitors are stored de-energized, the internal oxide layer is removed slowly. Due to the leakage current the oxide layer is unrenewed. If the capacitor starts running with rated voltage there is a high leakage current which can destroy the capacitor.
In order to avoid defectives, the KEB COMBIVERT must be started up depending on the storage period in accordance with the following specification:

Storage period < 1 year			
• Start-up without special measures			
Storage period 1…2 years			
• Operate frequency inverter one hour without modulation			
Storage period 2…3 years			
• Remove all cables from the power circuit; especially of braking resistor or module			
• Open control release			
• Connect variable transformer to inverter input			
• Increase variable transformer slowly to indicated input voltage (>1 min) and remain at least on the specified time.			
	Voltage class	Input voltage	Residence time
	400 V	0…280 V	15 min
		280…400 V	15 min
		400…500 V	1 h
Storage period > 3 years			
• Input voltages as before, however double the times per year. Eventually change capacitors.			

After expiration of this start-up the KEB COMBIVERT can be operated on nominal rating conditions or delivered to a new storage.

A.5.1 Cooling circuit

The cooling circuit must be completely empty if a unit shall be switched off for a longer period. The cooling circuit must be blown out additionally with compressed air at temperatures below 0°C.

Annex B

B.1 Certification

B.1.1 CE Marking

CE marked frequency inverter and servo drives were developed and manufactured to comply with the regulations of the Low-Voltage Directive 2006/95/EC.
The inverter or servo drive must not be started until it is determined that the installation complies with the Machine directive (2006/42/EC) as well as the EMC-directive (2004/108/EC) (note EN 60204).
The frequency inverters and servo drives meet the requirements of the Low-Voltage Directive 2006/95/EC. The harmonized standards of the series EN 61800-5-1 in connection with EN 60439-1 and EN 60146 were used.
This is a product of limited availability in accordance with IEC 61800-3. This product may cause radio interference in residential areas; In this case the operator may need to take corresponding measures.

B.1.2 UL Marking

c UL us	Acceptance according to UL is marked at KEB inverters with the adjacent logo on the type plate.

To be conform according to UL for the use on the North American and Canadian Market the following instructions must be observed (original text of the UL):

- Control Board Rating (max. 30Vdc, 1A)
- „Maximum Surrounding Air Temperature 45°C“
- Degree of Overload Protection provided internally by the Drive, in percent of full load current.
- For KEB Control boards type „Basic (B)“ or „Compact (C)“ motor overload protection has to be added by using the internal motor thermal sensor.
  For KEB Control boards type „Application (A, E, H)“, „General (G, M)“ or „Application Safety (K, L, P)“ motor protection has to set by parameters Pn14 and Pn15. See manual for details.
- Wiring Terminals marked to indicate proper connections for the power supply, load and control circuit.
- „Use 75°C Copper Conductors Only“
- Terminals - Torque Value for Field Wiring Terminals, the value to be according to the R/C or Unlisted Terminal Block used.
- Ground Terminals - „Ground Stud and Nut shall be connected with UL Listed Ring Connectors (ZMVV), rated suitable“. The suitable Torque Value of the Nuts in Nm.
- „Devices are intended for use in pollution degree 2 environment“ (or similar wording)
- ”Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the Manufacturer Instructions, National Electrical Code and any additional local codes”, or the equivalent“.

Short Circuit rating and Branch Circuit Protection:

All 240V models:
„Suitable For Use On A Circuit Capable Of Delivering Not More Than 100 kA rms Symmetrical Amperes, 240 Volts Maximum when Protected by Class ___ Fuses, rated ____ Amperes as specified in table I”:

or when Protected by A Circuit Breaker Having an Interrupting rating Not Less than 100 kA rms Symmetrical Amperes, 480V maximum, rated ____ Amperes as specified in table I”:

All 480V Models:
„Suitable For Use On A Circuit Capable Of Delivering Not More Than 100 kA rms Symmetrical Amperes, 480 Volts Maximum when Protected by Class ____ Fuses, rated ___ Amperes as specified in table I”:

or when Protected by A Circuit Breaker Having an Interrupting rating Not Less than 100 kA rms Symmetrical Amperes, 480V maximum, rated ___ Amperes as specified in table I”:

Table I Branch Circuit Protection for KEB inverters F4-R and F5/F6–R housing:

a) UL 248 Fuses; Class RK5 or L as specified below

Inverter F5/F6	Input Voltage (V)	UL 248 Fuse type L, max [A]	UL 248 Fuse type RK5, max [A]
17	240 / 3ph	–	110
18	240 / 3ph	–	125
19	240 / 3ph	–	150
20	240 / 3ph	–	175
21	240 / 3ph	–	200
17	480 / 3ph	125	60
18	480 / 3ph	150	70
19	480 / 3ph	200	90
20	480 / 3ph	250	100
21	480 / 3ph	300	150
22	480 / 3ph	400	175
23	480 / 3ph	500	200
24	480 / 3ph	–	250

b) UL 489 Circuit Breaker

Inverter F5/F6	Input Voltage (V)	UL 489 MCCB(*) max [A]	Siemens Cat. No.
17	240 / 3ph	150 A	DG-frame, 3VL 150 UL
18	240 / 3ph	150 A	DG-frame, 3VL 150 UL
19	240 / 3ph	150 A	DG-frame, 3VL 150 UL
20	240 / 3ph	250 A	FG-frame 3VL 250 UL
21	240 / 3ph	250 A	FG-frame 3VL 250 UL
17	480 / 3ph	–	–
18	480 / 3ph	150 A	DG-frame 3VL 150 UL
19	480 / 3ph	150 A	DG-frame 3VL 150 UL
20	480 / 3ph	150 A	DG-frame 3VL 150 UL
21	480 / 3ph	150 A	DG-frame, 3VL 150 UL
22	480 / 3ph	150 A	DG-frame, 3VL 150 UL
23	480 / 3ph	250 A	FG-frame 3VL 250 UL
24	480 / 3ph	250 A	FG-frame 3VL 250 UL

Annex C

C.1 Installation of water-cooled units

In continuous operation water-cooled inverters are operated with lower temperature than air-cooled inverters. This has positive effects on lifetime-relevant components such as fan and DC link circuit capacitors and power modules (IGBT). Also the temperature dependent switching losses are positively effected. The use of water-cooled KEB COMBIVERT frequency inverters is offered in the drive technology, because there are process-caused coolants available with some applications. The following instructions must be observed absolutely when this units are used.

C.1.1 Heat sink and operating pressure

Design system	Material (voltages)	Max. operating pressure	Connecting duct
Extrusion casting heat sink	Aluminium (-1.67 V)	10 bar	0000650-G140

The heat sinks are sealed with sealing rings and posses a surface protection (anodized) even in the ducts.

	In order to avoid a deformation of the heat sink and the damages involved, the indicated max. operating pressure may not be exceeded briefly also by pressure peaks.
	Pay attention to the guidelines 97/23/EG of pressure units.

C.1.2 Materials in the cooling cicuit

For the screw connections and also for the metallic articles in the cooling circuit which are in contact with the coolant (electrolyte) a material is to be selected, which forms a small voltage difference to the heat sink in order to avoid contact corrosion and/or pitting corrosion (electro-chemical voltage series, see table 1.5.2). An aluminum screw connection or ZnNi coated steel screw connection is recommended. Other materials must be examined in each case before employment. The specific case of application must be checked by the customer in tuning of the complete cooling circuit and must be classified according to the used materials. With hoses and seals take care that halogen-free materials are used.
A liability for occuring damages by wrongly used materials and from this resulting corrosion cannot be taken over!

Table 1.5.2 Electro-chemical voltage series / standard potentials against hydrogen

Material	generated Ion	Standard potential	Material	generated Ion	Standard potential
Lithium	Li^{+}	-3.04 V	Cobald	Co^{2+}	-0.28 V
Potassium	K^{+}	-2.93 V	Nickel	Ni^{2+}	-0.25 V
Calcium	Ca^{2+}	-2.87 V	Tin	Sn^{2+}	-0.14 V
Sodium	Na^{+}	-2.71 V	Lead	Pb^{3+}	-0.13 V
Magnesium	Mg^{2+}	-2.38 V	Iron	Fe^{3+}	-0.037 V
Titan	Ti^{2+}	-1.75 V	Hydrogen	$2H^{+}$	0.00 V

Table 1.5.2 Electro-chemical voltage series / standard potentials against hydrogen					
Material	generated Ion	Standard potential	Material	generated Ion	Standard potential
Aluminium	Al^{3+}	-1.67 V	Copper	Cu^{2+}	0.34 V
Manganese	Mn^{2+}	-1.05 V	Carbon	C^{2+}	0.74 V
Zinc	Zn^{2+}	-0.76 V	Silver	Ag^{+}	0.80 V
Chrome	Cr^{3+}	-0.71 V	Platinum	Pt^{2+}	1.20 V
Iron	Fe^{2+}	-0.44 V	Gold	Au^{3+}	1.42 V
Cadmium	Cd^{2+}	-0.40 V	Gold	Au^{+}	1.69 V

C.1.3 Requirements on the coolant

The requirements on the coolant are depending on the ambient conditions, as well as from the used cooling system. General requirements on the coolant:

Standards	TrinkwV 2001, DIN EN 12502 part 1-5, DIN 50930 part 6, DVGW work sheet W216
VGB Cooling water directive	The VGB cooling water directive (VGB-R 455 P) contains instructions about common process technology of the cooling. Particulary the interactions between cooling water and components of the cooling system are described.
pH-value	Aluminum is particularly corroded by lixiviums and salts. The optimal pH value for aluminum should be in the range of 7.5… 8.0.
Abrasive substances	Abrasive substances as used in abrasive (quartz sand), clogging the cooling circuit.
Copper cuttings	Copper cuttings can attach the aluminum and this leads to a galvanic corrosion. Copper should not be used together with aluminum due to electro-chemical voltage difference.
Hard water	Cooling water may not cause scale deposits or loose excretions. It shall have a low total hardness (<20°d) especially carbon hardness.
Soft water	Soft water (<7°dH) corrodes the material.
Frost protection	An appropriate antifreeze must be used for applications when the heat sink or the coolant is exposed temperatures below zero. Use only products of one manufacturer for a better compatibility with other additives.
Corrosion protection	Additives can be used as corrosion protection. In connection with frost protection the antifreeze must have a concentration of 20…25 Vol %, in order to avoid a change of the additives.

Special requirements for open and half-open cooling systems:

Impurities	Mechanical impurities in half-open cooling systems can be counteracted when appropriate water filters are used.
Salt concentration	The salt content can increase through evaporation at half-open systems. Thus the water is more corrosive. Adding of fresh water and removing of process water works against.
Algae and myxobacteria	Algae and myxobacteria can arise caused by increased water temperature and contact with atmospheric oxygen. The algae and myxobacteria clog the filters and obstruct the water-flow. Biocide containing additives can avoid this. Especially at longer OFF periods of the cooling circuit preventive maintenance is necessary.
Organic materials	The contamination with organic materials must be kept as small as possible, because separate slime can be caused by this

Damages at the unit which are caused by clogged, corroded heat sinks or other obvious operating errors, leads to the loss of the warranty claims.

C.1.4 Connection to the cooling system

- Screw in connecting duct in accordance with the manual
- The connection to the coolant must be carried out with flexible, pressure-resistant hoses and secured with clamps.
- Pay attention to flux direction and check tightness!
- The cooling flow must always be started before starting the KEB COMBIVERT.

The connection to the cooling system can occur as closed or open cooling circuit. The connection to a closed cycle cooling circuit is recommended, because the danger of contamination of coolant is very small. Preferably also a monitoring of the pH value of the coolant should be installed.
Pay attention to a corresponding cable cross section at required equipotential bonding in order to avoid electro-chemical procedures.

C.1.5 Coolant temperature and moisture condensation

The inlet temperature may not exceed 40 °C. The maximum heat sink temperature is 60 °C or 90 °C depending on the power unit and overload capacity (see „Technical data“). To ensure a safe operation the coolant output temperature must be 10 K below this temperature.
Due to high air humidity and high temperatures it can lead to moisture condensation. Moisture condensation is dangerous for the inverter, because the inverter can be destroyed through eventual occuring short-circuits.

The user must guarantee that any moisture condensation is avoided!

In order to avoid a moisture condensation the following possibilities can be done. The application of both methods is recommended.

Supply of temper coolant

This is possible by using heatings in the cooling circuit for the control of the coolant temperature. The following dew point table is available for this:

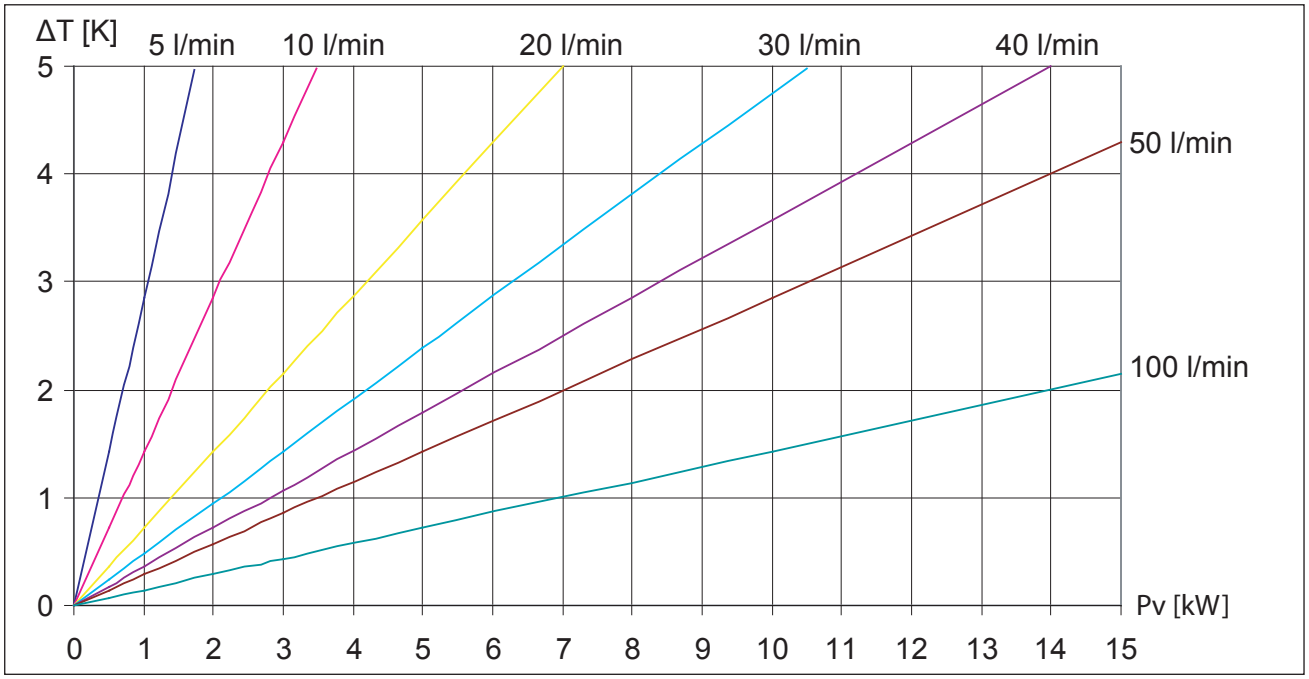
Coolant inlet temperature [°C] is depending on ambient temperature and air humidity

Air humidity [%] / Surrounding temperature [°C]	10	20	30	40	50	60	70	80	90	100
-25	-45	-40	-36	-34	-32	-30	-29	-27	-26	-25
-20	-42	-36	-32	-29	-27	-25	-24	-22	-21	-20
-15	-37	-31	-27	-24	-22	-20	-18	-16	-15	-15
-10	-34	-26	-22	-19	-17	-15	-13	-11	-11	-10
-5	-29	-22	-18	-15	-13	-11	-8	-7	-6	-5
0	-26	-19	-14	-11	-8	-6	-4	-3	-2	0
5	-23	-15	-11	-7	-5	-2	0	2	3	5
10	-19	-11	-7	-3	0	1	4	6	8	9
15	-18	-7	-3	1	4	7	9	11	13	15
20	-12	-4	1	5	9	12	14	16	18	20
25	-8	0	5	10	13	16	19	21	23	25
30	-6	3	10	14	18	21	24	26	28	30
35	-2	8	14	18	22	25	28	31	33	35
40	1	11	18	22	27	31	33	36	38	40
45	4	15	22	27	32	36	38	41	43	45
50	8	19	28	32	36	40	43	45	48	50

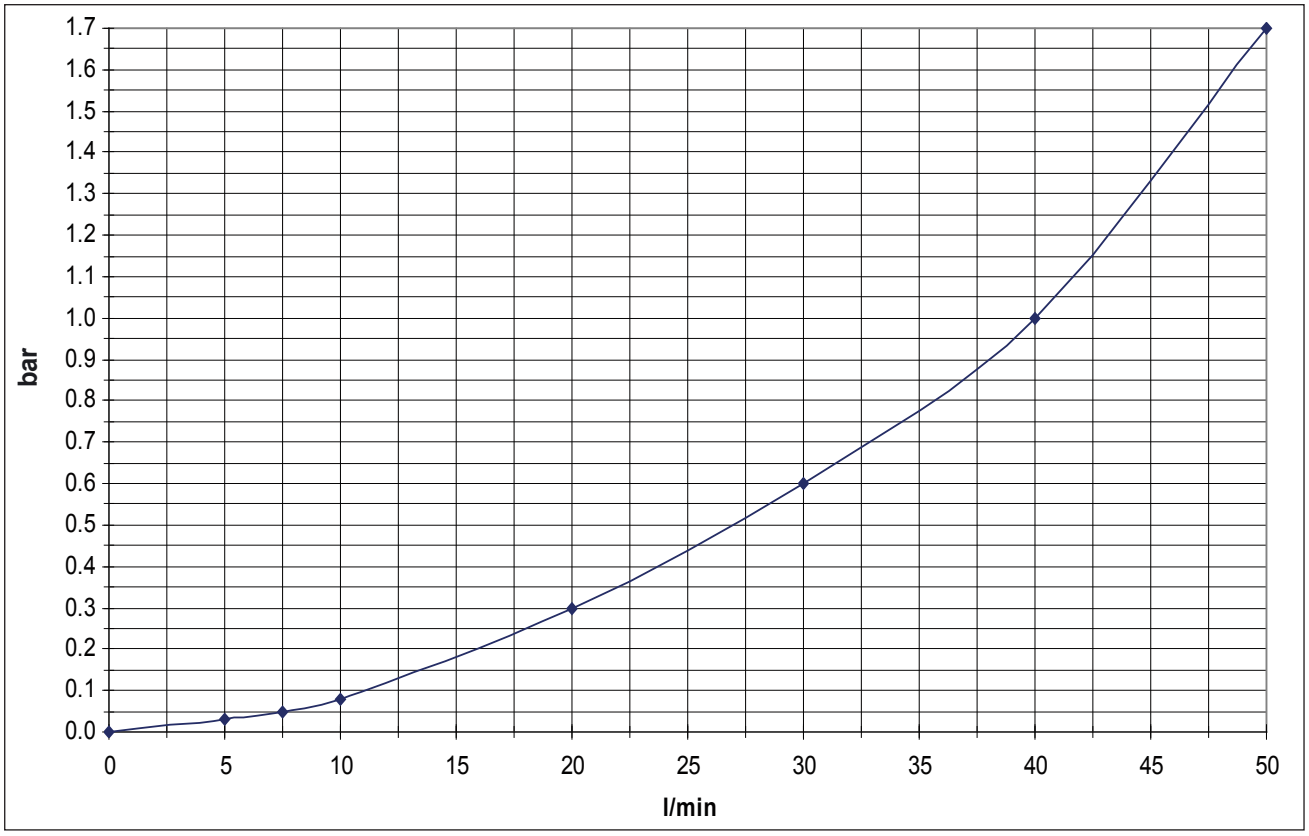
Temperature Control

The cooling system can be connected by means of pneumatic or magnetic valves. A relay is frontend. In order to avoid pressure surges, the valves for the temperature control must be inserted in the flow line of the cooling circuit. All usual valves can be used. Pay attention that the valves are faultless and do not clamp.

C.1.6 Coolant heating depending on power loss and flow rate with water



C.1.7 Typically fall of pressure depending on the rate of flow

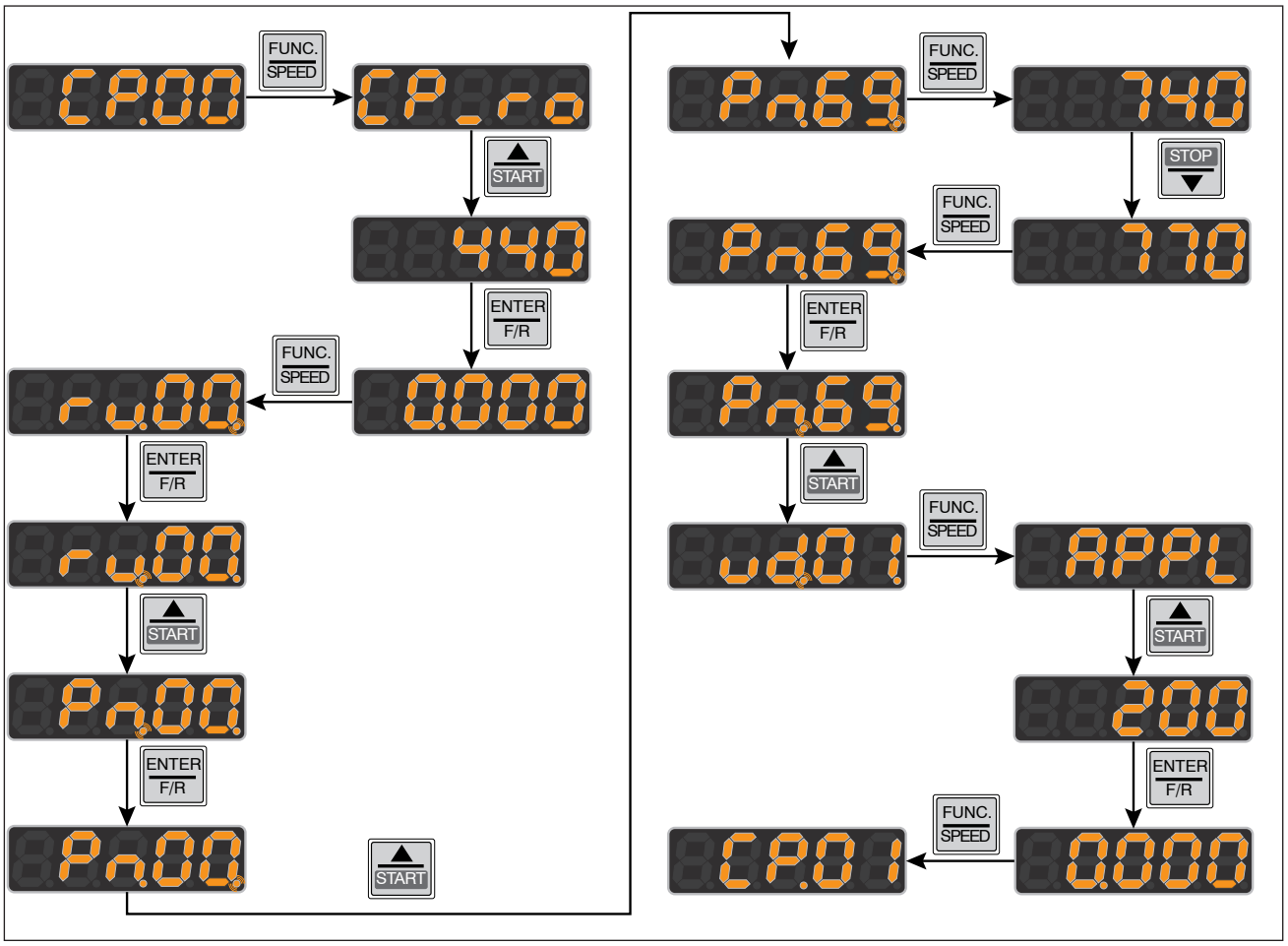


Annex D

D.1 Changing the response threshold of the braking transistor

(not valid for control type „BASIC“)

To avoid a premature switching of the brake transistor at an input rated voltage of 480 Vac, the response threshold must be controlled or adjusted according to the following graphic.



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