COMBIVERT



4.0...15kW

Translation of original manual		
Mat.No.	Rev.	
00F50EB-KE00	1E	



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1. Preface

1.1 General

First we would like to welcome you as a customer of the company Karl E. Brinkmann GmbH and congratulation to the purchase of this product. You have decided for a product on highest technical level.

The described hard- and software are developments of the Karl E. Brinkmann GmbH. The enclosed documents correspond to conditions valid at printing. Misprint, mistakes and technical changes reserved.

The instruction manual must be made available to the user. Before working with the unit the user must become familiar with it. This especially applies to the knowledge and observance of the following safety and warning indications. The pictographs used in this instruction manual have following meaning:

	warning	Is used, if life or health of the user is in danger or if substantial damage to property can occur.
--	---------	-----------------------------------------------------------------------------------------------------

observe at	Is used, if a measure is necessary for safe and trouble-free operation.
all costs	

Information Aid Tip	Is used, if a measure simplifies the handling or operation of the unit.
---------------------------	-------------------------------------------------------------------------

1.2 Safety instructions

Observe safety a		Precondition for all further steps is the knowledge and obser-
	operating instruc-	vance of the safety -, EMC- and operating instructions (Part 1
	tions	"Before Starting" 0000NEB-0000"). This instruction is provid-
	10115	ed with the unit or by download of www.keb.de.

Non-observance of the safety instructions leads to the loss of any liability claims. The safety and warning instructions specified in this manual do not lay claim on completeness. This list is not exhaustive.

1.3 Validity and liability

The use of our units in the target products is outside of our control and therefore lies exclusively in the area of responsibility of the machine manufacturer.

The information contained in the technical documentation, as well as any user-specific advice in spoken and written and through tests, are made to best of our knowledge and information about the application. However, they are considered for information only without responsibility. This also applies to any violation of industrial property rights of a third-party.

Selection of our units in view of their suitability for the intended use must be done generally by the user.

Tests can only be done within the application by the machine manufacturer. They must be repeated, even if only parts of hardware, software or the unit adjustment are modified.

Unauthorised opening and tampering may lead to bodily injury and property damage and may entail the loss of warranty rights. Original spare parts and authorized accessories by the manufacturer serve as security. The use of other parts excludes liability for the consequences arising out of.

The suspension of liability is especially valid also for operation interruption loss, loss of profit, data loss or other damages. This is also valid, if we referred first to the possibility of such damages.

If single regulations should be or become void, invalid or impracticable, the effectivity of all other regulations or agreements is not affected.

1.4 Copyright

The customer may use the instruction manual as well as further documents or parts from it for internal purposes. Copyrights are with KEB and remain valid in its entirety. All rights reserved.

KEB®, COMBIVERT®, KEB COMBICONTROL® and COMBIVIS® are registered trademarks of Karl E. Brinkmann GmbH.

Other wordmarks or/and logos are trademarks (TM) or registered trademarks (®) of their respective owners and are listed in the footnote on the first occurrence. When creating our documents we pay attention with the utmost care to the rights of third parties. Should we have not marked a trademark or breach a copyright, please inform us in order to have the possibility of remedy.

1.5 Specified application

The KEB COMBIVERT serves exclusively for stepless open loop / closed-loop speed control of three-phase a.c. motors.



The operation of other electric consumers is prohibited and can lead to the destruction of the unit.

The used semiconductors and components of KEB are developed and dimensioned for the use in industrial products. If the KEB COMBIVERT is used in machines, which work under exceptional conditions or if essential functions, life-supporting measures or an extraordinary safety step must be fulfilled, the necessary reliability and security must be ensured by the machine builder. The operation of the KEB COMBIVERT outside the indicated limit values of the technical data leads to the loss of any liability claims.

Units with safety function are limited to a service life of 20 years. The units must be changed after this time.

1.6 Product description

This instruction manual describes the power circuits of the following units:

Unit type:	Frequency inverter
Series:	COMBIVERT F5/F6
Power range:	5.57.5 kW / 230 V class
	4.015kW / 400 V class
Housing size:	E
Version:	air and water-cooled

Features of the power circuits:

- · only slight switching losses due to IGBT
- low noise development due to high switching frequency
- extensive safety device for current, voltage and temperature
- voltage and current monitoring in static and dynamic operation
- · conditionally short circuit proof and earth-fault proof
- hardware current limit
- integrated cooling fan

1.7 Unit identification

15 F5 K 1 E-3 5 0 A

E -3 5 0 A						
	Cooling					
	0, 5, A, F Heat sink (standard)					
	1, B, G Flat rear					
	2, C, H Water cooling					
	3, D, I Convection					
	Encoder interface					
	0:none					
	Switching frequency; short time current limit; overcurrent limit					
	0 2 kHz; 125%; 150% 5 4 kHz; 150%; 180% A 8 kHz; 180%; 216% F 16 kHz; 200%; 240%					
	1 4 kHz; 125 %; 150 % 6 8 kHz; 150 %; 180 % B 16 kHz; 180 %; 216 % G 2 kHz; 400 %; 480 %					
	2 8kHz; 125%; 150% 7 16kHz; 150%; 180% C 2kHz; 200%; 240% H 4kHz; 400%; 480%					
	3 16kHz; 125%; 150% 8 2kHz; 180%; 216% D 4kHz; 200%; 240% I 8kHz; 400%; 480% 4 2kHz; 150%; 180% 9 4kHz; 180%; 216% F 8kHz; 200%; 240% K 16kHz; 400%; 480%					
	4 2 kHz; 150 %; 180 % 9 4 kHz; 180 %; 216 % E 8 kHz; 200 %; 240 % K 16 kHz; 400 %; 480 %					
	Input identification					
	0 1ph 230 VAC/DC 5 400 V class DC A 6ph 400 VAC					
	1 3ph 230 VAC/DC 6 1ph 230 VAC B 3ph 600 VAC					
	2 1/3ph 230 VAC/DC 7 3ph 230 VAC C 6ph 600 VAC					
	3 3ph 400 VAC/DC 8 1/3ph 230 VAC D 600 VDC					
	4 230 V class DC 9 3ph 400 VAC					
	Housing type A, B, D, E, G, H, R, U, W, P					
	Accessories (AD with safety relay)					
	0, A none					
	1, B Braking transistor					
	2, C integrated filter					
	3, D Braking transistor and integrated filter					
	Control type					
	A APPLICATION K like A with safety technology					
	B BASIC (controlled frequency inverter) ¹⁾					
	C COMPACT (controlled frequency inverter)					
	E SCL P like E with safety technology					
	G GENERAL (controlled frequency inverter)					
	H ASCL L like H with safety technology					
	M MULTI (regulated, field-oriented frequency inverter for three-phase asynchronous motors)					

S SERVO (regulated frequency inverter for synchronous motors)

Series F5/F6

Inverter size

1) Devices with control type "BASIC" are subject to export authorisation according to entry 3A225 Annex I of the Dual-Use Regulation.

For more information, see "Technical Data".

1.8 Installation instructions

1.8.1 Cooling systems

The KEB COMBIVERT F5/F6 is available for different cooling systems:

Heat sink with cooling fan (mounted version)

The standard version is delivered with heat sink and cooling fan.

Special versions

The dissipation of power loss must be guaranteed by the machine builder.

Flat rear

There is no heat sink at this version. The unit must be mounted on an appropriate ground for heat dissipation.

Water cooling

This version is dimensioned for the connection to an available cooling system. The dissipation of the power loss must be ensured by the machine builder. In order to avoid moisture condensation, the minimum inlet temperature may not decrease the ambient temperature. The max. inlet temperature may not exceed 40°C. No aggressive coolant shall be used. Measures against contamination and calcination must be done externally. We recommend a pressure of 4 bar on the cooling system.

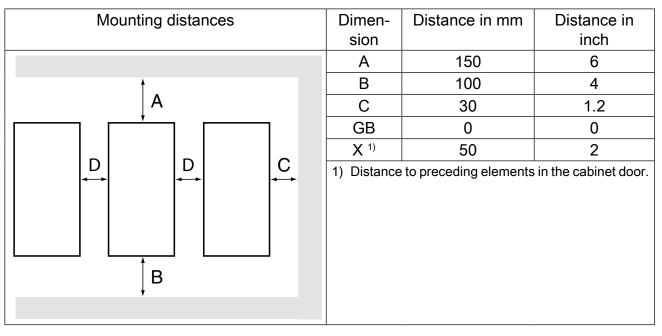
Convection (trough-mount version)

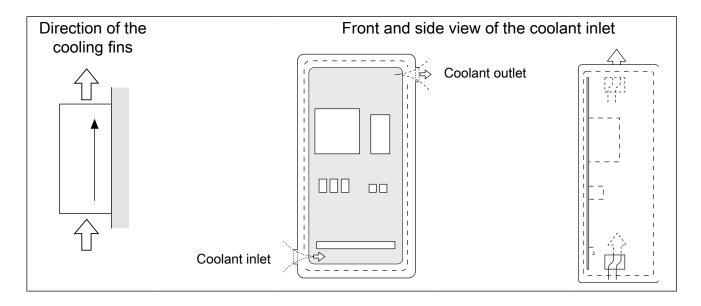
In this version the heat sink is placed externally with a cutout in the control cabinet.



Heat sinks can reach temperatures, which can cause burns when touching. If in case of structural measures a direct contact cannot be avoided, a warning notice "hot surface" must be mounted at the machine.

1.8.2 Control cabinet installation





See annex C for instructions of water-cooled units.

1.9 Safety and operating instructions



Safety and operating instructions for drive converter (in accordance with: Low-Voltage Directive 2006/95/EC)

1. General

In operation, drive converter depending on their degree of protection, may have live, uninsulated and possibly also moving or rotating parts, as well as hot surfaces.

In case of inadmissible removal of the required covers, of improper use, wrong installation or maloperation, there is the danger of serious personal injury and damage to property.

For further information, see documentation.

All operations serving transport, installation and commissioning as well as maintenance are to be carried out by skilled technical personnel (Observe IEC 364 or CENEL-EC HD 384 or DIN VDE 0100 and IEC 664 or DIN/VDE 0110 and national accident prevention rules!).

For the purposes of these basic safety instructions, "skilled technical personnel" means persons who are familiar with the installation, mounting, commissioning and operation of the product and have the qualifications needed for the performance of their functions.

2. Specified application

Drive converter are components which are intended for the installation in electric systems or machines.

In case of installation in machinery, commissioning of the drive converter (i.e. the starting of normal operation) is prohibited until the machinery has been proved to conform to the provisions of the directive 2006/42/EC (Machinery Safety Directive - MSD). Account is to be taken of EN 60204.

The drive converter meet the requirements of the Low-Voltage directive 2006/95/EC. They are subject to the harmonized standards of the series EN61800-5-1.

The technical data as well as information concerning the supply conditions shall be taken from the rating plate and from the documentation and shall be strictly observed.

3. Transport, storage

The instructions for transport, storage and proper use shall be complied with.

The climatic conditions shall be in conformity with EN 61800-5-1.

4. Installation

The installation and cooling of the appliances shall be in accordance with the specifications in the pertinent documentation.

The drive converter shall be protected against excessive strains. In particular, no components must be bent or isolating distances altered in the course of transportation or handling. No contact shall be made with electronic components and contacts. Drive converter contain electrostatic sensitive components which are liable to damage through improper use. Electric components must not be mechanically damaged or destroyed (potential health risks).

5. Electrical connection

When working on live drive converter, the applicable national accident prevention rules (e.g. VBG 4) must be complied with.

The electrical installation shall be carried out in accordance with the relevant requirements (e.g. cross-sectional areas of conductors, fusing, PE connection). For further information, see documentation.

Instructions for the installation in accordance with EMC requirements, like screening, earthing, location of filters and wiring, are contained in the drive converter documentation. They must always be complied with, also for drive converter bearing a CE marking. Observance of the limit values required by EMC law is the responsibility of the manufacturer of the installation or machine.

6. Operation

Installations which include drive converter shall be equipped with additional control and protective devices in accordance with the relevant applicable safety requirements, e.g. act respecting technical equipment, accident prevention rules etc.. Changes to the drive converter by means of the operating software are admissible.

After disconnection of the drive converter from the voltage supply, live appliance parts and power terminals must not be touched immediately because of possibly energized capacitors. In this respect, the corresponding signs and markings on the drive converter must be observed.

During operation, all covers and doors shall be kept closed. **7. Maintenance**

The manufacturer's documentation shall be followed. KEEP SAFETY INSTRUCTIONS IN A SAFE PLACE!

2. Technical Data

2.1 Operating conditions

	EN 61800-2	class	
			Inverter product standard: rated specifications
	EN61800-5-1		Inverter product standard: general safety
	2110100001		max. 2000 m above sea level
Site altitude			(over 1000 m a derating of 1% per 100 m must be take
			into consideration) ⁴⁾
s during oper	ation		
Temperature		3K3	extended to -1045 °C (use frost protection for water
•			cooling systems and temperatures below zero)
Humidity	EN60721-3-3		585% (without condensation)
	2110012100		
	-		
		3S2	
	sport	01/0	
	-		Drain heat sink completely
	-		(without condensation)
	EN 60721-3-2		may 100 m/a ² ; 11 ma
	-		max. 100 m/s ² ; 11 ms
	-		
	200	232	
	age	164	Drain heat sink completely
	-		(without condensation)
	-		
	EN60721-3-1		max. 100 m/s²; 11 ms
	-		
	-		
	EN 60529		
		-	Pollution degree 2
	EN61800-3		Inverter product standard: EMC
erence			
	_	C2 ¹⁾²⁾	earlier limit value A (B optional) according to EN5501
interferences	—	C2 ²⁾	earlier limit value according to EN55011
			AD (air discharge) and CD (contact discharge)
	EN61000-4-4	2kV	
			Phase-phase / phase-ground
	EN61000-4-3	10 V/m	
	EN61000-4-6	10 V	0.15-80MHz
by high frequency lields			
Voltage variation / EN 61		3	+10%-15%
voltage drop			90%
Voltage unsymmetries /		3	3%
ency changes			2%
	Humidity Vibration Gas Solids s during trans Temperature Humidity Vibration Surge Gas Solids s for the stora Temperature Humidity Vibration Surge Gas Solids Solids Solids	Humidity EN 60721-3-3 Gas Solids Solids EN 60721-3-3 s during transport EN 60721-3-2 Temperature Humidity Vibration EN 60721-3-2 Surge Gas Solids EN 60721-3-2 Surge Gas Solids EN 60721-3-2 Solids EN 60721-3-1 Surge Gas Solids EN 60721-3-1 Surge Gas Solids EN 60721-3-1 Gas Solids Solids EN 60721-3-1 Gas EN 60721-3-1 Gas Solids Solids EN 60721-3-1 Gas EN 60721-3-1 Gas EN 60721-3-1 Solids EN 61000-3 erence interferences interferences - interfaces EN 61000-4-2 wer interfaces EN 61000-4-4 wer interfaces EN 61000-4-5 nagnetic fields EN 61000-4-6 age variation / voltage drop	Humidity VibrationEN 60721-3-3 $3K3$ Solids3C23M1Gas3C2solids3S2s during transport2K3Temperature Humidity2K3Vibration Surge2K3Gas2C2Solids2S2s for the storage2K3Temperature Humidity1K4Humidity1K3Vibration Surge1K4Humidity1K3Vibration Surge1K4Humidity1K3Vibration Surge1K4Humidity1K3Vibration Surge1K4Humidity1K3Vibration Surge1K2EN 60721-3-11M1M11C2Solids1S2EN 60529IP20IEC 664-1EN 61800-3interferences-C2 $^{1)2}$ interferences-C2 $^{2)}$ nitytic dischargesEN 61000-4-2wer interfacesEN 61000-4-4wer interfacesEN 61000-4-4wer interfacesEN 61000-4-3wer interfacesEN 61000-4-3unces, induced equency fieldsEN 61000-4-6age variation / voltage dropEN 61000-2-1asymmetries / EN 61000-2-43

2)	The specified value is only meet in connection with a corresponding filter.
3)	Depending on the operating conditions and corresponding power reduction, higher temperatures are permissible after consulting KEB.
4)	There is no "safe isolation" of the control above 2000 m.



2.2 Technical data of the 230V class

Inverter size			13	14	
Housing size	E	E			
Phases			3 3		
Output rated power	9.5	13			
Max. rated motor power		[kW]	5.5	7.5	
Output rated current		[A]	24	33	
Max. short time current	1)	[A]	36	49.5	
OC-tripping current		[A]	43	59	
Input rated current		[A]	31	43	
Max. permissible main fuse gG	5)	[A]	35	50	
Rated switching frequency		[kHz]	8	4	
Max. switching frequency	10)	[kHz]	16	16	
Power dissipation at nominal operating		[W]	290	350	
Power dissipation at DC operating		[W]	365	300	
Standstill current at 4 kHz	2)	[A]	24	33	
Standstill current at 8 kHz	2)	[A]	24	24	
Standstill current at 16 kHz	2)	[A]	16.8	16.8	
Min. frequency at continuous full load		[Hz]	6	6	
Max. heat sink temperature			90°C (194°F)		
Motor cable cross-section	3)	[mm²]	6	10	
Min. braking resistor	4)	[Ω]	16	16	
Max. braking current	4)	[A]	25	25	
Overload characteristic			(see annex A)		
Input rated voltage		[V]	230 (UL: 240)		
Input voltage range Uin		[V]	180260 ±0		
Input voltage at DC operation		[V]	250370 ±0		
Mains frequency		[Hz]	50 / 60 ±2		
permitted mains forms			TN, TT, IT ⁶), Δ-mains ⁷⁾		
Output voltage	8)	[V]	3 x 0Uin		
Output frequency	9)	[Hz]	0400		
Max. motor line length shielded		[m]	100		
Cooling mode (L=air; W=water)			L	L	

1) With regulated systems 5% are to be subtracted as overmodulation capacity

2) Max. current before the OL2 function triggers (not at F5 in operating mode v/f)

3) Recommended minimum cross section of the motor line for rated power and a cable length of upto 100 m (CU)

4) This data is only valid for units with internal braking transistor (see "Unit identification")

5) Protection in accordance with UL see annex B

6) IT system optional

7) Phase conductor grounded mains are only permissible without HF filters

8) The voltage at the motor is dependent on the series-connected units and on the control method (see A.3)

9) The real output frequency is depending of the parameterisation. The output frequency is to be limited in such way that 1/10 of the switching frequency is not exceeded. Output frequencies above 599 Hz are possible by changing the operating mode at control type "BASIC" (xxF5Bxx-xxxx) as well as for special devices on request. This devices are subject to export authorisation according to entry 3A225 Annex I of the Dual-Use Regulation and they are labeled accordingly on the delivery note. The output frequency is limited to max. 599 Hz for all other control types. This devices are not subject to export authorisation.

10) With F6-K control board only 8 kHz.



The technical data are for 2/4-pole standard motors. With other pole numbers the inverter must be dimensioned onto the motor rated current. Contact KEB for special or medium frequency motors.

2.3 Technical data of the 400 V class

		12	13	14	15	16
		Е	E	Е	E	E
		3	3	3	3	3
	[kVA]	6.6	8.3	11	17	23
	[kW]	4.0	5.5	7.5	11	15
	[A]	9.5	12	16.5	24	33
1)	[A]	17	21.6	29.7	36	49.5
	[A]	21	25.9	35.6	43	59
	[A]	13	17	23	31	43
7)	[A]	20	25	25	35	50
	[kHz]	16	16	8	4	2
12)	[kHz]	16	16	16	16	16 ⁶⁾
	[W]	300	250	320	350	330
	[W]	285	230	295	310	275
2)	[A]	9.5	12	16.5	24	27
2)	[A]	9.5	12	16.5	16	16.5
2)	[A]	9.5	12	10	10	10
	[Hz]	6	6	6	6	6
			90	°C (194	°F)	
3)	[mm ²]	2.5	4	1	6	10
4)	[Ω]			25		
4)	[A]	21 21 32			32	
			(se	e annex	(A)	
5)	[V]					
	[V]	305528 ±0				
	[V]	420746 ±0				
	[Hz]	50 / 60 ±2				
		TN, TT, IT ⁸⁾ , Δ mains ⁹⁾				
10)	[V]	3 x 0Uin				
11)	[Hz]	0 - max. 599				
	[m]	100				
		L	L	L	L W	L W
		_	-	_	_	_
	7) 12) 2) 2) 2) 3) 4) 4) 5) 10)	[kW] [A] 1) [A] [KHz] 12) [kHz] [W] [W] 2) [A] 2) [A] 2) [A] 2) [A] 2) [A] 2) [A] 3) [mm²] 4) [Q] 4) [A] 5) [V] [V] [V] [Hz] [Hz] 10) [V] 11) [Hz]	E 3 [kVA] 6.6 [kW] 4.0 [A] 9.5 1) [A] 17 [A] 21 [A] 13 7) [A] 20 [kHz] 16 12) [kHz] 16 12) [kHz] 16 12) [kHz] 16 12) [kHz] 16 20 [A] 9.5 2) [A] 9.5 4) [Q] [Q] 4) [A] [Q] [V] [V] [V] [V] [V] [V] [V] [V] [V] [U] [V]	EE33[kVA]6.68.3[kW]4.05.5[A]9.5121)[A]1721.6[A]2125.9[A]13177)[A]2025[kHz]161612)[kHz]161612)[kHz]161612)[kHz]16162)[A]9.5122)[A]9.5122)[A]9.5122)[A]9.5122)[A]9.5122)[A]9.5122)[A]9.5124)[Q]394)[A]21(See5)[V]400[V]30[V]42[Hz]5510)[V]311)[Hz]0[m][m]1	E E E 3 3 3 [kVA] 6.6 8.3 11 [kW] 4.0 5.5 7.5 [A] 9.5 12 16.5 1) [A] 17 21.6 29.7 [A] 21 25.9 35.6 [A] 13 17 23 7) [A] 20 25 25 [kHz] 16 16 8 12) [kHz] 16 16 16 [W] 300 250 320 [W] 285 230 295 2) [A] 9.5 12 16.5 2) [A] 9.5 12 10 [Hz] 6 6 6 90°C (194 3) [mm²] 2.5 4 4) [Ω] 39 4) [A] 21 (see annex 5) [V]	$\begin{array}{c c c c c c c c c c c c c c c c c c c $

1) With regulated systems 5% are to be subtracted as overmodulation capacity

2) Max. current before the OL2 function triggers (not at F5 in operating mode v/f)

3) Recommended minimum cross section of the motor line for rated power and a cable length of upto 100 m (copper)

4) This data is only valid for units with internal brake transistor GTR 7 (see "Unit identification")

5) At rated voltages \geq 460 V multiply the rated current with factor 0.86

6) With BASIC control board only 2 kHz, with COMPACT 8 kHz

7) Protection in accordance with UL see annex B

8) Restrictions when using HF filters

9) Phase conductor grounded mains are only permissible without HF filters

10) The voltage at the motor is dependent on the series-connected units and on the control method (see A.3)

11) The real output frequency is depending on the parameterisation. The output frequency is to be limited in such way that 1/10 of the switching frequency is not exceeded. Output frequencies above 599 Hz are possible by changing the operating mode at control type "BASIC" (xxF5Bxx-xxxx) as well as for special devices on request. This devices are subject to export authorisation according to entry 3A225 Annex I of the Dual-Use Regulation and they are labeled accordingly on the delivery note. The output frequency is limited to max. 599 Hz for all other control types. This devices are not subject to export authorisation.

12) With F6-K control board only 8 kHz.

The technical data are for 2/4-pole standard motors. With other pole numbers the inverter must be dimensioned onto the motor rated current. Contact KEB for special or medium frequency motors.



No braking resistor may be connected for control type "Basic" at an input rated voltage of 480 Vac. The response threshold of the braking transistsor (Pn.69) for all other controls without safety technology (A, E, G, H, M) must be adjusted at least to 770 Vdc (see annex D).

2.4 DC supply

2.4.1 Calculation of the DC input current

The **DC input current** of the inverter is basically determined by the used motor. The data can be taken from the motor name plate.

230V class :

$$I_{DC} = \frac{\sqrt{3} \cdot \text{rated motor voltage} \cdot \text{rated motor current} \cdot \text{Motor } \cos \varphi}{\text{DC voltage } (310 \text{ V})}$$

00V class :
 $\sqrt{3} \cdot \text{rated motor voltage} \cdot \text{rated motor current} \cdot \text{Motor } \cos \varphi$

4

I_{DC}=

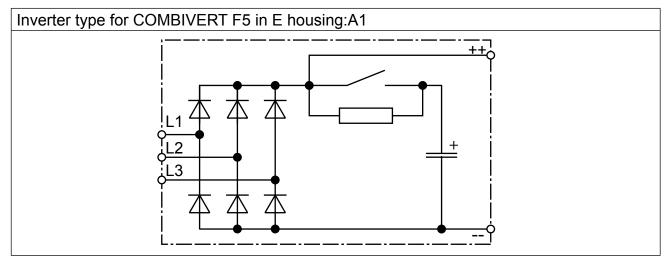
• rated motor current • wotor cosy

The **DC input peak current** is determined by the operating range.

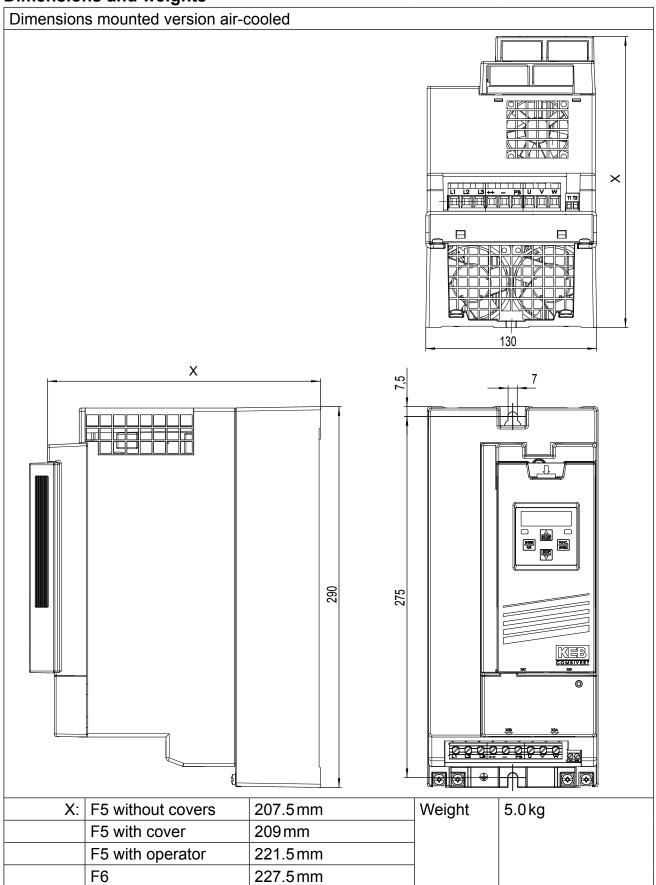
- · If you accelerate on the hardware current limit, the short-time current limit of the inverter must be used in the formula above (instead of the rated motor current).
- If the motor in normal operation is never stressed with rated torque, it can be calculated with the real motor current.

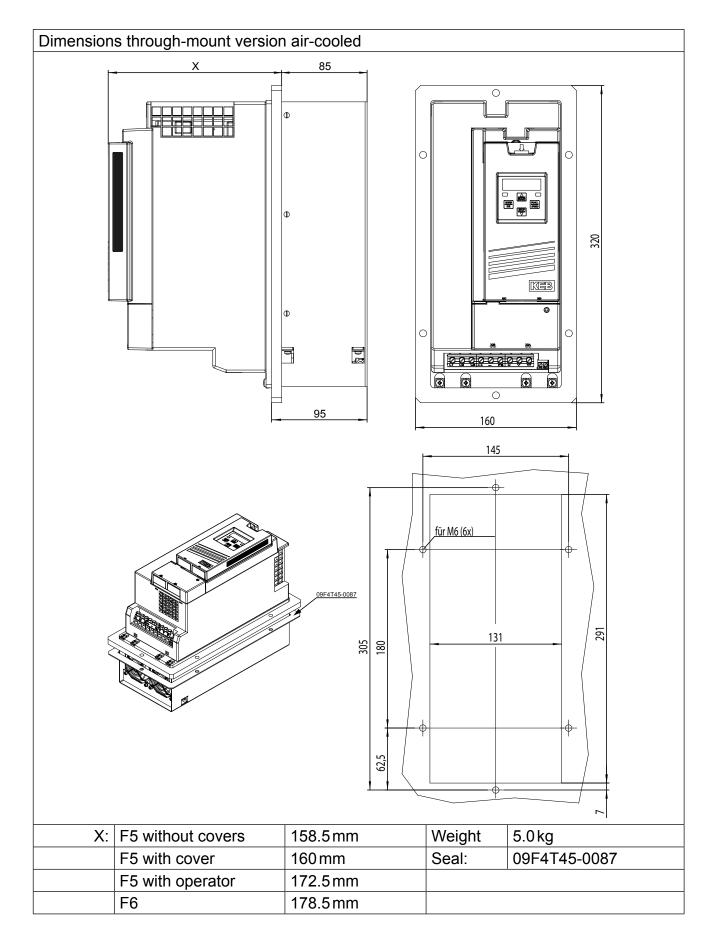
2.4.2 Internal input circuit

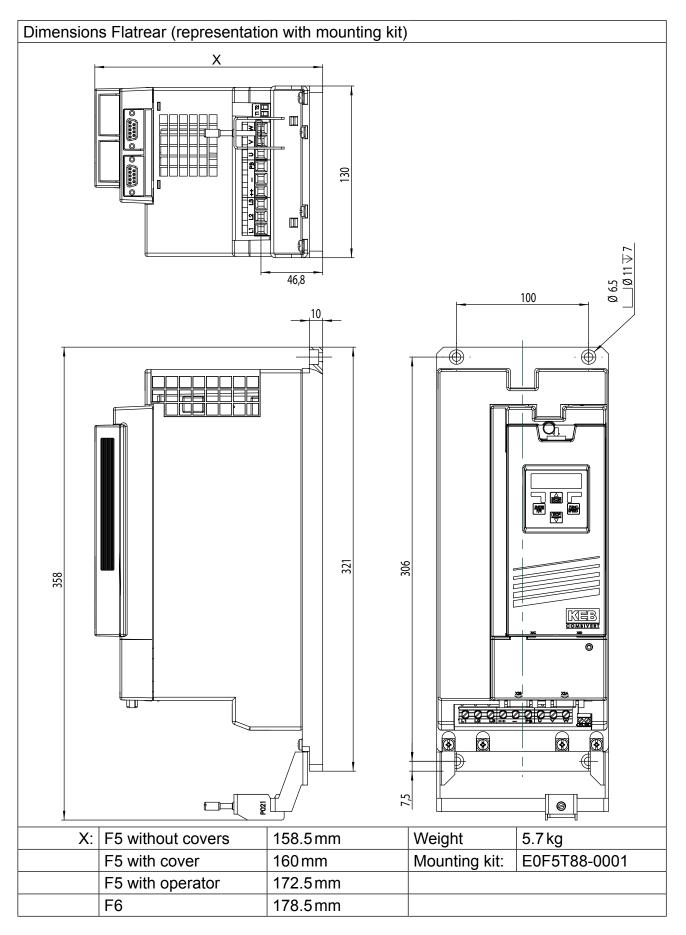
The COMBIVERT F5/F6 in E housing corresponds to the inverter type A1. Pay attention to the inverter type in DC interconnection and in operation at regenerative units.

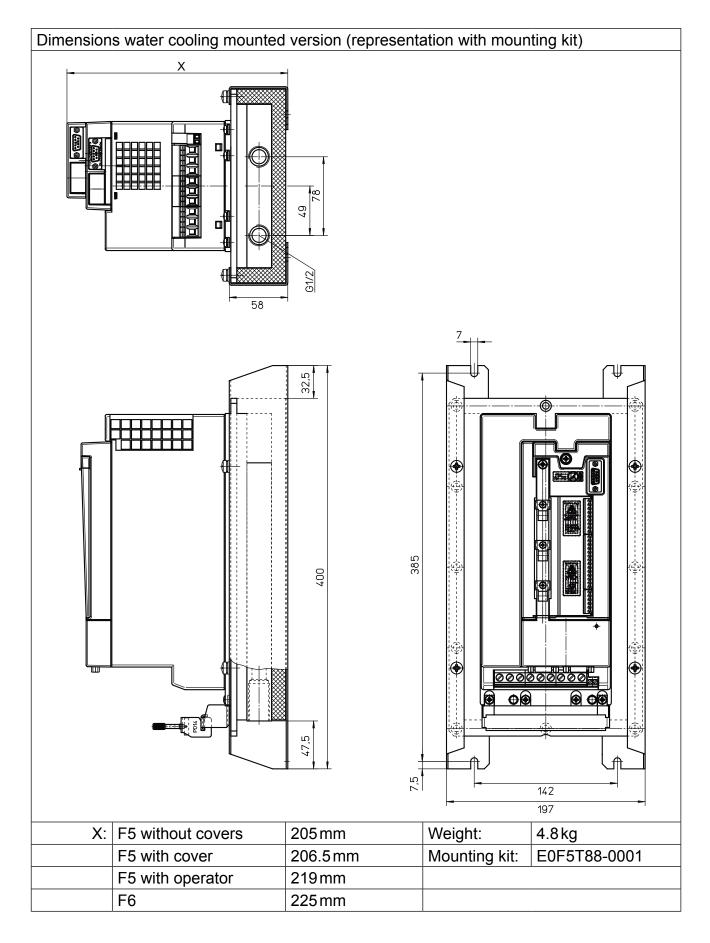


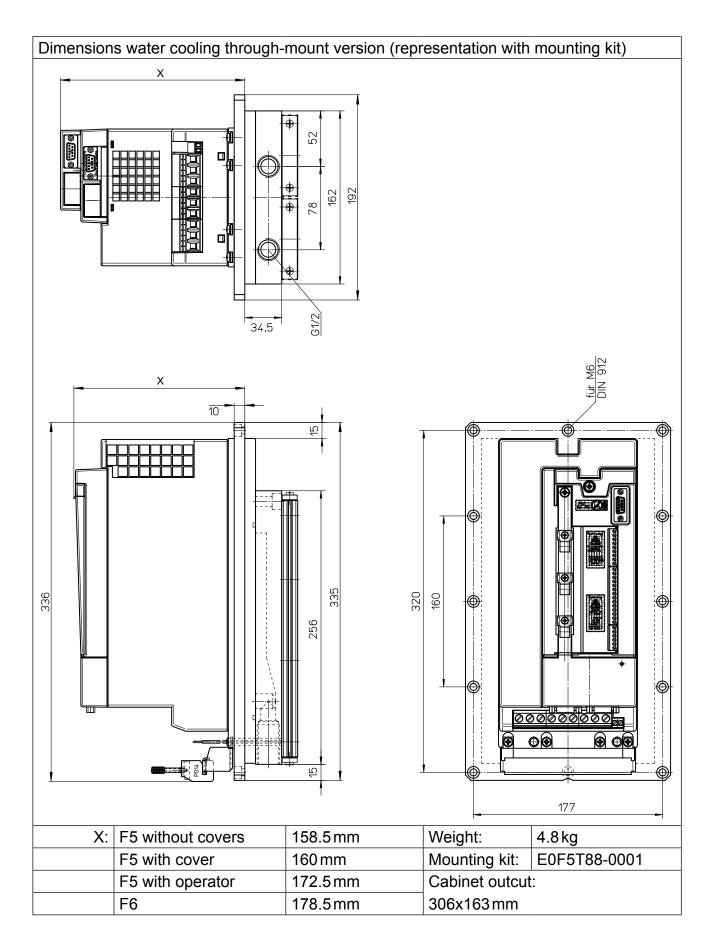
2.5 Dimensions and weights

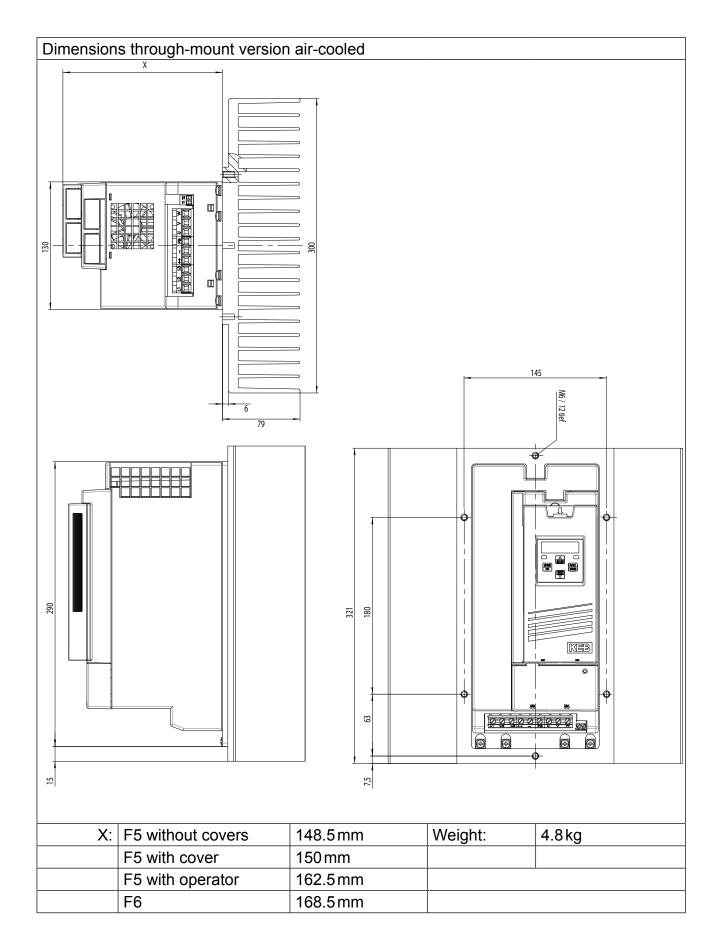












2.6 Terminal strips of the power circuit



Observe input voltage, since 230 V and 400 V class possible

All terminal strips following the requirements of the EN 60947-7-1 (IEC 60947-7-1)

Housing size 12/13/14.E.400 V	Name	Function	Cable cross-section	ons
			Terminals I	No.
	L1, N		ins connection	
	L1, L2, L3	3-phase ma	ins connection	
	U, V, W	Motor conne	ection	
	++, PB	Connection	for braking resistor	
	++,	Connection	for braking module,	1
		regenerative	e- and supply unit or as	•
		DC voltage		
		250370V	DC (230V class)	
			DC (400 V class)	
	T1, T2	Connection	for temperature sensor	2
	PE, 🕀	Connection	for shielding / earthing	3

Housing size 13/14.E.200 V and	Name	Function	Cable cross-sections
15/16.E.400V			Terminals No.
	L1, L2, L3	3-phase ma	ins connection
	U, V, W	Motor conne	ection
	++, PB		for braking resistor
	++,	Connection	for braking module,
		regenerative	e- and supply unit or as
		DC voltage	input
		250370 V	DC (230V class)
		420720 V	DC (400 V class)
	T1, T2	Connection	for temperature sensor 2
	PE, 🕀	Connection for	shielding /earthing 3

2.6.1 Permissible cable cross-sections and tightening torques of the terminals

	permissib	le cross-section	Tightenir	ng torque			
		fer	rule				
	mm²		AV	VG	Nm	lb inch	
No.	min	max	min	max	INITI		
1	0.25	4	24	10	1.5	5	
2	0.25	1.5	26	14	1.5	5	
3		Screw M4 for	1.3	11			
4	2.5	10	22	8	1.3	11	

2.7 Accessories

2.7.1 Filter and chokes

Voltage class	Inverter	Filter	Mains choke 50 Hz	Motor choke 100 Hz	
	size		(4 % Uk)	(4 % Uk)	
	13	15E5T60-1001	15Z1B03-1000	15Z1F04-1010	
230 V	10	16E6T60-3000	102 1000-1000	13211 04-1010	
200 V	14	16E5T60-1001	16Z1B03-1000	16Z1F04-1010	
	17	16E6T60-3000	1021003-1000	10211 04-1010	
Voltage class	Inverter	Filter	Mains choke 50 Hz	Motor choke 100 Hz	
_	size		(4 % Uk)	(4 % Uk)	
	12		12Z1B04-1000	12Z1F04-1010	
	12	12E6T60-3000	1221004-1000	1221104-1010	
	13	14E4T60-1001	13Z1B04-1000	13Z1F04-1010	
	15	14E6T60-3000	1321004-1000	1321104-1010	
400 V	14	14E4T60-1001	14Z1B04-1000	14Z1F04-1010	
400 V	14	14E6T60-3000	1421004-1000	1421104-1010	
	15	15E4T60-1001	15Z1B04-1000	15Z1F04-1010	
	15	16E6T60-3000	1021004-1000	1521104-1010	
	16	16E5T60-1001	16Z1B04-1000	16Z1F04-1010	
	10	16E6T60-3000	1021004-1000	102104-1010	

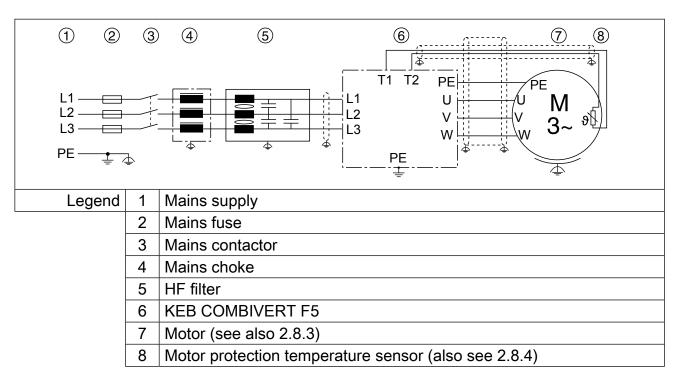
2.8 Connection Power Unit

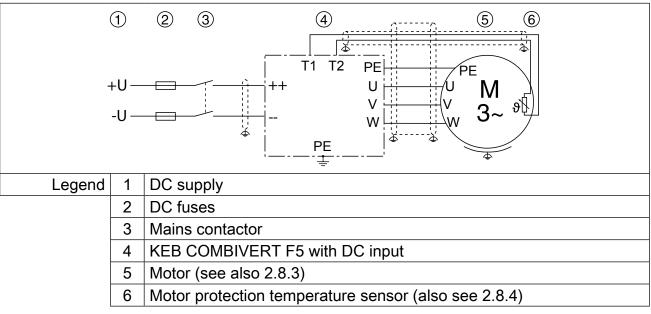
2.8.1 Mains and motor connection

Absolutely pay attention to the supply voltage of the KEB COMBIVERT. A 230 V unit at 400 V mains is destroyed immediately.

Exchanging mains and motor connection leads to immediate destruction of the unit.

Pay attention to the supply voltage and the correct polarity of the motor!





Connection Power Unit

2.8.2 Selection of the motor cable

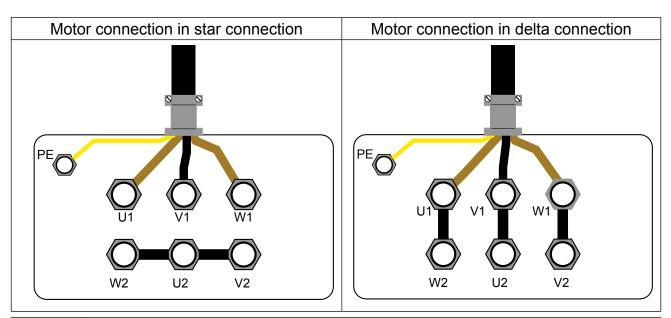
The correct selection and wiring of the motor cable is very important:

- lower abrasion of the motor bearings by leakage currents
- improved EMC characteristics
- · lower symmetrical operating capacities
- less losses by transient currents

2.8.3 Connection of the motor

As a standard the connection of the motor must be carried out in accordance with the following table:

Connection of the motor						
230/400	V motor	400/690	√ motor			
230 V	400 V	400 V	690 V			
Delta	Star	Delta	Star			





The connecting-up instructions of the motor manufacturer are generally valid!

Protect motor against voltage peaks!	Inverters switch with dv/dt of approx. 5kV/µs at the output. Voltage peaks at the motor which endanger the insulation system can occur especially in case of long motor lines (> 15m). A motor choke, a dv/dt-filter or sine-wave filter can be used
	for protection of the motor.

2.8.3.1 Motor cable length for parallel operation of motors The resulting motor cable length for parallel operation of motors, or parallel installation with multiple cables arises from the following formula:

resulting motor cable length = \sum single line length x $\sqrt{Anumber of motor lines}$

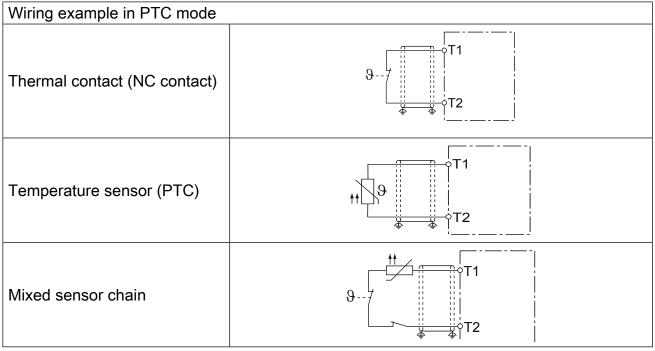
2.8.4 Temperature detection T1, T2

In.17	Function of T1,	Pn.72	Resistance	Display ru.46	Error/Warn-
	T2	(dr33)		(F6 => ru28)	ing 1)
			< 750 Ω	T1-T2 closed	_
F v/h	PTC (in accord-	4	0.75…1.65kΩ (reset resistance)	undefined	_
5xh	ance with DIN EN 60947-8)		1.654 kΩ (tripping resistance)	undefined	x
			>4kΩ	T1-T2 open	х
1)	1) The column is valid at factory setting. The function must be programmed accordingly with parameters Pn.12, Pn.13, Pn.62 and Pn.72 for F5 in operating mode GENERAL.				



Do not lay PTC cable of the motor (also shielded) together with control cable !
PTC cable inside the motor cable only permissible with double shielding !

2.8.4.1 Use of the temperature input



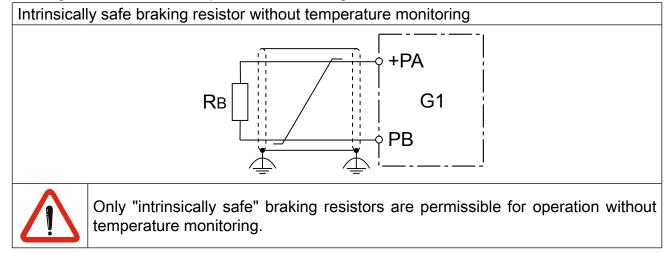
The function can be switched off with Pn.12="7" (CP.28) if no evaluation of the input is desired (standard in operating mode GENERAL). Alternatively a bridge can be installed between T1 and T2.

Connection Power Unit

2.8.5 Connection of a braking resistor

	Braking resistors dissipate the produced energy of the motor into heat during generatoric operation. Thus braking resistors can cause very high surface temperatures. During assembly pay attention to appropriate protection against contact and fire.
1	The use of a regenerative unit is reasonable for applications which produce a lot of regenerative energy. Regeneration of excess energy into the mains.
4	The mains voltage must always be switched off in order to guarantee fire protec- tion in case of a defective braking transistor.
4	The frequency inverter remains in operation in spite of switched off power supply in generatoric operation. An error must be released by external wiring which switches the modulation off in the inverter. This can occur e.g. at terminals T1/T2 or via digital input. The frequency inverter must be programmed accordingly in each case.
4	No braking resistor may be connected for control type "Basic" at an input rated voltage of 480 Vac. The response threshold of the braking transistsor (Pn.69) for all other controls without safety technology (A, E, G, H, M) must be adjusted at least to 770 Vdc (see annex D).

2.8.5.1 Braking resistor without temperature monitoring

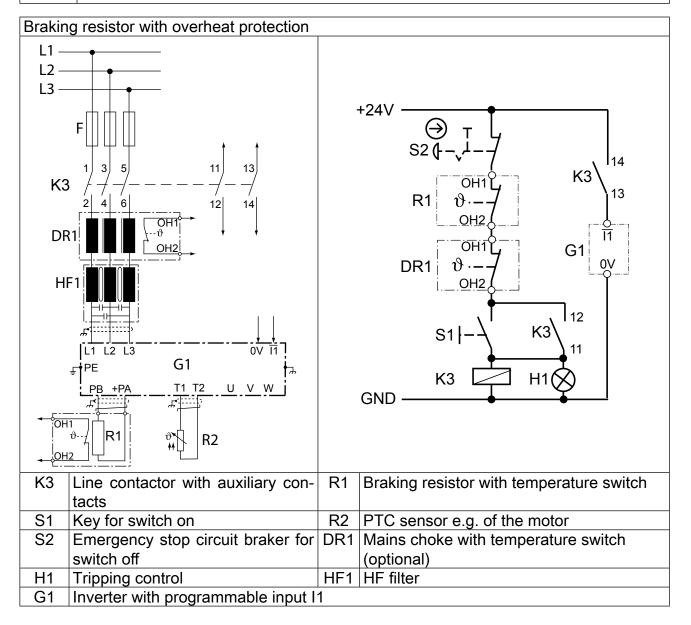


2.8.5.2 Braking resistor with overheat protection

This circuit offers a direct protection with defective braking transistor (GTR7). The braking resistor overheats and opens the terminals OH1 and OH2 with defective GTR7. The OH terminals open the holding circuit of the input contactor, so that the input voltage is switched off in error case. An error in inverter is released by opening the auxiliary contacts of K3. Regenerative operation is also secured by the internal fault disconnection. The input must be programmed and inverted to "external error". Automatic restarting after cooling of the braking resistor is prevented by the self-holding circuit of K3.

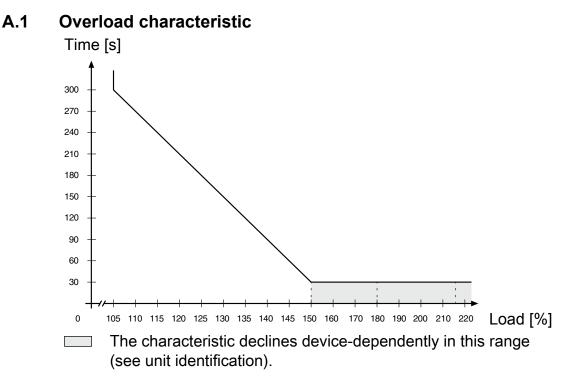


If the PTC evaluation of the motor at terminals T1/T2 is not used, these terminals can be used instead of the programmable input.





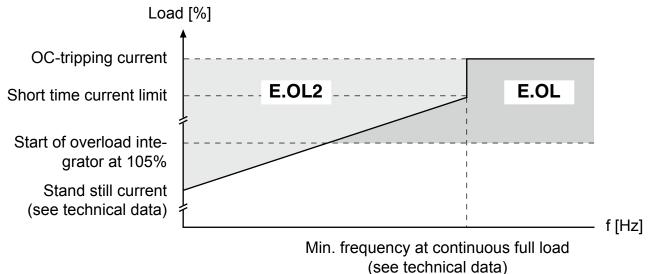
Annex A



On exceeding a load of 105% the overload integrator starts. When falling below the integrator counts backwards. If the integrator achieves the overload characteristic that corresponds to the inverter, the error E.OL is triggered.

A.2 Overload protection in the lower speed range

(only operating mode MULTI and SERVO)



A PT1 element (τ = 280 ms) starts if the permissible current is exceeded. After its sequence of operation the error E.OL2 is triggered.

A.3 Calculation of the motor voltage

The motor voltage for dimensioning of the drive is depending on the used components. The mains voltage reduces according to the following table:

Mains choke Uk	4%	Example:
Inverter open-loop	4%	Closed-loop inverter with mains- and motor choke at
Inverter closed-loop	8%	non-rigid supply system:
Motor choke Uk	1%	400V mains voltage - 15% = 340V motor voltage
Non-rigid supply sys-	2%	
tem		

A.4 Shut down

All work may only be done by qualified personnel. The security must be ensured as follows:

- Disconnect power supply at MCCB
- Secure against restarting
- Await discharge time of capacitors (if necessary controlling by measurement at "+PA" and "-", respectively "++" and "--")
 - and "--")
- Ensure loss of voltage by measurement

A.4.1 Maintenance

In order to avoid premature ageing and avoidable malfunctions, the measures mentioned below must be carried out in the appropriate cycle.

Cycle	Function
	Pay attention to unusual noises of the motor (e.g. vibrations) as well as of the
Constant	frequency inverter (e.g. fan).
Constant	Pay attention to unusual smells of the motor or frequency inverter (e.g. evapo-
	ration of capacitor electrolyte, braise of the motor winding)
	Check unit for loose screws and plugs and if necessary tighten up.
	Clean frequency inverter from dirt and dust deposits. Pay attention especially
	to cooling fins and protective grid of the fans.
Monthly	Examine and clean extracted air filter and cooling air filter of the control cabi-
	net.
	Examine function of the fans of the KEB COMBIVERT. The fans must be re-
	placed in case of audible vibrations or squeak.
Annual	Check the connecting ducts for corrosion and change it if necessary for units
Annual	with water cooling.

A.4.2 Storage

The DC link of the KEB COMBIVERT is equipped with electrolytic capacitors. If the electrolytic aluminium capacitors are stored de-energized, the internal oxide layer is removed slowly. Due to the leakage current the oxide layer is unrenewed. If the capacitor starts running with rated voltage there is a high leakage current which can destroy the capacitor. In order to avoid defectives, the KEB COMBIVERT must be started up depending on the stor-

age period in accordance with the following specification:

Storage period < 1 year	Storage period < 1 year				
 Start-up without special measurements 	ures				
Storage period 12 years					
· Operate frequency inverter on	e hour without modulation				
Storage period 23 years					
· Remove all cables from the pc	ower circuit; especially of brakin	g resistor or module			
Open control release	· · · · · · · · · · · · · · · · · · ·				
Connect variable transformer t	to inverter input				
Increase variable transformer	slowly to indicated input volta	ge (>1 min) and remain at			
least on the specified time.					
Voltage class	Input voltage	Residence time			
	0160 V	15 min			
230 V	160220V	15 min			
220260V 1h					
	0280 V 15 min				
400 V 280400 V 15 min					
	400500 V	1h			
Storage period > 3 years					

 Input voltages as before, however double the times per year. Eventually change capacitors.

After expiration of this start-up the KEB COMBIVERT can be operated on nominal rating conditions or delivered to a new storage.

A.4.3 Cooling circuit

The cooling circuit must be completely empty if a unit shall be switched off for a longer period. The cooling circuit must be blown out additionally with compressed air at temperatures below 0° C.

A.4.4 Fault correction

A defective device should only be repaired by KEB or an authorized partner. Defective components, modules or options may only be replaced by original parts. The device must be returned in original packaging with a detailed bug report.

A.4.5 Disposal

Defective devices which should not be repaired or which are not safe because of their service life are applied as electronic waste and must be disposed as hazardous waste according to the local regulations.

Annex B

B.1 Certification

B.1.1 CE Marking

CE marked frequency inverter and servo drives were developed and manufactured to comply with the regulations of the Low-Voltage Directive 2006/95/EC.

The inverter or servo drive must not be started until it is determined that the installation complies with the Machine directive (2006/42/EC) as well as the EMC-directive (2004/108/EC) (note EN 60204).

The frequency inverters and servo drives meet the requirements of the Low-Voltage Directive 2006/95/EC. They are subject to the harmonized standards of the series EN61800-5-1.

This is a product of limited availability in accordance with IEC 61800-3. This product may cause radio interference in residential areas. In this case the operator may need to take corresponding measures.

B.1.2 UL Marking



Acceptance according to UL is marked at KEB inverters with the adjacent logo on the type plate.

To be conform according to UL for use on the North American and Canadian Market the following additionally instructions must be observed (original text of the UL-File):

- For control cabinet mounting as "Open Type"
- "Only for use in WYE 480V/277V supply sources"
- Operator and Control Board Rating of relays (30 Vdc.: 1A)
- Maximum Surrounding Air Temperature 45 °C (113 °F)
- Overload protection at 130% of inverter output rated current (see type plate)
- Motor protection by adjustment of inverter parameters. For adjustment see application manual parameters Pn.14 and Pn.15.
- "Use 60/75°C Copper Conductors Only"
- Terminals Torque Value for Field Wiring Terminals, the value to be according to the R/C Terminal Block used.
- Use in a Pollution Degree 2 environment
- "Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the Manufacturer Instructions, National Electrical Code and any additional local codes", or the equivalent".

further on next side

• "E Housing, Series COMBIVERT Cat. No. 12, 13, 14, 15 or 16 followed by F5, followed by B or C, followed by 0, 1, 2 or 3, A, B, C or D, followed by E-, followed by four suffixes

E Housing, Series COMBIVERT Cat. No. 12, 13, 14, 15 or 16 followed by F6, followed by B or C, followed by 0, 1, 2 or 3, A, B, C or D, followed by E-, followed by three suffixes and followed by 4 or E or J.

Motor Overtemperature Protection:

above drive models are not provided with load and speed sensitive overload protection and thermal memory retention up on shutdown or loss of power (for details see NEC, article 430.126(A)(1)".

For 240 V Models:

"Suitable For Use On A Circuit Capable Of Delivering Not More Than 10000 rms Symmetrical Amperes, 240 Volts Maximum, when Protected by Fuses, see Instruction Manual for specified fuse details and alternate Branch Circuit Protection details."

For 480 V Models:

"Suitable For Use On A Circuit Capable Of Delivering Not More Than 10000 rms Symmetrical Amperes, 480 Volts Maximum, when Protected by Fuses, see Instruction Manual for specified fuse details and alternate Branch Circuit Protection details."

For all Models: Branch Circuit P

Inverter	Input	UL 248	Semiconductor fuses			
model	Voltage	Fuse class RK5 or J or CC	Cat. No.			
F5/F6	(V)	[A]	(#)			
12	480 / 3ph	25	50 140 06 25			
13	240 / 3ph	40	50 140 06 80			
13	480 / 3ph	25	50 140 06 40			
14	240 / 3ph	50	50 140 06 100			
14	480 / 3ph	30	50 140 06 50			
15	480 / 3ph	40	50 140 06 80			
16	480 / 3ph	50	50 140 06 100			
(#) manufactured by Siba Sicherungen-Bau GmbH						

The voltage rating of the Class rated fuses shall be at least equal to the voltage rating of the Drives.

Branch Circuit Protection:

Type E Self Protected Manual Motor Controllers for Drive series inverters F5–E and F6-E.

Listed (NKJH) Type E Self Protected Manual Motor Controllers. Type and manufacturer and electrical ratings as specified below: 240V devices:

Inverter model F5/F6	Drive input rat- ing	Self Protected Manual Motor Controller Type and manufacturer	Self Protected Manual Motor Controller rating
13	240V/ 3ph	PKZMO–32E, Eaton Industries	230V/3ph, 10 hp
14	240V/ 3ph	PKZM4–50E, Eaton Industries	230V/3ph, 15 hp

480V devices:

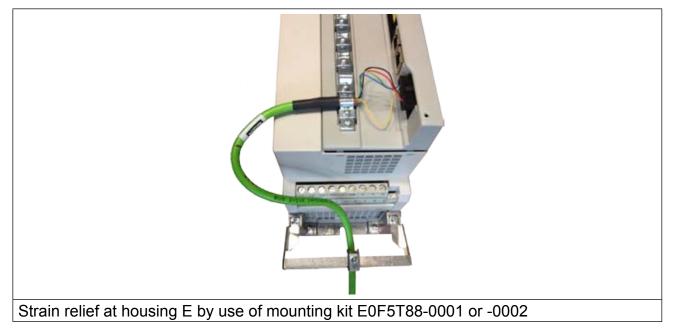
Inverter	Drive input rat-	Self Protected	Self Protected
model	ing (#)	Manual Motor Controller Type	Manual Motor Controller
F5/F6		and manufacturer	rating
12	480V/ 3ph	PKZMO-25E, Eaton Industries	480Y/277V, 15 hp
13	480V/ 3ph	PKZMO-25E, Eaton Industries	480Y/277V, 15 hp
14	480V/ 3ph	PKZMO-25E, Eaton Industries	480Y/277V, 15 hp
15	480V/ 3ph	PKZM4-40E, Eaton Industries	480Y/277V, 30 hp
16	480V/ 3ph	PKZM4-40E, Eaton Industries	480Y/277V, 30 hp

(#) all Drives series which use a Self Protected Motor Controller rated 480Y/277V are suitable for 480y/277V sources only.

Only for F6 housing E series:

"For Connector CN300 on Control Board:

Only use KEB Cable assembly Cat.No. 00H6L41-0xxx or 00H6L53-2xxx (where x = any digit) and use strain relief provisions as described below:"



Annex C

C.1 Installation of water-cooled units

In continuous operation water-cooled inverters are operated with lower temperature than air-cooled inverters. This has positive effects on lifetime-relevant components such as fan and DC link circuit capacitors and power modules (IGBT). Also the temperature dependent switching losses are positively effected. The use of water-cooled KEB COMBIVERT frequency inverters is offered in the drive technology, because there are process-caused coolants available with some applications. The following instructions must be observed absolutely when this units are used.

C.1.1 Heat sink and operating pressure

Design system	Material (voltage)	Max. operating pres- sure	Connecting duct
2-plate heat sink	Aluminium (-1.67V)	6 bar	0000650-G140

The heat sinks are sealed with sealing rings and posses a surface protection (anodized) even in the ducts.



In order to avoid a deformation of the heat sink and the damages involved, the indicated max. operating pressure may not be exceeded briefly also by pressure peaks.

Pay attention to the guidelines 97/23/EC of pressure units.

C.1.2 Materials in the cooling cicuit

For the screw connections and also for the metallic articles in the cooling circuit which are in contact with the coolant (electrolyte) a material is to be selected, which forms a small voltage difference to the heat sink in order to avoid contact corrosion and/or pitting corrosion (electrochemical series, see table 1.5.2). An aluminum screw connection or ZnNi coated steel screw connection is recommended. Other materials must be examined in each case before employment. The specific case of application must be checked by the customer in tuning of the complete cooling circuit and must be classified according to the used materials. With hoses and seals take care that halogen-free materials are used.

Liability for occuring damages by wrongly used materials and from this resulting corrosion cannot be taken over!

Table 1.5.2	Electrochemical series / standard potentials against hydrogen						
Material	generated lon	Standard po- tential	Material	generated lon	Standard po- tential		
Lithium	Li⁺	-3.04 V	Cobald	Co ²⁺	-0.28 V		
Potassium	K⁺	-2.93V	Nickel	Ni ²⁺	-0.25 V		
Calcium	Ca ²⁺	-2.87 V	Tin	Sn ²⁺	-0.14 V		
Sodium	Na⁺	-2.71V	Lead	Pb ³⁺	-0.13 V		
Magnesium	Mg ²⁺	-2.38 V	Iron	Fe ³⁺	-0.037 V		
Titan	Ti ²⁺	-1.75V	Hydrogen	2H⁺	0.00 V		
Aluminium	Al ³⁺	-1.67 V	Copper	Cu ²⁺	0.34 V		

Table 1.5.2	Electrochemica	Electrochemical series / standard potentials against hydrogen					
Material	generated lon	Standard po- tential	Material	generated lon	Standard po- tential		
Manganese	Mn ²⁺	-1.05V	Carbon	C ²⁺	0.74 V		
Zinc	Zn ²⁺	-0.76V	Silver	Ag⁺	0.80 V		
Chrome	Cr³⁺	-0.71V	Platinum	Pt ²⁺	1.20 V		
Iron	Fe ²⁺	-0.44 V	Gold	Au ³⁺	1.42 V		
Cadmium	Cd ²⁺	-0.40 V	Gold	Au⁺	1.69 V		

C.1.3 Requirements on the coolant

The requirements on the coolant are depending on the ambient conditions, as well as from the used cooling system. General requirements on the coolant:

Standards	TrinkwV 2001, DIN EN 12502 part 1-5, DIN 50930 part 6, DVGW work sheet W216			
VGB Cooling water direc- tive	The VGB cooling water directive (VGB-R 455 P) contains instructions about common process technology of the cooling. Particulary the in- teractions between cooling water and components of the cooling sys- tem are described.			
pH-value	Aluminum is particularly corroded by lixiviums and salts. The optimal pH value for aluminum should be in the range of 7.5 8.0.			
Abrasive substanc- es	Abrasive substances as used in abrasive (quartz sand), clogging the cooling circuit.			
Copper cuttings	Copper cuttings can attach the aluminum and this leads to a galvanic corrosion. Copper should not be used together with aluminum due to electro-chemical voltage difference.			
Hard water	Cooling water may not cause scale deposits or loose excretions. It shall have a low total hardness (<20°d) especially carbon hardness.			
Soft water	Soft water (<7°dH) corrodes the material.			
Frost protection	An appropriate antifreeze must be used for applications when the heat sink or the coolant is exposed temperatures below zero. Use only products of one manufacturer for a better compatibility with other additives.			
Corrosion protec- tion	Additives can be used as corrosion protection. In connection with frost protection the antifreeze must have a concentration of 2025 Vol %, in order to avoid a change of the additives.			

Special requirements for open and half-open cooling systems:

Impurities	Mechanical impurities in half-open cooling systems can be counter- acted when appropriate water filters are used.				
Salt concentration	The salt content can increase through evaporation at half-open sys- tems. Thus the water is more corrosive. Adding of fresh water and removing of process water works against.				
Algae and myxo- bacteria	Algae and myxobacteria can arise caused by increased water tem- perature and contact with atmospheric oxygen. The algae and myxo- bacteria clog the filters and obstruct the water-flow. Biocide containing additives can avoid this. Especially at longer OFF periods of the cool- ing circuit preventive maintenance is necessary.				
Organic materials	The contamination with organic materials must be kept as small as possible, because separate slime can be caused by this				
Damages at the unit which are caused by clogged, corroded heat sinks or other obvious operating errors, leads to the loss of the warranty claims.					

C.1.4 Connection to the cooling system

- Screw in connecting duct in accordance with the manual
- The connection to the coolant must be carried out with flexible, pressure-resistant hoses and secured with clamps.
- · Pay attention to flux direction and check tightness!
- The cooling flow must always be started before starting the KEB COMBIVERT.

The connection to the cooling system can occur as closed or open cooling circuit. The connection to a closed cycle cooling circuit is recommended, because the danger of contamination of coolant is very small. Preferably also a monitoring of the pH value of the coolant should be installed.

Pay attention to a corresponding cable cross-section at required equipotential bonding in order to avoid electro-chemical procedures.

C.1.5 Coolant temperature and moisture condensation

The inlet temperature may not exceed 40 °C. The maximum heat sink temperature is 90 °C depending on the power unit and overload capacity (see "Technical data"). To ensure a safe operation the coolant output temperature must be 10 K below this temperature.

Due to high air humidity and high temperatures it can lead to moisture condensation. Moisture condensation is dangerous for the inverter, because the inverter can be destroyed by any resulting short-circuits.

The user must guarantee that any moisture condensation is avoided!

In order to avoid a moisture condensation the following possibilities can be done. The application of both methods is recommended.

Supply of temper coolant

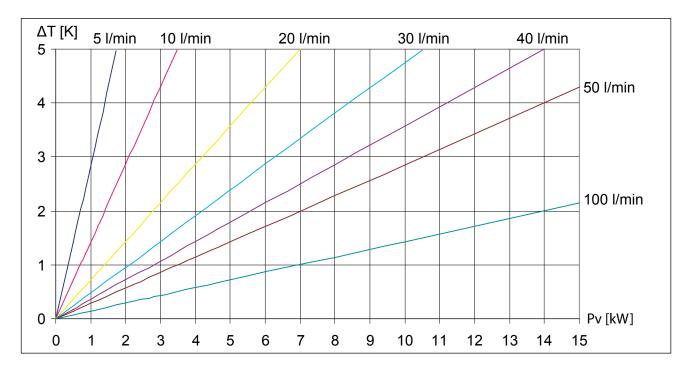
This is possible by using heatings in the cooling circuit for the control of the coolant temperature. The following dew point table is available for this:

Air humidity [%]	10	20	30	40	50	60	70	80	90	100
Surrounding										
temperature [°C]										
-25	-45	-40	-36	-34	-32	-30	-29	-27	-26	-25
-20	-42	-36	-32	-29	-27	-25	-24	-22	-21	-20
-15	-37	-31	-27	-24	-22	-20	-18	-16	-15	-15
-10	-34	-26	-22	-19	-17	-15	-13	-11	-11	-10
-5	-29	-22	-18	-15	-13	-11	-8	-7	-6	-5
0	-26	-19	-14	-11	-8	-6	-4	-3	-2	0
5	-23	-15	-11	-7	-5	-2	0	2	3	5
10	-19	-11	-7	-3	0	1	4	6	8	9
15	-18	-7	-3	1	4	7	9	11	13	15
20	-12	-4	1	5	9	12	14	16	18	20
25	-8	0	5	10	13	16	19	21	23	25
30	-6	3	10	14	18	21	24	26	28	30
35	-2	8	14	18	22	25	28	31	33	35
40	1	11	18	22	27	31	33	36	38	40
45	4	15	22	27	32	36	38	41	43	45
50	8	19	28	32	36	40	43	45	48	50

Coolant inlet temperature [°C] is depending on ambient temperature and air humidity

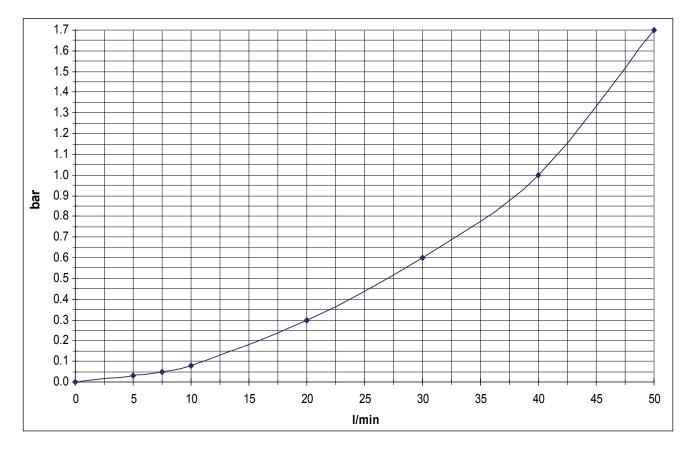
Temperature control

The cooling system can be connected by means of pneumatic or magnetic valves. A relay is frontend. In order to avoid pressure surges, the valves for the temperature control must be inserted before the cooling circuit. All usual valves can be used. Pay attention that the valves are faultless and do not clamp.



C.1.6 Coolant heating depending on power loss and flow rate with water

C.1.7 Typically fall of pressure depending on the rate of flow

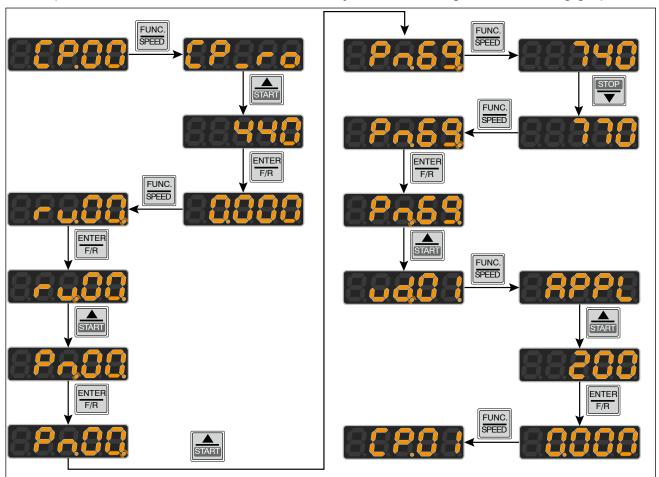


Annex D

D.1 Changing the response threshold of the braking transistor

(not valid for control type "BASIC")

To avoid a premature switching of the brake transistor at an input rated voltage of 480 Vac, the response threshold must be controlled or adjusted according to the following graphic.







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